CSC 2515: Probabilistic Classification

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- Multi-class classification with:
 - Least-squares regression
 - Logistic Regression
 - K-NN
- Classification Bayes classifier
- Estimate probability densities from data
- Making decisions: Risk
- Classification Multi-dimensional Bayes classifier
- Naive Bayes

Discriminant Functions for K > 2 classes

- Use K − 1 classifiers, each solving a two class problem of separating point in a class C_k from points not in the class.
- Known as 1 vs all or 1 vs the rest classifier



• PROBLEM: More than one good answer!

Discriminant Functions for K > 2 classes

- Introduce K(K-1)/2 two-way classifiers, one for each possible pair of classes
- Each point is classified according to majority vote amongst the disc. func.
- Known as the 1 vs 1 classifier



• PROBLEM: Two-way preferences need not be transitive

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- What is the shape of the overall decision boundary?

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- In Euclidean space, an object is **convex** if for every pair of points within the object, every point on the straight line segment that joins the pair of points is also within the object



• Which object is convex?

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- Consider 2 points \mathbf{x}_A and \mathbf{x}_B that lie inside decision region R_k
- Any convex combination $\hat{\mathbf{x}}$ of those points also will be in R_k

$$\hat{\mathbf{x}} = \lambda \mathbf{x}_{\mathcal{A}} + (1-\lambda) \mathbf{x}_{\mathcal{B}}$$



Multi-class classification via the "softmax"

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- For the target vector, if there are K classes we often use a 1-of-K encoding, i.e., a vector of K target values containing a single 1 for the correct class and zeros elsewhere
- Let $\mathbf{T} \in \{0,1\}^{N \times K}$ for N training examples and K classes

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- How do we obtain the weights?

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The derivative is the error times the input

Softmax for 2 Classes

• Let's write the probability of one of the classes

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• The over-parameterization of the softmax is because the probabilities must add to 1.

• Can directly handle multi class problems



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- **Discriminative** classifiers estimate parameters of decision boundary/class separator directly from labeled sample
 - learn boundary parameters directly (logistic regression), or
 - learn mappings from inputs to classes (least-squares, neural nets)

Bayes Classifier

- Aim to diagnose whether patient has diabetes: classify into one of two classes (yes C=1; no C=0)
- Run battery of tests
- Given patient's results: $\mathbf{x} = [x_1, x_2, \cdots, x_d]^T$ we want to update class probabilities using Bayes Rule:

$$p(C|\mathbf{x}) = \frac{p(\mathbf{x}|C)p(C)}{p(\mathbf{x})}$$

More formally

$$\mathsf{posterior} = \frac{\mathsf{Class}\ \mathsf{likelihood} \times \mathsf{prior}}{\mathsf{Evidence}}$$

• How can we compute $p(\mathbf{x})$ for the two class case?

$$p(\mathbf{x}) = p(\mathbf{x}|C=0)p(C=0) + p(\mathbf{x}|C=1)p(C=1)$$

• Start with single input/observation per patient: white blood cell count

$$p(C = 1|x = 50) = \frac{p(x = 50|C = 1)p(C = 1)}{p(x = 50)}$$

- Need class-likelihoods, priors
- Prior: In the absence of any observation, what do I know about the problem?
- What would you use as prior?



Which probability distribution makes sense for p(x|C)?

- Let's assume that the class-conditional densities are Gaussian
- How can I fit a Gaussian distribution to my data?

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- First divide the training examples into two classes according to t⁽ⁱ⁾, and for each class take all the examples and fit a Gaussian to model p(x|C)

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• Write $\frac{d\ell_{log-loss}}{d\mu}$ and $\frac{d\ell_{log-loss}}{d\sigma^2}$ and equal it to 0 to find the parameters μ and σ^2

$$\frac{\partial \ell_{\log-loss}}{\partial \mu} = \frac{\partial \left(\frac{N}{2} \ln \left(2\pi\sigma^2\right) + \sum_{i=1}^{N} \frac{(x^{(i)} - \mu)^2}{2\sigma^2}\right)}{\partial \mu}$$

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Thus

$$\mu = \frac{1}{N} \sum_{i=1}^{N} x^{(i)}$$

$$\frac{\partial \ell_{\log-loss}}{\partial \sigma^2} = \frac{\partial \left(\frac{N}{2} \ln \left(2\pi\sigma^2\right) + \sum_{i=1}^{N} \frac{(x^{(i)} - \mu)^2}{2\sigma^2}\right)}{\partial \sigma^2}$$

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Thus

$$\sigma^2 = \frac{1}{N} \sum_{i=1}^{N} (x^{(i)} - \mu)^2$$
• We can compute the parameters in closed form for each class by taking the training points that belong to that class

$$\mu = \frac{1}{N} \sum_{i=1}^{N} x^{(i)}$$
$$\sigma^{2} = \frac{1}{N} \sum_{i=1}^{N} (x^{(i)} - \mu)^{2}$$

• Now given a new observation and the estimated class-likelihoods and the prior, we can obtain **posterior probability** for class C = 1

$$p(C = 1|x) = \frac{p(x|C = 1)p(C = 1)}{p(x)}$$

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=
$$\frac{p(x|C = 1)p(C = 1)}{p(x|C = 0)p(C = 0) + p(x|C = 1)p(C = 1)}$$

Diabetes Example

- Doctor has a prior p(C = 0) = 0.8, how?
- Example x = 50, p(x = 50|C = 0) = 0.11, and p(x = 50|C = 1) = 0.42
- How were p(x = 50 | C = 0) and p(x = 50 | C = 1) computed?
- How can I compute p(C = 1)?
- Which class is more likely? Do I have diabetes?



- Use Bayes classifier to classify new patients (unseen test examples)
- Simple Bayes classifier: estimate posterior probability of each class
- What should the decision criterion be?

$$R(y|\mathbf{x}) = \sum_{c=1}^{C} L(y,t)p(t=c|x)$$

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• To minimize conditional risk given x, the classifier must decide

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• This is the best possible classifier in terms of generalization, i.e., expected misclassification rate on new examples.

• Optimal rule $y = \arg \max_{c} p(t = c | x)$ is equivalent to

$$y = c \quad \Leftrightarrow \quad \frac{p(t = c|x)}{p(t = j|x)} \ge 1 \quad \forall j \neq c$$

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• Where have we used this rule before?

Decision Boundary

- The Bayes classifier will construct decision boundary: used to classify new patients (unseen test examples)
- Can be view as a simple linear classifier

$$C = egin{cases} 1 & ext{if } x \geq T \ 0 & ext{otherwise} \end{cases}$$



Bayes Classifier

- Aim to diagnose whether patient has diabetes: classify into one of two classes (yes C=1; no C=0)
- Run battery of tests
- Given patient's results: $\mathbf{x} = [x_1, x_2, \cdots, x_d]^T$ we want to update class probabilities using Bayes Rule:

$$p(C|\mathbf{x}) = \frac{p(\mathbf{x}|C)p(C)}{p(\mathbf{x})}$$

More formally

$$\mathsf{posterior} = \frac{\mathsf{Class}\ \mathsf{likelihood} \times \mathsf{prior}}{\mathsf{Evidence}}$$

• How can we compute $p(\mathbf{x})$ for the two class case?

$$p(\mathbf{x}) = p(\mathbf{x}|C=0)p(C=0) + p(\mathbf{x}|C=1)p(C=1)$$

Classification: Diabetes Example

• Before we had a single input/observation per patient: white blood cell count

$$p(C = 1|x = 50) = \frac{p(x = 50|C = 1)p(C = 1)}{p(x = 50)}$$

Classification: Diabetes Example

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$$p(C = 1|x = 50) = rac{p(x = 50|C = 1)p(C = 1)}{p(x = 50)}$$

- Add second observation: Plasma glucose value
- Can construct bivariate normal (Gaussian) distribution of each class



• Gaussian (or normal) distribution:

$$p(\mathbf{x}|t=k) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp\left[-(\mathbf{x} - \mu_k)^T \Sigma^{-1} (\mathbf{x} - \mu_k)\right]$$

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• Each class k has associated mean vector, but typically the classes share a single covariance matrix

- Multiple measurements (sensors)
- *d* inputs/features/attributes
- N instances/observations/examples

$$\mathbf{X} = \begin{bmatrix} x_1^{(1)} & x_2^{(1)} & \cdots & x_d^{(1)} \\ x_1^{(2)} & x_2^{(2)} & \cdots & x_d^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(N)} & x_2^{(N)} & \cdots & x_d^{(N)} \end{bmatrix}$$

Multivariate Parameters

Mean

$$\mathbb{E}[\mathbf{x}] = [\mu_1, \cdots, \mu_d]^T$$

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• Covariance

$$\Sigma = Cov(\mathbf{x}) = \mathbb{E}[(\mathbf{x} - \mu)^{T}(\mathbf{x} - \mu)] = \begin{bmatrix} \sigma_{1}^{2} & \sigma_{12} & \cdots & \sigma_{1d} \\ \sigma_{12} & \sigma_{2}^{2} & \cdots & \sigma_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{d1} & \sigma_{d2} & \cdots & \sigma_{d}^{2} \end{bmatrix}$$

Mean

$$\mathbb{E}[\mathbf{x}] = [\mu_1, \cdots, \mu_d]^T$$

Covariance

$$\boldsymbol{\Sigma} = Cov(\mathbf{x}) = \mathbb{E}[(\mathbf{x} - \mu)^{T}(\mathbf{x} - \mu)] = \begin{bmatrix} \sigma_{1}^{2} & \sigma_{12} & \cdots & \sigma_{1d} \\ \sigma_{12} & \sigma_{2}^{2} & \cdots & \sigma_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{d1} & \sigma_{d2} & \cdots & \sigma_{d}^{2} \end{bmatrix}$$

Correlation = Corr(x) is the covariance divided by the product of standard deviation

$$\rho_{ij} = \frac{\sigma_{ij}}{\sigma_i \sigma_j}$$

Multivariate Gaussian Distribution

• $\mathbf{x} \sim \mathcal{N}(\mu, \Sigma)$, a Gaussian (or normal) distribution defined as $p(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp\left[-(\mathbf{x} - \mu_k)^T \Sigma^{-1} (\mathbf{x} - \mu_k)\right]$



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Mahalanobis distance (x – μ_k)^TΣ⁻¹(x – μ_k) measures the distance from x to μ in terms of Σ

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- Mahalanobis distance (x μ_k)^TΣ⁻¹(x μ_k) measures the distance from x to μ in terms of Σ
- It normalizes for difference in variances and correlations

Urtasun & Zemel (UofT)

Bivariate Normal



Bivariate Normal

 $Cov(x_1, x_2)=0, Var(x_1)=Var(x_2)$

 $Cov(x_1, x_2)=0, Var(x_1)>Var(x_2)$







Urtasun & Zemel (UofT)

- GBC decision boundary: based on class posterior
- Take the class which has higher posterior probability

$$\log p(t_k | \mathbf{x}) = \log p(\mathbf{x} | t_k) + \log p(t_k) - \log p(\mathbf{x}) = -\frac{d}{2} \log(2\pi) - \frac{1}{2} \log |\Sigma_k^{-1}| - \frac{1}{2} (\mathbf{x} - \mu_k)^T \sigma_k^{-1} (\mathbf{x} - \mu_k) + \log p(t_k) - \log p(\mathbf{x})$$

• Decision: which class has higher posterior probability

Decision Boundary



Shared Covariance Matrix



• Learn the parameters using maximum likelihood

$$\begin{split} \ell(\phi, \mu_0, \mu_1, \Sigma) &= -\log \prod_{n=1}^N p(\mathbf{x}^{(n)}, t^{(n)} | \phi, \mu_0, \mu_1, \Sigma) \\ &= -\log \prod_{n=1}^N p(\mathbf{x}^{(n)} | t^{(n)}, \mu_0, \mu_1, \Sigma) p(t^{(n)} | \phi) \end{split}$$

• What have I assumed?

• Assume the prior is Bernoulli (we have two classes)

$$p(t|\phi) = \phi^t (1-\phi)^{1-t}$$

• You can compute the ML estimate in closed form

$$\begin{split} \phi &= \frac{1}{N} \sum_{n=1}^{N} \mathbb{1}[t^{(n)} = 1] \\ \mu_0 &= \frac{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = 0] \cdot \mathbf{x}^{(n)}}{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = 0]} \\ \mu_1 &= \frac{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = 1] \cdot \mathbf{x}^{(n)}}{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = 1]} \\ \Sigma &= \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}^{(n)} - \mu_{t^{(n)}}) (\mathbf{x}^{(n)} - \mu_{t^{(n)}})^T \end{split}$$

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• How many parameters required now? And before?

Diagonal Covariance



Diagonal Covariance, isotropic



• Classification only depends on distance to the mean

- o prior
- assuming features are conditionally independent given the class
- likelihood for each x_i

o prior

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- likelihood for each x_i

The decision rule

$$y = \arg \max_{k} p(t = k) \prod_{i=1}^{d} p(x_i | t = k)$$

o prior

- assuming features are conditionally independent given the class
- likelihood for each x_i

The decision rule

$$y = \arg \max_{k} p(t = k) \prod_{i=1}^{d} p(x_i | t = k)$$

• If the assumption of conditional independence holds, NB is the optimal classifier

- o prior
- assuming features are conditionally independent given the class
- likelihood for each x_i

The decision rule

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- What's the regularization?

Gaussian Naive Bayes

Assume

$$p(x_i|t=k) = rac{1}{\sqrt{2\pi\sigma_{ik}}} \exp\left[rac{-(x_i - \mu_{ik})^2}{2\sigma_{ik}^2}
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• Maximum likelihood estimate of parameters

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• Similar for the variance

• If you examine $p(t = 1 | \mathbf{x})$ under GBC, you will find that it looks like this:

$$p(t|\mathbf{x}, \phi, \mu_0, \mu_1, \Sigma) = rac{1}{1 + \exp(-\mathbf{w}(\phi, \mu_0, \mu_1, \Sigma)^T \mathbf{x})}$$

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- So the decision boundary has the same form as logistic regression!
- When should we prefer GBC to LR, and vice versa?

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- When these distributions are non-Gaussian, in limit of large N, LR beats GBC

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- Represent email as feature vector, length equals number of words in vocabulary, binary feature x_i is 1 iff the word i appears in email msg
- Each of these binary conditional probabilities is Bernoulli, with parameter ϕ_i
- When we estimate parameters by maximizing joint likelihood of data, get sensible updates: \(\phi_{i|t=1}\) is fraction of the spam emails in which word \(i\) appears

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- Class posterior probabilities = 0/0
- Instead use this parameter estimate:

$$\phi_{i|t=1} = \frac{1}{N} \sum_{n=1}^{N} \frac{\mathbb{1}[t^{(n)} = 1 \land x_i^{(n)} = 1]}{\mathbb{1}[t^{(n)} = 1] + \alpha K}$$

• K is number of classes, parameter α acts like "pseudo-count": prior observations of words