

# Support Vector Machines

CSC 411 Tutorial

April 1, 2015

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Many thanks to Renjie Liao, Jake Snell, Yujia Li and Kevin Swersky for much of the following material.



# Brief Review of SVMs

Out[9]:

## Machine Learning



what society thinks I do



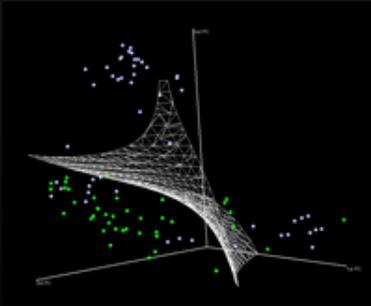
what my friends think I do



what my parents think I do

$$L_p = \frac{1}{2} \|w\|^2 - \sum_{i,j} \alpha_{ij} (x_i \cdot w + b) + \sum_{i,j} \alpha_{ij}$$
$$\alpha_{ij} \geq 0, \forall i$$
$$w = \sum_{i,j} \alpha_{ij} x_j, \sum_{i,j} \alpha_{ij} = 0$$
$$\nabla_{\hat{y}}(\theta_t) = \frac{1}{n} \sum_{i=1}^n \nabla \ell(x_i, y_i; \theta_t) + \nabla r(\theta_t)$$
$$\theta_{t+1} = \theta_t - \eta_t \nabla \ell(x_{i(t)}, y_{i(t)}; \theta_t) - \eta_t \cdot \nabla r(\theta_t)$$
$$\mathbb{E}_{i(t)}[\ell(x_{i(t)}, y_{i(t)}; \theta_t)] = \frac{1}{n} \sum_i \ell(x_i, y_i; \theta_t)$$

what other programmers think I do



what I think I do

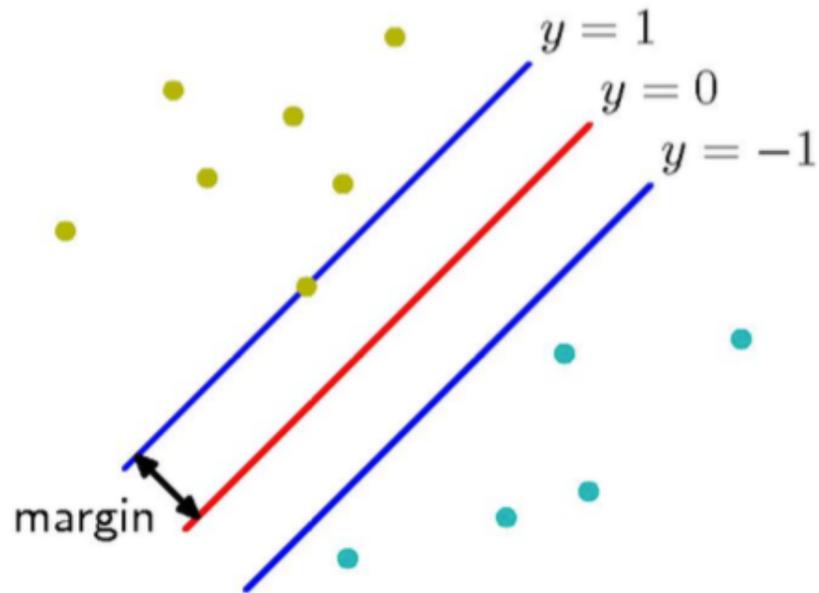
```
>>> from sklearn import svm
```



what I really do

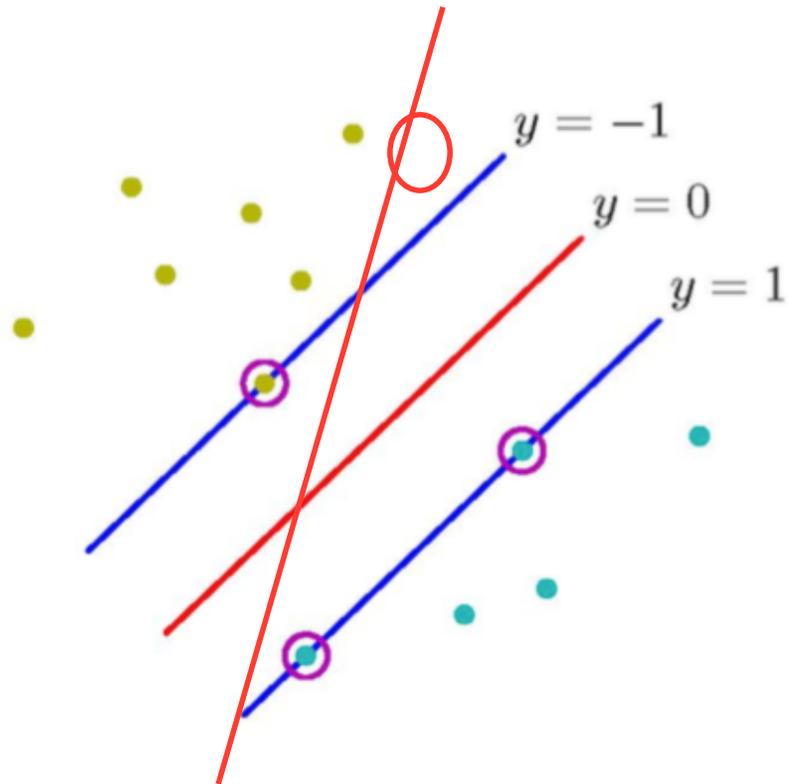
# Geometric Intuition

Out[13]:



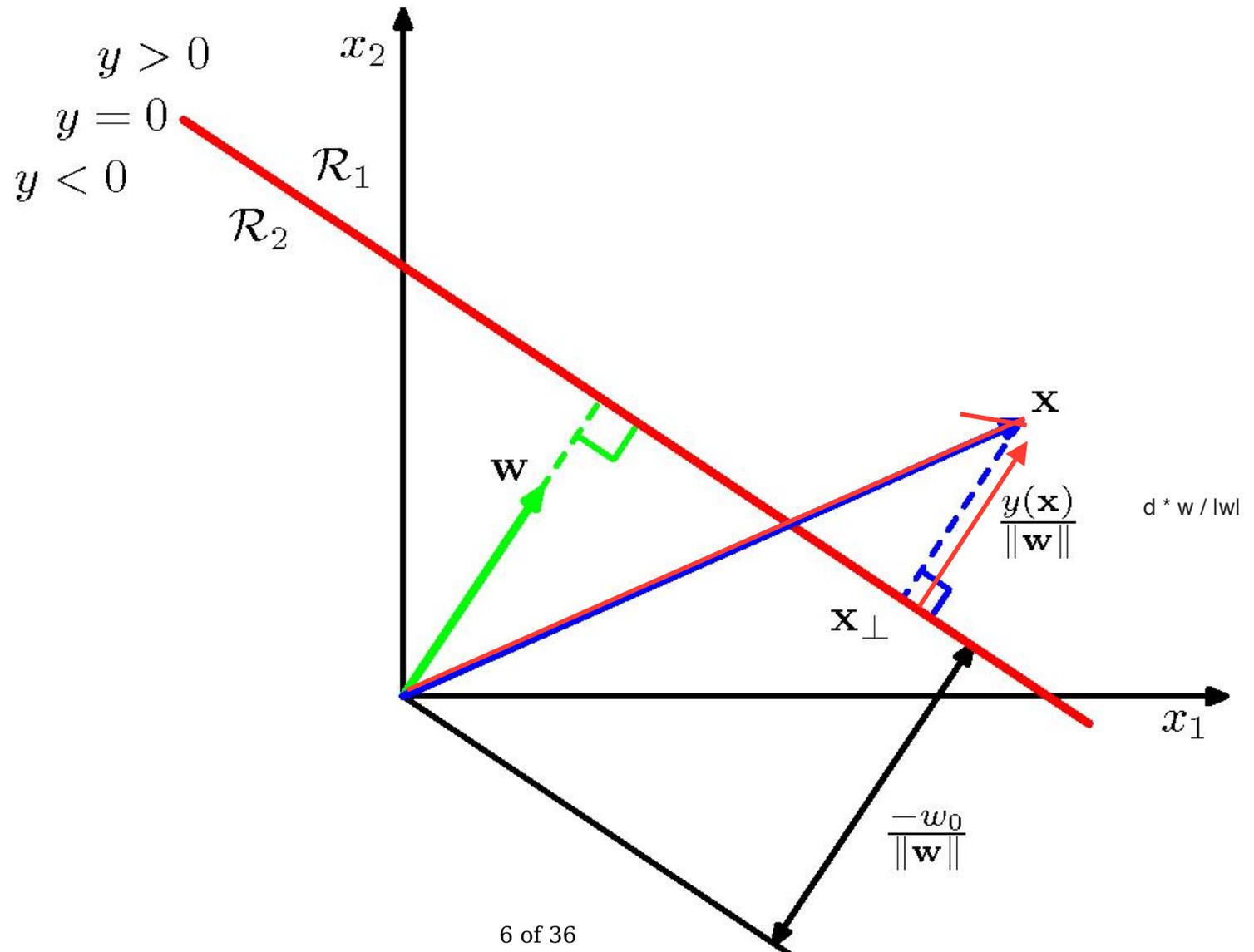
# Geometric Intuition

Out[14]:



# Margin Derivation

Out[16]:



## Margin Derivation

Compute the distance  $d_n$  of an arbitrary point  $x_n$  in the (+) class to the separating hyperplane.

$$\begin{aligned}w^T \left( x_n - d_n \frac{w}{\|w\|} \right) + b &= 0 \\w^T x_n - d_n \frac{w^T w}{\|w\|} + b &= 0 \\w^T x_n + b &= d_n \|w\| \\d_n &= \frac{w^T x_n + b}{\|w\|}\end{aligned}$$

If we let  $t_n \in \{1, -1\}$  denote the class of  $x_n$ , then the distance becomes

$$d_n = \frac{t_n (w^T x_n + b)}{\|w\|}$$

We can set  $d_n = \frac{1}{\|w\|}$  for the point  $x_n$  closest to the decision boundary, leading to the problem:

$$\begin{aligned}\max \quad & \frac{1}{\|w\|} \\ \text{s.t.} \quad & t_n (w^T x_n + b) \geq 1, \text{ for } n = 1 \dots N\end{aligned}$$

## SVM Problem

But scaling  $w \rightarrow \kappa w$  and  $b \rightarrow \kappa b$  doesn't change  $d_n = \frac{t_n(w^T x_n + b)}{\|w\|}$ .

or equivalently:

$$\begin{aligned} & \min \frac{1}{2} \|w\|^2 \\ \text{s.t. } & t_n(w^T x_n + b) \geq 1, \text{ for } n = 1 \dots N \end{aligned}$$

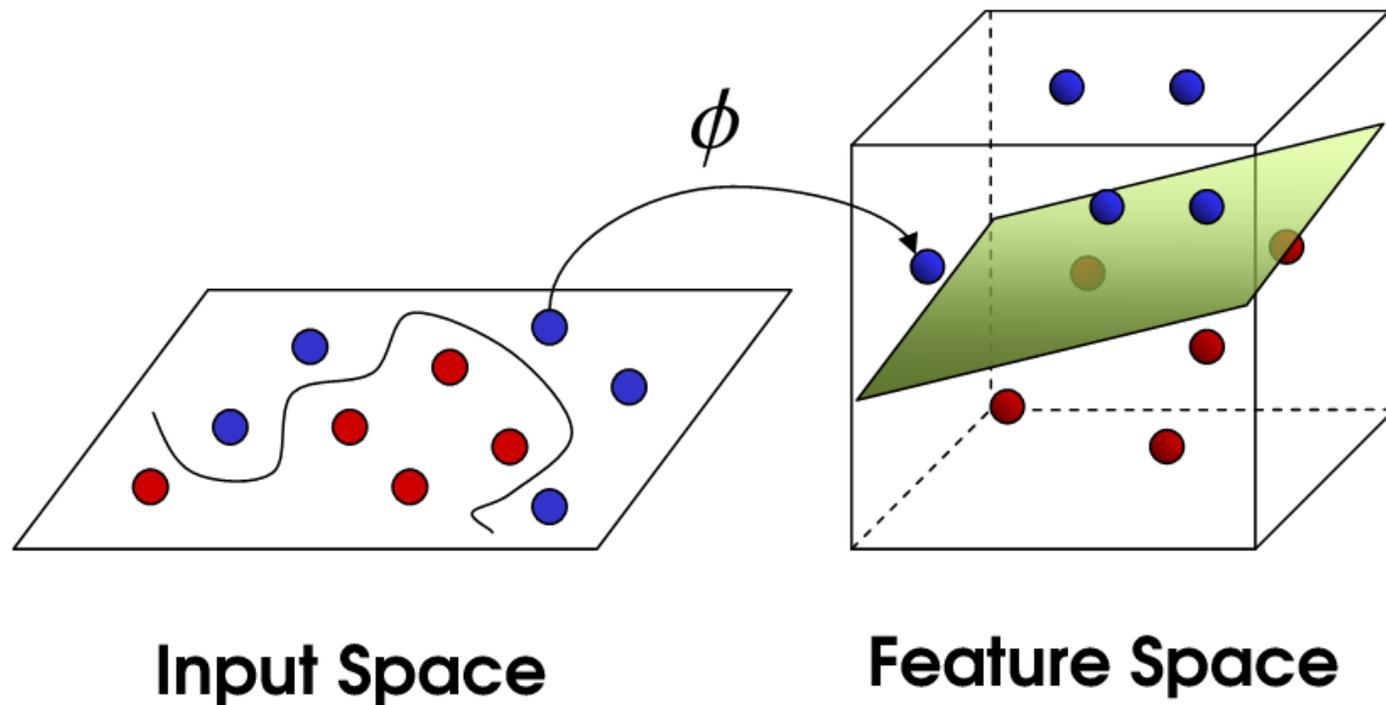
## Non-linear SVMs

For a linear SVM,  $y(x) = w^T x + b$ .

We can just as well work in an alternate feature space:  $\tilde{y}(x) = w^T \phi(x) + b$ .

<http://i.imgur.com/Wuxy0.png>

Out[17]:



# Non-linear SVMs

<http://www.youtube.com/watch?v=3liCbRZPrZA>

Out[19]: SVM with polynomial kernel visualization



# Non-linear SVMs

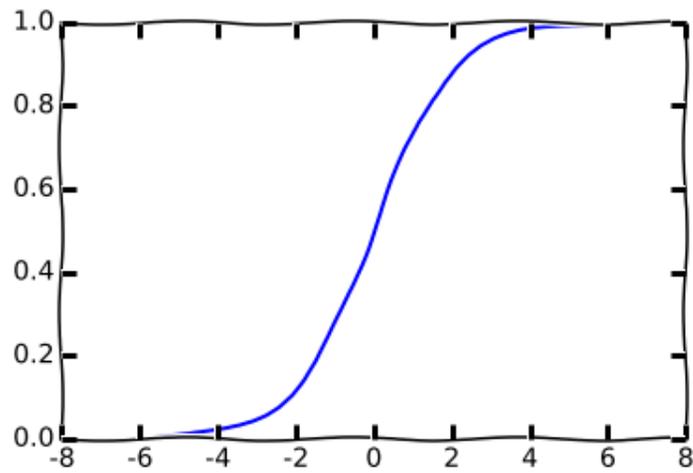
Demo (by Andrej Karparthy and LIBSVM):

<http://cs.stanford.edu/people/karpathy/svmjs/demo/>  
<https://www.csie.ntu.edu.tw/~cjlin/libsvm/>

# SVMs vs Logistic Regression

# Logistic Regression

Out[21]: [`matplotlib.lines.Line2D` at 0x7fb3ad1af0f0>]



# Logistic Regression

- Assign probability to each outcome  
 $P(y = 1|x) = \sigma(w^T x + b)$

- Train to maximize likelihood

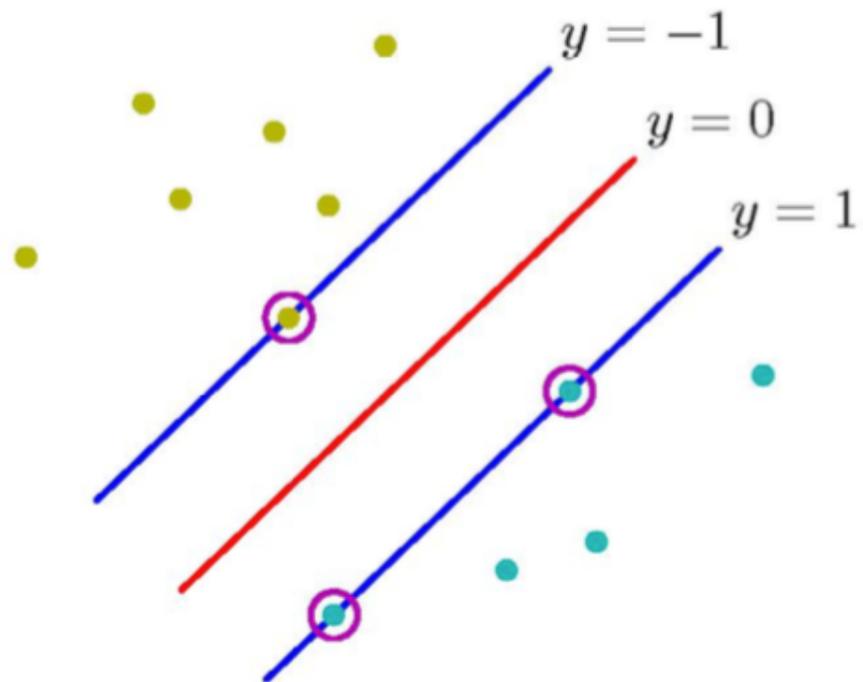
$$\mathcal{L}(w) = \prod_{n=1}^N \sigma(w^T x_n + b)^{y_n} (1 - \sigma(w^T x_n + b))^{1-y_n}$$

- Linear decision boundary

$$\hat{y} = I[w^T x + b \geq 0]$$

# SVMs

Out[22]:



# SVMs

- Enforce a margin of separation  
 $y_n(w^T x_n + b) \geq 1$ , for  $n$   
 $= 1 \dots N$
- Linear decision boundary  
 $\hat{y} = I[w^T x + b \geq 0]$

- Train to find the maximum margin

$$\min \frac{1}{2} \|w\|^2$$

s.t.  $y_n(w^T x_n + b) \geq 1$ , for  $n$   
 $= 1 \dots N$

# Comparison

- **Logistic regression** wants to maximize the probability of the data.
  - The greater the distance from each point to the decision boundary, the better.
- **SVMs** want to maximize the distance from the closest points (support vectors) to the decision boundary.
  - Doesn't care about points that aren't support vectors.

## A Different Take

Consider an alternate form of the logistic regression decision function:

$$\hat{y} = \begin{cases} 1 & \text{if } P(y = 1|x) \geq P(y = 0|x) \\ 0 & \text{otherwise} \end{cases}$$
$$P(y = 1|x) \propto \exp(w^T x + b)$$
$$P(y = 0|x) \propto 1$$

## A Different Take

Suppose we don't actually care about the probabilities. All we want to do is make the right decision.

We can put a constraint on the likelihood ratio, for some constant  $c > 1$ :

$$\frac{P(y = 1|x_n)}{P(y = 0|x_n)} \geq c$$

## A Different Take

Take the log of both sides:

$$\log P(y = 1|x_n) - \log P(y = 0|x_n) \geq \log c$$

Recalling that  $P(y = 1|x_n) \propto \exp(w^T x_n + b)$  and  $P(y = 0|x_n) \propto 1$ :

$$\begin{aligned} w^T x_n + b - 0 &\geq \log c \\ w^T x_n + b &\geq \log c \end{aligned}$$

But  $c$  is arbitrary, so set it s.t.  $\log c = 1$ :

$$w^T x_n + b \geq 1$$

Similiary the negative sample case should be:

$$-(w^T x_n + b) \geq 1$$

Try to derive it by yourself.

## A Different Take

So now we have  $(2y_n - 1)(w^T x_n + b) \geq 1$ , for  $n = 1 \dots N$ . But this may not have a unique solution, so put a quadratic penalty on the weights to make the solution unique:

$$\begin{aligned} \min \quad & \frac{1}{2} \|w\|^2 \\ \text{s.t.} \quad & (2y_n - 1)(w^T x_n + b) \geq 1, \text{ for } n = 1 \dots N \end{aligned}$$

This gives us a SVM!

By asking logistic regression to make the right **decisions** instead of maximizing the **probability** of the data, we derived an SVM.

# Likelihood Ratio

The **likelihood ratio** drives this derivation:

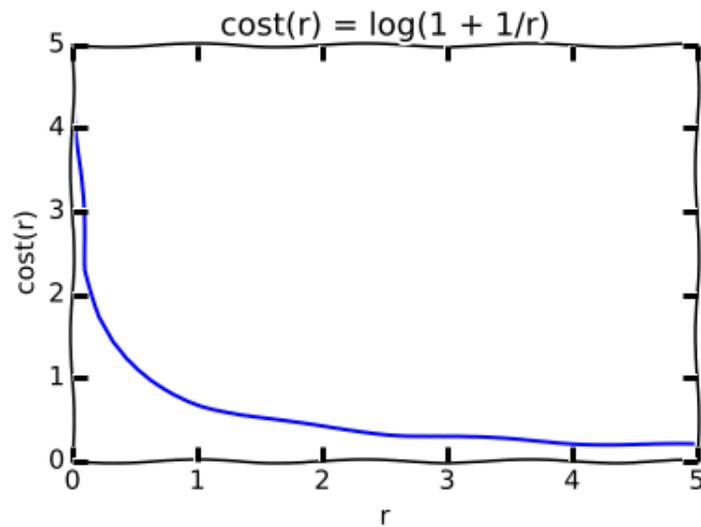
$$r = \frac{P(y = 1|x)}{P(y = 0|x)} = \frac{\exp(w^T x + b)}{1} = \exp(w^T x + b)$$

Different classifiers assign **different costs** to  $r$ .

## LR Cost

Choose  $\text{cost}(r) = \log\left(1 + \frac{1}{r}\right)$  (for a positive example)

Out[23]: <matplotlib.text.Text at 0x7fb3ad135748>



## LR Cost

$$\begin{aligned}\log\left(1 + \frac{1}{r}\right) &= \log(1 + \exp(-(w^T x + b))) \\ &= -\log \frac{1}{1 + \exp(-(w^T x + b))} \\ &= -\log \sigma(w^T x + b)\end{aligned}$$

Minimizing  $\text{cost}(r)$  is the same as minimizing the negative log-likelihood objective for logistic regression!

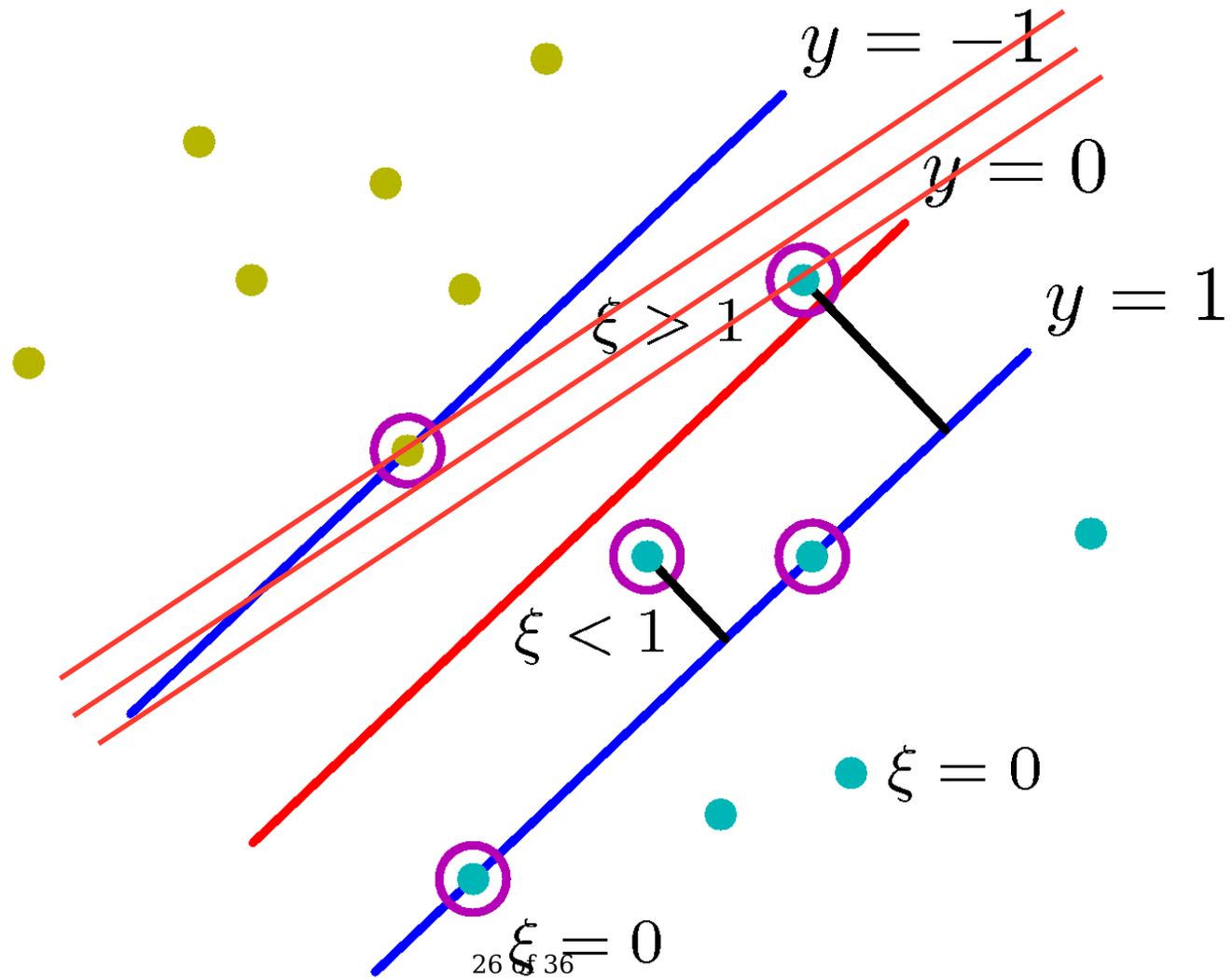
## SVM with Slack Variables

If the data is not linearly separable, we can introduce slack variables.

$$\begin{aligned} \min \quad & \frac{1}{2} \|w\|^2 + C \sum_{n=1}^N \xi_n \\ \text{s.t.} \quad & y_n (w^T x_n + b) \geq 1 - \xi_n, \text{ for } n = 1 \dots N \\ & \text{and } \xi_n \geq 0, \text{ for } n = 1 \dots N \end{aligned}$$

# SVM with Slack Variables

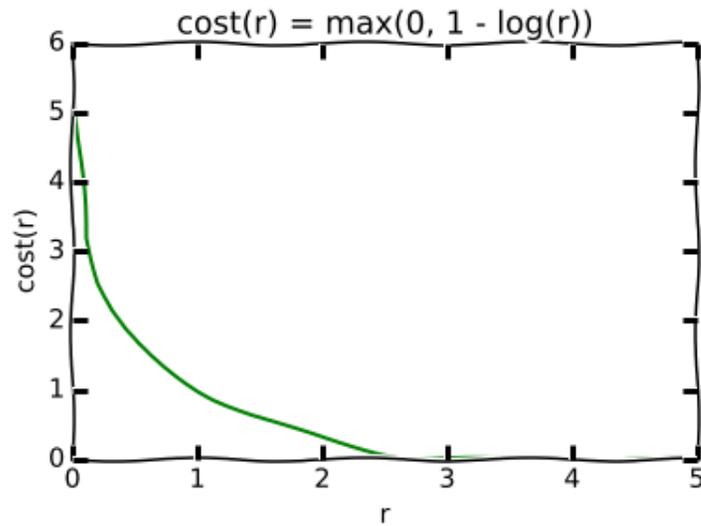
Out[24]:



## SVM Cost

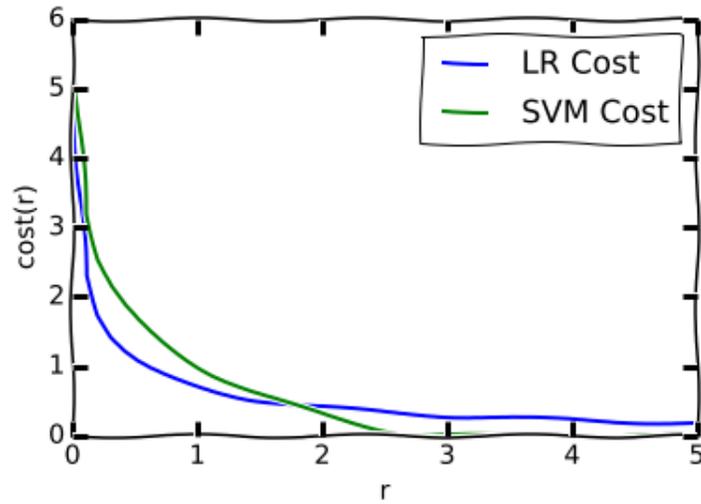
Choose  $\text{cost}(r) = \max(0, 1 - \log(r)) = \max(0, 1 - (w^T x + b))$

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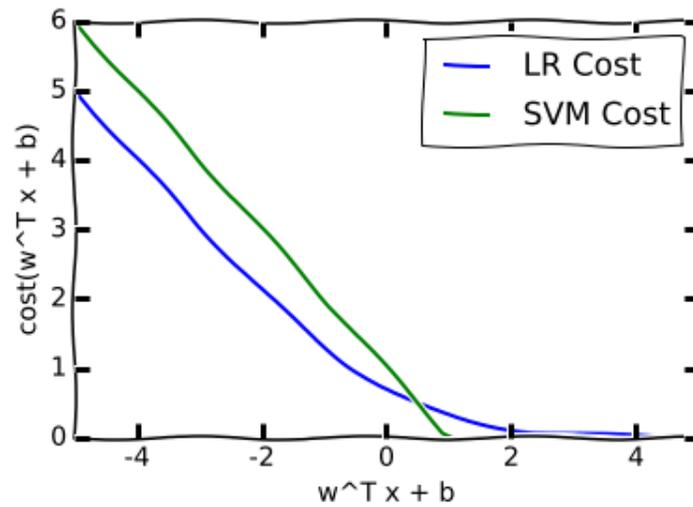
## Plotted in terms of $r$

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## Plotted in terms of $w^T x + b$

Out[27]: <matplotlib.legend.Legend at 0x7fb3acf98710>



# Exploiting the Connection between LR and SVMs

## Kernel Trick for LR

In the dual form, the SVM decision boundary is

$$y(x) = w^T \phi(x) + b = \sum_{n=1}^N \alpha_n t_n K(x, x_n) + b = 0$$

We could plug this into the LR cost:

$$\log \left( 1 + \exp \left( - \sum_{n=1}^N \alpha_n t_n K(x, x_n) - b \right) \right)$$

# Multi-class SVMs

Recall multi-class logistic regression

$$P(y = i|x) = \frac{\exp(w_i^T x + b_i)}{\sum_k \exp(w_k^T x + b_k)}$$

## Multi-class SVMs

Suppose instead we just want the decision rule to satisfy

$$\frac{P(y = i|x)}{P(y = k|x)} \geq c, \text{ for } k \neq i$$

Taking logs as before,

$$(w_i^T x + b_i) - (w_k^T x + b_k) \geq 1, \text{ for } k \neq i$$

## Multi-class SVMs

Now we have the quadratic program for multi-class SVMs.

$$\begin{aligned} & \min \frac{1}{2} \|w\|^2 \\ \text{s.t. } & (w_{y_n}^T x_n + b_{y_n}) - (w_k^T x_n + b_k) \geq 1, \text{ for } n = 1 \dots N, k \neq y_n \end{aligned}$$

## LR and SVMs are closely linked

- Both can be viewed as taking a probabilistic model and minimizing some cost associated with the likelihood ratio.
- This allows use to extend both models in principled ways.

# Which to Use?

## Logistic regression

- Gives calibrated probabilities that can be interpreted as confidence in a decision.
- Unconstrained, smooth objective.
- Can be used within Bayesian models.

## SVMs

- No penalty for examples where the correct decision is made with sufficient confidence, which can lead to good generalization.
- Dual form gives sparse solutions when using the kernel trick, leading to better scalability.