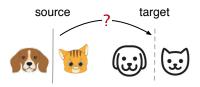
# **Optimal Representations for Covariate Shift**

#### Yangjun Ruan

Joint with Yann Dubois, Chris J. Maddison

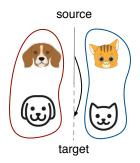
**ICLR 2022** 

ML experiences distribution shifts from train (source) to test (target)



ML experiences distribution shifts from train (source) to test (target)

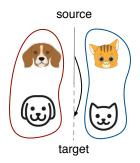
**Goal:** learn robust representations Z of data X from which source  $(d_s)$  predictors perform well on target  $(d_t)$ 



ML experiences distribution shifts from train (source) to test (target)

**Goal:** learn robust representations Z of data X from which source  $(d_s)$  predictors perform well on target  $(d_t)$ 

**Optimal**  $Z^*$ : all source optimal predictors minimize target risk



We characterize the optimally robust  $Z^*$  to covariate shift

 $\odot$  prove sufficient and necessary condition for optimal  $Z^*$ 

We characterize the optimally robust  $Z^*$  to covariate shift

- $\odot$  prove sufficient and necessary condition for optimal  $Z^*$
- $\odot$  derive practical self-supervised objectives for learning  $Z^*$

We characterize the optimally robust  $Z^*$  to covariate shift

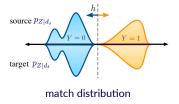
- $\odot$  prove sufficient and necessary condition for optimal  $Z^*$
- $\odot$  derive practical self-supervised objectives for learning  $Z^*$
- ③ show why CLIP [4] is more robust over other SSL methods

We characterize the optimally robust  $Z^*$  to covariate shift

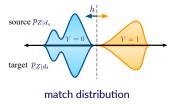
- $\odot$  prove sufficient and necessary condition for optimal  $Z^*$
- $\odot$  derive practical self-supervised objectives for learning  $Z^*$
- © show why CLIP [4] is more robust over other SSL methods
- improve CLIP's robustness with our objectives

# Theory: Characterizing $Z^*$

**Desiderata:** reduce to typical ML setup in Z space

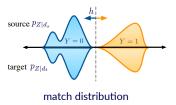


**Desiderata:** reduce to typical ML setup in Z space



✓ Sufficient condition (...most previous work hinted towards)

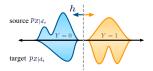
**Desiderata:** reduce to typical ML setup in Z space



- ✓ Sufficient condition (...most previous work hinted towards)
- X Necessary? Achievable?

#### Minimal sufficiency: $Z^*$ should

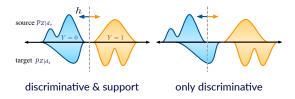
- remain discriminative about Y
- have invariant support



discriminative & support

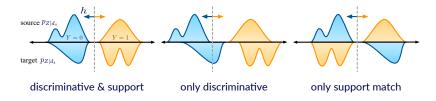
#### Minimal sufficiency: $Z^*$ should

- remain discriminative about Y
- have invariant support



#### Minimal sufficiency: $Z^*$ should

- remain discriminative about Y
- have invariant support



### Formalization with domain generalization (DG) language:

- 1. Given
  - A set of domains  $\mathcal{D}$
  - ullet Domain-specific  $\left\{p_{X,\,Y\,|\,\,d}
    ight\}_{d\in\mathcal{D}}$
  - Loss  $\ell: \mathcal{Y} \times \Gamma \to \mathbb{R}_{\geq 0}$

[Asm: discrete finite]

[Asm: gen. covariate shift]

### Formalization with domain generalization (DG) language:

- 1. Given
  - A set of domains  $\mathcal{D}$
  - Domain-specific  $\left\{p_{X,Y\mid d}\right\}_{d\in\mathcal{D}}$
  - Loss  $\ell: \mathcal{Y} \times \Gamma \to \mathbb{R}_{\geq 0}$
- 2. Learn an encoder  $p_{Z|X}$

[Asm: discrete finite]

[Asm: gen. covariate shift]

#### Formalization with domain generalization (DG) language:

- 1. Given
  - A set of domains  $\mathcal{D}$
  - Domain-specific  $\{p_{X,Y|d}\}_{d\in\mathcal{D}}$
  - Loss  $\ell: \mathcal{Y} \times \Gamma \to \mathbb{R}_{\geq 0}$

- [Asm: discrete finite]
- [Asm: gen. covariate shift]

- 2. Learn an encoder  $p_{Z|X}$
- 3. Measure DG risk:
  - Select a random source  $D_s$  and target  $D_t$
  - Train a source predictor:  $h \in \mathcal{H}_{D_s}^* := \arg\min_h \mathrm{R}_h^{D_s} \left[ Y | Z \right]$
  - Measure target risk  $R_h^{D_t}[Y|Z]$

where 
$$\mathrm{R}_{\scriptscriptstyle h}^{\scriptscriptstyle d}\left[\left.Y\right|\left.Z\right]:=\mathbb{E}_{p_{Z,\left.Y\right|\left.d}}[\ell(\left.Y,h(Z)\right)]\right.$$

**Goal:** minimize the idealized domain generalization (IDG) risk w.r.t. Z

$$\mathbf{R}_{\mathrm{IDG}}\left[\left.Y\right|Z\right] := \underbrace{\mathbb{E}_{p_{Ds,D_t}}}_{\substack{\mathsf{random} \\ \mathsf{domains}}} \underbrace{\sup_{h \in \mathcal{H}_{Ds}^*}}_{\substack{h \in \mathcal{H}_{Ds}^*}} \underbrace{\mathbb{R}_{h}^{D_t}\left[\left.Y\right|Z\right]}_{\substack{\mathsf{target risk}}}$$

#### **Uniform guarantees:**

- · random domains
- worst-case source predictor

**Goal:** minimize the idealized domain generalization (IDG) risk w.r.t. Z

$$\mathbf{R}_{\mathrm{IDG}}\left[\left.Y\right|Z\right] := \underbrace{\mathbb{E}_{p_{Ds},D_t}}_{\substack{\mathsf{random} \\ \mathsf{domains}}} \underbrace{\sup_{h \in \mathcal{H}_{Ds}^*}}_{\substack{h \in \mathcal{H}_{Ds}^* \\ \mathsf{risk} \ \mathsf{min}}} \underbrace{\mathbf{R}_h^{D_t}\left[\left.Y\right|Z\right]}_{\substack{\mathsf{target} \ \mathsf{risk}}}$$

#### **Uniform guarantees:**

- random domains
- worst-case source predictor

#### **Idealized setup** for simplicity:

- population risk used for source predictor selection
- universal hypothesis class

#### Theorem (Optimality conditions, informal)

Under generalized covariate shift and some mild assumptions,  $Z^{*}$  is optimal for IDG if and only if it

- remains discriminative:  $R[Y|Z^*] = R[Y|X]$
- has invariant support:  $\operatorname{supp}(p_{Z^* \mid d_s}) = \operatorname{supp}(p_{Z^* \mid d_t}), \ \forall d_s, d_t \in \mathcal{D}$

#### Theorem (Optimality conditions, informal)

Under generalized covariate shift and some mild assumptions,  $Z^*$  is optimal for IDG if and only if it

- remains discriminative:  $R[Y|Z^*] = R[Y|X]$
- has invariant support:  $\operatorname{supp}(p_{Z^* \mid d_s}) = \operatorname{supp}(p_{Z^* \mid d_t}), \ \forall d_s, d_t \in \mathcal{D}$

achievable sufficient and necessary condition

#### Theorem (Optimality conditions, informal)

Under generalized covariate shift and some mild assumptions,  $Z^*$  is optimal for IDG if and only if it

- remains discriminative:  $R[Y|Z^*] = R[Y|X]$
- has invariant support:  $\operatorname{supp}(p_{Z^* \mid d_s}) = \operatorname{supp}(p_{Z^* \mid d_t}), \ \forall d_s, d_t \in \mathcal{D}$
- achievable sufficient and necessary condition
- requires access to labeled target domain

#### Proposition (No free lunch for IDG, informal)

Let  $Z_{d_s}$  be any rep. chosen on some source  $d_s$  and C a constant rep.

Under mild assumptions, if  $Z_{d_s}$  outperforms C on some "good" targets outside the source's support, there are many "bad" targets on which  $Z_{d_s}$  is strictly worse than C.

#### Proposition (No free lunch for IDG, informal)

Let  $Z_{d_s}$  be any rep. chosen on some source  $d_s$  and C a constant rep.

Under mild assumptions, if  $Z_{d_s}$  outperforms C on some "good" targets outside the source's support, there are many "bad" targets on which  $Z_{d_s}$  is strictly worse than C.

- ✓ implies the failure of current DG methods
  - ② unable to outperform ERM on a unified benchmark [3]
  - insufficient access to or strong asmp. on targets

#### Proposition (No free lunch for IDG, informal)

Let  $Z_{d_s}$  be any rep. chosen on some source  $d_s$  and C a constant rep.

Under mild assumptions, if  $Z_{d_s}$  outperforms C on some "good" targets outside the source's support, there are many "bad" targets on which  $Z_{d_s}$  is strictly worse than C.

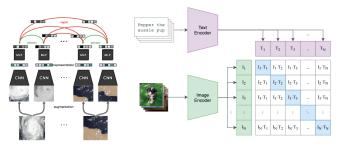
- ✓ implies the failure of current DG methods
  - ② unable to outperform ERM on a unified benchmark [3]
  - insufficient access to or strong asmp. on targets
- \* how to deal with necessary (but unrealistic) access to targets?

# Method: Learning $Z^*$ with SSL

# **Deviation: Self-Supervised Learning (SSL)**

Recent SSL methods learn transferable and robust reps.:

- train on large-scale unlabelled data (≫= ImageNet)
- use augmentations as surrogate information for Y



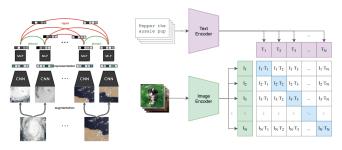
SimCLR [1]: image aug.

CLIP [4]: text caption as aug.

# **Deviation: Self-Supervised Learning (SSL)**

Recent SSL methods learn transferable and robust reps.:

- train on large-scale unlabelled data (≫= ImageNet)
- use augmentations as surrogate information for Y



SimCLR [1]: image aug.

CLIP [4]: text caption as aug.

Robustness of different SSL methods varies:

© CLIP achieves incredible robustness to distribution shifts

### **Augmentation** A for learning $Z^*$ :

 $\bullet \;$  Label-perserving: retain information about Y

## **Augmentation** A for learning $Z^*$ :

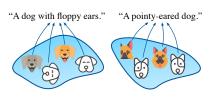
- ullet Label-perserving: retain information about Y
- Domain-agnostic: no correlation with domain

#### **Augmentation** A for learning $Z^*$ :

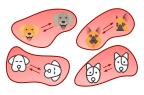
- Label-perserving: retain information about Y
- Domain-agnostic: no correlation with domain

#### Domain-agnostic A

- ✓ Example: image-text aug. (e.g., CLIP [4])
- ✗ Counterexample: standard image aug. (e.g., SimCLR [1])



CLIP aug.  $\Rightarrow$  domain-agnostic rep.



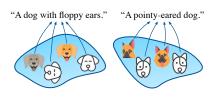
SimCLR aug.  $\Rightarrow$  domain-correlated rep.

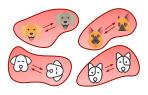
### **Augmentation** A for learning $Z^*$ :

- ullet Label-perserving: retain information about Y
- Domain-agnostic: no correlation with domain

#### Domain-agnostic A

- ✓ Example: image-text aug. (e.g., CLIP [4])
- ✗ Counterexample: standard image aug. (e.g., SimCLR [1])





CLIP aug.  $\Rightarrow$  domain-agnostic rep.

SimCLR aug.  $\Rightarrow$  domain-correlated rep.

implies the incredible robustness of CLIP over other SSL models

### Proposition (Learning $Z^*$ with domain-agnostic A)

Let  $p_{A \mid X}$  be a domain-agnostic augmenter. Then any optimal solution  $p_{Z^* \mid X}$  of the following objective is optimal for IDG:

$$\max_{p_{Z\mid X}} \text{I}[A; Z]$$
 s.t. 
$$\text{supp}(p_{Z\mid d}) = \text{supp}(p_Z), \ \forall d \in \mathcal{D}$$

### Proposition (Learning $Z^*$ with domain-agnostic A)

Let  $p_{A \mid X}$  be a domain-agnostic augmenter. Then any optimal solution  $p_{Z^* \mid X}$  of the following objective is optimal for IDG:

$$\max_{p_{Z\mid X}} \mathrm{I}[A;Z]$$
 s.t. 
$$\mathrm{supp}(p_{Z\mid d}) = \mathrm{supp}(p_Z), \ \forall d \in \mathcal{D}$$

- No Yanymore!
- support invariance constraint

### **Practical objectives:**

$$\underset{p_{Z \mid X}}{\arg \min} \quad \underbrace{-\operatorname{I}[A;Z]}_{\text{max. MI}} + \lambda \quad \underbrace{\operatorname{B}[Z,D]}_{\text{dom. bottleneck}}$$

#### **Practical objectives:**

$$\underset{p_{Z \mid X}}{\arg \min} \quad \underbrace{-\operatorname{I}[A;Z]}_{\text{max. MI}} + \lambda \quad \underbrace{\operatorname{B}[Z,D]}_{\text{dom. bottleneck}}$$

- Maximize I[A; Z]: MI lower bound (e.g., InfoNCE)
- Domain bottleneck B[Z, D]: enforce support invariance

#### **Practical objectives:**

$$\underset{p_{Z|X}}{\operatorname{arg\,min}} \quad \underbrace{-\operatorname{I}[A;Z]}_{\text{max. MI}} + \lambda \quad \underbrace{\operatorname{B}[Z,D]}_{\text{dom. bottlened}}$$

- Maximize I[A; Z]: MI lower bound (e.g., InfoNCE)
- Domain bottleneck B[Z, D]: enforce support invariance

Domain bottleneck: previous DG methods (e.g., DANN [2]) can apply

- $\square$  Contrastive adversarial domain (CAD) bottleneck I[Z;D]
  - © Requires no explicit trainable domain classifier
  - © Constructs an implicit domain classifier from contrastive var. dist.
- $\square$  Entropy (Ent) bottleneck H[Z]
  - © Requires no access to domain information

**Summary:** one can learn optimal  $Z^*$  with SSL using:

- large-scale unlabeled data
- contrastive learning with domain-agnostic augmentations
- domain bottlenecks

## Experiments

## Exploiting Pretrained CLIP for $Z^*$

Motivation: CLIP was trained

- ✓ with 400M image-text augmentations
- without explicit domain bottlenecks

#### Idea:

- Finetune CLIP with bottlenecks on available data
- Evaluate with linear probe on DomainBed [3]

## Exploiting Pretrained CLIP for $Z^*$

Algorithm	VLCS	PACS	OfficeHome	DomainNet	
ERM DomainBed SOTA		$86.7 \pm 0.3 \\ 87.2 \pm 0.1$	$66.4 \pm 0.5 \\ 68.4 \pm 0.2$	$41.3 \pm 0.1 \\ 41.8 \pm 0.1$	
DINO + CAD	69.6 ± 0.6	$\textbf{76.1} \pm \textbf{0.1}$	56.9 ± 0.5	$33.6 \pm 0.1$	
CLIP CLIP + CAD	$ \begin{vmatrix} 80.7 \pm 0.4 \\ 81.6 \pm 0.1 \end{vmatrix} $	$93.7 \pm 0.8$ $94.9 \pm 0.3$	$79.6 \pm 0.1 \\ 80.0 \pm 0.2$	$52.8 \pm 0.1 \\ 53.7 \pm 0.1$	

© SOTA result with domain-agnostic aug. and bottlenecks!

## **Towards Generic Robust Representations with SSL**

**Idea:** learn task- and domain-agnostic robust reps.

- Task: use LAION-400M [5] with text-image contrastive loss
- Domain: finetune CLIP with Ent bottleneck

## **Towards Generic Robust Representations with SSL**

Idea: learn task- and domain-agnostic robust reps.

- Task: use LAION-400M [5] with text-image contrastive loss
- Domain: finetune CLIP with Ent bottleneck

**Evaluate:** natural distribution shift [6]

	IN	IN-V2	IN-S	YT-BB	IN-Vid	ObjNet	IN-A	IN-R	Avg.
Pretrained	75.2	64.2	41.0	58.4	71.6	42.8	27.5	62.9	52.6
Tuned w/o Ent	73.8	62.1	37.0	56.9	68.8	41.3	26.0	58.1	50.0
Tuned w/ Ent	74.2	62.7	38.9	58.1	70.1	42.1	26.2	60.8	51.3

- © Consistently improved robustness with bottlenecks!
- © Gains could be larger if end-to-end trained with bottlenecks!

#### **Future Directions**

- Non-idealized setups: finite sample case, constrained hypothesis?
- Approx. optimality: relaxed constraints?
- More practical methods for learning  $Z^*$ ?
- Implicit regularization effect for learning Z\*?
- ..

# Thank you!

#### Amazing co-authors:



Yann Dubois



Chris J. Maddison

#### References i

- [1] T. Chen et al. A simple framework for contrastive learning of visual representations. In *ICML*, 2020.
- [2] Y. Ganin, E. Ustinova, H. Ajakan, P. Germain, H. Larochelle, F. Laviolette, M. Marchand, and V. Lempitsky. **Domain-adversarial training of neural networks.** *The journal of machine learning research*, 17(1):2096–2030, 2016.
- [3] I. Gulrajani and D. Lopez-Paz. In search of lost domain generalization. In *ICLR*, 2021.
- [4] A. Radford et al. Learning transferable visual models from natural language supervision. In *ICML*, 2021.

#### References ii

- [5] C. Schuhmann et al. Laion-400m: Open dataset of clip-filtered 400 million image-text pairs. arXiv preprint arXiv:2111.02114, 2021.
- [6] R. Taori et al. Measuring robustness to natural distribution shifts in image classification. arXiv preprint arXiv:2007.00644, 2020.