## Homework 2

Deadline: Thursday, Oct. 15, at 11:59pm.
Submission: You need to submit x files through Markus $\mathbb{T}^{1}$

- Your answers to Questions 1, 2, and 3, as hw2.pdf.
- Your code for Question 1c, as q1.py.
- Your code for Question 2b and 2c, as q2.py.

Neatness Point: One of the 20 points will be given for neatness. You will receive this point as long as we don't have a hard time reading your solutions or understanding the structure of your code.

Late Submission: $10 \%$ of the marks will be deducted for each day late, up to a maximum of 3 days. After that, no submissions will be accepted.

Computing: To install Python and required libraries, see the instructions on the course web page.
Collaboration: Homeworks are individual work. See the course websit $\|^{2}$ for detailed policies.

1. [5pts] Robust Regression. One problem with linear regression using squared error loss is that it can be sensitive to outliers. Another loss function we could use is the Huber loss, parameterized by a hyperparameter $\delta$ :

$$
\begin{aligned}
L_{\delta}(y, t) & =H_{\delta}(y-t) \\
H_{\delta}(a) & = \begin{cases}\frac{1}{2} a^{2} & \text { if }|a| \leq \delta \\
\delta\left(|a|-\frac{1}{2} \delta\right) & \text { if }|a|>\delta\end{cases}
\end{aligned}
$$

(a) $[\mathbf{2 p t}]$ Sketch the Huber loss $L_{\delta}(y, t)$ and squared error loss $L_{\mathrm{SE}}(y, t)=\frac{1}{2}(y-t)^{2}$ for $t=0$ and for $\delta=\{1,0.5,0.1\}$ (for Huber loss), either by hand or using a plotting library. Based on your sketch, why would you expect the Huber loss to be more robust to outliers?
(b) $[\mathbf{1 p t}]$ Just as with linear regression, assume a linear model:

$$
y=\mathbf{w}^{T} \mathbf{x}+b .
$$

Give formulas for the partial derivatives $\partial L_{\delta} / \partial \mathbf{w}$ and $\partial L_{\delta} / \partial b$. (We recommend you find the derivative $H_{\delta}^{\prime}(a)$, and then give your answers in terms of $H_{\delta}^{\prime}(y-t)$.)
(c) $[\mathbf{2 p t}]$ Write Python code to perform (full batch mode) gradient descent on this model [using the gradients you derived above]. Assume the training dataset is given as a design matrix $X$ and target vector $\mathbf{y}$. Initialize $\mathbf{w}$ and $b$ to all zeros. Your code should be vectorized, i.e. you should not have a for loop over training examples or input dimensions. You may find the function np. where helpful. (Submit your code as q1.py.) In order to make sure your code runs, you can check your function with random matrices for $X$ and $y$. Use the code snippet in q1_helper.py.

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## 2. [11pts] Locally Weighted Regression.

(a) $[3 \mathbf{p t s}]$ Given $\left\{\left(\mathbf{x}^{(1)}, y^{(1)}\right), . .,\left(\mathbf{x}^{(N)}, y^{(N)}\right)\right\}$ and positive weights $a^{(1)}, \ldots, a^{(N)}$ show that the solution to the weighted least squares problem

$$
\begin{equation*}
\mathbf{w}^{*}=\arg \min \frac{1}{2} \sum_{i=1}^{N} a^{(i)}\left(y^{(i)}-\mathbf{w}^{T} \mathbf{x}^{(i)}\right)^{2}+\frac{\lambda}{2}\|\mathbf{w}\|^{2} \tag{1}
\end{equation*}
$$

is given by the formula

$$
\begin{equation*}
\mathbf{w}^{*}=\left(\mathbf{X}^{T} \mathbf{A} \mathbf{X}+\lambda \mathbf{I}\right)^{-1} \mathbf{X}^{T} \mathbf{A} \mathbf{y} \tag{2}
\end{equation*}
$$

where $\mathbf{X}$ is the design matrix (defined in class) and $\mathbf{A}$ is a diagonal matrix where $\mathbf{A}_{i i}=$ $a^{(i)}$
It may help you to review Section 3.1 of the $\csc 321$ notes ${ }^{3}$.
(b) [5pts] Locally reweighted least squares combines ideas from k-NN and linear regression. For each new test example $\mathbf{x}$ we compute distance-based weights for each training example $a^{(i)}=\frac{\exp \left(-\left\|\mathbf{x}-\mathbf{x}^{(i)}\right\|^{2} / 2 \tau^{2}\right)}{\sum_{j} \exp \left(-\left\|\mathbf{x}-\mathbf{x}^{(j)}\right\|^{2} / 2 \tau^{2}\right)}$, computes $\mathbf{w}^{*}=\arg \min \frac{1}{2} \sum_{i=1}^{N} a^{(i)}\left(y^{(i)}-\mathbf{w}^{T} \mathbf{x}^{(i)}\right)^{2}+$ $\frac{\lambda}{2}\|\mathbf{w}\|^{2}$ and predicts $\hat{y}=\mathbf{x}^{T} \mathbf{w}^{*}$. Complete the implementation of locally reweighted least squares by providing the missing parts for q2_helper.py.

Important things to notice while implementing: First, do not invert any matrix, use a linear solver (numpy.linalg.solve is one example). Second, notice that $\frac{\exp \left(A_{i}\right)}{\sum_{j} \exp \left(A_{j}\right)}=$ $\frac{\exp \left(A_{i}-B\right)}{\sum_{j} \exp \left(A_{j}-B\right)}$ but if we use $B=\max _{j} A_{j}$ it is much more numerically stable as $\frac{\exp \left(A_{i}\right)}{\sum_{j} \exp \left(A_{j}\right)}$ overflows/underflows easily. This is handled automatically in the scipy package with the scipy.misc.logsumexp functiont
(c) [3pt] Based on our understanding of overfitting and underfitting, how would you expect the training error and the validation error to vary as a function of $\tau$ ? (I.e., what do you expect the curves to look like?)
Now run the experiment. Randomly hold out $30 \%$ of the dataset as a validation set. Compute the average loss for different values of $\tau$ in the range $[10,1000]$ on both the training set and the validation set. Plot the training and validation losses as a function of $\tau$ (using a $\log$ scale for $\tau$ ). Was your guess correct?
Please include the plots in hw2.pdf, and include your code in q2.py.
3. [3pts] AdaBoost. The goal of this question is to show that the AdaBoost algorithm changes the weights in order to force the weak learner to focus on difficult data points. Here we consider the case that the target labels are from the set $\{-1,+1\}$ and the weak learner also returns a classifier whose outputs belongs to $\{-1,+1\}$ (instead of $\{0,1\}$ ). Consider the $t$-th iteration of AdaBoost, where the weak learner is

$$
h_{t} \leftarrow \underset{h \in \mathcal{H}}{\operatorname{argmin}} \sum_{i=1}^{N} w_{i} \mathbb{I}\left\{h\left(\mathbf{x}^{(i)}\right) \neq t^{(i)}\right\},
$$

[^1]the $w$-weighted classification error is
$$
\operatorname{err}_{t}=\frac{\sum_{i=1}^{N} w_{i} \mathbb{I}\left\{h_{t}\left(\mathbf{x}^{(i)}\right) \neq t^{(i)}\right\}}{\sum_{i=1}^{N} w_{i}},
$$
and the classifier coefficient is $\alpha_{t}=\frac{1}{2} \log \frac{1-\mathrm{err}_{t}}{\text { err }_{t}}$. (Here, log denotes the natural logarithm.) AdaBoost changes the weights of each sample depending on whether the weak learner $h_{t}$ classifies it correctly or incorrectly. The updated weights for sample $i$ is denoted by $w_{i}^{\prime}$ and is
$$
w_{i}^{\prime} \leftarrow w_{i} \exp \left(-\alpha_{t} t^{(i)} h_{t}\left(\mathbf{x}^{(i)}\right)\right) .
$$

Show that the error w.r.t. $\left(w_{1}^{\prime}, \ldots, w_{N}^{\prime}\right)$ is exactly $\frac{1}{2}$. That is, show that

$$
\operatorname{err}_{t}^{\prime}=\frac{\sum_{i=1}^{N} w_{i}^{\prime} \mathbb{I}\left\{h_{t}\left(\mathbf{x}^{(i)}\right) \neq t^{(i)}\right\}}{\sum_{i=1}^{N} w_{i}^{\prime}}=\frac{1}{2}
$$

Note that here we use the weak learner of iteration $t$ and evaluate it according to the new weights, which will be used to learn the $t+1$-st weak learner. What is the interpretation of this result?

## Tips:

- Start from err ${ }_{t}^{\prime}$ and divide the summation to two sets of $E=\left\{i: h_{t}\left(\mathbf{x}^{(i)}\right) \neq t^{(i)}\right\}$ and its complement $E^{c}=\left\{i: h_{t}\left(\mathbf{x}^{(i)}\right)=t^{(i)}\right\}$.
- Note that

$$
\frac{\sum_{i \in E} w_{i}}{\sum_{i=1}^{N} w_{i}}=\operatorname{err}_{t}
$$


[^0]:    ${ }^{1}$ https://markus.teach.cs.toronto.edu/csc2515-2020-09
    2 https://www.cs.toronto.edu/~huang/courses/csc2515_2020f/index.html

[^1]:    $\sqrt[3]{\text { http://www.cs.toronto.edu/~rgrosse/courses/csc321_2018/readings/L02\%20Linear\%20Regression.pdf }}$
    ${ }^{4}$ https://docs.scipy.org/doc/scipy-0.14.0/reference/generated/scipy.misc.logsumexp.html

