

GenAssets: Generating in-the-wild 3D Assets in Latent Space

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Motivation

+ Simulation is Important for Developing Safe Autonomous Systems



World Modeling (Digital Twin Creation)

+ Existing Approaches:





Artistic-created CAD assets

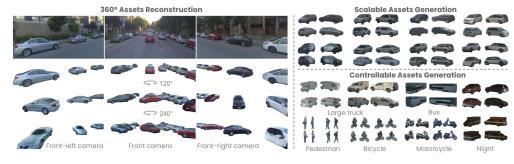
- Requires manual efforts
- Lacks diversity
- Lacks Realism

Per-scene Reconstruction

Slow optimization

- Lacks diversity
- Lacks Giversity
 Lacks Completion

GenAssets: Learning Assets Recon/Generation from in-the-wild Data



GenAssets for Simulation

+ Replacing Existing Actors with Generated Counterparts



+ Generating Extreme Scenario Variations



GenAssets Method

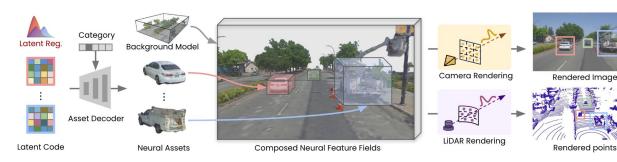
- + Learning Latent Asset Representations via Occlusion-Aware Neural Rendering
 - Motivation: Learning a compact and complete latent space for neural assets

\circ Approach

- Each assets is represented as a low dimensional latent code
- A shared asset decoder is trained to map the latent code into neural assets
- The neural assets is composed with learnable background models to form a compositional neural scene representation
- The scene representation is rendered to match real-world sensor observations

• Benefit

- Trained across many scenes to learn asset priors
- Compact space learning to reduce computation and memory for large datasets
- Latent bottleneck encourages the model to learn asset priors
- Infer occluded or unobserved regions from sparse observations.

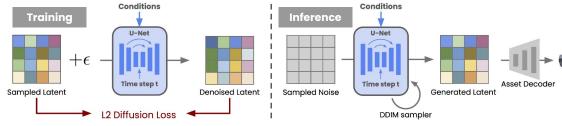


Learning Latent Asset Diffusion Model

- Motivation: Learning asset generation in the latent space with diffusion model
- Approach
 - Training a diffusion probabilistic model in the latent space
- Sample from the learned diffusion priors using the DDIM solver
- The asset decoder decodes the generated latent code to the neural asset

o Benefit

- Focusing on essential contents of the data
- Operating in a computationally efficient, compact space
- Support both conditional or unconditional generation



Learning Objective

• Reconstruction loss and regularization in latent space

$$\mathcal{L} = \mathcal{L}_{\text{rgb}} + \lambda_{\text{perp}} \mathcal{L}_{\text{perp}} + \lambda_{\text{adv}} \mathcal{L}_{\text{adv}} + \lambda_{\text{lid}} \mathcal{L}_{\text{lid}} + \lambda_{\text{KL}} \mathcal{L}_{\text{KL}}$$

$$\circ \text{ Latent diffusion loss}$$

$$\mathcal{L}_{\text{diff}} = \mathbb{E}_{\mathbf{c}, \boldsymbol{\epsilon}, t} \left[\frac{1}{2} w^{(t)} \| f_{\text{diff}}(\mathbf{c}^{(t)}, t) - \boldsymbol{\epsilon} \|_2^2 \right]$$

The actor ahead executes a U-turn



Generative Models

- Synthetic / Object-centric
- Lacks 3D supervision
- Domain Gap





Results Asset Reconstruction • Sparse View Synthesis ********************* Taraet frames (90%) G3R Street Gaussian GT NeuRAD Ours • Novel Camera Synthesis V Source: Front camera 🔿 🕺 Target: Front-left camera G3R GT Street Gaussian NeuRAD Ours • 360° Synthesis GT G3R Street Gaussian NeuRAD Ours **Asset Generation** • Unconditional Generation EG3D DiscoScene SSDNeRF Ours • Conditional Generation Car Construction vehicle Bus Fruck Pedestrian Bicycle Motorcycle Night time • Single Image to 3D Generation