

CSC 338 Lecture 7 (Short Lecture)

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We want to solve linear least squares problems:

$$A\underline{x} \approx \underline{b} \quad A \in \mathbb{R}^{m \times n}, \quad m > n.$$

⇒ Normal Equation (worse conditioning compared to original problem)

⇒ QR Factorization using Householder transformations

↓
Factor $A = Q \begin{bmatrix} R_{n \times n} \\ 0_{(m-n) \times n} \end{bmatrix} b = Q \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$

a.k.a. Elementary ↓ Reflectors

where Q orthogonal
 R upper triangular

$$H = I - 2 \frac{\underline{v}\underline{v}^T}{\underline{v}^T \underline{v}}$$

So $\min_{\underline{x}} \|A\underline{x} - \underline{b}\|_2 = \min_{\underline{x}} \left\| \begin{bmatrix} R \\ 0 \end{bmatrix} \underline{x} - \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \right\|_2$
 $= \|c_2\|_2$

choose \underline{v} to annihilate elements below the diagonal

eg// $A = \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$

we will reduce A to the form $A = Q \begin{bmatrix} R \\ 0 \end{bmatrix}$

First Step ~ eliminate below the first entry in

$\underline{a}_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$ using a Householder transform.

$\underline{v}_1 = \underline{a}_1 \pm \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} \leftarrow \|\underline{a}_1\|_2 = \sqrt{1^2 + 2^2 + 2^2} = 3$

we choose + to avoid cancellation, so ①

$$\underline{v}_1 = \underline{a}_1 + \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}.$$

①. Verify that $H_1 \underline{a}_1$ ~~is~~ eliminates all but the first element $\leftarrow H_1 = I - 2 \frac{\underline{v}_1 \underline{v}_1^T}{\underline{v}_1^T \underline{v}_1}$

$$H_1 \underline{a}_1 = \underline{a}_1 - 2 \underline{v}_1 \frac{\underline{v}_1^T \underline{a}_1}{\underline{v}_1^T \underline{v}_1} = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} - 2 \cdot \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} \frac{8/2}{24} = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$$

$$\textcircled{2} H_1 \begin{bmatrix} -4 \\ 3 \\ 2 \end{bmatrix} = \begin{bmatrix} -4 \\ 3 \\ 2 \end{bmatrix} - 2 \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} \frac{-16+6+4}{24} = \begin{bmatrix} -2 \\ 4 \\ 3 \end{bmatrix}$$

$$\text{so } H_1 A = \begin{bmatrix} -3 & -2 \\ 0 & 4 \\ 0 & 3 \end{bmatrix}$$

we don't compute H_1 explicitly.

(But for illustration purposes
$$H_1 = I - 2 \frac{\underline{v}_1 \underline{v}_1^T}{\underline{v}_1^T \underline{v}_1} = \begin{bmatrix} -\frac{1}{3} & -\frac{2}{3} & -\frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} & -\frac{1}{3} \\ -\frac{2}{3} & -\frac{1}{3} & \frac{2}{3} \end{bmatrix})$$

Second Step ~ eliminate below the first entry in the remaining submatrix. $\underline{a}_2 = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$ $\|\underline{a}_2\| = \sqrt{5}$

$$\text{Take } \underline{v}_2 = \underline{a}_2 \oplus \begin{bmatrix} 5 \\ 0 \end{bmatrix} = \begin{bmatrix} 9 \\ 3 \end{bmatrix}$$

This choice of \underline{v}_2 will map $\underline{a}_2 \rightarrow \begin{bmatrix} -5 \\ 0 \end{bmatrix}$

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we don't need to represent H_2 explicitly,
but.

$$H_2 = \left[\begin{array}{c|c} I & \\ \hline & I - 2 \frac{v v^T}{v^T v} \end{array} \right] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -4/5 & -3/5 \\ 0 & -3/5 & 4/5 \end{bmatrix}$$

$$\text{So } H_2 H_1 A = \begin{bmatrix} -3 & -2 \\ 0 & -5 \\ 0 & 0 \end{bmatrix} \quad \text{So set } Q = \begin{bmatrix} -3 & -2 \\ 0 & -5 \end{bmatrix}$$

$$Q = H_1^{-1} H_2^{-1}$$

$$\Rightarrow A = Q \begin{bmatrix} R \\ 0 \end{bmatrix}$$