Priority Queue

Collection of priority-job pairs; priorities are comparable.

- insert(p, j)
- max(): read(-only) job of max priority
- extract-max(): read and remove job of max priority
- increase-priority(i, p'): increase priority of pair i

It's like:

- a hospital's emergency room
- an OS's ordering of things to do
- your ordering of things to study

Heap

A heap is one way to store a priority queue. A heap is:

- a binary tree
- "nearly complete": every level *i* has 2^{*i*} nodes, except the bottom level; the bottom nodes flush to the left
- ► at each node: its priority ≥ both children's priorities



Heap insert: Example

Insert priority 15. At the bottom level, leftmost free space.



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! Order of priorities bad. Fix: swap with parent.

Heap insert: Example



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Heap insert: Example



 $\sqrt{}$ The tree is still "nearly-complete". $\sqrt{}$ Order of priorities good.

Heap insert: Summary

- 1. create new node at bottom level, leftmost free place (keep the tree "nearly-complete")
- 2. put priority (and job) in new node
- 3. v := that new node
- 4. "Float up as needed": while v has parent with smaller priority: swap them v := v.parent

Worst case time $\Theta(height)$.

Later we will see why $height = \lfloor \lg n \rfloor$. Therefore worse case time $\Theta(\lg n)$.



Someone has to take the throne replace the blank!



Replace by the bottom level, rightmost item.

- $\sqrt{}$ The tree is still "nearly-complete".
 - ! Order of priorities bad. Fix: swap with the larger child. (Why not the smaller child?)



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Heap extract-max: Summary

- 1. Replace root by bottom level, rightmost item (keep the tree "nearly-complete".)
- **2**. *v* := root
- **3**. "heapify at *v*":

while v has larger child: swap with the largest child v := that child node

Worst case $\Theta(height)$ time.

Next we will see why $height = \lfloor \lg n \rfloor$. Therefore worse case time $\Theta(\lg n)$.

Heap: Height

Let *n* be the number of nodes, *h* be the height.



$$(2^{h} - 1) + 1 \leq n \leq 2^{h+1} - 1$$
$$2^{h} \leq n < 2^{h+1}$$
$$h \leq \lg n < h+1$$
$$h = \lfloor \lg n \rfloor$$

Heap in Array/Vector





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Heap in Array/Vector



Convenience:

- Where to insert/remove: simply at the end.
- Saves space. (No pointers to store.)

Formulas for:

- left child of index *i*: index $2 \times i$
- right child of index *i*: index $2 \times i + 1$
- parent of index i: index [i/2]

Heapsort

Heapsort sorts an array via an intermediate max-heap.

Two stages:

 "Build max-heap": Turn the array into max-heap form. Basic idea: heapify at nodes that have children, bottom-up order:

for $v := \lfloor size/2 \rfloor$ down to 1: heapify at v

2. Repeatedly extract-max, put answer at the end.

Basic idea: The array slot freed up by extract-max is exactly where you want the max to land at.



for $v := \lfloor size/2 \rfloor$ down to 1: heapify at v.



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Repeatedly Extract-Max



for i := size down to 1: m := extract-max(); A[i] := m

Repeatedly Extract-Max



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Repeatedly Extract-Max



for i := size down to 1: m := extract-max(); A[i] := m

Heapsort Time

1. Turn array into heap: A node at height *h* takes *h* iterations to fix; fewer than $n/2^h$ such nodes.

$$\sum_{h=0}^{\lfloor \lg n \rfloor} \frac{n}{2^h} \times h \le n \times \sum_{h=0}^{\infty} \frac{h}{2^h}$$

= $n \times \text{constant}$ (convergent series)

So O(n) time. (Faster than *n* inserts.)

2. Repeatedly extract-max: $O(n \lg n)$ time.

Total $O(n \lg n)$ time.