Choosing augmenting paths in the Ford-Fulkerson algorithm

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In what follows we assume that all edge capacities are non-negative integers. Let $n$ be the number of nodes and $m$ be the number of edges in the flow network. It is reasonable to assume that every node is reachable from $s$ (unreachable nodes are not used in any $s \rightarrow t$ flow and can be deleted from the graph, along with their incoming and outgoing edges). Note that under this assumption $m \geq n - 1$ and so $n = O(m)$. Let $C$ be the sum of the capacities of the edges out of the source $s$.

We have seen that in the Ford-Fulkerson algorithm it is possible to choose augmenting paths so that $C$ augmenting steps are performed before the algorithm terminates. Since each iteration takes $O(m)$ time, the overall running time of this basic version of the Ford-Fulkerson algorithm (where augmenting paths are chosen arbitrarily) is $O(mC)$. This is a so-called pseudopolynomial algorithm: its running time is polynomial in the numeric value of the input, rather than the size of the input’s binary representation.

We will now see that by choosing augmenting paths more wisely, we can improve the performance of the algorithm dramatically.

Choosing a “widest” path

Let $(G, s, t, c)$ be a flow network with integer capacities, and $f$ be a flow in this flow network. Consider the residual graph $G_f$. We define the width of an $s \rightarrow t$ path $p$ in $G_f$ to be the minimum residual capacity of any edge on $p$. Note that this is the amount by which the flow $f$ is improved if we augment it along $p$. Instead of picking an arbitrary augmenting path, we will choose an augmenting path of maximum width — i.e., a path that improves the value of the flow as much as is possible in a single augmenting step.

Exercise. Describe an algorithm that, given the residual graph in adjacency list form, finds a widest $s \rightarrow t$ path in $O(m \log n)$ time. (Hint: Modify an algorithm we discussed earlier in the course.)

It turns out that if we always choose the augmenting path in this way, the Ford-Fulkerson algorithm will finish in at most $O(m \log C)$ iterations. Each iteration now takes $O(m \log n)$ time, rather than $O(m)$ time as in the basic Ford-Fulkerson algorithm; this is because finding a widest $s \rightarrow t$ path takes $O(m \log n)$ time, while finding an arbitrary $s \rightarrow t$ path can be done in just $O(m)$ time using depth- or breadth-first search. Thus, the overall running time of the algorithm with this way of choosing augmenting paths is $O(m^2 \log n \log C)$. This is polynomial in the input size.

Choosing a path with fewest edges

Another way to choose augmenting paths to ensure good performance of the Ford-Fulkerson algorithm is to always use as augmenting path one with the fewest edges. We can find such a path in $O(m)$ time using breadth-first search (starting at $s$).

It turns out that with this choice of augmenting paths, the Ford-Fulkerson algorithm is guaranteed to terminate after at most $mn$ augmentations, independent of the capacities, assuming that each arithmetic operation can be performed in $O(1)$ time. (The algorithm only adds or subtracts capacities.) Thus, the overall running time of the algorithm with this way of choosing augmenting paths is $O(m^2 n)$. This is polynomial in the input size, and independent of the capacities. Algorithms whose performance does not depend at all on the numeric value of the input (assuming $O(1)$-time arithmetic operations on numbers
regardless of their size) are called **strongly polynomial**. Thus, the Ford-Fulkerson algorithm with this method of choosing augmenting paths is strongly polynomial.

In the remainder of this document we prove that each of these methods of choosing augmenting paths results in the stated bounds for the number of iterations. These proofs are optional material for the course: You should know the two ways of choosing augmenting paths and their effect on the running time of the Ford-Fulkerson algorithm, but you are not required to read the proofs. I do hope that some of you will find them interesting.

### Number of iterations using widest augmenting paths

**Step 1.** Let $f$ be any flow and $f^*$ be a maximum flow of $(G, s, t, c)$. Let $\delta$ be an upper bound on the widths of all augmenting paths of $G_f$; that is, the width of every augmenting path of $G_f$ is at most $\delta$. We will show that

$$V(f^*) - V(f) \leq m \cdot \delta. \tag{1}$$

The proof of this is similar to the proof that the value of the maximum flow is equal to the value of a minimum $(s, t)$-cut.

We define the following $(s, t)$-cut: Let $S$ be the set of nodes reachable from $s$ in $G_f$ via a path of width **greater than** $\delta$; and let $T$ be the remaining nodes of $G_f$. By the definition of $\delta$, $t \in T$ (every $s \rightarrow t$ path has width at most $\delta$, so there is no $s \rightarrow t$ path of width greater than $\delta$). So $(S, T)$ is an $(s, t)$-cut.

**Claim 1** For every $e \in out(S) \cap in(T)$, $f(e) \geq c(e) - \delta$; and for every $e \in out(T) \cap in(S)$, $f(e) \leq \delta$.

**Proof.** If $(u, v) \in out(S) \cap in(T)$ and $f(u, v) < c(e) - \delta$, then $G_f$ has a forward edge $(u, v)$ with residual capacity more than $\delta$. Since $u \in S$, $v$ is also reachable in $G_f$ from $s$ using edges with residual capacity more than $\delta$, and therefore $v \in S$ — contradicting that $(u, v) \in out(S) \cap in(T)$. Similarly, if $(u, v) \in out(T) \cap in(S)$ and $f(u, v) > \delta$, then $G_f$ has a backward edge $(v, u)$ with residual capacity more than $\delta$. Since $v \in S$, $u$ is also reachable in $G_f$ from $s$ using edges with residual capacity more than $\delta$, and therefore $u \in S$ — contradicting that $(u, v) \in out(T) \cap in(S)$. \qed

We now have:

$$V(f) = \sum_{e \in out(S) \cap in(T)} f(e) - \sum_{e \in out(T) \cap in(S)} f(e) \quad \text{[Flow value lemma]}$$

$$\geq \sum_{e \in out(S) \cap in(T)} (c(e) - \delta) - \sum_{e \in out(T) \cap in(S)} \delta \quad \text{[Claim 1]}$$

$$= \sum_{e \in out(S) \cap in(T)} c(e) - \sum_{e \in \left(out(S) \cap in(T)\right) \cup \left(out(T) \cap in(S)\right)} \delta$$

$$\geq \sum_{e \in out(S) \cap in(T)} c(e) - m \cdot \delta \quad \text{[\leq m edges cross cut $(S, T)$ in either direction]}$$

$$\geq V(f^*) - m \cdot \delta$$

where, in the last inequality, we use the fact that the value of any flow (in particular $f^*$) is at most the capacity of any cut (in particular $(S, T)$). Rearranging, we get (1).

**Step 2.** Let $f$ be any flow and $f^*$ be a maximum flow of $(G, s, t, c)$. Let $P$ be a maximum-width path in the residual graph $G_f$, and $f'$ be the result of augmenting $f$ on path $P$; that is, $f' = \text{AUGMENT}(f, P)$. We
will show that
\[
V(f^*) - V(f') \leq (V(f^*) - V(f)) \cdot (1 - \frac{1}{m}).
\] (2)

To prove this, we use the result of Step 1.
Let \( b \) be the width of \( P \), (the maximum-width augmenting path in \( G_f \)). Therefore, every augmenting path in \( G_f \) has width at most \( b \). By (1),
\[
V(f^*) - V(f) \leq m \cdot b
\] (3)
Let \( f' = \text{AUGMENT}(f, P) \). Thus,
\[
V(f') = V(f) + b
\] (4)

Therefore,
\[
\frac{V(f^*) - V(f')}{V(f^*) - V(f)} = \frac{V(f^*) - (V(f) + b)}{V(f^*) - V(f)} \quad \text{[by (4)]}
\]
\[= 1 - \frac{b}{V(f^*) - V(f)} \]
\[\leq 1 - \frac{b}{mb} \quad \text{[by (3)]}
\]
\[= 1 - \frac{1}{m}
\]

Rearranging, we get (2).

**Step 3.** Now we will use the result of Step 2 to prove that, if we use the maximum-width augmentation path in each iteration, the Ford-Fulkerson algorithm will finish after \( O(m \log C) \) iterations.

Let \( f_0 \) be the trivial flow (that carries no traffic in any edge), and \( f_i \) be the flow after \( i \) augmentation steps, where in each step we choose the maximum width augmenting path. By (2) and straightforward induction, \( V(f^*) - V(f_i) \leq (V(f^*) - V(f_0)) \cdot (1 - 1/m)^i \). Note that \( V(f_0) = 0 \) and \((1 - 1/m)^i < e^{-i/m}\) (since \( 1/m \neq 0 \), and \( 1 - x < e^{-x} \) for all \( x \neq 0 \)). Thus, \( V(f^*) - V(f_i) < V(f^*) \cdot e^{-i/m} \). Letting \( i = m \ln C \), we get \( V(f^*) - V(f_i) < V(f^*)/C \leq 1 \) (for the last inequality we use the fact that, by definition of \( C \), \( V(f^*) \leq C \)). Since each \( f_i \) is an integral flow and \( f^* \) is a maximum flow, it follows that \( V(f^*) - V(f_i) = 0 \), i.e., \( V(f_i) = V(f^*) \). So, after at most \( i = m \ln C = O(m \log C) \) augmentations, the algorithm computes a maximum flow.

**Number of iterations using shortest augmenting paths**

In what follows, when we speak of “shortest path” we mean a path with the minimum number of edges (as opposed to the minimum sum of capacities, as in the weighted shortest path problem).

Our aim is to show that by always choosing a shortest augmenting path, the Ford-Fulkerson algorithm will terminate after at most \( mn \) iterations. The basic intuition behind this fact is as follows. Each augmenting step causes at least one edge to be deleted from the residual graph. It may also cause some edges to be inserted. The deleted edges make shortest paths longer. And, it turns out, that re-inserted edges do not create paths that are shorter than those that already exist. Thus, shortest paths to nodes get longer and longer. Since a shortest \( s \to t \) path cannot have more than \( n - 1 \) edges, after some number of augmenting steps \( s \) and \( t \) will become disconnected, meaning that the FF algorithm terminates. A careful counting argument shows that this must happen after no more than \( mn \) augmenting steps. We now give the detailed proof that makes this intuition precise.

Let \( G_k \) be the residual graph after \( k \) augmenting steps, using the shortest path method. Define the **depth** of a node \( u \) in \( G_k \) to be the minimum number of edges on any path from \( s \) to \( u \) in \( G_k \) (i.e., the
depth of \( u \) on a BFS tree of \( G_k \) rooted at \( s \); we denote this as \( \text{depth}_k(u) \). Consider how augmenting step \( k + 1 \) changes the residual graph \( G_k \) to \( G_{k+1} \). Let \( p = u_0, u_1, \ldots, u_m \) be the augmenting path of \( G_k \) used in this step, where \( u_0 = s \) and \( u_k = t \), and each node \( u_i \) has depth \( i \) in \( G_k \); this is because, by the choice of augmenting paths, \( p \) is a shortest path from \( s \) to \( t \). For each edge \((u_i, u_{i+1})\) on \( p \):

- If \((u_i, u_{i+1})\) is a forward edge, this edge is deleted from the residual graph if and only if the augmenting step saturated \((u_i, u_{i+1})\); and the reverse edge \((u_{i+1}, u_i)\) is added to the residual graph as a backward edge if and only if the augmenting step had zero flow before the augmenting step.
- If \((u_i, u_{i+1})\) is a backward edge, this edge is deleted from the residual graph if and only if the augmenting step removed all flow from \((u_{i+1}, u_i)\); and the reverse edge \((u_{i+1}, u_i)\) is added to the residual graph as a forward edge if and only if the edge \((u_{i+1}, u_i)\) was saturated before the augmenting step.

No other changes to the set of edges of the residual graph are made by the augmenting step. So, every edge added to the residual graph during augmenting step \( k + 1 \) goes from a node with depth \( i + 1 \) to a node with depth \( i \) in \( G_k \). Thus, we have:

**Claim 2** If an edge \((u, v)\) is added to the residual graph \( G_{k+1} \) during augmenting step \( k + 1 \) (i.e., \((u, v)\) is not in \( G_k \) but is in \( G_{k+1} \)), then \( \text{depth}_{k+1}(u) = \text{depth}_k(v) + 1 \).

Next we will show that the depth of a node does not increase as a result of an augmenting step.

**Claim 3** For every node \( u \), \( \text{depth}_{k+1}(u) \geq \text{depth}_k(u) \).

**Proof.** Let \( u \) be any node, and let \( u_1, u_2, \ldots, u_m \), where \( u_1 = s \) and \( u_m = u \) be a shortest (fewest edges) path from \( s \) to \( u \) in \( G_{k+1} \). By definition of depth, \( \text{depth}_{k+1}(u_i) = i \) for each \( i \), \( 1 \leq i \leq m \).

By induction we show that, for each \( i \), \( 1 \leq i \leq m \), \( \text{depth}_k(u_i) \leq \text{depth}_{k+1}(u_i) \). This is clearly true for the basis \( i = 1 \), since \( u_1 = s \) and \( s \) is has depth 0 in every residual graph. Suppose, it is true for \( u_i \), for some \( i \), \( 1 \leq i < m \); we will prove that it is true for \( u_{i+1} \). There are two cases: either edge \((u_i, u_{i+1})\) is in \( G_k \), or it was added to the residual graph in augmenting step \( k + 1 \).

**Case 1.** \((u_i, u_{i+1})\) is in \( G_k \). In this case, we have:

\[
\begin{align*}
\text{depth}_k(u_{i+1}) & \leq \text{depth}_k(u_i) + 1 & \text{[since \((u_i, u_{i+1})\) is in \( G_k \)]} \\
& \leq \text{depth}_{k+1}(u_i) + 1 & \text{[by the IH]} \\
& = i + 1 & \text{[since \( \text{depth}_{k+1}(u_i) = i \)]} \\
& = \text{depth}_{k+1}(u_{i+1}) & \text{[since \( \text{depth}_{k+1}(u_{i+1}) = i + 1 \)]}
\end{align*}
\]

**Case 2.** \((u_i, u_{i+1})\) is not in \( G_k \) but is added to \( G_{k+1} \). In this case, we have:

\[
\begin{align*}
\text{depth}_k(u_{i+1}) & \leq \text{depth}_k(u_{i+1}) + 1 & \text{[by Claim 2]} \\
& = \text{depth}_k(u_i) & \text{[by the IH]} \\
& \leq \text{depth}_{k+1}(u_i) & \text{[by the IH]} \\
& \leq i + 1 & \text{[since \( \text{depth}_{k+1}(u_i) = i \)]} \\
& = \text{depth}_{k+1}(u_{i+1}) & \text{[since \( \text{depth}_{k+1}(u_{i+1}) = i + 1 \)]}
\end{align*}
\]

In each augmenting step, at least one edge is deleted from the residual graph, namely every edge on the augmenting path that has minimum residual capacity \( b \). Let \((u, v)\) be an edge that is deleted in augmenting step \( \ell \), and let \( i = \text{depth}_\ell(v) \). Since \((u, v)\) is on an augmenting path, which is a shortest \( s \rightarrow t \) path,
depth_{\ell}(u) = i - 1. If (u, v) is added to the residual graph as a result of a subsequent augmenting step \( k + 1 > \ell \), by Claim 2, depth_{k}(u) = depth_{k}(v) + 1. And since by Claim 3 the depth of a node does not decrease in successive augmentations, depth_{k}(v) \geq depth_{\ell}(v). So, depth_{k+1}(u) \geq depth_{k}(u) = depth_{k}(v) + 1 \geq depth_{\ell}(v) + 1 = i + 1. Thus, the depth of node u must have increased by at least 2 (from \( i - 1 \) to \( i + 1 \)) between an augmenting step \( \ell \) that deleted (u, v) from the residual graph and the subsequent augmenting step \( k + 1 \) that reinserted it. Since the minimum depth of a node is 0 and the maximum is \( n - 1 \), an edge can be added at most \( n/2 \) times to the residual graph. Since there are at most \( 2m \) edges in the residual graph, and each augmenting step deletes at least one edge, after \( 2m(n/2) = mn \) augmenting steps all edges will have been deleted and cannot be inserted (because each of them will have been re-inserted the maximum number of times that it can). Thus, the Ford-Fulkerson algorithm terminates after at most \( mn \) augmenting steps if at each step we chose to augment the flow along a shortest \( s \rightarrow t \) path in the residual graph.