# CSC2515 Midterm Review Part 2

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- Thursday Oct 22 11:59am EDT to Friday Oct 23 11:59am EDT
- Designed to take 2.5 to 3 hours for well-prepared students
- What might be on the midterm?
  - Everything covered in detail during lecture
- What will NOT be on the midterm?
  - Programming
  - New concepts introduced in Homeworks
  - Anything from tutorials that wasn't in the lectures slides
  - Anything from the textbooks that wasn't in the lecture slides

- Week 7 is on the midterm.
- Piazza will be set to "private posts only" during the midterm.
- Please refrain from starting discussions in existing threads on Piazza.
- Submission (detailed instructions on midterm):
  - (recommended) print and scan
  - (not recommended) write from scratch; LaTeX
- Leave plenty of time at the end for submission.
- Open book
  - Allowed: all lecture slides, course notes, textbooks
  - Not allowed: Google, any computational software (Ex: Wolfram Alpha, graphing tools)
- SGS course drop deadline: Monday October 26

#### Lecture 1

- k-Nearest Neighbors
- Bayes Optimality
- Lecture 2
  - Decision trees and Information theory (information gain)
  - Bias Variance
  - Bagging
- Lecture 3
  - Linear regression
  - Logistic regression

- Lecture 4
  - Gradient descent
  - L<sup>1</sup>,L<sup>2</sup> regularization (covered in previous tutorial, see Q3 in 19 midterm)
  - SVMs (covered in previous tutorial, see Q6 in 19 midterm)
  - Boosting, additive models

# Midterm Topics (This Time)

- Lecture 5
  - PCA
  - K-means
  - Maximum likelihood estimation (MLE)
- Lecture 6
  - Maximum a-posteriori (MAP)
  - Full Bayesian parameter estimation
  - Naive Bayes
  - Gaussian discriminant analysis
- Lecture 7
  - EM algorithm
  - Gaussian mixture models

- Goal: reduce  $\boldsymbol{x} \in \mathbb{R}^{D}$  to  $\boldsymbol{z} \in \mathbb{R}^{K}$
- Idea: find orthonormal basis  $\boldsymbol{U} \in \mathbb{R}^{D \times K}$
- $z = \boldsymbol{U}^T(\boldsymbol{x} \boldsymbol{\mu})$
- Solving for U: argmin of reconstruction error = argmax of code vector variance
- Solution: columns of U are eigenvectors of Σ with top K eigenvalue magnitudes.



Show that PCA is translationally invariant. Shifting all data  $\mathbf{x}' = \mathbf{x} + \mathbf{\delta}$  does not change the principal components or the code vectors.

### K-Means

- Goal: reduce  $\mathbf{x} \in \mathbb{R}^{D}$  to  $\mathbf{z} \in \{1, ..., K\}$ •  $\min_{\mu_{j}, S_{j}} \sum_{j=1}^{K} \sum_{x_{i} \in S_{j}} ||x_{i} - \mu_{j}||^{2}$
- Two steps:
  - Assignment:  $x_i \in S_k \longleftrightarrow k = \arg \min_i ||x_i \mu_j||^2$

• Refitting: 
$$\mu_j = \frac{1}{|S_j|} \sum_{x_i \in S_j} x_i$$



Assume that cluster assignments are fixed. Show that, for one specific value of the learning rate  $\alpha$ , the "refitting" step is equivalent to performing batch gradient descent on the original loss function.

#### MLE

• 
$$\theta^* = \arg \max_{\theta} p(D|\theta) = \arg \max_{\theta} \log p(D|\theta) = \arg \max_{\theta} \sum_{i=1}^{N} \log p(D_i|\theta)$$
  
MAP

• 
$$\theta^* = \arg \max_{\theta} p(\theta|D) = \arg \max_{\theta} \frac{p(\theta)p(D|\theta)}{p(D)}$$
  
=  $\arg \max_{\theta} \log p(\theta) + \log p(D|\theta)$ 

• How do we choose a good prior?

These both give point estimates for  $\theta^*!$ 

• 
$$p(\theta|D) = \frac{p(\theta)p(D|\theta)}{p(D)} = \frac{1}{Z}p(\theta)p(D|\theta) \propto p(\theta)p(D|\theta)$$
  
•  $Z = \int p(\theta)p(D|\theta) \ d\theta$  (normalization constant)

- Instead of a point estimate, now we have a distribution for  $p(\theta|D)$
- Can compute the probability distribution over the next data point:

$$p(D'|D) = \int p(\theta|D)p(D'|\theta) \ d heta$$

• True/False - The MAP and MLE estimates can only be equal when the number of training examples is very large.

• True/False - MAP computes the mean of the posterior distribution.

Consider the following procedure used to generate random integers between 0 and  $2^k - 1$  (inclusive):

- Start with the set of all integers between 0 and  $2^k 1$ .
- (\*) Flip a biased coin with probability of heads =  $\alpha$ 
  - If it is a head (0), remove the first half of the (remaining) numbers.
  - If it is a tail (1), remove the second half of the (remaining) numbers.
  - If only one number is left, return that number
  - Otherwise, go back to step (\*).

a) For a particular outcome *b*, let  $n_1(b)$  be the number of 1's in the binary expansion of *b*, and  $n_0(b)$  be the number of 0's. What is the likelihood of *b* given  $\alpha$ ?

## MAP Question

b) In order to estimate  $\alpha \in [0, 1]$ , we generate *n* random numbers. We assume the following prior distribution for  $\alpha$ :  $p(\alpha) = 6\alpha(1 - \alpha)$ . What is the MAP estimate for  $\alpha$  using these *n* observations?

### Naive Bayes

• 
$$p(t = k | x_1, ..., x_D) \propto p(t = k, x_1, ..., x_D)$$
  
=  $p(t = k)p(x_1, ..., x_D | t = k)$   
=  $p(t = k) \prod_{j=1}^{D} p(x_j | t = k)$ 

- Learn  $p(x_j | t = k)$  separately (ex: by MLE)
  - Bernoulli Naive Bayes
  - Gaussian Naive Bayes

• 
$$p(t = k | x_1, ..., x_D) = \frac{1}{Z} p(t = k) \prod_{j=1}^D p(x_j | t = k)$$
  
•  $Z = p(\mathbf{x}) = \sum_k p(t = k) p(x_1, ..., x_D | t = k)$ 

• If *x* is continuous, instead of making the Naive Bayes assumption, we can model

$$p(x_1,...,x_D|t=k)$$

by a multivariate Gaussian.

- $\boldsymbol{x}|t = k \sim \mathcal{N}(\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$
- Can compute  $\mu_k$  and  $\Sigma_k$  using MLE.

For the binary classification case:

- General  $\Sigma_k$  : conic section
- $\Sigma_1 = \Sigma_2$ : linear decision boundary
- $\Sigma_k$  diagonal: Gaussian Naive Bayes
- $\Sigma_1 = \Sigma_2 = \sigma^2 I$ : decision boundary bisects class means

## Naive Bayes Question

You are doing binary classification on a dataset with two features using a Naive Bayes classifier. You compute  $p(x_j|t = k)$  as the following categorical distributions. Assume the two classes are equally likely.

	t = 0	t = 1
$x_1 = -1$	0.2	0.3
$x_1 = 0$	0.4	0.6
$x_1 = 1$	0.4	0.1

	t = 0	t = 1
$x_2 = -1$	0.4	0.1
$x_2 = 0$	0.5	0.3
$x_2 = 1$	0.1	0.6

For a data point x = (-1, 1), calculate p(t = 0|x) and p(t = 1|x)