

## Lecture 7 — November 2, 2015

Aleksandar Nikolov

Scribe: Assimakis Kattis

## 1 Computing Discrepancy

*Last lecture:* We showed that given  $A \in [-1, 1]^{m \times n}$ , we can compute  $x \in \{\pm 1\}^m$  such that  $\|Ax\|_\infty = O(\sqrt{n \log(2m/n)})$ . This leads to further questions:

- Assume  $\text{disc}(A)$  is small (e.g.  $\text{disc}(A) = 0$ ), can we compute  $x$  that does better than Spencer's bound (that is,  $o(\sqrt{n \log(2m/n)})$  in *polylog*( $m, n$ ) time?
- More generally, can we efficiently approximate combinatorial discrepancy?

Unfortunately, the answer to both these questions is that we cannot (unless  $P = NP$ ).

**Theorem** ([CNN11]). *For  $A \in \{0, 1\}^{O(n) \times n}$ , it is NP-hard to distinguish between the cases:*

1.  $\text{disc}(A) = 0$
2.  $\text{disc}(A) = \Omega(\sqrt{n})$  (Spencer's bound)

*Note: The same holds for set systems, where  $A$  is the incidence matrix.*

Here we prove the above for  $A \in \{-4, -3, \dots, 4\}^{O(n) \times n}$ .

**Theorem** ([Gur03]). *[2-2 Set Splitting]*

*For  $S = \{S_1, \dots, S_m\}$  with  $m = O(n)$ , if  $\forall i |S_i| = 4$  and  $S_i \subseteq [n]$ , where each  $j \subseteq [n]$  appears in at most 4 sets, it is NP-hard to distinguish between the cases:*

1.  $\text{disc}(S) = 0$
2.  $\forall x \in \{\pm 1\}^n, |\{i : |\sum_{j \in S_i} x_j| \neq 0\}| \geq \alpha m$ , where  $\alpha \approx 1/22$  a small constant

Suffices to reduce from this to our problem.

*Reduction:* Set  $B \in \{0, 1\}^{m \times n}$  the incidence matrix of  $S$ . This has dimension  $m \times n$ , with 4 1s in each row/column, by construction of  $S$ . Set  $H \in \{\pm 1\}^{m \times m}$ , the Hadamard matrix, which has the property that  $H^T H = mI$ . We denote the  $i$ th row of  $H$  as  $h_i$  and the  $j$ th column of  $B$  as  $b_j$ .

Define  $A = HB$ , where  $A_{ij} = h_i \cdot b_j$ . Note that since there are at most 4 non-zero entries in  $b_j$  and  $h_i \in \{\pm 1\}^m$ , we have that  $A_{ij} \in \{-4, \dots, 4\}$ .

We now prove that this reduction is sufficient for our purposes.

**Claim.**  $\text{disc}(S) = 0 \Rightarrow \text{disc}(A) = 0$ .

*Proof.* For  $\text{disc}(S) = 0$ , by definition  $\exists x \in \{\pm 1\}^n$  s.t.  $Bx = 0$ . This implies that  $Ax = HBx = H0 = 0$  and so  $\text{disc}(A) = 0$ .  $\square$

**Claim.**  $\forall x \in \{\pm 1\}^n, |\{i : |\sum_{j \in S_i} x_j| \neq 0\}| \geq \alpha m \Rightarrow \text{disc}(A) = \Omega(\sqrt{n})$

*Proof.* By assumption we know that the number of sets  $S_i$  for which  $|\sum_{j \in S_i} x_j| \neq 0$  is bounded below by  $\alpha m$ . Since the total number of such sets is an integer and thus at least 1, we have that:

$$\|Bx\|_2^2 = \sum_{i=1}^m \left( \sum_{j \in S_i} x_j \right)^2 \geq \alpha m$$

By comparing maximum to average discrepancy, we get that:

$$\begin{aligned} \|HBx\|_\infty^2 &\geq \frac{1}{m} \|HBx\|_2^2 = \frac{1}{m} x^T B^T H^T HBx = x^T B^T Bx = \|Bx\|_2^2 \geq \alpha m \\ \therefore \text{disc}(A) = \text{disc}(HB) &\geq \sqrt{\alpha m} = \Omega(\sqrt{n}) \end{aligned}$$

$\square$

## 2 Hereditary Discrepancy

We can define the (stronger) notion of hereditary discrepancy as follows:

$$\text{herdisc}(A) = \max_{S \subseteq [n]} \text{disc}(A_S)$$

where  $A \in \mathbb{R}^{m \times n}$  and  $A_S$  the matrix which consists of the columns of  $A$  which are indexed by  $S$ .

For hereditary discrepancy, there are a number of things that we can say about its approximations.

**Theorem** ([AGH13]).  $\forall \epsilon > 0$ , it is NP-hard to obtain a  $(2 - \epsilon)$  approximation to  $\text{herdisc}(A)$  better than a factor of 2.

**Theorem** ([NT15]). There exists a polytime computable function  $f$  such that  $\forall A \in \mathbb{R}^{m \times n}$ :

$$\frac{f(A)}{C \log(m)^{3/2}} \leq \text{herdisc}(A) \leq f(A)$$

We begin by looking at upper bounds for hereditary discrepancy:

Norms of Rows: For  $a_{i*}$  the  $i$ -th row of  $A$ , we can define:

$$r(A) = \max_{i=1}^m \|a_{i*}\|_2$$

For  $x \in \{\pm 1\}^n$  chosen uniformly at random  $\Rightarrow_{w.h.p} \|Ax\|_\infty = O(\sqrt{\log 2m}) \cdot r(A)$

$$\therefore \text{disc}(A) = r(A) \cdot O(\sqrt{\log 2m}) \quad (1)$$

We notice that  $(Ax)_i = \langle a_{i*}, x \rangle$  and since the projection of Euclidian distance never increases, this implies that  $r(A_S) \leq r(A)$ . Thus:

$$\text{herdisc}(A) = \max_S \text{disc}(A_S) = \max_S r(A_S) \cdot O(\sqrt{\log 2m}) = r(A) \cdot O(\sqrt{\log 2m})$$

Norms of Columns: For  $a_{*i}$  the  $i$ -th column of  $A$ , we can similarly define:

$$c(A) = \max_{i=1}^n \|a_{*i}\|_2$$

Some relevant results and conjectures pertaining to this definition are shown below.

**Beck-Fiala Theorem:** For  $A \in \{0, 1\}^{m \times n}$ , we have  $\text{disc}(A) \leq 2 \max_j \#\{1\text{'s in } a_{*j}\} = 2 \cdot c(A)^2$

**Beck-Fiala Conjecture:** For  $A \in \{0, 1\}^{m \times n}$ ,  $\text{disc}(A) = O(1) \cdot c(A)$

**Komlós Conjecture:**  $\forall A \in \mathbb{R}^{m \times n}$ ,  $\text{disc}(A) = O(1) \cdot c(A)$

**Banaszczyk:**  $\forall A \in \mathbb{R}^{m \times n}$ ,  $\text{disc}(A) = O(\sqrt{\log 2m}) \cdot c(A)$

Finally, since  $c(A_S) \leq c(A)$ , the above result implies:

$$\text{herdisc}(A) \leq c(A) \cdot O(\sqrt{\log 2m})$$

Combining with (1), the above also yields:

$$\text{disc}(A) \leq \min\{c(A), r(A)\} \cdot \text{polylog}(m)$$

### 3 Factorization

**Theorem** ([Ban98]). *Let  $K \subseteq \mathbb{R}^m$  be convex and closed, with:*

$$\mathbb{P}(g \in K) \geq 1/2 \text{ where } g \sim N(0, I)$$

*Then for  $A \in \mathbb{R}^{m \times n}$ ,  $\exists x \in \{\pm 1\}^n$  s.t.  $Ax \in 5 \cdot c(A) \cdot K$*

**Theorem** ([Lar14]). *For  $A \in \mathbb{R}^{m \times n}$  with  $A = UV$ , where  $U, V$  arbitrary, we have that:*

$$\text{disc}(A) \leq r(U) \cdot c(V) \cdot O(\sqrt{\log 2m})$$

*Proof.* Define  $K$  as follows:

$$K = \{y : \|Uy\|_\infty \leq 2 \cdot r(U) \cdot \sqrt{\log(2m)}\}$$

We will denote  $u_i$  as the  $i$ th row of  $U$ .

**Theorem** (Gaussian Concentration Inequality).  $h \sim N(0, \sigma^2) \Rightarrow \mathbb{P}(|h| > t\sigma) \leq e^{-t^2/2}$

For  $g \sim N(0, I)$ , we can bound  $\mathbb{P}(g \in K)$  as follows:

$$\begin{aligned} \mathbb{P}(g \in K) &= \mathbb{P}\left(|\langle u_i, g \rangle| \leq 2 \cdot r(U) \cdot \sqrt{\log(2m)}, \forall i \in [m]\right) \\ &\geq 1 - \sum_{i=1}^m \mathbb{P}\left(|\langle u_i, g \rangle| \geq 2 \cdot r(U) \cdot \sqrt{\log(2m)}\right) \\ &\geq 1 - \sum_{i=1}^m \frac{1}{2m} \geq 1/2 \end{aligned}$$

The last inequality follows by the property that for  $g \sim N(0, I)$ , we have  $\langle u_i, g \rangle \sim N(0, \|u_i\|_2^2)$ . By setting  $t = 2\sqrt{\log(2m)}$  and noticing that by definition  $\forall i, \|u_i\|_2^2 \leq r(U)^2$ , applying the Gaussian concentration inequality above yields the lower bound.

Now, the above result means we can apply the result of [Ban98] to  $K$  with matrix  $V$ :

$$\begin{aligned} \exists x \in \{\pm 1\}^n \text{ s.t. } Vx \in 5 \cdot c(V) \cdot K \\ \Leftrightarrow \|UVx\|_\infty = \text{disc}(A) \leq 10 \cdot c(V) \cdot r(U) \cdot \sqrt{\log 2m} \end{aligned}$$

□

**Definition** ( $\gamma_2$  norm). We can define the  $\gamma_2$  norm of a matrix  $A \in \mathbb{R}^{n \times m}$  as:

$$\gamma_2(A) = \min \{r(U) \cdot c(V) : UV = A\}$$

The above result then becomes:

$$\text{disc}(A) = \gamma_2(A) \cdot O\left(\sqrt{\log(2m)}\right)$$

We additionally note that since  $A_S = UV_S$ , then  $c(V_S) \leq c(V) \Rightarrow \gamma_2(A_S) \leq \gamma_2(A)$ .

Efficient computation of  $\gamma_2$

**Definition.** A vector program is an optimization problem with vector variables  $\{v_i\}_{i=1}^n \in \mathbb{R}^n$ , whose objective function and constraints are linear in  $\langle v_i, v_j \rangle$  where  $i, j \in [n]$ .

It is known that every vector program can be approximated efficiently by a semidefinite program (SDP). Thus, if we can show that  $\gamma_2(A)$  can be written as a vector program, this suffices in showing that it is efficiently computable.

**Claim.** For  $A \in \mathbb{R}^{m \times n}$ ,  $\gamma_2(A)$  can be written as the following vector program:

$$\begin{aligned}
& \text{minimize} && t \\
& \text{subject to} && \langle u_i, v_j \rangle = A_{ij} \\
& && \langle u_i, u_i \rangle \leq t \\
& && \langle v_j, v_j \rangle \leq t \\
& && u_i, v_j \in \mathbb{R}^{m+n} \\
& \text{where} && (i, j) \in [m] \times [n],
\end{aligned}$$

*Proof.* Denote  $t^*$  the optimal solution, with  $u_i^*, v_j^*$  corresponding vectors.

We first show  $\gamma_2(A) \leq t^*$ .

If we define  $U$  as having  $u_i^*$  as its  $i$ th row and  $V$  as having  $v_j^*$  as its  $j$ th column, then  $(UV)_{ij} = \langle u_i^*, v_j^* \rangle = A_{ij}$ . Thus, we get that  $UV = A$ .

Since  $\forall i, \langle u_i^*, u_i^* \rangle \leq t^*$ , this implies that  $\forall i, \|u_i^*\|_2^2 \leq t^*$ , or that  $r(U)^2 \leq t^*$ . Similarly,  $c(V)^2 \leq t^*$ .

As  $U$  and  $V$  satisfy  $A = UV$ , we have that:

$$\therefore \gamma_2(A) \leq r(U) \cdot c(V) \leq t^*$$

We now show that  $t^* \leq \gamma_2(A)$ .

Pick  $U, V$ , the optimal matrices for which  $r(U) \cdot c(V) = \gamma_2(A)$ .

Setting  $\alpha = \sqrt{\frac{c(V)}{r(U)}}$ , we have that  $A = (\alpha U)(\frac{1}{\alpha} V)$ .

Now define  $u_i$  the  $i$ th row of  $\alpha U$  and  $v_j$  the  $j$ th row of  $(1/\alpha)V$ .

$$r(\alpha U) = \sqrt{\frac{c(V)}{r(U)}} r(U) = \sqrt{c(V) \cdot r(U)}$$

$$c((1/\alpha)V) = \sqrt{\frac{r(U)}{c(V)}} c(V) = \sqrt{c(V) \cdot r(U)}$$

The two equalities above imply that:

$$\langle u_i, u_i \rangle = \|u_i\|_2^2 \leq r(\alpha U)^2 = \frac{c(V)}{r(U)} r(U)^2 = c(V) \cdot r(U) = \gamma_2(A)$$

A similar argument shows this for  $\langle v_j, v_j \rangle$ . However, since  $t^*$  is the minimum  $t$  for which  $\langle u_i, u_i \rangle \leq t$ , this implies that  $t^* \leq \gamma_2(A)$ . Thus,  $t^* = \gamma_2(A)$ .  $\square$

## References

- [AGH13] Per Austrin, Venkatesan Guruswami, and Johan Håstad. Sat is np-hard. In *Electronic Colloquium on Computational Complexity, TR13-159*, 2013.
- [Ban98] Wojciech Banaszczyk. Balancing vectors and gaussian measures of n-dimensional convex bodies. *Random Structures & Algorithms*, 12(4):351–360, 1998.
- [CNN11] Moses Charikar, Alantha Newman, and Aleksandar Nikolov. Tight hardness results for minimizing discrepancy. In *Proceedings of the twenty-second annual ACM-SIAM symposium on Discrete Algorithms*, pages 1607–1614. SIAM, 2011.
- [Gur03] Venkatesan Guruswami. Inapproximability results for set splitting and satisfiability problems with no mixed clauses. *Algorithmica*, 38(3):451–469, 2003.
- [Lar14] Kasper Green Larsen. On range searching in the group model and combinatorial discrepancy. *SIAM Journal on Computing*, 43(2):673–686, 2014.
- [NT15] Aleksandar Nikolov and Kunal Talwar. Approximating hereditary discrepancy via small width ellipsoids. In *Proceedings of the Twenty-Sixth Annual ACM-SIAM Symposium on Discrete Algorithms*, pages 324–336. SIAM, 2015.