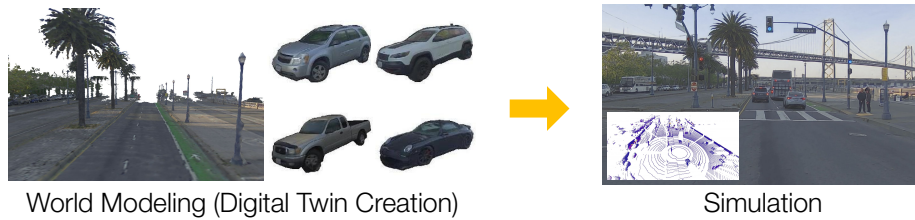
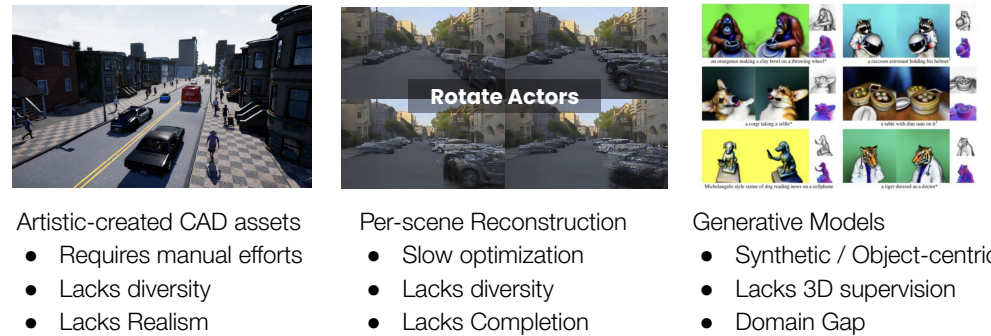


Motivation

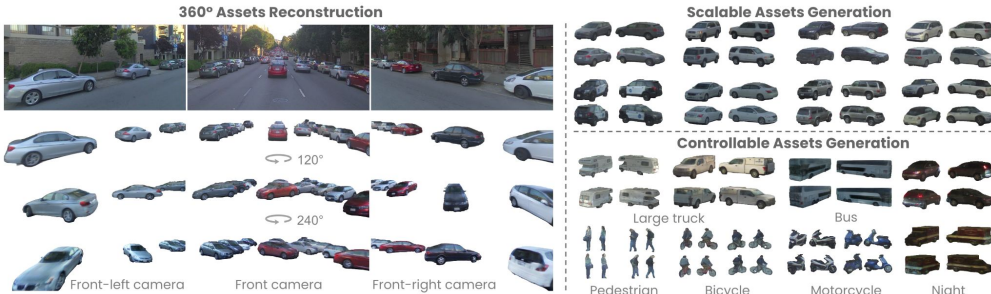
+ Simulation is Important for Developing Safe Autonomous Systems



+ Existing Approaches:

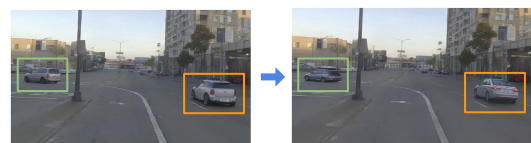


+ GenAssets: Learning Assets Recon/Generation from in-the-wild Data



GenAssets for Simulation

+ Replacing Existing Actors with Generated Counterparts



	mAP↑	AP@1m↑	AP@2m↑
Real	27.08	8.58	26.99
Real + Sim	29.32	9.78	29.18

GenAssets augmentation improves 3D detection

+ Generating Extreme Scenario Variations

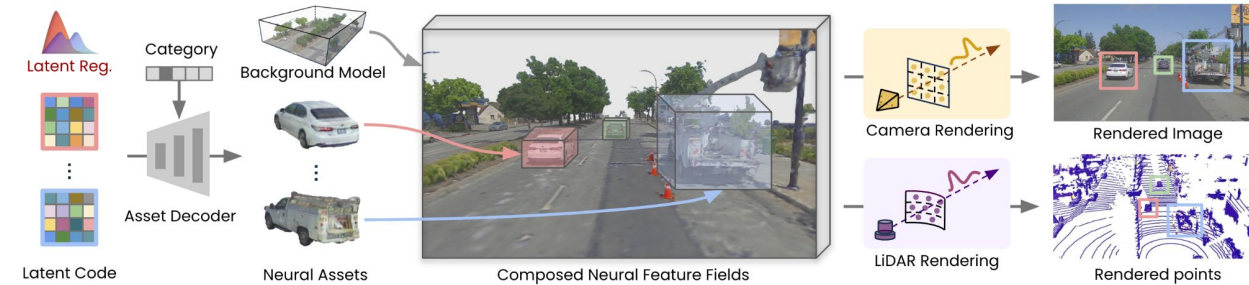


The actor ahead executes a U-turn

GenAssets Method

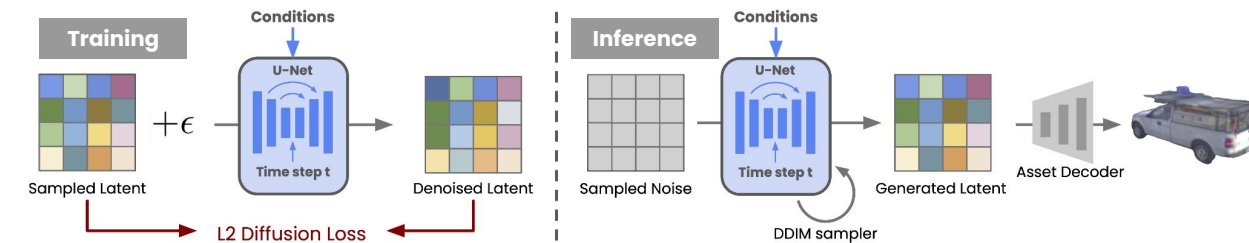
+ Learning Latent Asset Representations via Occlusion-Aware Neural Rendering

- Motivation:** Learning a compact and complete latent space for neural assets
- Approach**
 - Each asset is represented as a low dimensional *latent code*
 - A shared *asset decoder* is trained to map the latent code into *neural assets*
 - The *neural assets* is composed with learnable background models to form a compositional neural scene representation
 - The scene representation is rendered to match real-world sensor observations
- Benefit**
 - Trained across many scenes to learn asset priors
 - Compact space learning to reduce computation and memory for large datasets
 - Latent bottleneck encourages the model to learn asset priors
 - Infer occluded or unobserved regions from sparse observations.



+ Learning Latent Asset Diffusion Model

- Motivation:** Learning asset generation in the latent space with diffusion model
- Approach**
 - Training a diffusion probabilistic model in the latent space
 - Sample from the learned diffusion priors using the DDIM solver
 - The *asset decoder* decodes the generated latent code to the neural asset
- Benefit**
 - Focusing on essential contents of the data
 - Operating in a computationally efficient, compact space
 - Support both conditional or unconditional generation

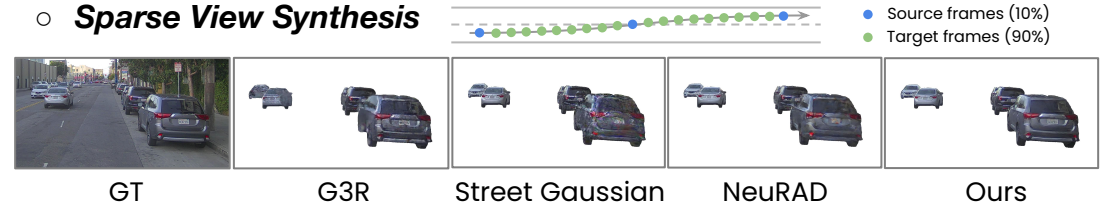


+ Learning Objective

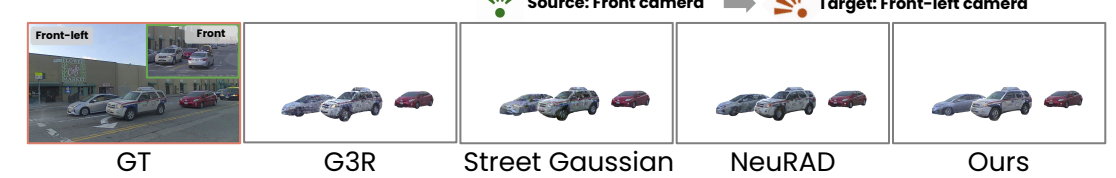
- Reconstruction loss and regularization in latent space
 - Latent diffusion loss
- $$\mathcal{L} = \mathcal{L}_{\text{rgb}} + \lambda_{\text{perp}} \mathcal{L}_{\text{perp}} + \lambda_{\text{adv}} \mathcal{L}_{\text{adv}} + \lambda_{\text{lid}} \mathcal{L}_{\text{lid}} + \lambda_{\text{KL}} \mathcal{L}_{\text{KL}}$$
- $$\mathcal{L}_{\text{diff}} = \mathbb{E}_{\mathbf{c}, \epsilon, t} \left[\frac{1}{2} w^{(t)} \|f_{\text{diff}}(\mathbf{c}^{(t)}, t) - \epsilon\|_2^2 \right]$$

Results

+ Asset Reconstruction



+ Novel Camera Synthesis

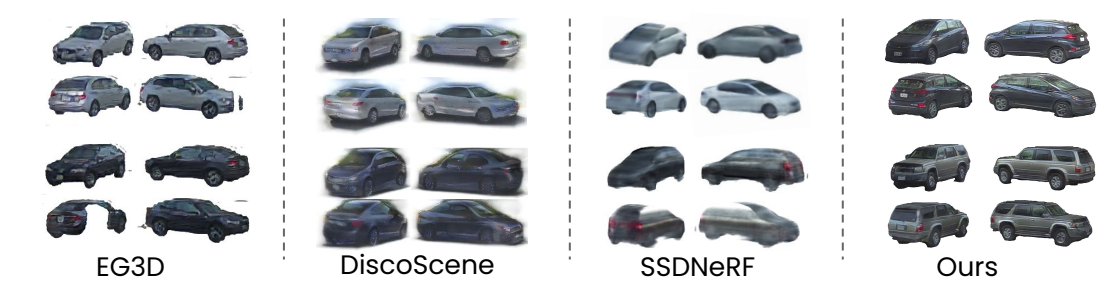


+ 360° Synthesis

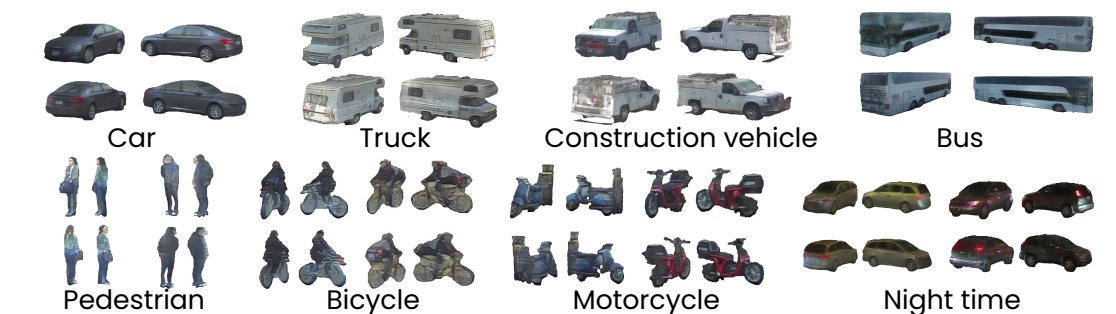


+ Asset Generation

+ Unconditional Generation



+ Conditional Generation



+ Single Image to 3D Generation

