

①

L18 Learning Probabilistic Models

So far, we've learned.

- what is a Bayes Net.
- the meaning of a Bayes Net.
- answer probabilistic queries.

Where does a Bayes Net come from?
(structure, parameters)

- ① ask an expert.
- ② learn it from data.

Hypotheses H : h_1, h_2, h_3, h_4, h_5

Data D :

d_1 : 1st candy is lime.

d_2 : 2nd candy is lime.

d_3 :

A prior over ^{the} hypotheses

$$P(H) = [0.1, 0.2, 0.4, 0.2, 0.1].$$

Candy Example

- a bag of candies w/ 2 flavours (cherry & lime)
- same wrapper for both flavours
- sold in bags w/ different ratios.

h_1 : 100% cherry

h_2 : 75% cherry

h_3 : 50% cherry

h_4 : 25% cherry

h_5 : 0% cherry

After eating N candies, (c cherries, l limes, $N = c + l$).

- What is the flavour ratio of the bag?
- What will be the flavour of the next candy?

(2)

① Bayesian learning

- calculates the probability of each hypothesis given the data

$$P(h_i|d) = \alpha P(d|h_i) P(h_i) \quad \begin{matrix} \rightarrow \text{normalizing constant} = \frac{1}{P(d)} \\ \downarrow \end{matrix}$$

α \downarrow \hookrightarrow hypothesis prior
 prob prior of hypothesis
 given data \hookrightarrow likelihood of data given hypothesis

$$P(h_1|d) = \alpha P(d|h_1) P(h_1)$$

$$= \alpha * 0^2 * 0.1 = \alpha * 0 = 0\%$$

$$P(h_2|d) = \alpha * 0.25^2 * 0.2 = \alpha * 0.0125 \cong 3.8\%$$

$$P(h_3|d) = \alpha * 0.5^2 * 0.4 = \alpha * 0.1 \cong 30.8\%$$

$$P(h_4|d) = \alpha * 0.75^2 * 0.2 = \alpha * 0.1125 \cong 34.6\%$$

$$P(h_5|d) = \alpha * 1^2 * 0.1 = \alpha * 0.1 \approx 30.8\%$$

$$\alpha = 1 / (0 + 0.0125 + 0.1 + 0.1125 + 0.1) = \frac{1}{0.325}$$

(3)

② Bayesian prediction. x : next candy is lime.

$$\begin{aligned} P(x|d) &= \sum_i P(x|d \wedge h_i) P(h_i|d) \\ &= \sum_i P(x|h_i) P(h_i|d) \end{aligned}$$

The weighted average of the predictions of the individual hypotheses

$$\begin{aligned} P(x|d) &= 0*0 + 0.25*0.038 + 0.5*0.308 + 0.75*0.346 \\ &\quad + 1*0.308 = 73.1\% \end{aligned}$$

Properties:

- The Bayesian prediction eventually agrees w/
the true hypothesis.
 - optimal: Given the prior, the Bayesian prediction
is correct more often than any other prediction.
 - no overfitting: prior penalizes complex hypotheses.
- Good*

Price to pay:

- large or infinite hypothesis space.
- the summation/integration may ~~not~~ be tractable
to calculate.

(4)

Maximum a posteriori (MAP).

- make a prediction based on the most probable hypothesis

$$h_{\text{MAP}} = \underset{h_i}{\operatorname{argmax}} P(h_i | d), \quad P(x | d) \cong P(x | h_{\text{MAP}})$$

$$P(x | d) = P(x | h_4) = 75\% \quad h_{\text{MAP}} = h_4.$$

Properties:

- GOOD**
- Finding h_{MAP} is often much easier than Bayesian prediction.
(opt prob) (summation/integral).
 - No overfitting.

- MAP prediction is less accurate than Bayes prediction.
but they converge as data increases.
- Finding h_{MAP} may still be Intractable.

$$h_{\text{MAP}} = \underset{h}{\operatorname{argmax}} P(h | d)$$

$$= \underset{h}{\operatorname{argmax}} P(h) P(d | h)$$

$$= \underset{h}{\operatorname{argmax}} P(h) \prod_i P(d_i | h) \leftarrow \text{non-linear opt.}$$

can take log to linearize.

$$h_{\text{MAP}} = \underset{h}{\operatorname{argmax}} \left[\log P(h) + \log \sum_i \log P(d_i | h) \right]$$

(5)

Maximum Likelihood.

simplify MAP by assuming uniform prior

$$P(h_i) = P(h_j) \quad \forall i, j.$$

$$h_{MAP} = \arg \max_h \underbrace{P(h)}_{\text{constant}} P(d|h)$$

$$h_{ML} = \arg \max_h P(d|h) \quad / \quad h_{MAP} = \arg \max_h P(h|d).$$

make prediction based on h_{ML} only

$$P(d|h_1) = 0^2 = 0.$$

$$P(d|h_2) = 0.25^2 = 0.0625.$$

$\vdots \quad \vdots$

$$P(d|h_5) = 1^2 = 1$$

$$h_{ML} = h_5 \quad P(x|h_5) = 1$$

Properties:

- h_{ML} is often easier to find than h_{MAP} .

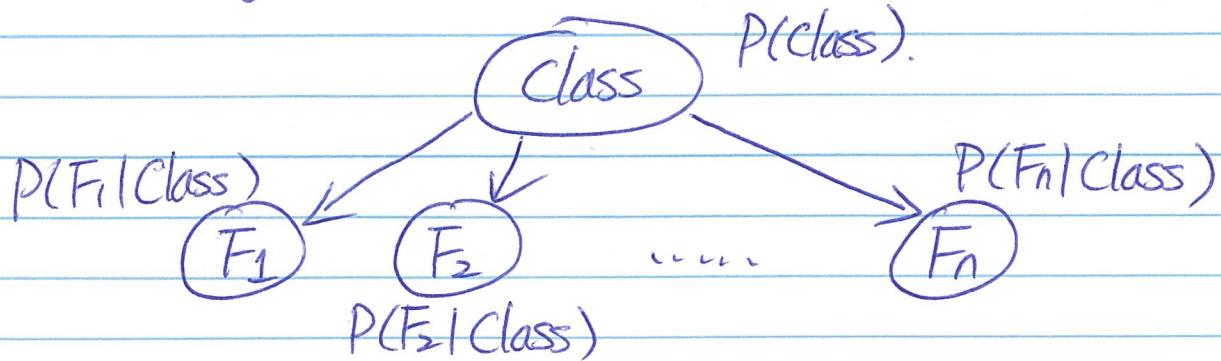
GOOD

$$h_{ML} = \arg \max_h \sum_i \log P(d_i|h).$$

- ML prediction is less accurate than Bayesian or MAP.
but all converge as data increases.
- susceptible to overfitting.

(6)

Naive Bayes model - ML Parameter Learning.

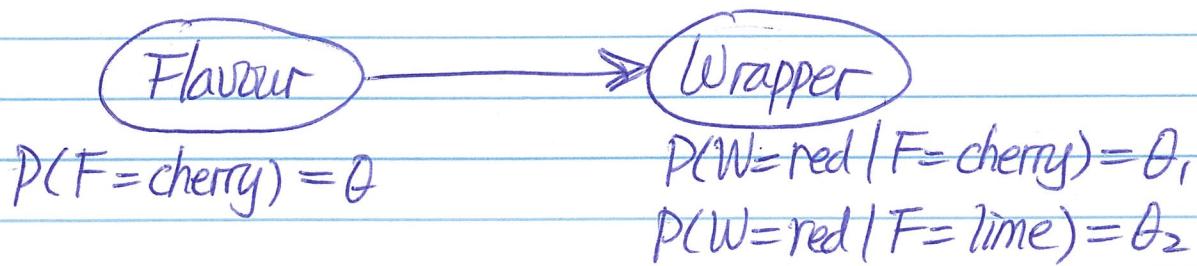


"naive": the "feature" variables are not actually conditionally independent given the "class" variables.

- works surprisingly well even when the conditional independence assumption is not true.

Example: red/green wrappers

- wrapper for each candy is selected probabilistically depending on the flavour.



Unwrap N candies, c cherries, l limes $N=c+l$.

cherries: r_c red, g_c green.

lime: r_l red, g_l green.