### CSC304 Lectures 4 & 5

Game Theory
(PoA, PoS, Cost sharing & congestion games, Potential function, Braess' paradox)

## Recap

- Nash equilibria (NE)
  - > No agent wants to change their strategy
  - > Guaranteed to exist if mixed strategies are allowed
  - > Could be multiple
- Pure NE through best-response diagrams
- Mixed NE through the indifference principle

## Worst and Best Nash Equilibria

- What can we say after we identify all Nash equilibria?
  - Compute how "good" they are in the best/worst case
- How do we measure "social good"?
  - Game with only rewards?
    Higher total reward of players = more social good
  - Game with only penalties?
    Lower total penalty to players = more social good
  - Game with rewards and penalties?
    No clear consensus...

## Price of Anarchy and Stability

Price of Anarchy (PoA)

"Worst NE vs optimum"

Max total reward

Min total reward in any NE

or

Max total cost in any NE
Min total cost

Price of Stability (PoS)

"Best NE vs optimum"

Max total reward

Max total reward in any NE

or

Min total cost in any NE
Min total cost

 $PoA \ge PoS \ge 1$ 

# Revisiting Stag-Hunt

Hunter 2 Hunter 1	Stag	Hare
Stag	(4 , 4)	(0 , 2)
Hare	(2 , 0)	(1 , 1)

- Max total reward = 4 + 4 = 8
- Three equilibria
  - > (Stag, Stag) : Total reward = 8
  - > (Hare, Hare): Total reward = 2
  - > (1/3 Stag 2/3 Hare, 1/3 Stag 2/3 Hare)
    - Total reward =  $\frac{1}{3} * \frac{1}{3} * 8 + \left(1 \frac{1}{3} * \frac{1}{3}\right) * 2 \in (2,8)$
- Price of stability? Price of anarchy?

# Revisiting Prisoner's Dilemma

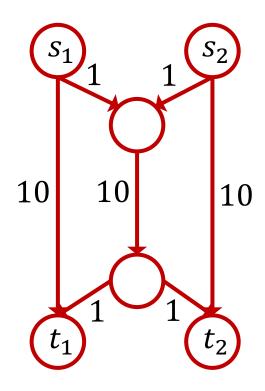
John Sam	Stay Silent	Betray
Stay Silent	(-1 , -1)	(-3 , 0)
Betray	(0 , -3)	(-2 , -2)

- Min total cost = 1 + 1 = 2
- Only equilibrium:
  - $\triangleright$  (Betray, Betray) : Total cost = 2 + 2 = 4

Price of stability? Price of anarchy?

# **Cost Sharing Game**

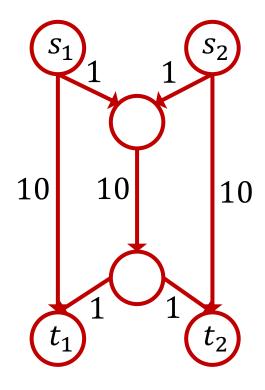
- n players on directed weighted graph G
- Player *i* 
  - $\triangleright$  Wants to go from  $s_i$  to  $t_i$
  - > Strategy set  $S_i$  = {directed  $S_i \rightarrow t_i$  paths}
  - $\triangleright$  Denote his chosen path by  $P_i \in S_i$
- Each edge e has cost  $c_e$  (weight)
  - > Cost is split among all players taking edge e
  - $\triangleright$  That is, among all players i with  $e \in P_i$



# Cost Sharing Game

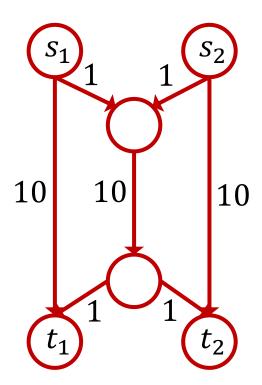
- Given strategy profile  $\vec{P}$ , cost  $c_i(\vec{P})$  to player i is sum of his costs for edges  $e \in P_i$
- Social cost  $C(\vec{P}) = \sum_{i} c_i(\vec{P})$

- Note:  $C(\vec{P}) = \sum_{e \in E(\vec{P})} c_e$ , where...
  - >  $E(\vec{P})$ ={edges taken in  $\vec{P}$  by at least one player}
  - > Why?



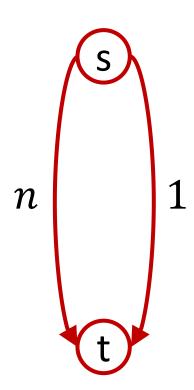
# Cost Sharing Game

- In the example on the right:
  - What if both players take direct paths?
  - What if both take middle paths?
  - What if one player takes direct path and the other takes middle path?
- Pure Nash equilibria?



# Cost Sharing: Simple Example

- Example on the right: n players
- Two pure NE
  - $\triangleright$  All taking the n-edge: social cost = n
  - > All taking the 1-edge: social cost = 1
    - Also the social optimum
- Price of stability: 1
- Price of anarchy: n
  - > We can show that price of anarchy  $\leq n$  in every cost-sharing game!



# Cost Sharing: PoA

 Theorem: The price of anarchy of a cost sharing game is at most n.

#### Proof:

- > Suppose the social optimum is  $(P_1^*, P_2^*, ..., P_n^*)$ , in which the cost to player i is  $c_i^*$ .
- > Take any NE with cost  $c_i$  to player i.
- $\triangleright$  Let  $c'_i$  be his cost if he switches to  $P_i^*$ .
- $\triangleright$  NE  $\Rightarrow c_i' \geq c_i$  (Why?)
- $\triangleright$  But :  $c_i' \le n \cdot c_i^*$  (Why?)
- $> c_i \le n \cdot c_i^*$  for each  $i \Rightarrow$  no worse than  $n \times$  optimum

# Cost Sharing

#### Price of anarchy

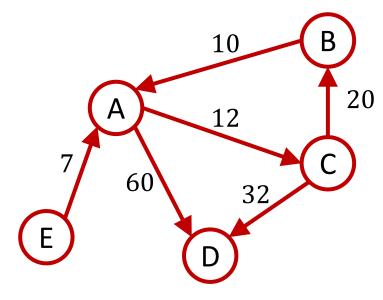
- $\triangleright$  Every cost-sharing game: PoA  $\le n$
- $\triangleright$  Example game with PoA = n
- > Bound of *n* is tight.

#### Price of stability?

- > In the previous game, it was 1.
- > In general, it can be higher. How high?
- > We'll answer this after a short detour.

# **Cost Sharing**

- Nash's theorem shows existence of a mixed NE.
  - > Pure NE may not always exist in general.
- But in both cost-sharing games we saw, there was a PNE.
  - What about a more complex game like the one on the right?



10 players:  $E \rightarrow C$ 

27 players:  $B \rightarrow D$ 

19 players:  $C \rightarrow D$ 

## Good News

Theorem: Every cost-sharing game has a pure Nash equilibrium.

- Proof:
  - > Via "potential function" argument

## Step 1: Define Potential Fn

- Potential function:  $\Phi: \prod_i S_i \to \mathbb{R}_+$ 
  - > This is a function such that for every pure strategy profile  $\vec{P} = (P_1, ..., P_n)$ , player i, and strategy  $P'_i$  of i,

$$c_i(P'_i, \vec{P}_{-i}) - c_i(\vec{P}) = \Phi(P'_i, \vec{P}_{-i}) - \Phi(\vec{P})$$

- ➤ When a single player *i* changes her strategy, the change in potential function equals the change in cost to *i*!
- ➤ Note: In contrast, the change in the social cost C equals the total change in cost to all players.
  - Hence, the social cost will often not be a valid potential function.

## Step 2: Potential $F^n \rightarrow pure Nash Eq$

- A potential function exists ⇒ a pure NE exists.
  - $\triangleright$  Consider a  $\vec{P}$  that minimizes the potential function.
  - $\triangleright$  Deviation by any single player i can only (weakly) increase the potential function.
  - $\triangleright$  But change in potential function = change in cost to i.
  - > Hence, there is no beneficial deviation for any player.

 Hence, every pure strategy profile minimizing the potential function is a pure Nash equilibrium.

## Step 3: Potential F<sup>n</sup> for Cost-Sharing

- Recall:  $E(\vec{P}) = \{\text{edges taken in } \vec{P} \text{ by at least one player} \}$
- Let  $n_e(\vec{P})$  be the number of players taking e in  $\vec{P}$

$$\Phi(\vec{P}) = \sum_{e \in E(\vec{P})} \sum_{k=1}^{n_e(\vec{P})} \frac{c_e}{k}$$

• Note: The cost of edge e to each player taking e is  $c_e/n_e(\vec{P})$ . But the potential function includes all fractions:  $c_e/1$ ,  $c_e/2$ , ...,  $c_e/n_e(\vec{P})$ .

## Step 3: Potential F<sup>n</sup> for Cost-Sharing

$$\Phi(\vec{P}) = \sum_{e \in E(\vec{P})} \sum_{k=1}^{n_e(\vec{P})} \frac{c_e}{k}$$

- Why is this a potential function?
  - > If a player changes path, he pays  $\frac{c_e}{n_e(\vec{P})+1}$  for each new edge e, gets back  $\frac{c_f}{n_f(\vec{P})}$  for each old edge f.
  - > This is precisely the change in the potential function too.
  - > So  $\Delta c_i = \Delta \Phi$ .

## Potential Minimizing Eq.

- Minimizing the potential function gives some pure Nash equilibrium
  - > Is this equilibrium special? Yes!
- Recall that the price of anarchy can be up to n.
  - $\triangleright$  That is, the worst Nash equilibrium can be up to n times worse than the social optimum.

A potential-minimizing pure Nash equilibrium is better!

## Potential Minimizing Eq.

$$\sum_{e \in E(\vec{P})} c_e \leq \Phi(\vec{P}) = \sum_{e \in E(\vec{P})} \sum_{k=1}^{n_e(\vec{P})} \frac{c_e}{k} \leq \sum_{e \in E(\vec{P})} c_e * \sum_{k=1}^{n} \frac{1}{k}$$
Social cost
$$\forall \vec{P}, \ C(\vec{P}) \leq \Phi(\vec{P}) \leq C(\vec{P}) * H(n)$$

$$= \sum_{k=1}^{n} 1/n = O(\log n)$$

$$C(\vec{P}^*) \leq \Phi(\vec{P}^*) \leq \Phi(OPT) \leq C(OPT) * H(n)$$
Potential minimizing eq. Social optimum

## Potential Minimizing Eq.

• Potential-minimizing PNE is  $O(\log n)$ -approximation to the social optimum.

- Thus, in every cost-sharing game, the price of stability is  $O(\log n)$ .
  - $\triangleright$  Compare to the price of anarchy, which can be n

## **Congestion Games**

- Generalize cost sharing games
- n players, m resources (e.g., edges)
- Each player i chooses a set of resources  $P_i$  (e.g.,  $s_i \rightarrow t_i$  paths)
- When  $n_j$  player use resource j, each of them get a cost  $f_j(n_j)$
- Cost to player is the sum of costs of resources used

## **Congestion Games**

- Theorem [Rosenthal 1973]: Every congestion game is a potential game.
- Potential function:

$$\Phi(\vec{P}) = \sum_{j \in E(\vec{P})} \sum_{k=1}^{n_j(\vec{P})} f_j(k)$$

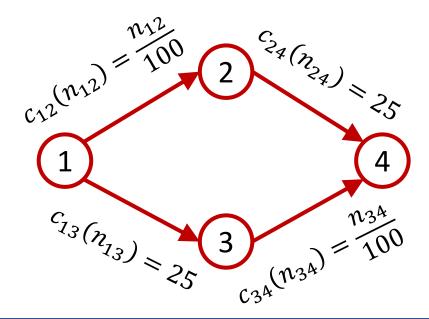
 Theorem [Monderer and Shapley 1996]: Every potential game is equivalent to a congestion game.

### **Potential Functions**

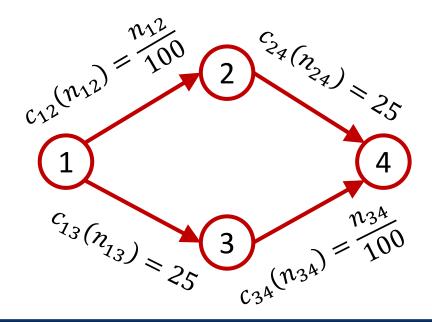
- Potential functions are useful for deriving various results
  - > E.g., used for analyzing amortized complexity of algorithms
- Bad news: Finding a potential function that works may be hard.

- In cost sharing,  $f_i$  is decreasing
  - > The more people use a resource, the less the cost to each.
- $f_i$  can also be increasing
  - > Road network, each player going from home to work
  - > Uses a sequence of roads
  - > The more people on a road, the greater the congestion, the greater the delay (cost)
- Can lead to unintuitive phenomena

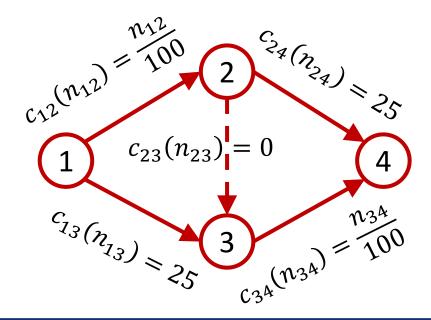
- Parkes-Seuken Example
  - > 2000 players want to go from 1 to 4
  - $\gt 1 \rightarrow 2$  and  $3 \rightarrow 4$  are "congestible" roads
  - $> 1 \rightarrow 3$  and  $2 \rightarrow 4$  are "constant delay" roads



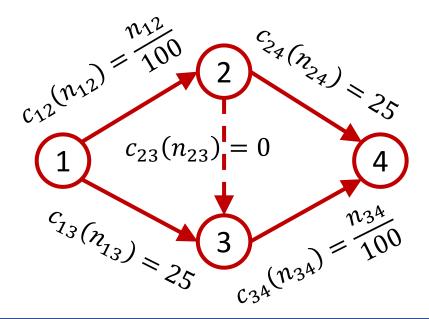
- Pure Nash equilibrium?
  - > 1000 take  $1 \rightarrow 2 \rightarrow 4$ , 1000 take  $1 \rightarrow 3 \rightarrow 4$
  - $\triangleright$  Each player has cost 10 + 25 = 35
  - Anyone switching to the other creates a greater congestion on it, and faces a higher cost



- What if we add a zero-cost connection  $2 \rightarrow 3$ ?
  - > Intuitively, adding more roads should only be helpful
  - > In reality, it leads to a greater delay for everyone in the unique equilibrium!



- Nobody chooses  $1 \rightarrow 3$  as  $1 \rightarrow 2 \rightarrow 3$  is better irrespective of how many other players take it
- Similarly, nobody chooses  $2 \rightarrow 4$
- Everyone takes  $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$ , faces delay = 40!



- In fact, what we showed is:
  - > In the new game,  $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$  is a strictly dominant strategy for each player!

