CSC 2515: Machine Learning Lecture 1 - Introduction and Nearest Neighbours

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• Broad introduction to machine learning

- ▶ First half: algorithms and principles for supervised learning
 - nearest neighbors, decision trees, ensembles, linear regression, logistic regression, SVMs
 - ▶ neural nets!
- ▶ Unsupervised learning: PCA, K-means, mixture models
- Basics of reinforcement learning
- This course is taught as a stand-alone grad course for the first time.
 - ▶ But the structure and difficulty will be similar to past years, when it was cross-listed as an undergrad course.
 - ▶ The majority of students are from outside Computer Science.

Course Website:

https://www.cs.toronto.edu/~rgrosse/courses/csc2515_2019/

Slides will be posted to web page in advance of lecture, but I'll continue to make edits up to Thursday night. So please re-download!

We will use Piazza for **discussions**.

- URL to be sent out
- Your grade **does not depend on your participation on Piazza**. It's just a good way for asking questions, discussing with your instructor, TAs and your peers

Recommended readings will be given for each lecture. But the following will be useful throughout the course:

- Hastie, Tibshirani, and Friedman: "The Elements of Statistical Learning"
- Christopher Bishop: "Pattern Recognition and Machine Learning", 2006.
- Kevin Murphy: "Machine Learning: a Probabilistic Perspective", 2012.
- David Mackay: "Information Theory, Inference, and Learning Algorithms", 2003.
- Shai Shalev-Shwartz & Shai Ben-David: "Understanding Machine Learning: From Theory to Algorithms", 2014.

There are lots of freely available, high-quality ML resources.

Course Information

See Metacademy (https://metacademy.org) for additional background, and to help review prerequisites.



- 5 written homeworks, due roughly every other week.
 - Combination of pencil & paper derivations and short programming exercises
 - \blacktriangleright Each counts for 10%, except that the lowest mark counts for 5%.
 - ▶ Worth 45% in total.
- Read some classic papers.
 - ▶ Worth 5%, honor system.
- Midterm
 - ▶ Oct. 30, 4-6pm
 - ▶ Worth 15% of course mark
- Final Exam
 - ▶ Dec. 17, 3-6pm
 - ▶ Worth 35% of course mark

Collaboration on the assignments is not allowed. Each student is responsible for his/her own work. Discussion of assignments should be limited to clarification of the handout itself, and should not involve any sharing of pseudocode or code or simulation results. Violation of this policy is grounds for a semester grade of F, in accordance with university regulations.

The schedule of assignments will be posted on the course web page.

Assignments should be handed in by 11:59pm; a late penalty of 10% per day will be assessed thereafter (up to 3 days, then submission is blocked).

Extensions will be granted only in special situations, and you will need a Student Medical Certificate or a written request approved by the course coordinator at least one week before the due date.

What is learning?

"The activity or process of gaining knowledge or skill by studying, practicing, being taught, or experiencing something."

Merriam Webster dictionary

"A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P, if its performance at tasks in T, as measured by P, improves with experience E."

Tom Mitchell

- For many problems, it's difficult to program the correct behavior by hand
 - recognizing people and objects
 - understanding human speech
- Machine learning approach: program an algorithm to automatically learn from data, or from experience
- Why might you want to use a learning algorithm?
 - ▶ hard to code up a solution by hand (e.g. vision, speech)
 - ▶ system needs to adapt to a changing environment (e.g. spam detection)
 - ▶ want the system to perform *better* than the human programmers
 - privacy/fairness (e.g. ranking search results)

- It's similar to statistics...
 - ▶ Both fields try to uncover patterns in data
 - ▶ Both fields draw heavily on calculus, probability, and linear algebra, and share many of the same core algorithms
- But it's not statistics!
 - Stats is more concerned with helping scientists and policymakers draw good conclusions; ML is more concerned with building autonomous agents
 - Stats puts more emphasis on interpretability and mathematical rigor; ML puts more emphasis on predictive performance, scalability, and autonomy

- Types of machine learning
 - ► **Supervised learning:** have labeled examples of the correct behavior
 - **Reinforcement learning:** learning system receives a reward signal, tries to learn to maximize the reward signal
 - ► Unsupervised learning: no labeled examples instead, looking for interesting patterns in the data

- 1957 Perceptron algorithm (implemented as a circuit!)
- 1959 Arthur Samuel wrote a learning-based checkers program that could defeat him
- 1969 Minsky and Papert's book *Perceptrons* (limitations of linear models)
- 1980s Some foundational ideas
 - Connectionist psychologists explored neural models of cognition
 - ▶ 1984 Leslie Valiant formalized the problem of learning as PAC learning
 - ▶ 1988 Backpropagation (re-)discovered by Geoffrey Hinton and colleagues
 - ▶ 1988 Judea Pearl's book *Probabilistic Reasoning in Intelligent* Systems introduced Bayesian networks

- $\bullet~1990\mathrm{s}$ the "AI Winter", a time of pessimism and low funding
- But looking back, the '90s were also sort of a golden age for ML research
 - Markov chain Monte Carlo
 - ▶ variational inference
 - kernels and support vector machines
 - boosting
 - convolutional networks
- 2000s applied AI fields (vision, NLP, etc.) adopted ML
- 2010s deep learning
 - ▶ 2010-2012 neural nets smashed previous records in speech-to-text and object recognition
 - increasing adoption by the tech industry
 - $\blacktriangleright~2016$ AlphaGo defeated the human Go champion

Computer vision: Object detection, semantic segmentation, pose estimation, and almost every other task is done with ML.



Figure 4. More results of Mask R-CNN on COCO test images, using ResNet-101-FPN and running at 5 fps, with 35.7 mask AP (Table 1).



Instance segmentation - • Link





DAQUAR 1553 What is there in front of the sofa? Ground truth: table IMG+BOW: table (0.74) 2-VIS+BLSTM: table (0.88) LSTM: chair (0.47)



COCOQA 5078 How many leftover donuts is the red bicycle holding? Ground truth: three IMG+BOW: two (0.51) 2-VIS+BLSTM: three (0.27) BOW: one (0.29)

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Speech: Speech to text, personal assistants, speaker identification...



NLP: Machine translation, sentiment analysis, topic modeling, spam filtering.

Real world example: Che New York Times articles:

music band songs rock album jazz pop song singer night	book life novel story books man stories love children family	art museum show exhibition artist paintings painting century works	game Rnicks points team season play games night coach	show film television movie series says life man character know
theater	clinton	stock	restaurant	budget
play	bush	market	sauce	tax
production	campaign	percent	menu	governor
show	gore	fund	food	county
stage	political	investors	dishes	mayor
street	republican	funds	street	billion
broadway	dole	companies	dining	taxes
director	presidential	stocks	dinner	plan
musical	senator	investment	chicken	legislature
directed	bouse	trading	served	tiscal

Playing Games



DOTA2 - • Link

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E-commerce & Recommender Systems : Amazon, netflix, ...

Inspired by your shopping trends



Related to items you've viewed See more



Why this class?

2017 Kaggle survey of data science and ML practitioners: what data science methods do you use at work?



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ML workflow sketch:

- 1. Should I use ML on this problem?
 - ▶ Is there a pattern to detect?
 - Can I solve it analytically?
 - ▶ Do I have data?
- 2. Gather and organize data.
- 3. Preprocessing, cleaning, visualizing.
- 4. Establishing a baseline.
- 5. Choosing a model, loss, regularization, \dots
- 6. Optimization (could be simple, could be a Phd...).
- 7. Hyperparameter search.
- 8. Analyze performance and mistakes, and iterate back to step 5 (or 3).

Implementing machine learning systems

- You will often need to derive an algorithm (with pencil and paper), and then translate the math into code.
- Array processing (NumPy)
 - vectorize computations (express them in terms of matrix/vector operations) to exploit hardware efficiency
 - ▶ This also makes your code cleaner and more readable!



z = np.zeros(m)for i in range(m): for j in range(n): z = np.dot(W, x) + bz[i] += W[i, j] * x[j] z[i] += b[i]

Implementing machine learning systems

• Neural net frameworks: PyTorch, TensorFlow, etc.

- automatic differentiation
- compiling computation graphs
- libraries of algorithms and network primitives
- ▶ support for graphics processing units (GPUs)
- Why take this class if these frameworks do so much for you?
 - ▶ So you know what to do if something goes wrong!
 - Debugging learning algorithms requires sophisticated detective work, which requires understanding what goes on beneath the hood.
 - ▶ That's why we derive things by hand in this class!



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Nearest Neighbours

- Today (and for the next 6 weeks) we're focused on supervised learning.
- This means we're given a training set consisting of inputs and corresponding labels, e.g.

Inputs	Labels
image	object category
image	caption
text	document category
audio waveform	text
:	
	Inputs image image text audio waveform :

What an image looks like to the computer:



[Image credit: Andrej Karpathy]

- Machine learning algorithms need to handle lots of types of data: images, text, audio waveforms, credit card transactions, etc.
- Common strategy: represent the input as an input vector in \mathbb{R}^d
 - Representation = mapping to another space that's easy to manipulate
 - ▶ Vectors are a great representation since we can do linear algebra!



Can use raw pixels:



Can do much better if you compute a vector of meaningful features.

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- Mathematically, our training set consists of a collection of pairs of an input vector $\mathbf{x} \in \mathbb{R}^d$ and its corresponding target, or label, t
 - Regression: t is a real number (e.g. stock price)
 - Classification: t is an element of a discrete set $\{1, \ldots, C\}$
 - These days, t is often a highly structured object (e.g. image)
- Denote the training set $\{(\mathbf{x}^{(1)}, t^{(1)}), \dots, (\mathbf{x}^{(N)}, t^{(N)})\}$
 - ▶ Note: these superscripts have nothing to do with exponentiation!

Nearest Neighbors

- Suppose we're given a novel input vector \mathbf{x} we'd like to classify.
- The idea: find the nearest input vector to **x** in the training set and copy its label.
- Can formalize "nearest" in terms of Euclidean distance

$$||\mathbf{x}^{(a)} - \mathbf{x}^{(b)}||_2 = \sqrt{\sum_{j=1}^d (x_j^{(a)} - x_j^{(b)})^2}$$

Algorithm:

1. Find example (\mathbf{x}^*, t^*) (from the stored training set) closest to **x**. That is:

$$\mathbf{x}^* = \underset{\mathbf{x}^{(i)} \in \text{train. set}}{\operatorname{argmin}} \operatorname{distance}(\mathbf{x}^{(i)}, \mathbf{x})$$

2. Output $y = t^*$

• Note: we don't need to compute the square root. Why?

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We can visualize the behavior in the classification setting using a Voronoi diagram.



Nearest Neighbors: Decision Boundaries

Decision boundary: the boundary between regions of input space assigned to different categories.



Nearest Neighbors: Decision Boundaries



Example: 3D decision boundary

k-Nearest Neighbors



- Nearest neighbors sensitive to noise or mis-labeled data ("class noise"). Solution?
- Smooth by having k nearest neighbors vote

Algorithm (kNN):

- 1. Find k examples $\{\mathbf{x}^{(i)}, t^{(i)}\}$ closest to the test instance \mathbf{x}
- 2. Classification output is majority class

$$y = \arg \max_{t^{(z)}} \sum_{r=1}^k \delta(t^{(z)}, t^{(r)})$$

[Pic by Olga Veksler]

K-Nearest neighbors

k=1



[Image credit: "The Elements of Statistical Learning"]

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K-Nearest neighbors

k=15



[Image credit: "The Elements of Statistical Learning"]

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Tradeoffs in choosing k?

- Small k
 - ▶ Good at capturing fine-grained patterns
 - ► May overfit, i.e. be sensitive to random idiosyncrasies in the training data
- Large k
 - ▶ Makes stable predictions by averaging over lots of examples
 - ▶ May underfit, i.e. fail to capture important regularities
- Rule of thumb: k < sqrt(n), where n is the number of training examples

K-Nearest neighbors

- We would like our algorithm to generalize to data it hasn't before.
- We can measure the generalization error (error rate on new examples) using a test set.



k - Number of Nearest Neighbors

[Image credit: "The Elements of Statistical Learning"]

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Validation and Test Sets

- k is an example of a hyperparameter, something we can't fit as part of the learning algorithm itself
- We can tune hyperparameters using a validation set:



• The test set is used only at the very end, to measure the generalization performance of the final configuration.

- Is KNN consistent? I.e., given enough data, will it give the "right" answer?
- To analyze this, suppose the inputs \mathbf{x} and targets t are random variables drawn independently and identically distributed (i.i.d.) from a data generating distribution with density $p(\mathbf{x}, t)$.
- The Bayes optimal classifier is the function $f(\mathbf{x})$ which minimizes the misclassification rate, i.e.

$$f(\mathbf{x}) = y_* = \arg\min_{y} \Pr(y \neq t \,|\, \mathbf{x}) = \arg\max_{y} \Pr(y = t \,|\, \mathbf{x}).$$

Its error rate is called the Bayes error.

• Question: how close does KNN get to the Bayes error in the limit of infinite data?

- Assume $p(\mathbf{x}, t)$ is smooth as a function of \mathbf{x} .
- Main idea: suppose N (the number of training examples) is very large, and consider a query point \mathbf{x}_q which we'd like to classify.
 - ▶ By smoothness, $p(t | \mathbf{x})$ is approximately constant for nearby \mathbf{x} .
 - ► Hence, the labels of the neighbors can be seen as independent random variables with PMF $p(t | \mathbf{x}_q)$.

Consistency

- First consider $k = 1, N \to \infty$.
 - ▶ y (the nearest neighbour prediction) and t (the true label at \mathbf{x}_q) are (approximately) independent random variables with PMF $p(t | \mathbf{x}_q)$.
 - Apply the Union Bound:

 $\Pr(t \neq y \,|\, \mathbf{x}_q) \le \Pr(t \neq y_* \,|\, \mathbf{x}_q) + \Pr(y_* \neq y \,|\, \mathbf{x}_q) = 2\Pr(t \neq y_* \,|\, \mathbf{x}_q).$

- ▶ I.e., the asymptotic error of 1-NN is at most twice the Bayes error.
- Now consider $k, N \to \infty$ and $k/N \to 0$.
 - ▶ The counts of neighbors' labels (approximately) follow a multinomial distribution with *k* trials.
 - ▶ For large k, the argmax will agree with the Bayes classifier with high probability. (E.g., apply the Central Limit Theorem.)
 - ▶ Hence, the KNN approaches the Bayes error, i.e. KNN is Bayes consistent.
- Bayes consistency is a very special property, and holds for hardly any of the algorithms covered in this course.

Pitfalls: The Curse of Dimensionality

- Consistency is great, but it might take a very large amount of data to get close to the Bayes error.
 - Especially in high dimensions! KNN suffers from the Curse of Dimensionality.
- How large does N need to be to guarantee we have an ϵ -neighbour?
- The volume of a single ball of radius ϵ is $\mathcal{O}(\epsilon^d)$
- The total volume of $[0, 1]^d$ is 1.
- Therefore $\mathcal{O}\left(\left(\frac{1}{\epsilon}\right)^d\right)$ balls are needed to cover the volume.



[Image credit: "The Elements of Statistical Learning"]

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• Another perspective on the Curse of Dimensionality: in high dimensions, "most" points are approximately the same distance. (Homework question coming up...)



• This is just one example of how 2-D visualizations of high-dimensional spaces can be extremely misleading!

Pitfalls: The Curse of Dimensionality

- Saving grace: some datasets may have low intrinsic dimension, i.e. lie on or near a low-dimensional manifold.
- E.g., natural images have a lot fewer degrees of freedom than the number of pixels in the image.
- The distance to the neighbors depends on the intrinsic dimension, not the dimension of the input space. Hence, KNN can still work in high dimensions, as long as the data are intrinsically low-dimensional.







Pitfalls: Normalization

- Nearest neighbors can be sensitive to the ranges of different features.
- Often, the units are arbitrary:



• Simple fix: normalize each dimension to be zero mean and unit variance. I.e., compute the mean μ_j and standard deviation σ_j , and take

$$\tilde{x}_j = \frac{x_j - \mu_j}{\sigma_j}$$

• Caution: depending on the problem, the scale might be important! (Can you think of an example?)

- Number of computations at training time: 0
- Number of computations at test time, per query (naïve algorithm)
 - \blacktriangleright Calculuate D-dimensional Euclidean distances with N data points: $\mathcal{O}(ND)$
 - Sort the distances: $\mathcal{O}(N \log N)$
- This must be done for *each* query, which is very expensive by the standards of a learning algorithm!
- Need to store the entire dataset in memory!
- Tons of work has gone into algorithms and data structures for efficient nearest neighbors with high dimensions and/or large datasets.

Example: Digit Classification

• Decent performance when lots of data

0123456789

- Yann LeCunn MNIST Digit Recognition
 - Handwritten digits
 - 28x28 pixel images: d = 784
 - 60,000 training samples
 - 10,000 test samples
- Nearest neighbour is competitive

Test Error Rat	te (%)
Linear classifier (1-layer NN)	12.0
K-nearest-neighbors, Euclidean	5.0
K-nearest-neighbors, Euclidean, deskewed	2.4
K-NN, Tangent Distance, 16x16	1.1
K-NN, shape context matching	0.67
1000 RBF + linear classifier	3.6
SVM deg 4 polynomial	1.1
2-layer NN, 300 hidden units	4.7
2-layer NN, 300 HU, [deskewing]	1.6
LeNet-5, [distortions]	0.8
Boosted LeNet-4, [distortions]	0.7

- KNN can perform a lot better with a good similarity measure.
- Example: shape contexts for object recognition. In order to achieve invariance to image transformations, they tried to warp one image to match the other image.
 - Distance measure: average distance between corresponding points on *warped* images
- Achieved 0.63% error on MNIST, compared with 3% for Euclidean KNN.
- Competitive with conv nets at the time, but required careful engineering.



[Belongie, Malik, and Puzicha, 2002. Shape matching and object recognition using shape contexts.]

Example: 80 Million Tiny Images

- 80 Million Tiny Images was the first extremely large image dataset. It consisted of color images scaled down to 32×32 .
- With a large dataset, you can find much better semantic matches, and KNN can do some surprising things.
- Note: this required a carefully chosen similarity metric.



[Torralba, Fergus, and Freeman, 2007. 80 Million Tiny Images.]

Example: 80 Million Tiny Images



[Torralba, Fergus, and Freeman, 2007. 80 Million Tiny Images.]

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