DECOUPLING SEMANTIC CONTEXT AND COLOR CORRELATION **IEEE ICME 2019** July 8-12, 2019 Shanghai, China WITH MULTI-TASK CROSS BRANCH REGULARIZATION Vishal Keshav, Tejpratap G.V.S.L SANSUNG

Samsung Research Institute Bengaluru, India

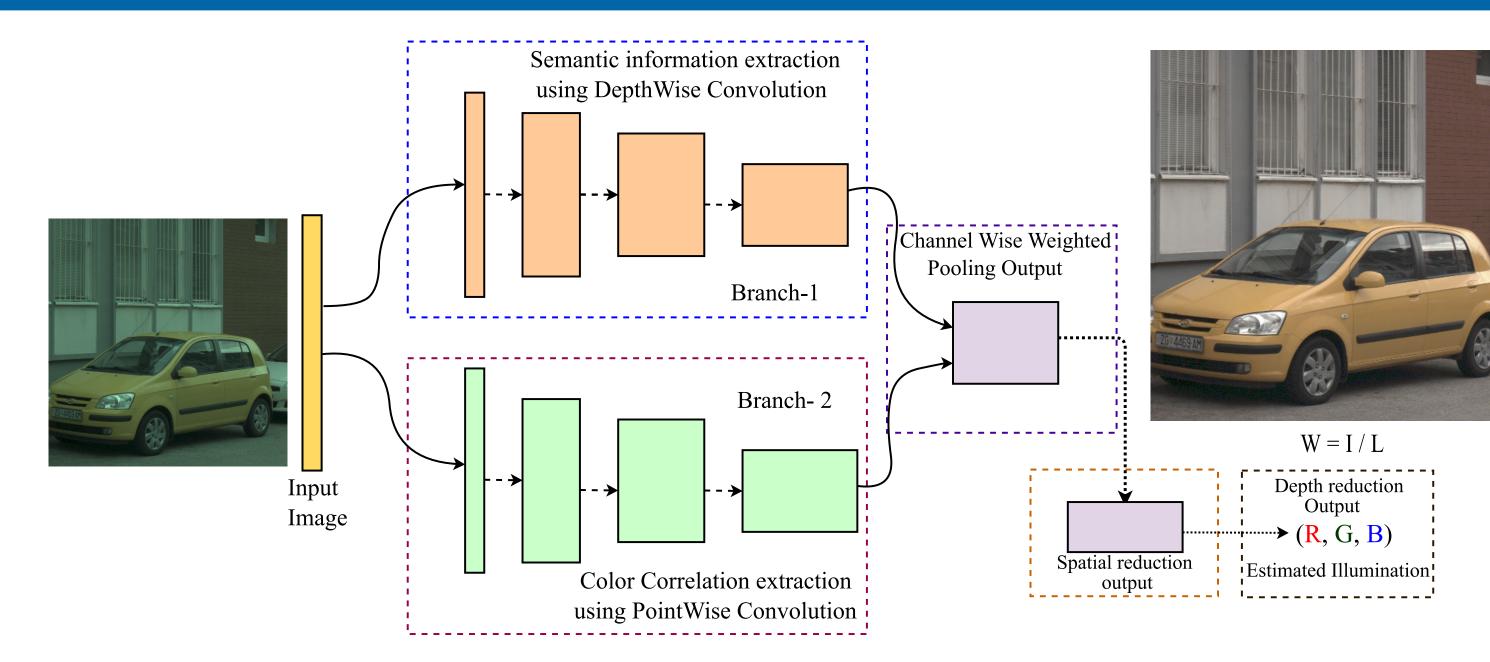
Introduction

Problem statement: Color constancy

$$I_{xy}^{rgb} = W_{xy}^{rgb} \times L^{rgb}$$

where \mathbf{I} is the illuminated image. \mathbf{W} is the white balanced image. L is the global illumination

Method (Baseline Architecture)



common across spatial region.

- Illumination estimation is an under constrained problem.
- Suppressing ambiguous image regions is challenging [1].
- Accurate methods are runtime inefficient.



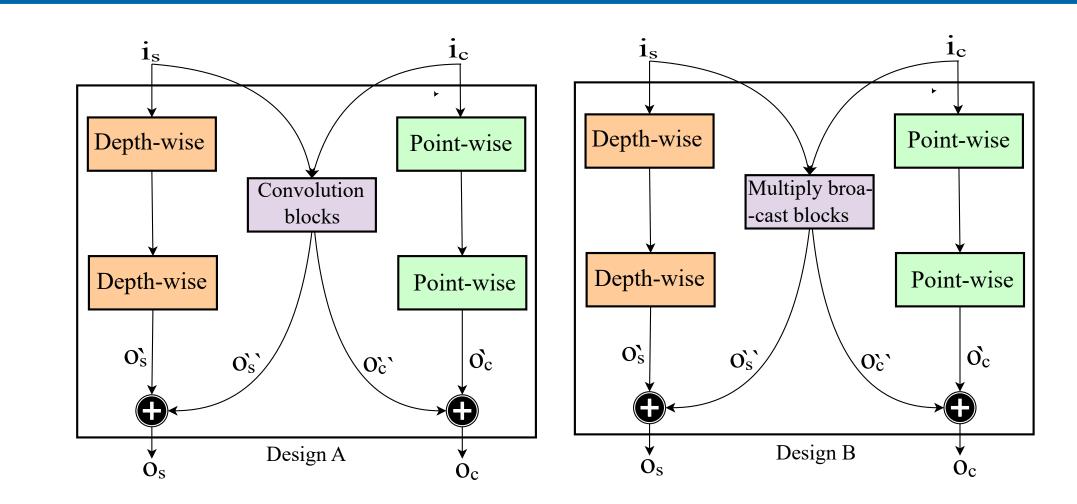
Assumptions

Cross-channel correlation captures statistical properties relevant for estimating illumination independently and identically across the pixels in all channels.

• Local patches captures the semantic properties in an image present across spatial domain without depending on color information.

Dual branch architecture for color constancy depicting respective output tensors of each layer.

Method (Regularizing Micro-blocks)



The two design variants of micro-block architecture for soft parameter sharing over baseline method. Non-linearization and pooling layers are not shown for a better depiction.

Approach

- Model illumination with IID assumption
 - $P(L_{x,y}|I_{x,y})$
- Capture relevant spatial regions with rich semantic value to disambiguate the ambiguous regions.
- Ensemble the estimated illumination from unambiguous portions and aggregate them for global illumination estimation.

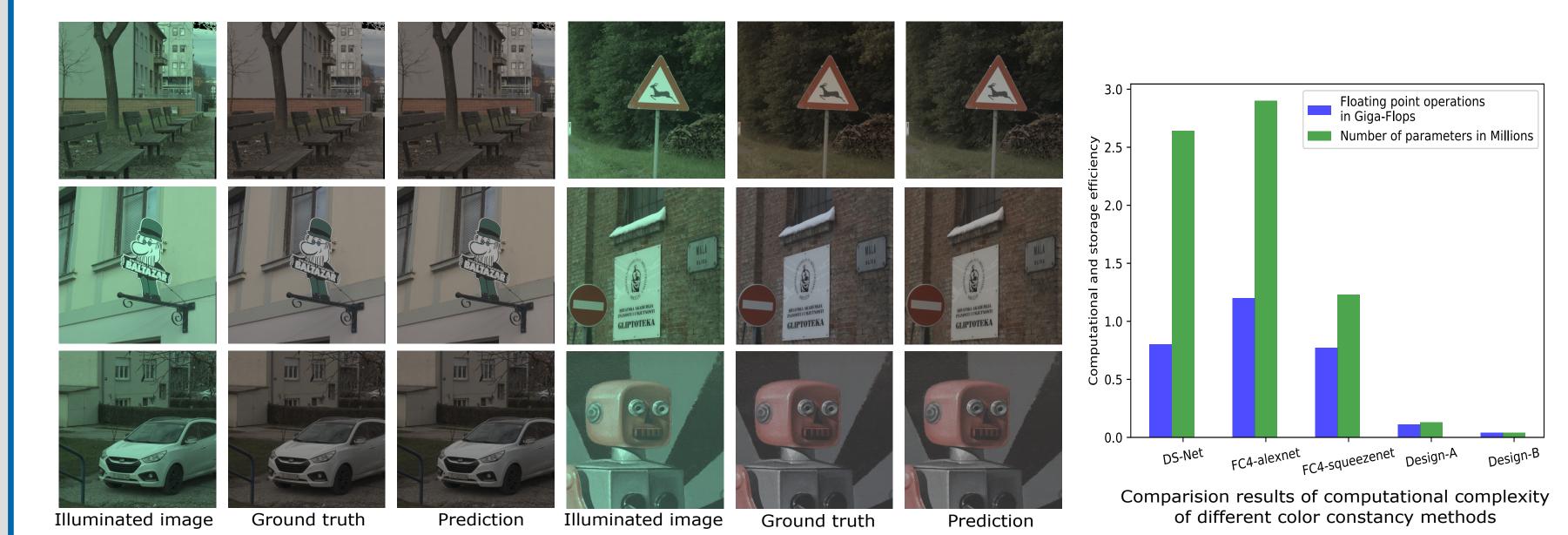
Method

- End-to-end trainable dual branch architecture for extracting color and semantic information independently.
- Point-wise convolution for capturing per pixel crosschannel correlation.
- Depth-wise convolution for computing the confidence maps for each channel in the image.
- Channel-wise weighted pooling to ensemble the estimated

Experimental Results



Semi-dense semantic and illumination feature maps from the respective branches.



illumination with respective confidence weight maps. • Soft parameter sharing across the branches to improve generalization accuracy.

References

[1] Yuanming Hu, Baoyuan Wang, and Stephen Lin, Fc4: Fully convolutional color constancy with confidence-weighted pooling, in Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR17), 2017

[2] Dongliang Cheng, Dilip K Prasad, and Michael S Brown, Illuminant estimation for color constancy: why spatial-domain methods work and the role of the color distribution, JOSA A, vol. 31, no. 5, 2014 [3] Nikola Banic and Sven Loncaric, Unsupervised learning for color constancy, in VISIGRAPP, 2018

Results on NUS-8 $[2]$ dataset								
Models	Mean	Tri	Best	Worst	Params	Flops		
		mean	25%	25%				
Gray-world	4.14	3.39	0.9	9	_	_		
DS-Net	2.24	1.68	0.48	5.28	2.64	0.031*		
FC4-alex	2.12	1.67	0.48	4.78	2.9	1.2		
FC4-squeeze	2.23	1.72	0.47	5.15	1.23	0.77		
$\mathbf{Design} \mathbf{A}$	2.102	1.72	0.576	4.469	0.13	0.11		
Design B	2.442	1.956	0.67	5.283	0.04	0.04		

Results on Cube[3] dataset								
Models	Mean	Tri-mean	Best	Worst				
			25%	25%				
Gray-world	3.75	3.15	0.69	8.18				
Color Tiger	2.94	2.66	0.61	5.88				
Restricted Color Tiger	1.64	1.05	0.24	4.37				
Baseline	1.701	1.276	0.345	4.003				
Design A	1.616	1.242	0.318	3.76				