

Using Bifurcations for Diversity in Differentiable Games

Beyond First-order Methods in ML Workshop, ICML 2021

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- Games are increasingly important in ML – ex., GANs, hyperparam opt., self-play, meta-learning, adversarial examples, numerous others.
- **Goal:** Want to find diverse solutions in differentiable games – ex., where players work together or battle each-other.

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- Bifurcations are areas where small changes cause solution differences. Saddles are a key bifurcation in conservative systems from following gradients.
- Following gradients in games is a non-conservative system, so more solution and bifurcation types.
- Because, Hessian's generalization for games – i.e., the *Game Hessian* – may have complex EVals from lack of symmetry.

$$\widehat{\mathcal{H}}^{\text{Game Hessian}} = \begin{bmatrix} \text{Player A Hessian } \nabla_{\theta_A}^2 \mathcal{L}_A & \nabla_{\theta_A} \nabla_{\theta_B} \mathcal{L}_A \\ \nabla_{\theta_B} \nabla_{\theta_A} \mathcal{L}_B^\top & \text{Player B Hessian } \nabla_{\theta_B}^2 \mathcal{L}_B \end{bmatrix}$$

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- We detect and allow for branching at new types of bifurcations – ex., Hopf where $\approx \Re$ EVal crosses 0.

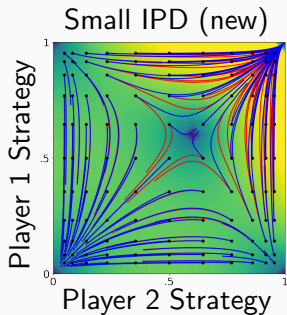
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- We detect and allow for branching at new types of bifurcations – ex., Hopf where $\approx \Re$ EVal crosses 0.
- We apply an arbitrary optimization algorithm after branching.

New Toy Problems

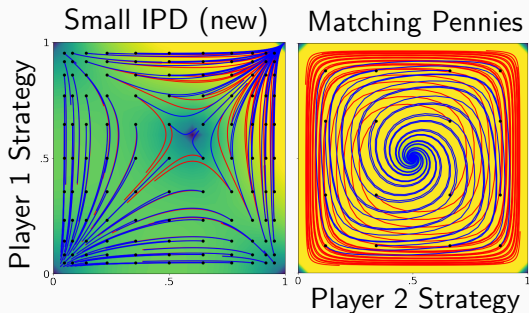
Following the gradient in red, LOLA [2] in blue



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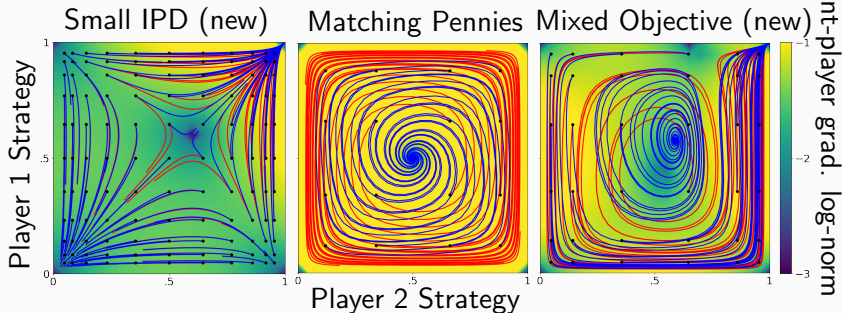
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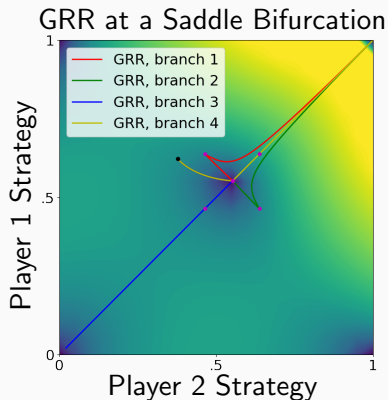
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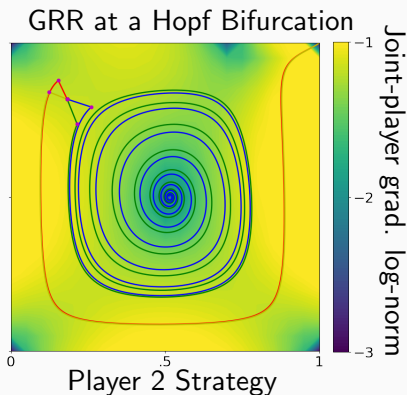
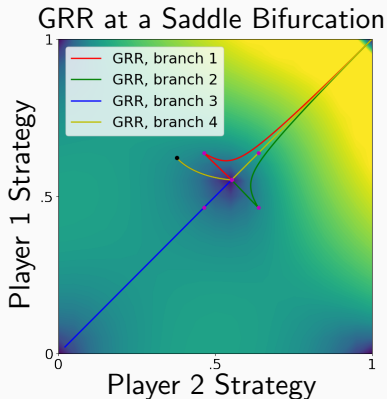
- Small IPD is a 2 param. Iterated Prisoner's Dilemma with TT and DD solutions, but only real EVals.
- Matching Pennies is a 2 param. rock-paper-scissors with imaginary EVals, but only 1 solution.
- Mixing these gives a 2 param. problem like the full IPD with multiple solutions, complex EVals, and a Hopf bifurcation.

Applying our Method on Toy Problems



- For both the small IPD (left) and mixed objective (right) our method – Game Ridge Rider (GRR) – finds all solutions.

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Finding Diverse Solutions in the Iterated Prisoners Dilemma

Search Strategy	Solution Mode	
	Cooperate	Defect
×20 Random init and LOLA [2]	✓	✗
×20 Random init and follow grad.	✗	✓

- Randomly initializing then applying a training method only finds 1 solution mode.

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Ours: Max entropy saddle and branch	✓	✓
Random init and branch	×	✓

- Randomly initializing then applying a training method only finds 1 solution mode.
- Our method finds both solution modes.
- If we don't start at a saddle, then branching doesn't affect the solution.

Takeaways

- Differentiable games generalize single-objective minimization, but with non-conservative dynamics from complex EVals.

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- We can view methods for diverse solutions in single-objective minimization – i.e., Ridge Rider (RR) – as finding bifurcations in conservative systems and branching.

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- Differentiable games generalize single-objective minimization, but with non-conservative dynamics from complex EVals.
- We can view methods for diverse solutions in single-objective minimization – i.e., Ridge Rider (RR) – as finding bifurcations in conservative systems and branching.
- This viewpoint allows usage of tools from dynamical systems to generalize RR to non-conservative systems.

Thanks!

Jonathan Lorraine



Jack Parker-Holder



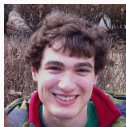
Paul Vicol



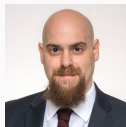
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References

[1] Jack Parker-Holder, Luke Metz, Cinjon Resnick, Hengyuan Hu, Adam Lerer, Alistair Letcher, Alexander Peysakhovich, Aldo Pacchiano, and Jakob Foerster. Ridge rider: Finding diverse solutions by following eigenvectors of the hessian. In *Advances in Neural Information Processing Systems*, volume 33, pages 753–765, 2020.

[2] Jakob Foerster, Richard Y Chen, Maruan Al-Shedivat, Shimon Whiteson, Pieter Abbeel, and Igor Mordatch. Learning with opponent-learning awareness. In *International Conference on Autonomous Agents and MultiAgent Systems*, pages 122–130, 2018.

Extra Slides

Proposed Algorithm

- Check out the paper for more details.

Algorithm 1 Game Ridge Rider (GRR)–red modifications

- 1: **Input:** ω^{Saddle} , α , ChooseFromArchive, **GetRidges**,
 - 2: **EndRide**, **Optimize**, UpdateRidge
 - 3: $\mathcal{A} = \text{GetRidges}(\omega^{\text{Saddle}})$ # Init. Archive
 - 4: **while** Archive \mathcal{A} non-empty **do**
 - 5: $j, \mathcal{A} = \text{ChooseFromArchive}(\mathcal{A})$
 - 6: $(\omega^j, e_j, \lambda_j) = \mathcal{A}_j$
 - 7: **while** **EndRide** $(\omega^j, e_j, \lambda_j)$ not True **do**
 - 8: $\omega^i \leftarrow \omega^j - \alpha e_j$ # Step along the ridge e_j
 - 9: $e_j, \lambda_j = \text{UpdateRidge}(\omega^j, e_j, \lambda_j)$
 - 10: $\omega^j = \text{Optimize}(\omega^j)$
 - 11: $\mathcal{A} = \mathcal{A} \cup \text{GetRidges}(\omega^j)$ # Add new ridges
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