Blending and Compositing



René Magritte, "The Red Model"

Many slides from Alexei Efros, Allan Jepson, Robert Collins CSC320: Introduction to Visual Computing Michael Guerzhoy

Image Compositing

1. Extract Sprites (e.g using Intelligent Scissors in Photoshop)







2. Blend them into the composite (in the right order)



Composite by David Dewey

Need Blending for Compositing

- The transition between the object and the background in real images is not sudden
- Thin features (e.g., hair) cause "mixed" pixels
- Motion while the picture is taken causes blur
- Semi-transparent objects



Combining Two Images



Alpha Blending / Feathering



The Alpha Matte

- An array the same size as the image
- α can be 1 (object 1), 0 (background/object 2), or between 0 and 1 (somewhere in between)



Effect of Window Size



"Ghosting" happens if the transition is too slow

Effect of Window Size



• "Seams" are visible if the transition is too fast

Good Window Size



"Optimal" Window: smooth but not ghosted

What is the Optimal Window?

To avoid seams

• window ≥size of largest prominent feature (and all the features)

To avoid ghosting

• window $\leq 2 \times size$ of smallest prominent feature

(explanation on the blackboard)

What is the Optimal Window?

For feathering to work:

- largest frequency <= 2*size of smallest frequency
- So image frequency content should occupy one "octave" (power of two)
 - I.e., $|F(\omega)|$ is large only for $2^k \le |\omega| \le 2^{\{k+1\}}$
- Key idea: Coarse structure should blend very slowly between images (lots of feathering), while fine details should transition more quickly

Reminder: 2D Discrete Fourier Transform

$$\hat{h}(k,l) = \sum_{n=0}^{N-1} \sum_{m=0}^{M-1} e^{-i(\omega_k n + \omega_l m)} h(n,m)$$
$$h(n,m) = \frac{1}{NM} \sum_{k=0}^{N-1} \sum_{l=0}^{M-1} e^{i(\omega_k n + \omega_l m)} \hat{h}(k,l)$$

Often it is convenient to express frequency in vector notation with $\vec{k} = (k, l)^t$, $\vec{n} = (n, m)^t$, $\vec{\omega}_{kl} = (\omega_k, \omega_l)^t$ and $\vec{\omega}^t \vec{n} = \omega_k n + \omega_l m$.

2D Fourier Basis Functions: Sinusoidal waveforms of different wavelengths (scales) and orientations. Sinusoids on $N \times M$ images with 2D frequency $\vec{\omega}_{kl} = (\omega_k, \omega_l) = 2\pi (k/N, l/M)$ are given by:

$$e^{i(\vec{\omega}^t \vec{n})} = e^{i\omega_k n} e^{i\omega_l m} = \cos(\vec{\omega}^t \vec{n}) + i\sin(\vec{\omega}^t \vec{n})$$

What if the Frequency Spread is Wide



Idea (Burt and Adelson)

- Compute $F_{left} = FFT(I_{left}), F_{right} = FFT(I_{right})$
- Decompose Fourier image into octaves (bands)
 - $F_{\text{left}} = F_{\text{left}}^{1} + F_{\text{left}}^{2} + \dots$
- Feather corresponding octaves F_{left}ⁱ with F_{right}ⁱ
 - Can compute inverse FFT and feather in spatial domain
- Sum feathered octave images in frequency domain
- (In practice, we implement this in spatial domain)

Laplacian Pyramid: Overview

Lowpass Images



Bandpass Images

Laplacian Pyramid: Overview



Reminder: Gaussian Pyramid

- Multi-level representation of an image
- The next level is smoothed and then downsampled every time



First three levels scaled to be the same size:



Laplacian Pyramid

- Each band of the Laplacian pyramid is the difference between two adjacent levels of the Gaussian pyramid, $[\vec{l}_0, \vec{l}_1, ..., \vec{l}_N]$
 - $\vec{\mathbf{b}}_k = \vec{\mathbf{l}}_k \mathbf{E} \, \vec{\mathbf{l}}_{k+1}$
 - EI_{k+1} is the up-sampled smoothed version of I_{k+1}

Laplacian Pyramid



A Laplacian pyramid with four levels:



The Laplacian Pyramid in Frequency Domain

- Reminder:
 - Each level of the Laplacian pyramid is the result of filtering an image with a band-pass filter

High-pass / band-pass:



Band-passed Hybrid Image

High frequency \rightarrow Low frequency



Construction: of $[\vec{\mathbf{b}}_0, \vec{\mathbf{b}}_1, ..., \vec{\mathbf{b}}_{L-1}, \vec{\mathbf{l}}_L]$.

$$\vec{\mathbf{l}}_0 = \vec{\mathbf{I}}$$

 $\vec{\mathbf{l}}_{k+1} = \mathbf{R} \vec{\mathbf{l}}_k$
 $\vec{\mathbf{b}}_k = \vec{\mathbf{l}}_k - \mathbf{E} \vec{\mathbf{l}}_{k+1}$

Reconstruction: of \vec{I} is exact (for any filters) and straightforward:

$$\vec{\mathbf{l}}_k = \vec{\mathbf{b}}_k + \mathbf{E} \, \vec{\mathbf{l}}_{k+1}$$

 $\vec{\mathbf{I}} = \vec{\mathbf{l}}_0$

Pyramid Blending



Left pyramid

blend

Right pyramid

Pyramid Blending









Laplacian Pyramid: Blending

General Approach:

- 1. Build Laplacian pyramids *LA* and *LB* from images *A* and *B*
- 2. Build a Gaussian pyramid *GR* from selected region *R*
- 3. Form a combined pyramid *LS* from *LA* and *LB* using nodes of *GR* as weights:
 - LS(i,j) = GR(I,j,)*LA(I,j) + (1-GR(I,j))*LB(I,j)
- 4. Collapse the *LS* pyramid to get the final blended image

Blending Regions



Horror Photo



© david dmartin (Boston College)

Stitching Photos for Panoramas



Simplification: Two-band Blending

Brown & Lowe, 2003

- Only use two bands: high freq. and low freq.
- Blends low freq. smoothly
- Blend high freq. with no smoothing: use binary alpha



2-band Blending



Low frequency ($\lambda > 2$ pixels)



High frequency (λ < 2 pixels)

Linear Blending

2-band Blending

Don't blend, CUT!



Moving objects become ghosts

So far we only tried to blend between two images. What about finding an optimal seam?

Minimal error boundary

overlapping blocks







overlap error

vertical boundary





min. error boundary