Learning Neural Networks - Part 2

Alice Gao Lecture 9 Readings: RN 18.7, PM 7.5.

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Gradient Descent

The Backpropagation Algorithm

When to use Decision Trees and Neural Networks

Revisiting the Learning goals

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By the end of the lecture, you should be able to

- Explain the steps of the gradient descent algorithm.
- Explain how we can modify gradient descent to speed up learning and ensure convergence.
- Describe the back-propagation algorithm including the forward and backward passes.
- Compute the gradient for a weight in a multi-layer feed-forward neural network.
- Describe situations in which it is appropriate to use a neural network or a decision tree.

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A 2-Layer Neural Network



Input layer

Hidden Layer

Output layer

Gradient Descent

"Walking downhill and always taking a step in the direction that goes down the most."

- A local search algorithm to find the minimum of a function.
- Steps of the algorithm:
 - Initialize weights randomly.
 - Change each weight in proportion to the negative of the partial derivative of the error with respect to the weight.

$$W:=W-\eta\frac{\partial E}{\partial W}$$

- η is the learning rate.
- Terminate after some number of steps when the error is small or when the changes get small.

Why update the weight proportional to the negative of the partial derivative?

- Suppose that we want to find the minimum of $y = x^2$.
- Start with $x = x_0$.
- In what direction should we change the value of x?

By what amount should we change the value of x? What is the step size? How do we update the weights based on the data points?

- Gradient descent updates the weights after sweeping through all the examples.
- ► To speed up learning, update weights after each example.
 - Incremental gradient descent
 - Stochastic gradient descent
- Trade off learning speed and convergence.
 - Batched gradient descent

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A 2-Layer Neural Network



Input layer

Hidden Layer

Output layer

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The Back-propagation Algorithm

- An efficient method of calculating the gradients in a multi-layer neural network.
- ► There are some training examples (x
 _n, y
 _n) and an error/loss function E(z2, y). Perform 2 passes.
 - ► Forward pass: compute the error *E* given the inputs and the weights.
 - Backward pass: compute the gradients $\frac{\partial E}{\partial W 2_{jk}}$ and $\frac{\partial E}{\partial W 1_{ij}}$.
- Update each weight by the sum of the partial derivatives for all the training examples.

Forward Pass for a 2-layer Network

Calculate the values of $z1_j$ and $z2_k$ and E.

$$a1_{j} = \sum_{i} x_{i}W1_{ij} \qquad z1_{j} = g(a1_{j}) \qquad (1)$$
$$a2_{k} = \sum_{j} z1_{j}W2_{jk} \qquad z2_{k} = g(a2_{k}) \qquad (2)$$

$$E(z2,y) \tag{3}$$



Input layer

Hidden Layer

Output layer

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Backward Pass for a 2-layer Network

Calculate the gradients for $W1_{ij}$ and $W2_{jk}$.

$$\frac{\partial E}{\partial W 2_{jk}} = \frac{\partial E}{\partial a 2_k} z 1_j = \delta 2_k z 1_j, \quad \delta 2_k = \frac{\partial E}{\partial z 2_k} g'(a 2_k)$$
(4)
$$\frac{\partial E}{\partial W 1_{ij}} = \frac{\partial E}{\partial a 1_j} x_i = \delta 1_j x_i, \qquad \delta 1_j = \left(\sum_k \delta 2_k W 2_{jk}\right) g'(a 1_j)$$
(5)



Input layer

Hidden Layer

Output layer

The recursive relationship

For unit
$$j$$
, $\delta_j = \frac{\partial E}{\partial a_j}$.

$$\delta_j = \begin{cases} \frac{\partial E}{\partial z_j} \times g'(a_j), & \text{base case, } j \text{ is an output unit} \\ \left(\sum_k \delta_k W_{jk}\right) \times g'(a_j), & \text{recursive case, } j \text{ is a hidden unit} \end{cases}$$
(6)

Base case:

Recursive case:



Output layer



Hidden Layer

Next layer

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When should we use Neural Network?

- ▶ High dimensional or real-valued inputs, noisy (sensor) data.
- Form of target function is unknown (no model).
- ▶ Not important for humans to explain the learned function.

When should we NOT use Neural Network?

- Difficult to determine the network structure (number of layers, number of neurons).
- Difficult to interpret weights, especially in multi-layered networks.
- Tendency to over-fit in practice (poor predictions outside of the range of values it was trained on).

Decision Tree v.s. Neural Network

- Data types.
- Size of data set.
- Form of target function.
- The architecture.
- Interpret the learned function.
- Time available for training and classification.

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