# CSC 411 Lecture 12: Principal Component Analysis

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- Today we'll cover the first unsupervised learning algorithm for this course: principal component analysis (PCA)
- Dimensionality reduction: map the data to a lower dimensional space
  - Save computation/memory
  - Reduce overfitting
  - Visualize in 2 dimensions
- PCA is a linear model, with a closed-form solution. It's useful for understanding lots of other algorithms.
  - Autoencoders
  - Matrix factorizations (next lecture)
- Today's lecture is very linear-algebra-heavy.
  - Especially orthogonal matrices and eigendecompositions.
  - Don't worry if you don't get it immediately next few lectures won't build on it
  - Not on midterm (which only covers up through L9)

# Projection onto a Subspace



- Here, the columns of **U** form an orthonormal basis for a subspace S.
- The projection of a point x onto S is the point x̃ ∈ S closest to x. In machine learning, x̃ is also called the reconstruction of x.
- z is its representation, or code.

# Projection onto a Subspace

- If we have a *K*-dimensional subspace in a *D*-dimensional input space, then  $\mathbf{x} \in \mathbb{R}^{D}$  and  $\mathbf{z} \in \mathbb{R}^{K}$ .
- If the data points x all lie close to the subspace, then we can approximate distances, dot products, etc. in terms of these same operations on the code vectors z.
- If K le D, then it's much cheaper to work with z than x.
- A mapping to a space that's easier to manipulate or visualize is called a representation, and learning such a mapping is representation learning.
- Mapping data to a low-dimensional space is called dimensionality reduction.



## Learning a Subspace

- How to choose a good subspace S?
  - Need to choose a vector  $\boldsymbol{\mu}$  and a  $D \times K$  matrix  $\mathbf{U}$  with orthonormal columns.
- Set  $\mu$  to the mean of the data,  $\mu = \frac{1}{N} \sum_{i=1}^{N} \mathbf{x}^{(i)}$
- Two criteria:
  - Minimize the reconstruction error

$$\min \frac{1}{N} \sum_{i=1}^{N} \|\mathbf{x}^{(i)} - \tilde{\mathbf{x}}^{(i)}\|^2$$

• Maximize the variance of the code vectors

$$\max \sum_{j} \operatorname{Var}(z_{j}) = \frac{1}{N} \sum_{j} \sum_{i} (z_{j}^{(i)} - \bar{z}_{i})^{2}$$
$$= \frac{1}{N} \sum_{i} ||\mathbf{z}^{(i)} - \bar{\mathbf{z}}||^{2}$$
$$= \frac{1}{N} \sum_{i} ||\mathbf{z}^{(i)}||^{2} \qquad \text{Exercise: show } \bar{\mathbf{z}} = 0$$

 ${\ensuremath{\,\circ\,}}$  Note: here,  $\bar{z}$  denotes the mean, not a derivative.

#### Learning a Subspace

• These two criteria are equivalent! I.e., we'll show

$$\frac{1}{N}\sum_{i=1}^{N} \|\mathbf{x}^{(i)} - \tilde{\mathbf{x}}^{(i)}\|^2 = \operatorname{const} - \frac{1}{N}\sum_{i} \|\mathbf{z}^{(i)}\|^2$$

Observation: by unitarity,

$$\|\mathbf{ ilde{x}}^{(i)}-oldsymbol{\mu}\|=\|\mathbf{U}\mathbf{z}^{(i)}\|=\|\mathbf{z}^{(i)}\|$$

• By the Pythagorean Theorem,



Choosing a subspace to maximize the projected variance, or minimize the reconstruction error, is called principal component analysis (PCA).

Recall:

• Spectral Decomposition: a symmetric matrix **A** has a full set of eigenvectors, which can be chosen to be orthogonal. This gives a decomposition

$$\mathbf{A} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\top},$$

where **Q** is orthogonal and **A** is diagonal. The columns of **Q** are eigenvectors, and the diagonal entries  $\lambda_j$  of **A** are the corresponding eigenvalues.

- I.e., symmetric matrices are diagonal in some basis.
- A symmetric matrix **A** is positive semidefinite iff each  $\lambda_j \ge 0$ .

# Principal Component Analysis

• Consider the empirical covariance matrix:

$$\mathbf{\Sigma} = rac{1}{N}\sum_{i=1}^{N}(\mathbf{x}^{(i)}-\boldsymbol{\mu})(\mathbf{x}^{(i)}-\boldsymbol{\mu})^{ op}$$

- Recall: Covariance matrices are symmetric and positive semidefinite.
- The optimal PCA subspace is spanned by the top K eigenvectors of Σ.
  - More precisely, choose the first K of any orthonormal eigenbasis for Σ.
  - The general case is tricky, but we'll show this for K = 1.
- These eigenvectors are called principal components, analogous to the principal axes of an ellipse.



# Deriving PCA

• For K = 1, we are fitting a unit vector **u**, and the code is a scalar  $z = \mathbf{u}^{\top} (\mathbf{x} - \boldsymbol{\mu})$ .

$$\frac{1}{N} \sum_{i} [z^{(i)}]^{2} = \frac{1}{N} \sum_{i} (\mathbf{u}^{\top} (\mathbf{x}^{(i)} - \boldsymbol{\mu}))^{2}$$

$$= \frac{1}{N} \sum_{i=1}^{N} \mathbf{u}^{\top} (\mathbf{x}^{(i)} - \boldsymbol{\mu}) (\mathbf{x}^{(i)} - \boldsymbol{\mu})^{\top} \mathbf{u}$$

$$= \mathbf{u}^{\top} \left[ \frac{1}{N} \sum_{i=1}^{N} (\mathbf{x}^{(i)} - \boldsymbol{\mu}) (\mathbf{x}^{(i)} - \boldsymbol{\mu})^{\top} \right] \mathbf{u}$$

$$= \mathbf{u}^{\top} \boldsymbol{\Sigma} \mathbf{u}$$

$$= \mathbf{u}^{\top} \mathbf{Q} \mathbf{A} \mathbf{Q}^{\top} \mathbf{u}$$

$$= \mathbf{a}^{\top} \mathbf{A} \mathbf{a}$$

$$= \sum_{j=1}^{D} \lambda_{j} a_{j}^{2}$$
Spectral Decomposition

# Deriving PCA

- Maximize  $\mathbf{a}^{\top} \mathbf{\Lambda} \mathbf{a} = \sum_{j=1}^{D} \lambda_j a_j^2$  for  $\mathbf{a} = \mathbf{Q}^{\top} \mathbf{u}$ .
  - This is a change-of-basis to the eigenbasis of  $\pmb{\Sigma}.$
- Assume the λ<sub>i</sub> are in sorted order. For simplicity, assume they are all distinct.
- Observation: since **u** is a unit vector, then by unitarity, **a** is also a unit vector. I.e.,  $\sum_{j} a_{j}^{2} = 1$ .
- By inspection, set  $a_1 = \pm 1$  and  $a_j = 0$  for  $j \neq 1$ .
- Hence,  $\mathbf{u} = \mathbf{Q}\mathbf{a} = \mathbf{q}_1$  (the top eigenvector).
- A similar argument shows that the kth principal component is the kth eigenvector of Σ. If you're interested, look up the Courant-Fischer Theorem.

#### Decorrelation

• Interesting fact: the dimensions of **z** are decorrelated. For now, let Cov denote the empirical covariance.

$$Cov(z) = Cov(\mathbf{U}^{\top}(\mathbf{x} - \boldsymbol{\mu}))$$
  
=  $\mathbf{U}^{\top} Cov(\mathbf{x})\mathbf{U}$   
=  $\mathbf{U}^{\top} \boldsymbol{\Sigma} \mathbf{U}$   
=  $\mathbf{U}^{\top} \mathbf{Q} \boldsymbol{\Lambda} \mathbf{Q}^{\top} \mathbf{U}$   
=  $(\mathbf{I} \quad \mathbf{0}) \boldsymbol{\Lambda} \begin{pmatrix} \mathbf{I} \\ \mathbf{0} \end{pmatrix}$  by orthogonality  
= top left  $K \times K$  block of  $\boldsymbol{\Lambda}$ 

- If the covariance matrix is diagonal, this means the features are uncorrelated.
- This is why PCA was originally invented (in 1901!).

#### Recap:

- Dimensionality reduction aims to find a low-dimensional representation of the data.
- PCA projects the data onto a subspace which maximizes the projected variance, or equivalently, minimizes the reconstruction error.
- The optimal subspace is given by the top eigenvectors of the empirical covariance matrix.
- PCA gives a set of decorrelated features.

- Consider running PCA on 2429 19x19 grayscale images (CBCL data)
- Can get good reconstructions with only 3 components



- PCA for pre-processing: can apply classifier to latent representation
  - For face recognition PCA with 3 components obtains 79% accuracy on face/non-face discrimination on test data vs. 76.8% for a Gaussian mixture model (GMM) with 84 states. (We'll cover GMMs later in the course.)
- Can also be good for visualization

# Applying PCA to faces: Learned basis

Principal components of face images ("eigenfaces")



# Applying PCA to digits



Next: two more interpretations of PCA, which have interesting generalizations.

- Autoencoders
- Matrix factorization (next lecture)

- An autoencoder is a feed-forward neural net whose job it is to take an input **x** and predict **x**.
- To make this non-trivial, we need to add a bottleneck layer whose dimension is much smaller than the input.



Why autoencoders?

- Map high-dimensional data to two dimensions for visualization
- Learn abstract features in an unsupervised way so you can apply them to a supervised task
  - Unlabled data can be much more plentiful than labeled data

# Linear Autoencoders

 The simplest kind of autoencoder has one hidden layer, linear activations, and squared error loss.

$$\mathcal{L}(\mathbf{x}, \widetilde{\mathbf{x}}) = \|\mathbf{x} - \widetilde{\mathbf{x}}\|^2$$

- This network computes  $\tilde{\mathbf{x}} = \mathbf{W}_2 \mathbf{W}_1 \mathbf{x}$ , which is a linear function.
- If K ≥ D, we can choose W<sub>2</sub> and W<sub>1</sub> such that W<sub>2</sub>W<sub>1</sub> is the identity matrix. This isn't very interesting.
  - But suppose K < D:
    - **W**<sub>1</sub> maps **x** to a *K*-dimensional space, so it's doing dimensionality reduction.



## Linear Autoencoders

- Observe that the output of the autoencoder must lie in a K-dimensional subspace spanned by the columns of W<sub>2</sub>.
- We saw that the best possible *K*-dimensional subspace in terms of reconstruction error is the PCA subspace.
- The autoencoder can achieve this by setting  $\mathbf{W}_1 = \mathbf{U}^{\top}$  and  $\mathbf{W}_2 = \mathbf{U}$ .
- Therefore, the optimal weights for a linear autoencoder are just the principal components!



#### Nonlinear Autoencoders

- Deep nonlinear autoencoders learn to project the data, not onto a subspace, but onto a nonlinear manifold
- This manifold is the image of the decoder.
- This is a kind of nonlinear dimensionality reduction.



• Nonlinear autoencoders can learn more powerful codes for a given dimensionality, compared with linear autoencoders (PCA)



## Nonlinear Autoencoders

Here's a 2-dimensional autoencoder representation of newsgroup articles. They're color-coded by topic, but the algorithm wasn't given the labels.

