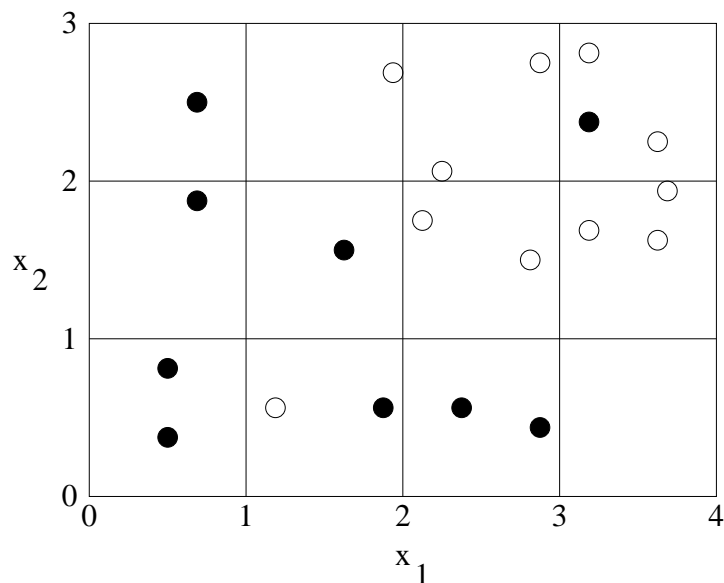


STA 414/2104, Spring 2012, Practice Problem Set #1

Note: these problems are not for credit, and not to be handed in

Question 1: Consider a classification problem in which there are two real-valued inputs, x_1 and x_2 , and a binary (0/1) target (class) variable, y . There are 20 training cases, plotted below. Cases where $y = 1$ are plotted as black dots, cases where $y = 0$ as white dots, with the location of the dot giving the inputs, x_1 and x_2 , for that training case.



- A) Estimate the error rate of the one-nearest-neighbor (1-NN) classifier for this problem using leave-one-out cross validation. (Ie, S-fold cross validation with S equal to the number of training cases, in which each training case is predicted using all the other training cases.)
- B) Suppose we use the three-nearest-neighbor (3-NN) method to estimate the probability that a test case is in class 1. For test cases with each of the following sets of input values, find the estimated probability of class 1.

$$x_1 = 1, x_2 = 1$$

$$x_1 = 2, x_2 = 2$$

$$x_1 = 3, x_2 = 0$$

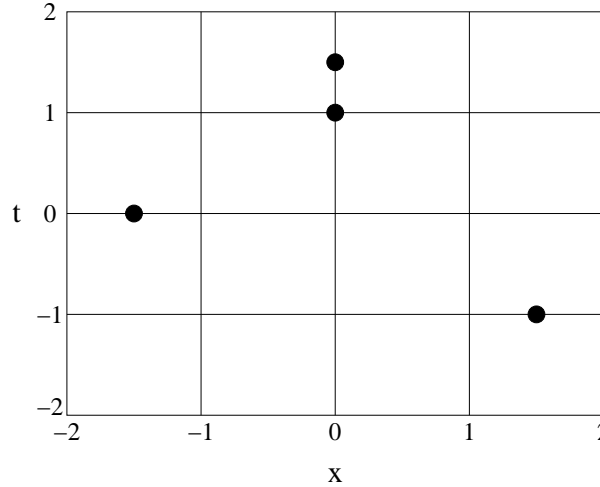
Question 2: Consider a linear basis function regression model, with one input and the following three basis functions:

$$\begin{aligned} \phi_0(x) &= 1 \\ \phi_1(x) &= x \\ \phi_2(x) &= \begin{cases} 1 - x^2 & \text{if } |x| < 1 \\ 0 & \text{if } |x| \geq 1 \end{cases} \end{aligned}$$

The model for the target variable, y , is that $P(y | x, \beta) = N(y | f(x, \beta), 1)$, where

$$f(x, \beta) = \sum_{j=0}^{m-1} \beta_j \phi_j(x)$$

Suppose we have four data points, as plotted below:



What is the maximum likelihood (least squares) estimate for the parameters β_0 , β_1 , and β_2 ? Elaborate calculations should not be necessary.

Question 3: Answer the following questions about linear basis function models, as fitted by least squares or penalized least squares.

Recall that the linear basis function model (for one case) has the form

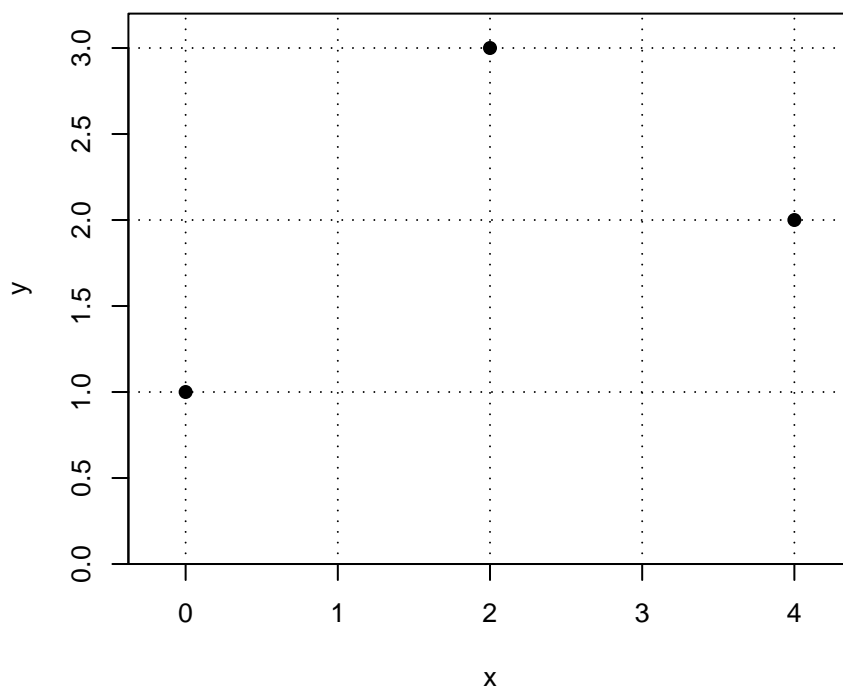
$$y = f(x, \beta) + \text{noise}$$

$$f(x, \beta) = \beta_0 + \sum_{j=1}^{m-1} \beta_j \phi_j(x) = \beta^T \phi(x)$$

and that the least squares estimate for β is $\hat{\beta} = (\Phi^T \Phi)^{-1} \Phi^T y$, where Φ is the $n \times m$ matrix of basis function values for the n training cases, and y is the vector of target values in these training cases.

- A) Is there always a unique least squares estimate for β (for any data, and any set of basis functions)?
- B) Is there always a unique penalized least squares estimate for β (for any data, and any set of basis functions), if the penalty is $\lambda \sum_{j=0}^{m-1} \beta_j^2$, with $\lambda > 0$? (Note that the penalty includes β_0 .)
- C) Suppose that there is only one input (so x is a scalar), and that $\phi_0(x) = 1$ and $\phi_j(x)$ for $j = 1, \dots, m - 1$ are Gaussian basis functions. Suppose we estimate β by penalized least squares, with penalty function $\lambda \sum_{j=1}^{m-1} \beta_j^2$. As λ gets bigger and bigger, what do the predictions for test cases approach? (Note that the penalty does not include β_0 .)

Question 4: Below is a plot of a dataset of $n = 3$ observations of (x_i, y_i) pairs:



In other words, the data points are $(0, 1)$, $(2, 3)$, $(4, 2)$.

Suppose we model this data with a linear basis function model with $m = 2$ basis functions given by $\phi_0(x) = 1$ and $\phi_1(x) = x$. We use a quadratic penalty of the form $\lambda\beta_1^2$, which penalizes only the regression coefficient for $\phi_1(x)$, not that for $\phi_0(x)$.

Suppose we use squared error from three-fold cross-validation (ie, with each validation set having only one case) to choose the value of λ . Suppose we consider only two values for λ — one very close to zero, and one very large. For the data above, will we choose λ near zero, or λ that is very big?

Question 5: Suppose that we observe a binary (0/1) variable, Y_1 . We do not know the probability, θ , that Y_1 will be 1, but we have a prior distribution for θ , that has the following density function on the interval $(0, 1)$:

$$P(\theta) = 12\left(\theta - \frac{1}{2}\right)^2$$

- A) Find as simple a formula as you can for the density function of the posterior distribution of θ given that we observe $Y_1 = 1$. Your formula should give the correctly normalized density.
- B) Suppose that Y_2 is a future observation, that is independent of Y_1 given θ . Find the predictive probability that $Y_2 = 1$ given that $Y_1 = 1$ — ie, find $P(Y_2 = 1 | Y_1 = 1)$.

Question 6: Let X_1, X_2, X_3, \dots for a sequence of binary (0/1) random variables. Given a value for θ , these random variables are independent, and $P(X_i = 1) = \theta$ for all i . Suppose that we are sure that θ is at least $1/2$, and that our prior distribution for θ for values $1/2$ and above is uniform on the interval $[1/2, 1]$. We have observed that $X_1 = 0$, but don't know the values of any other X_i .

- A) Write down the likelihood function for θ , based on the observation $X_1 = 0$.
- B) Find an expression for the posterior probability density function of θ given $X_1 = 0$, simplified as much as possible, with the correct normalizing constant included.
- C) Find the predictive probability that $X_2 = 1$ given that $X_1 = 0$.
- D) Find the probability that $X_2 = X_3$ given that $X_1 = 0$.

Question 7: Answer the following questions about Bayesian inference for linear basis function models. Recall that if the noise variance is σ^2 , and the prior distribution for β is Gaussian with mean zero and covariance matrix S_0 , the posterior distribution for β is Gaussian with mean m_n and covariance matrix S_n that can be written as follows:

$$S_n = \left[S_0^{-1} + (1/\sigma^2)\Phi^T\Phi \right]^{-1}, \quad m_n = S_n\Phi^T t / \sigma^2$$

and the marginal likelihood for the model is

$$-\frac{n}{2} \log(2\pi) - \frac{n}{2} \log(\sigma^2) - \frac{1}{2} \log \left(\frac{|S_0|}{|S_n|} \right) - \frac{1}{2} \|t - \Phi m_n\|^2 / \sigma^2 - \frac{1}{2} m_n^T S_0^{-1} m_n$$

For the questions below, assume that $S_0 = \omega^2 I$, for some positive ω .

- A) Suppose we set the noise variance, σ^2 , to be bigger and bigger, while fixing other aspects of the model. What will be the limiting values of the the posterior mean and covariance matrix?
- B) Suppose we set ω^2 , the prior variance of the β_j , to be bigger and bigger, while fixing other aspects of the model. What will be the limiting values of the the posterior mean, m_n , and covariance matrix, S_n ?
- C) Suppose we set ω^2 to be bigger and bigger while fixing other aspects of the model. What will be the limiting value of the marginal likelihood?
- D) Suppose there is only one input (so x is a scalar), and the basis functions are $\phi_j(x) = x^j$, for $j = 0, \dots, m - 1$. The Bayesian mean prediction for the value of y in a test case with input x is found by integrating the prediction based on β (ie, the expected value of y given x and β) with respect to the posterior distribution of β . Will this final mean prediction be a polynomial function of x ?