

CSC 411: Lecture 13: Mixtures of Gaussians and EM

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University of Toronto

Today

- Mixture of Gaussians
- EM algorithm
- Latent Variables

A Generative View of Clustering

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 - ▶ This makes it possible to judge different methods
 - ▶ It may help us decide on the number of clusters

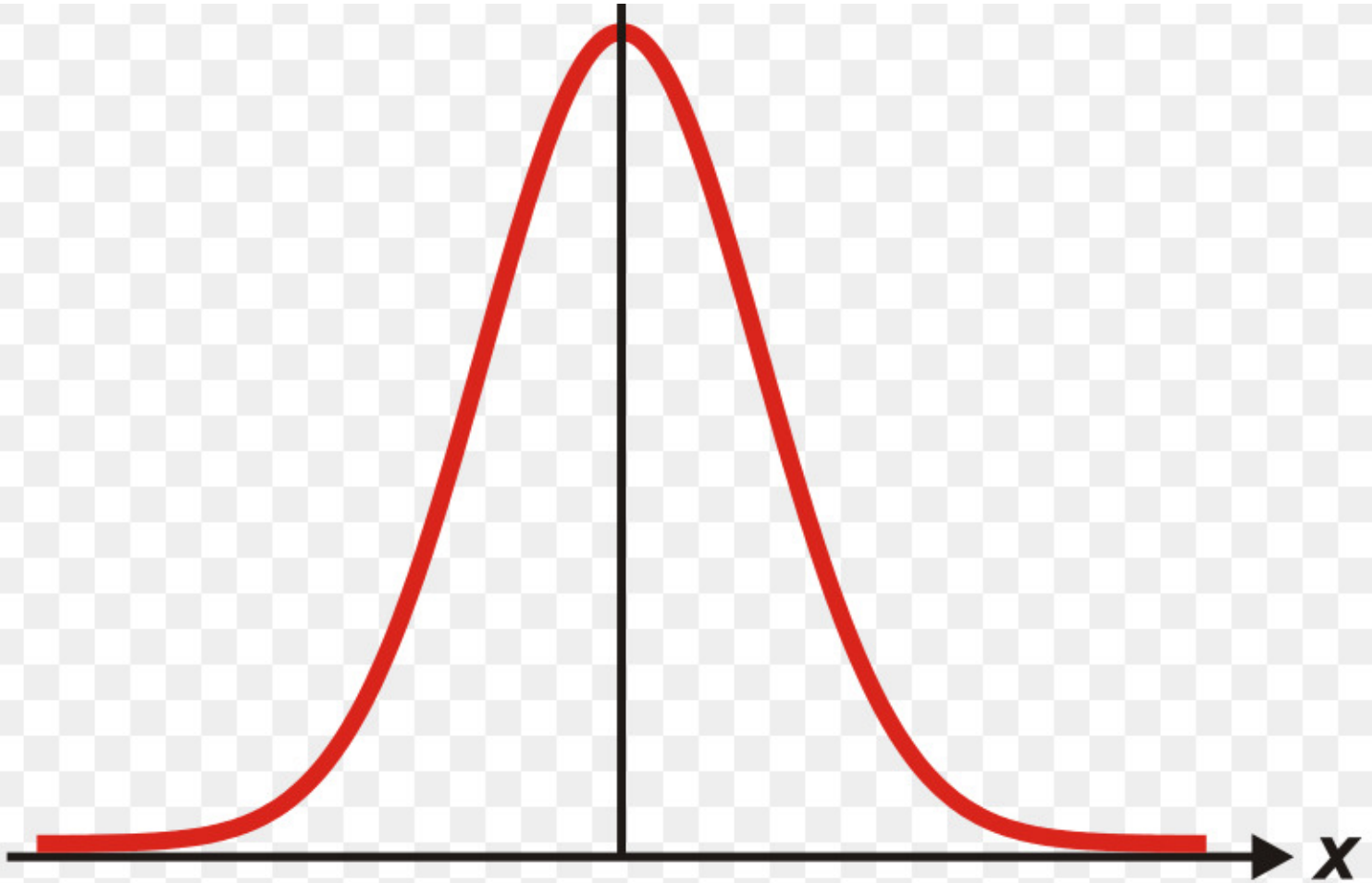
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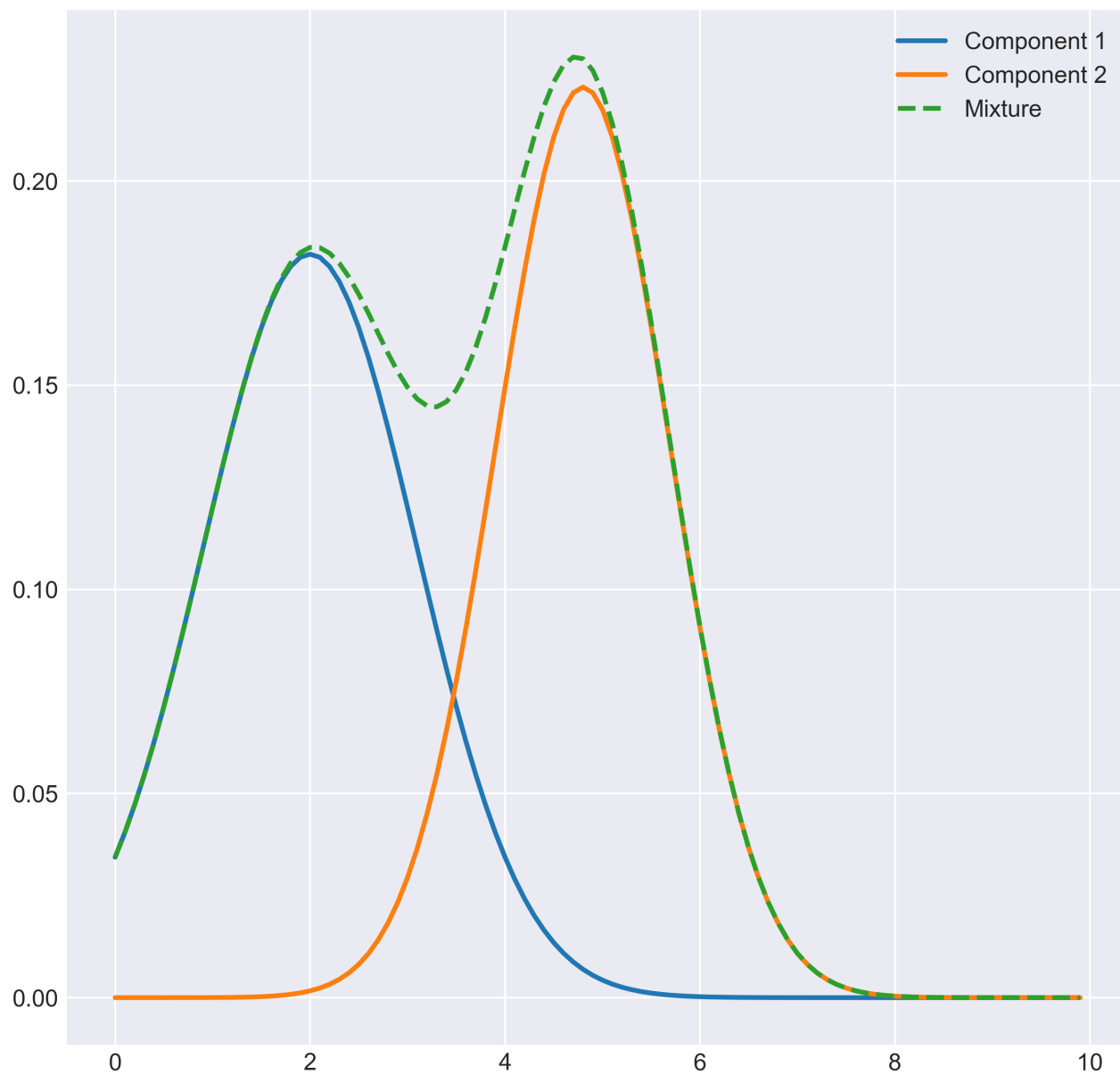
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 - ▶ Then we adjust the model parameters to maximize the probability that it would produce exactly the data we observed

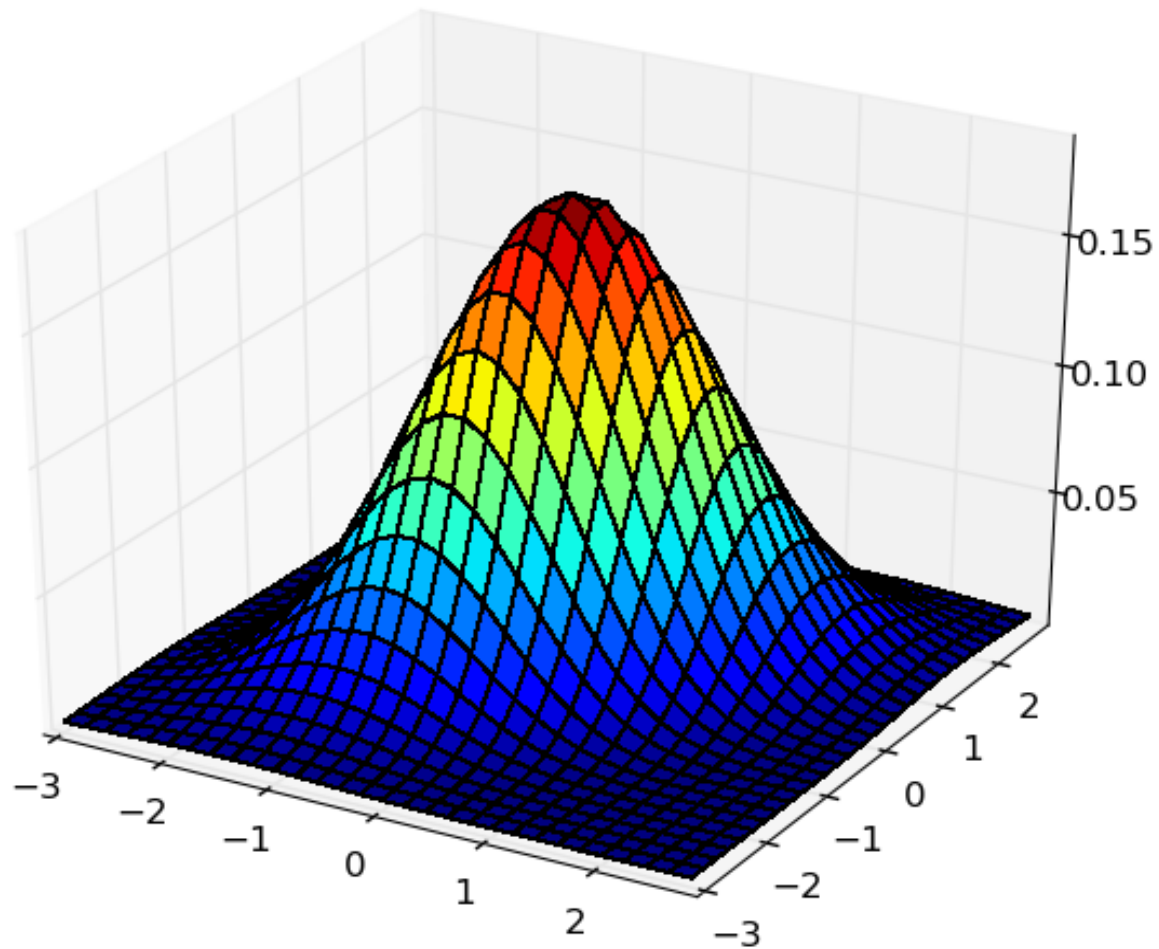
1D Gaussian



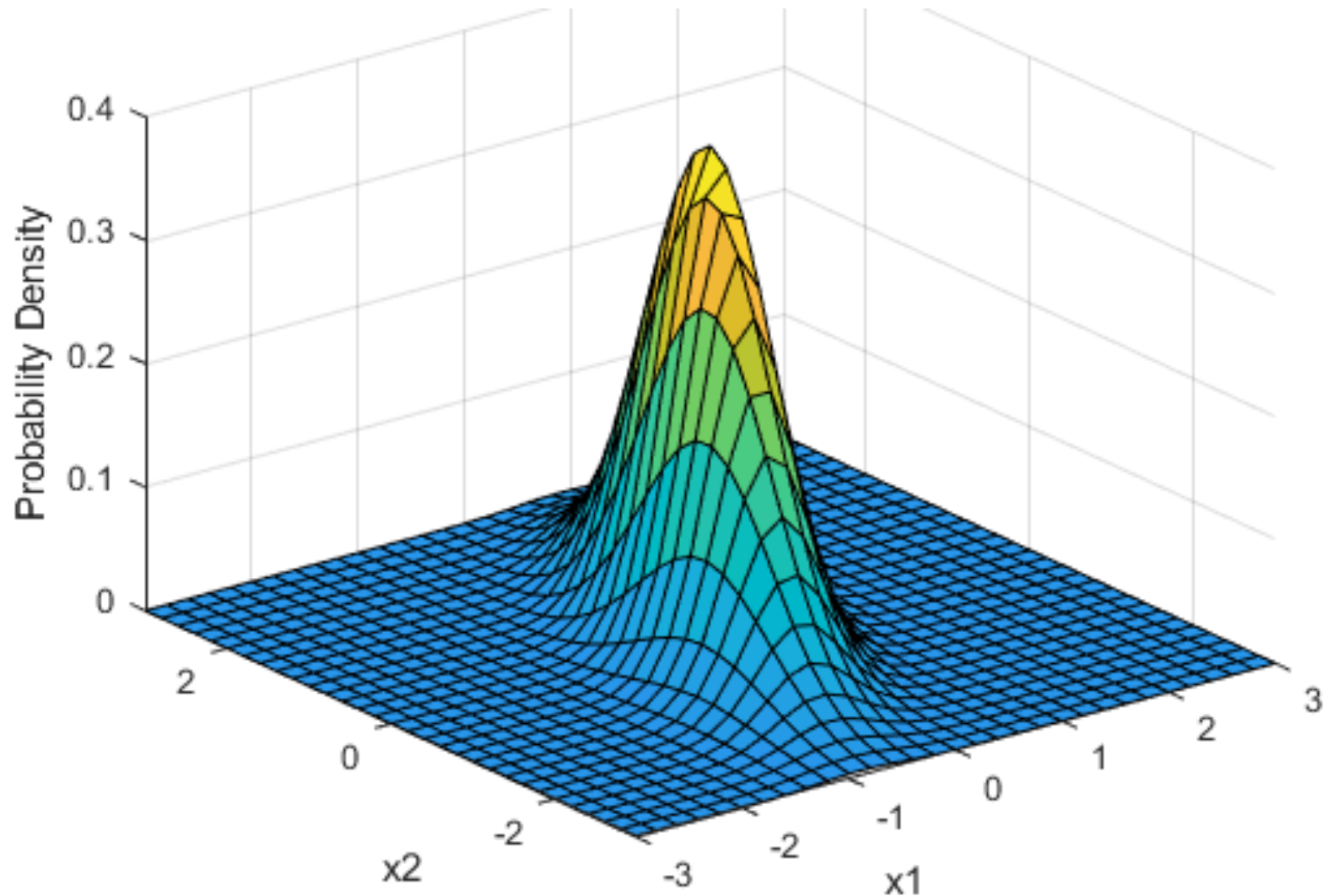
Mixture of 1D Gaussians



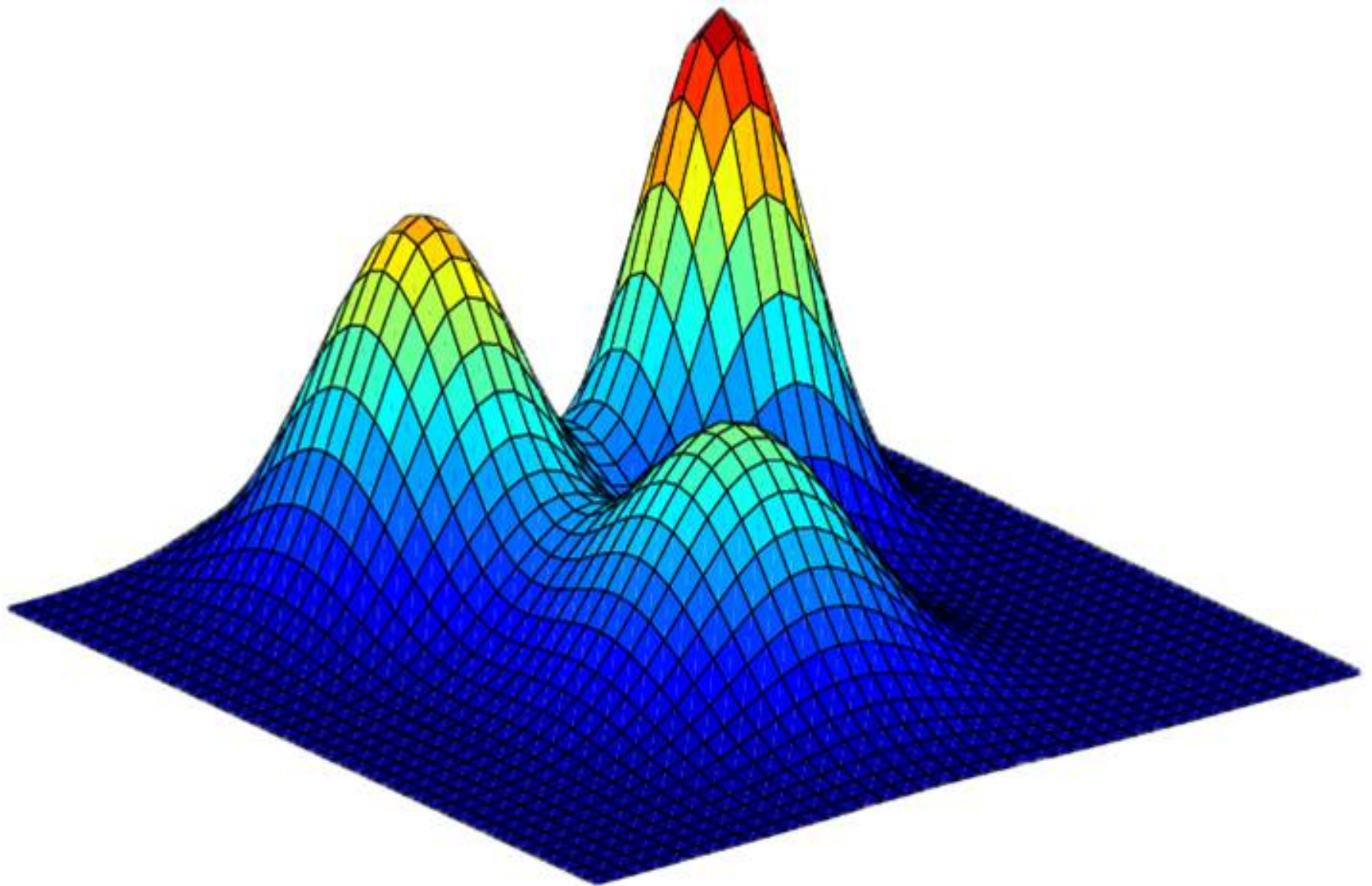
2D Gaussian



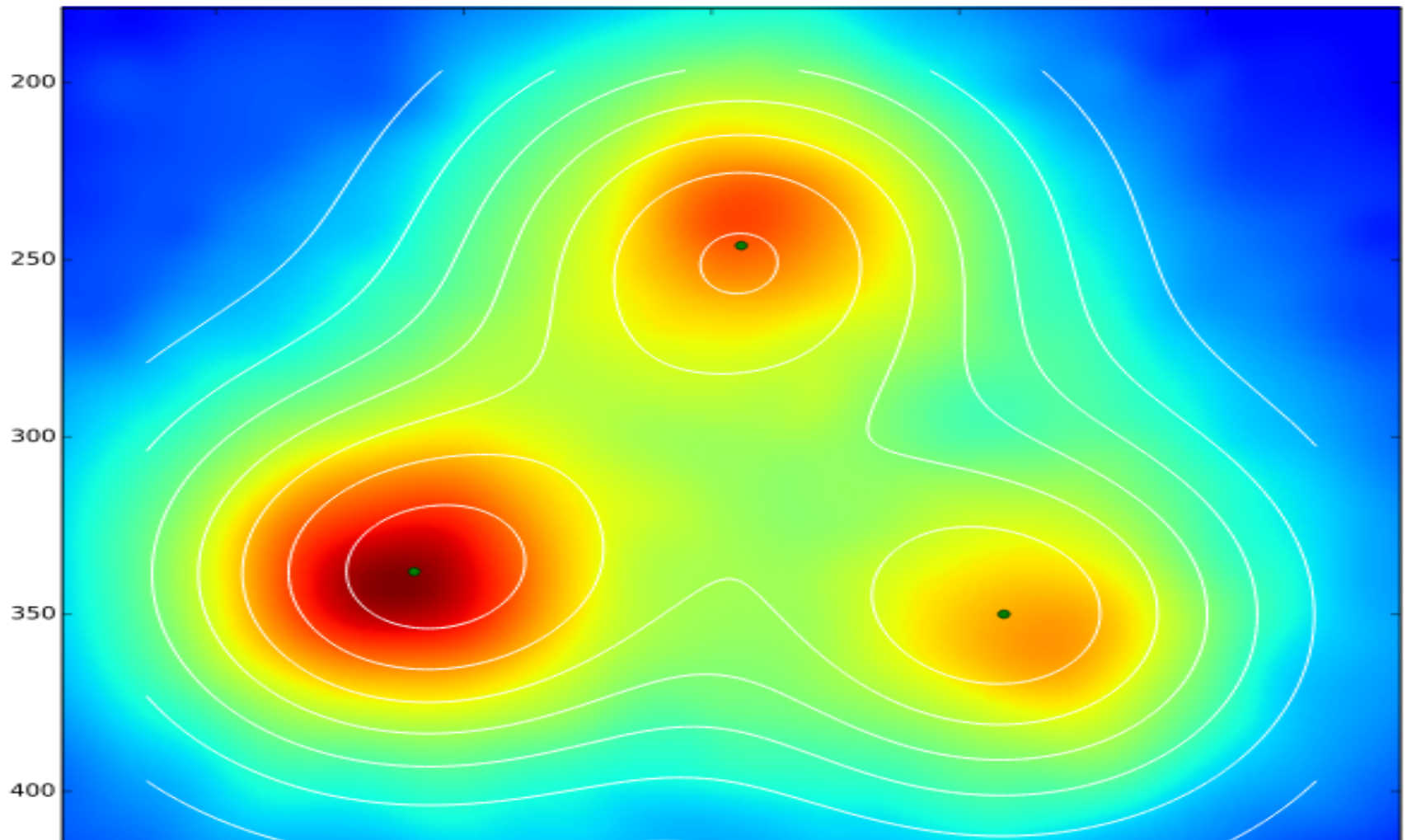
Elongated 2D Gaussian



Mixture of three Gaussians



MOG contours



Gaussian Mixture Model (GMM)

- A **Gaussian mixture model** represents a **distribution** as

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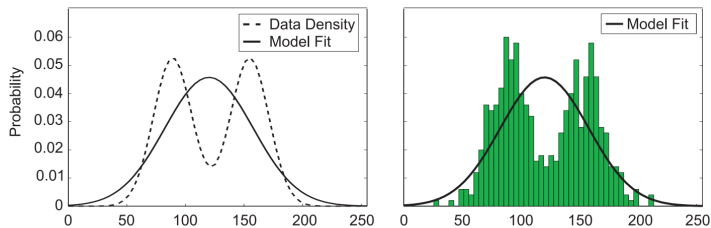
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- GMMs are **universal approximators of densities** (if you have enough Gaussians). Even diagonal GMMs are universal approximators.

Visualizing a Mixture of Gaussians – 1D Gaussians

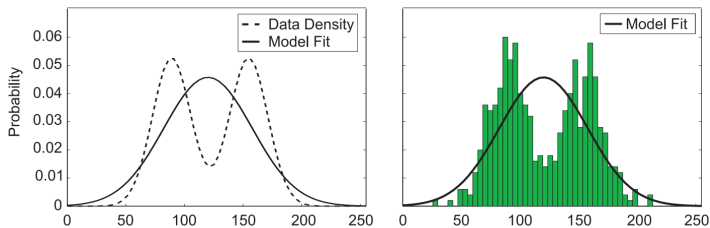
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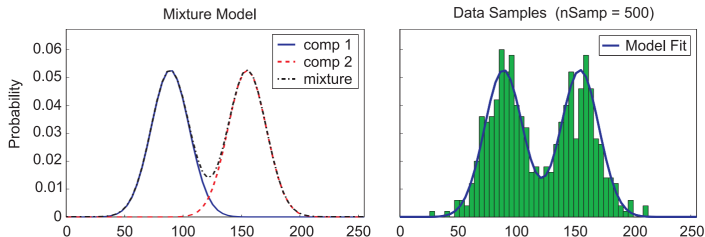
[Slide credit: K. Kutulakos]

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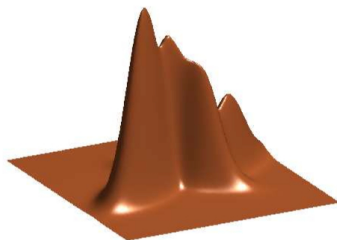
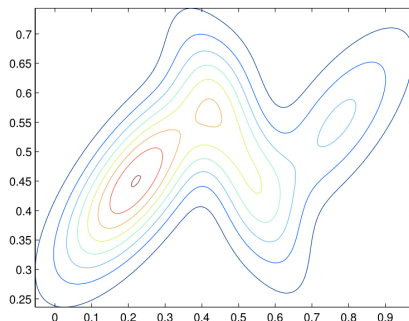
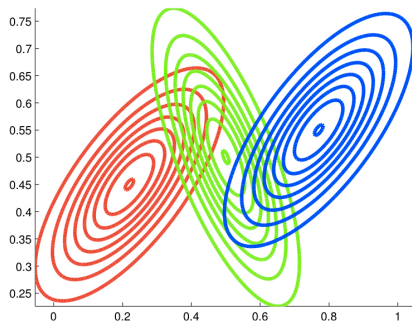


- Now, we are trying to fit a GMM (with $K = 2$ in this example):



[Slide credit: K. Kutulakos]

Visualizing a Mixture of Gaussians – 2D Gaussians



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- Don't forget to satisfy the constraints on π_k

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- Then:

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- In a **mixture model**, the identity of the component that generated a given datapoint is a latent variable

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- How can we optimize this?

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- We would get this (check old slides):

$$\begin{aligned}\mu_k &= \frac{\sum_{n=1}^N 1_{[z^{(n)}=k]} \mathbf{x}^{(n)}}{\sum_{n=1}^N 1_{[z^{(n)}=k]}} \\ \Sigma_k &= \frac{\sum_{n=1}^N 1_{[z^{(n)}=k]} (\mathbf{x}^{(n)} - \mu_k)(\mathbf{x}^{(n)} - \mu_k)^T}{\sum_{n=1}^N 1_{[z^{(n)}=k]}} \\ \pi_k &= \frac{1}{N} \sum_{n=1}^N 1_{[z^{(n)}=k]}\end{aligned}$$

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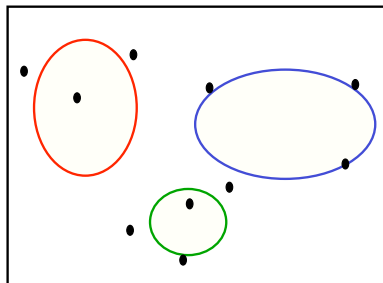
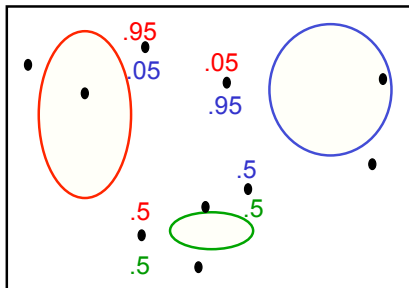
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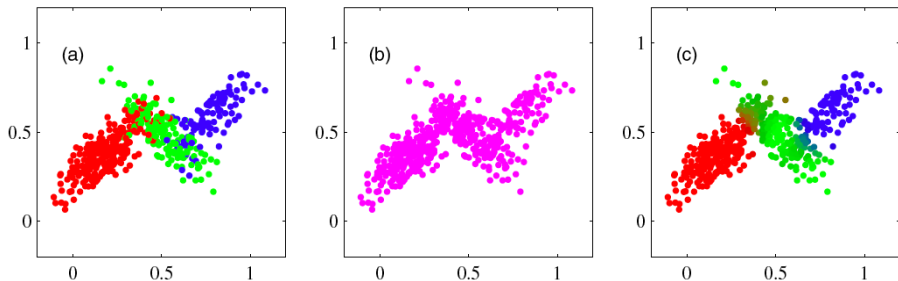
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- ▶ We can derive closed form updates for all parameters

Visualizing a Mixture of Gaussians



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E-Step: Responsibilities

- Conditional probability (using Bayes rule) of z given \mathbf{x}

$$\begin{aligned}\gamma_k = p(z = k|\mathbf{x}) &= \frac{p(z = k)p(\mathbf{x}|z = k)}{p(\mathbf{x})} \\ &= \frac{p(z = k)p(\mathbf{x}|z = k)}{\sum_{j=1}^K p(z = j)p(\mathbf{x}|z = j)} \\ &= \frac{\pi_k \mathcal{N}(\mathbf{x}|\mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}|\mu_j, \Sigma_j)}\end{aligned}$$

- γ_k can be viewed as the **responsibility**

M-Step: Estimate Parameters

- Log-likelihood:

$$\ln p(\mathbf{X}|\pi, \mu, \Sigma) = \sum_{n=1}^N \ln \left(\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}^{(n)} | \mu_k, \Sigma_k) \right)$$

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$$\frac{\partial \ln p(\mathbf{X}|\pi, \mu, \Sigma)}{\partial \mu_k} = 0 = \sum_{n=1}^N \frac{\pi_k \mathcal{N}(\mathbf{x}^{(n)}|\mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}|\mu_j, \Sigma_j)} \Sigma_k (\mathbf{x}^{(n)} - \mu_k)$$

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- We used:

$$\mathcal{N}(\mathbf{x}|\mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} \exp \left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu) \right)$$

and:

$$\frac{\partial (\mathbf{x}^T A \mathbf{x})}{\partial \mathbf{x}} = \mathbf{x}^T (A + A^T)$$

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$$\mu_k = \frac{1}{N_k} \sum_{n=1}^N \gamma_k^{(n)} \mathbf{x}^{(n)}$$

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- We just take the center-of gravity of the data that the Gaussian is responsible for
- Just like in K-means, except the data is weighted by the posterior probability of the Gaussian.
- Guaranteed to lie in the convex hull of the data (Could be big initial jump)



M-Step (variance, mixing coefficients)

- We can get similarly expression for the variance

$$\Sigma_k = \frac{1}{N_k} \sum_{n=1}^N \gamma_k^{(n)} (\mathbf{x}^{(n)} - \mu_k)(\mathbf{x}^{(n)} - \mu_k)^T$$

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- Note that this is not a closed form solution of the parameters, as they depend on the responsibilities $\gamma_k^{(n)}$, which are complex functions of the parameters
- But we have a simple iterative scheme to optimize

EM Algorithm for GMM

- **Initialize** the means μ_k , covariances Σ_k and mixing coefficients π_k
- Iterate until convergence:
 - ▶ **E-step**: Evaluate the responsibilities given current parameters

$$\gamma_k^{(n)} = p(z^{(n)}|\mathbf{x}) = \frac{\pi_k \mathcal{N}(\mathbf{x}^{(n)}|\mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}^{(n)}|\mu_j, \Sigma_j)}$$

- ▶ **M-step**: Re-estimate the parameters given current responsibilities

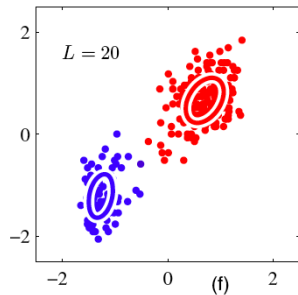
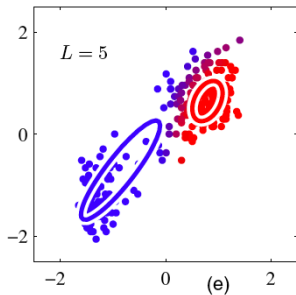
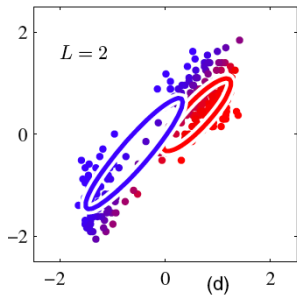
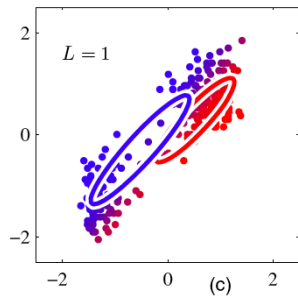
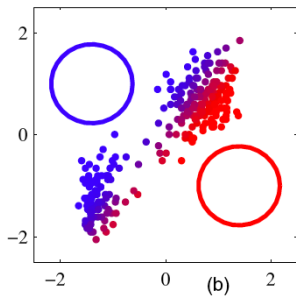
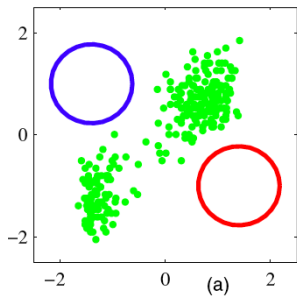
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- ▶ Evaluate log likelihood and check for convergence

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- In K-means, weights are 0 or 1

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- In the E-step we compute $p(\mathbf{Z}|\mathbf{X}, \Theta^{old})$
- In the M-step we maximize w.r.t Θ

$$Q(\Theta, \Theta^{old}) = \sum_z p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \ln p(\mathbf{X}, \mathbf{Z}|\Theta)$$

General EM Algorithm

1. Initialize Θ^{old}
2. E-step: Evaluate $p(\mathbf{Z}|\mathbf{X}, \Theta^{old})$
3. M-step:

$$\Theta^{new} = \arg \max_{\Theta} Q(\Theta, \Theta^{old})$$

where

$$Q(\Theta, \Theta^{old}) = \sum_{\mathbf{z}} p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \ln p(\mathbf{X}, \mathbf{Z}|\Theta)$$

4. Evaluate log likelihood and check for convergence (or the parameters). If not converged, $\Theta^{old} = \Theta$, Go to step 2

- Beyond this slide, read if you are interested in more details

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- A good way to show that this is OK is to show that there is a single function that is improved by both the E-step and the M-step.
 - ▶ The function we need is called **Free Energy**.

Why EM converges

- Free energy F is a cost function that is reduced by both the E-step and the M-step.

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- The **expected energy** term measures how difficult it is to generate each datapoint from the Gaussians it is assigned to. It would be happiest assigning each datapoint to the Gaussian that generates it most easily (as in K-means).
- The **entropy** term encourages "soft" assignments. It would be happiest spreading the assignment probabilities for each datapoint equally between all the Gaussians.

Free Energy

- Our goal is to maximize

$$p(\mathbf{X}|\Theta) = \sum_{\mathbf{z}} p(\mathbf{X}, \mathbf{z}|\Theta)$$

- Typically optimizing $p(\mathbf{X}|\Theta)$ is difficult, but $p(\mathbf{X}, \mathbf{Z}|\Theta)$ is easy
- Let $q(\mathbf{Z})$ be a distribution over the latent variables. For any distribution $q(\mathbf{Z})$ we have

$$\ln p(\mathbf{X}|\Theta) = \mathcal{L}(q, \Theta) + KL(q||p(\mathbf{Z}|\mathbf{X}, \Theta))$$

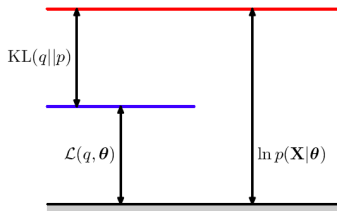
where

$$\begin{aligned}\mathcal{L}(q, \Theta) &= \sum_{\mathbf{z}} q(\mathbf{Z}) \ln \left\{ \frac{p(\mathbf{X}, \mathbf{Z}|\Theta)}{q(\mathbf{Z})} \right\} \\ KL(q||p) &= - \sum_{\mathbf{z}} q(\mathbf{Z}) \ln \left\{ \frac{p(\mathbf{Z}|\mathbf{X}, \Theta)}{q(\mathbf{Z})} \right\}\end{aligned}$$

More on Free Energy

- Since the KL-divergence is always positive and have value 0 only if $q(Z) = p(\mathbf{Z}|\mathbf{X}, \Theta)$
- Thus $\mathcal{L}(q, \Theta)$ is a lower bound on the likelihood

$$\mathcal{L}(q, \Theta) \leq \ln p(\mathbf{X}|\Theta)$$



E-step and M-step

$$\ln p(\mathbf{X}|\Theta) = \mathcal{L}(q, \Theta) + KL(q||p(\mathbf{Z}|\mathbf{X}, \Theta))$$

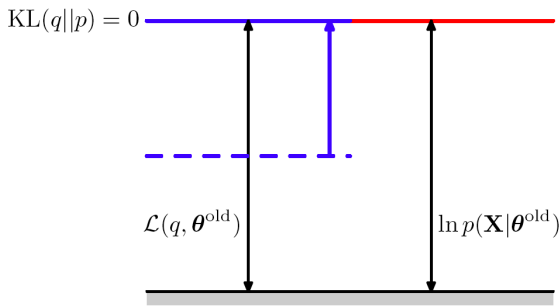
- In the E-step we maximize w.r.t $q(\mathbf{Z})$ the lower bound $\mathcal{L}(q, \Theta)$
- Since $\ln p(\mathbf{X}|\theta)$ does not depend on $q(\mathbf{Z})$, the maximum \mathcal{L} is obtained when the KL is 0
- This is achieved when $q(\mathbf{Z}) = p(\mathbf{Z}|\mathbf{X}, \Theta)$
- The lower bound \mathcal{L} is then

$$\begin{aligned}\mathcal{L}(q, \Theta) &= \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \ln p(\mathbf{X}, \mathbf{Z}|\Theta) - \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \ln p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \\ &= Q(\Theta, \Theta^{old}) + \text{const}\end{aligned}$$

with the content the entropy of the q distribution, which is independent of Θ

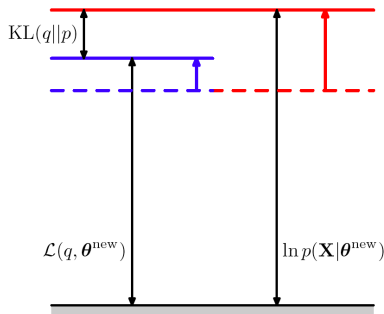
- In the M-step the quantity to be maximized is the expectation of the complete data log-likelihood
- Note that Θ is only inside the logarithm and optimizing the complete data likelihood is easier

Visualization of E-step



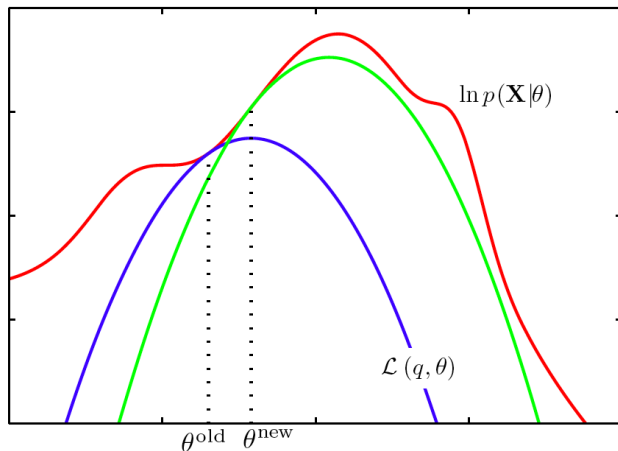
- The q distribution equal to the posterior distribution for the current parameter values Θ^{old} , causing the lower bound to move up to the same value as the log likelihood function, with the KL divergence vanishing.

Visualization of M-step



- The distribution $q(\mathbf{Z})$ is held fixed and the lower bound $\mathcal{L}(q, \Theta)$ is maximized with respect to the parameter vector Θ to give a revised value Θ^{new} . Because the KL divergence is nonnegative, this causes the log likelihood $\ln p(\mathbf{X}|\Theta)$ to increase by at least as much as the lower bound does.

Visualization of the EM Algorithm



- The EM algorithm involves alternately computing a lower bound on the log likelihood for the current parameter values and then maximizing this bound to obtain the new parameter values. See the text for a full discussion.

Summary: EM is coordinate descent in Free Energy

$$\begin{aligned}\mathcal{L}(q, \Theta) &= \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \ln p(\mathbf{X}, \mathbf{Z}|\Theta) - \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \ln p(\mathbf{Z}|\mathbf{X}, \Theta^{old}) \\ &= Q(\Theta, \Theta^{old}) + \text{const} \\ &= \text{expected energy} - \text{entropy}\end{aligned}$$

- The **E-step** minimizes F by finding the best distribution over hidden configurations for each data point.
- The **M-step** holds the distribution fixed and minimizes F by changing the parameters that determine the energy of a configuration.