

CSC 411 Lecture 9: SVMs and Boosting

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- Support Vector Machines
- Connection between Exponential Loss and AdaBoost

Binary Classification with a Linear Model

- Classification: Predict a discrete-valued target
- Binary classification: Targets $t \in \{-1, +1\}$
- Linear model:

$$z = \mathbf{w}^\top \mathbf{x} + b$$

$$y = \text{sign}(z)$$

- Question: How should we choose \mathbf{w} and b ?

Zero-One Loss

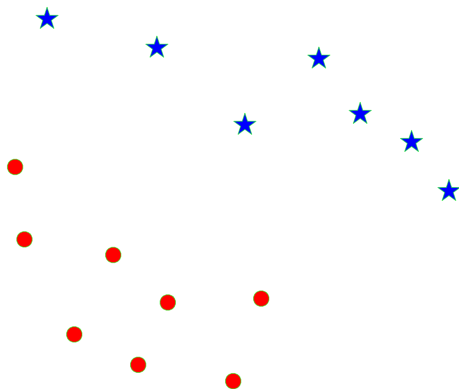
- We can use the 0 – 1 loss function, and find the weights that minimize it over data points

$$\begin{aligned}\mathcal{L}_{0-1}(y, t) &= \begin{cases} 0 & \text{if } y = t \\ 1 & \text{if } y \neq t \end{cases} \\ &= \mathbb{I}\{y \neq t\}.\end{aligned}$$

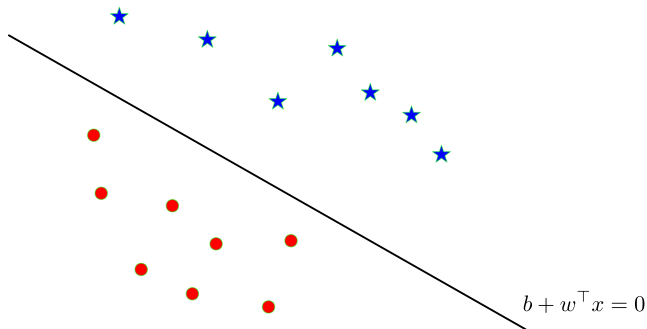
- But minimizing this loss is computationally difficult, and it can't distinguish different hypotheses that achieve the same accuracy.
- We investigated some other loss functions that are easier to minimize, e.g., logistic regression with the cross-entropy loss \mathcal{L}_{CE} .
- Let's consider a different approach, starting from the geometry of binary classifiers.

Separating Hyperplanes

Suppose we are given these data points from two different classes and want to find a linear classifier that separates them.

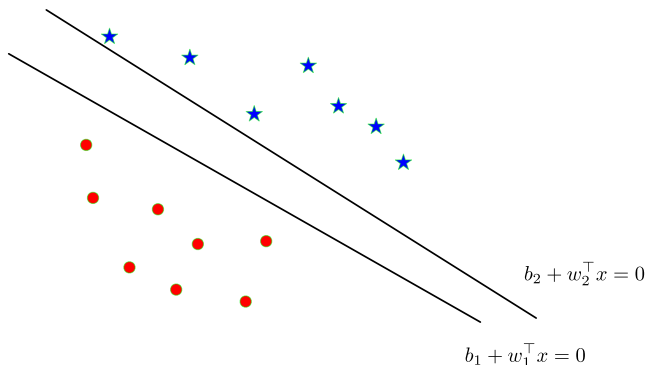


Separating Hyperplanes



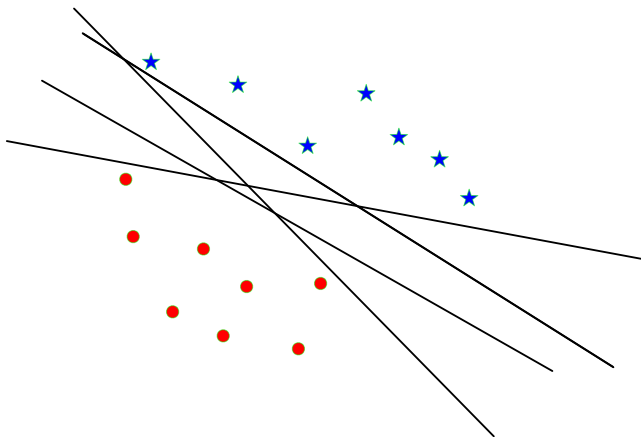
- The decision boundary looks like a line because $\mathbf{x} \in \mathbb{R}^2$, but think about it as a $D - 1$ dimensional hyperplane.
- Recall that a hyperplane is described by points $\mathbf{x} \in \mathbb{R}^D$ such that $f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b = 0$.

Separating Hyperplanes



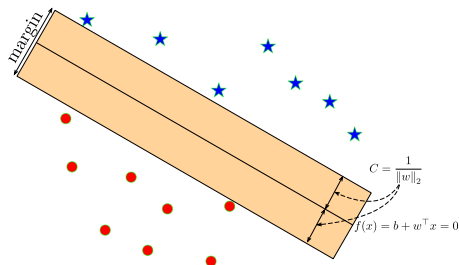
- There are multiple separating hyperplanes, described by different parameters (\mathbf{w}, b) .

Separating Hyperplanes



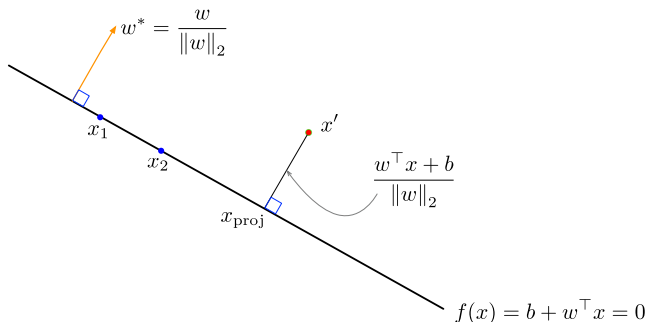
Optimal Separating Hyperplane

Optimal Separating Hyperplane: A hyperplane that separates two classes and maximizes the distance to the closest point from either class, i.e., maximize the **margin** of the classifier.



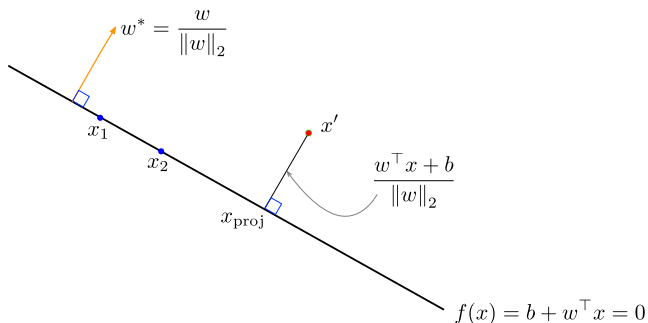
Intuitively, ensuring that a classifier is not too close to any data points leads to better generalization on the test data.

Geometry of Points and Planes



- Recall that the decision hyperplane is orthogonal (perpendicular) to \mathbf{w} .
- The vector $\mathbf{w}^* = \frac{\mathbf{w}}{\|\mathbf{w}\|_2}$ is a unit vector pointing in the same direction as \mathbf{w} .
- The same hyperplane could equivalently be defined in terms of \mathbf{w}^* .

Geometry of Points and Planes



The (signed) distance of a point \mathbf{x}' to the hyperplane is

$$\frac{\mathbf{w}^\top \mathbf{x}' + b}{\|\mathbf{w}\|_2}$$

Maximizing Margin as an Optimization Problem

- Recall: the classification for the i -th data point is correct when

$$\text{sign}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) = t^{(i)}$$

- This can be rewritten as

$$t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) > 0$$

- Enforcing a margin of C :

$$t^{(i)} \cdot \underbrace{\frac{(\mathbf{w}^\top \mathbf{x}^{(i)} + b)}{\|\mathbf{w}\|_2}}_{\text{signed distance}} \geq C$$

Maximizing Margin as an Optimization Problem

Max-margin objective:

$$\begin{aligned} & \max_{\mathbf{w}, b} C \\ \text{s.t.} & \frac{t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b)}{\|\mathbf{w}\|_2} \geq C \quad i = 1, \dots, N \end{aligned}$$

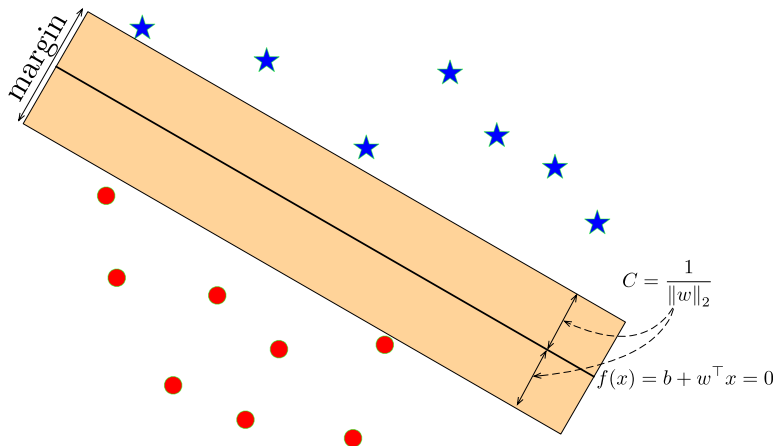
Plug in $C = 1/\|\mathbf{w}\|_2$ and simplify:

$$\underbrace{\frac{t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b)}{\|\mathbf{w}\|_2} \geq \frac{1}{\|\mathbf{w}\|_2}}_{\text{geometric margin constraint}} \iff \underbrace{t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) \geq 1}_{\text{algebraic margin constraint}}$$

Equivalent optimization objective:

$$\begin{aligned} & \min \|\mathbf{w}\|_2^2 \\ \text{s.t.} & t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) \geq 1 \quad i = 1, \dots, N \end{aligned}$$

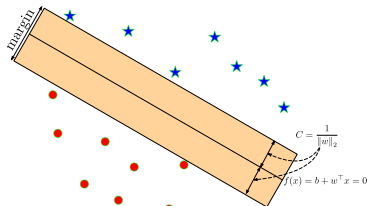
Maximizing Margin as an Optimization Problem



Maximizing Margin as an Optimization Problem

Algebraic max-margin objective:

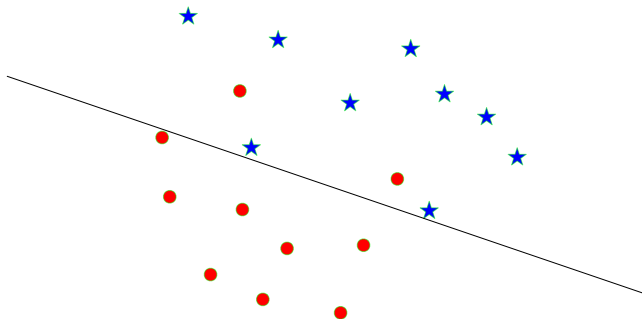
$$\begin{aligned} \min_{\mathbf{w}, b} \quad & \|\mathbf{w}\|_2^2 \\ \text{s.t.} \quad & t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) \geq 1 \quad i = 1, \dots, N \end{aligned}$$



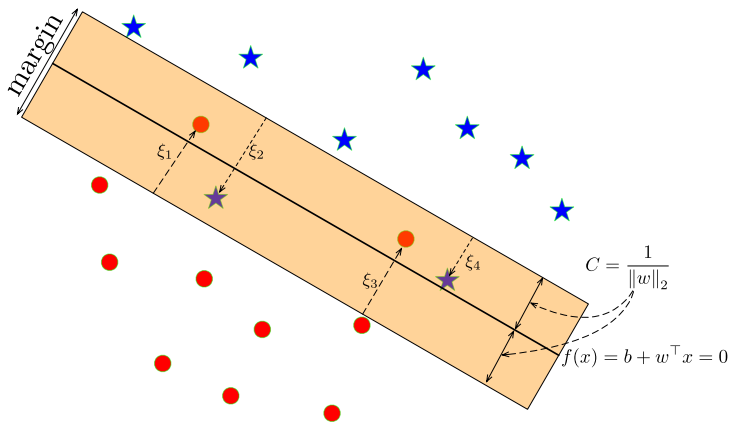
- Observe: if the margin constraint is not tight for $\mathbf{x}^{(i)}$, we could remove it from the training set and the optimal \mathbf{w} would be the same.
- The important training examples are the ones with algebraic margin 1, and are called **support vectors**.
- Hence, this algorithm is called the (hard) **Support Vector Machine (SVM)** (or Support Vector Classifier).
- SVM-like algorithms are often called **max-margin** or **large-margin**.

Non-Separable Data Points

How can we apply the max-margin principle if the data are **not** linearly separable?



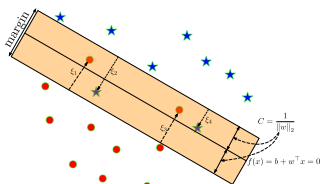
Maximizing Margin for Non-Separable Data Points



Main Idea:

- Allow some points to be within the margin or even be misclassified; we represent this with **slack variables** ξ_i .
- But constrain or penalize the total amount of slack.

Maximizing Margin for Non-Separable Data Points



- Soft margin constraint:

$$\frac{t^{(i)}(\mathbf{w}^T \mathbf{x}^{(i)} + b)}{\|\mathbf{w}\|_2} \geq C(1 - \xi_i),$$

for $\xi_i \geq 0$.

- Penalize $\sum_i \xi_i$

Maximizing Margin for Non-Separable Data Points

Soft-margin SVM objective:

$$\begin{aligned} \min_{\mathbf{w}, b, \xi} \quad & \frac{1}{2} \|\mathbf{w}\|_2^2 + \gamma \sum_{i=1}^N \xi_i \\ \text{s.t.} \quad & t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) \geq 1 - \xi_i \quad i = 1, \dots, N \\ & \xi_i \geq 0 \quad i = 1, \dots, N \end{aligned}$$

- γ is a hyperparameter that trades off the margin with the amount of slack.
 - ▶ For $\gamma = 0$, we'll get $\mathbf{w} = 0$. (Why?)
 - ▶ As $\gamma \rightarrow \infty$ we get the hard-margin objective.
- Note: it is also possible to constrain $\sum_i \xi_i$ instead of penalizing it.

From Margin Violation to Hinge Loss

Let's simplify the soft margin constraint by eliminating ξ_i . Recall:

$$\begin{aligned}t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) &\geq 1 - \xi_i & i = 1, \dots, N \\ \xi_i &\geq 0 & i = 1, \dots, N\end{aligned}$$

- Rewrite as $\xi_i \geq 1 - t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b)$.
- **Case 1:** $1 - t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) \leq 0$
 - ▶ The smallest non-negative ξ_i that satisfies the constraint is $\xi_i = 0$.
- **Case 2:** $1 - t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b) > 0$
 - ▶ The smallest ξ_i that satisfies the constraint is $\xi_i = 1 - t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b)$.
- Hence, $\xi_i = \max\{0, 1 - t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b)\}$.
- Therefore, the slack penalty can be written as

$$\sum_{i=1}^N \xi_i = \sum_{i=1}^N \max\{0, 1 - t^{(i)}(\mathbf{w}^\top \mathbf{x}^{(i)} + b)\}.$$

- We sometimes write $\max\{0, y\} = (y)_+$

From Margin Violation to Hinge Loss

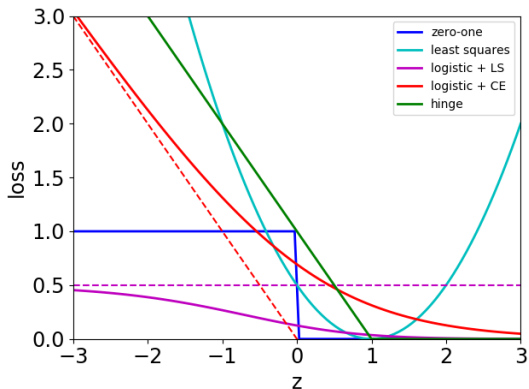
If we write $y^{(i)}(\mathbf{w}, b) = \mathbf{w}^\top \mathbf{x} + b$, then the optimization problem can be written as

$$\min_{\mathbf{w}, b, \xi} \sum_{i=1}^N \left(1 - t^{(i)} y^{(i)}(\mathbf{w}, b)\right)_+ + \frac{1}{2\gamma} \|\mathbf{w}\|_2^2$$

- The loss function $\mathcal{L}_H(y, t) = (1 - ty)_+$ is called the **hinge loss**.
- The second term is the L_2 -norm of the weights.
- Hence, the soft-margin SVM can be seen as a linear classifier with hinge loss and an L_2 regularizer.

Revisiting Loss Functions for Classification

Hinge loss compared with other loss functions



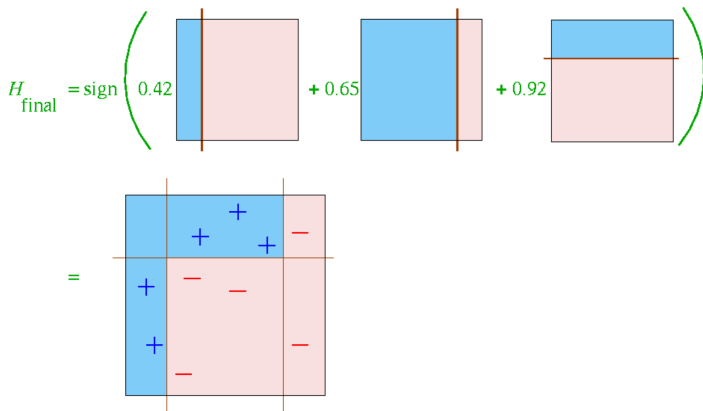
SVMs: What we Left Out

What we left out:

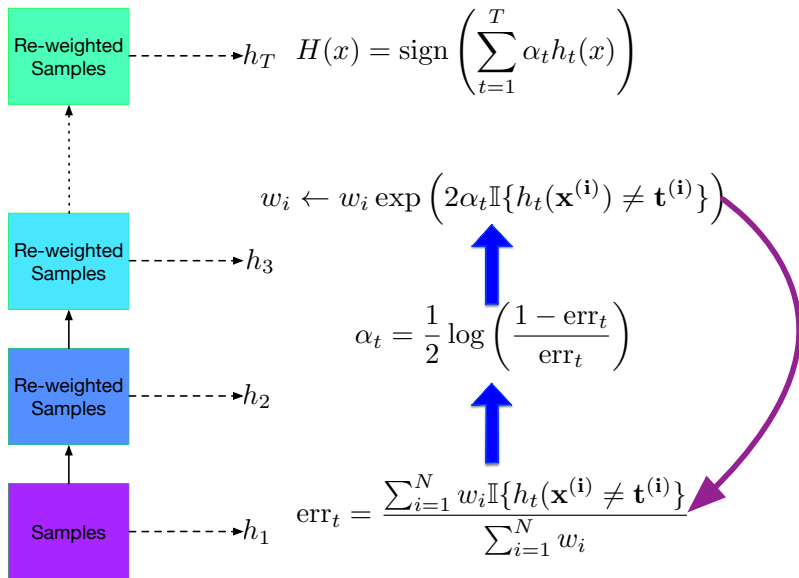
- How to fit \mathbf{w} :
 - ▶ One option: gradient descent
 - ▶ Can reformulate with the Lagrange dual
- The “kernel trick” converts it into a powerful nonlinear classifier. We’ll cover this later in the course.
- Classic results from learning theory show that a large margin implies good generalization.

AdaBoost Revisited

Part 2: reinterpreting AdaBoost in terms of what we've learned about loss functions.



AdaBoost Revisited



Additive Models

- Consider a hypothesis class \mathcal{H} with each $h_i : \mathbf{x} \mapsto \{-1, +1\}$ within \mathcal{H} , i.e., $h_i \in \mathcal{H}$. These are the “weak learners”, and in this context they’re also called **bases**.
- An **additive model** with m terms is given by

$$H_m(x) = \sum_{i=1}^m \alpha_i h_i(\mathbf{x}),$$

where $(\alpha_1, \dots, \alpha_m) \in \mathbb{R}^m$.

- Observe that we’re taking a linear combination of base classifiers, just like in boosting.
- We’ll now interpret AdaBoost as a way of fitting an additive model.

Stagewise Training of Additive Models

A greedy approach to fitting additive models, known as [stagewise training](#):

1. Initialize $H_0(x) = 0$
2. For $m = 1$ to T :
 - ▶ Compute the m -th hypothesis and its coefficient

$$(h_m, \alpha_m) \leftarrow \operatorname{argmin}_{h \in \mathcal{H}, \alpha} \sum_{i=1}^N \mathcal{L} \left(H_{m-1}(\mathbf{x}^{(i)}) + \alpha h(\mathbf{x}^{(i)}), t^{(i)} \right)$$

- ▶ Add it to the additive model

$$H_m = H_{m-1} + \alpha_m h_m$$

Additive Models with Exponential Loss

Consider the exponential loss

$$\mathcal{L}_E(y, t) = \exp(-ty).$$

We want to see how the stagewise training of additive models can be done.

$$\begin{aligned}(h_m, \alpha_m) &\leftarrow \operatorname{argmin}_{h \in \mathcal{H}, \alpha} \sum_{i=1}^N \exp\left(-\left[H_{m-1}(\mathbf{x}^{(i)}) + \alpha h(\mathbf{x}^{(i)})\right] t^{(i)}\right) \\ &= \sum_{i=1}^N \exp\left(-H_{m-1}(\mathbf{x}^{(i)}) t^{(i)} - \alpha h(\mathbf{x}^{(i)}) t^{(i)}\right) \\ &= \sum_{i=1}^N \exp\left(-H_{m-1}(\mathbf{x}^{(i)}) t^{(i)}\right) \exp\left(-\alpha h(\mathbf{x}^{(i)}) t^{(i)}\right) \\ &= \sum_{i=1}^N w_i^{(m)} \exp\left(-\alpha h(\mathbf{x}^{(i)}) t^{(i)}\right).\end{aligned}$$

Here we defined $w_i^{(m)} \triangleq \exp\left(-H_{m-1}(\mathbf{x}^{(i)}) t^{(i)}\right)$.

Additive Models with Exponential Loss

We want to solve the following minimization problem:

$$(h_m, \alpha_m) \leftarrow \operatorname{argmin}_{h \in \mathcal{H}, \alpha} \sum_{i=1}^N w_i^{(m)} \exp(-\alpha h(\mathbf{x}^{(i)})t^{(i)}).$$

- If $h(\mathbf{x}^{(i)}) = t^{(i)}$, we have $\exp(-\alpha h(\mathbf{x}^{(i)})t^{(i)}) = \exp(-\alpha)$.
- If $h(\mathbf{x}^{(i)}) \neq t^{(i)}$, we have $\exp(-\alpha h(\mathbf{x}^{(i)})t^{(i)}) = \exp(+\alpha)$.

(recall that we are in the binary classification case with $\{-1, +1\}$ output values).
We can divide the summation to two parts:

$$\begin{aligned} \sum_{i=1}^N w_i^{(m)} \exp(-\alpha h(\mathbf{x}^{(i)})t^{(i)}) &= e^{-\alpha} \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h(\mathbf{x}^{(i)}) = t_i\} + e^{\alpha} \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\} \\ &= (e^{\alpha} - e^{-\alpha}) \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\} + \\ &\quad e^{-\alpha} \sum_{i=1}^N w_i^{(m)} \left[\mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\} + \mathbb{I}\{h(\mathbf{x}^{(i)}) = t_i\} \right] \end{aligned}$$

Additive Models with Exponential Loss

$$\begin{aligned}\sum_{i=1}^N w_i^{(m)} \exp\left(-\alpha h(\mathbf{x}^{(i)})t^{(i)}\right) &= (e^\alpha - e^{-\alpha}) \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\} + \\ &\quad e^{-\alpha} \sum_{i=1}^N w_i^{(m)} \left[\mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\} + \mathbb{I}\{h(\mathbf{x}^{(i)}) = t_i\} \right] \\ &= (e^\alpha - e^{-\alpha}) \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\} + e^{-\alpha} \sum_{i=1}^N w_i^{(m)}.\end{aligned}$$

Let us first optimize h :

The second term on the RHS does not depend on h . So we get

$$h_m \leftarrow \operatorname{argmin}_{h \in \mathcal{H}} \sum_{i=1}^N w_i^{(m)} \exp\left(-\alpha h(\mathbf{x}^{(i)})t^{(i)}\right) \equiv \operatorname{argmin}_{h \in \mathcal{H}} \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\}.$$

This means that h_m is the minimizer of the weighted 0/1-loss.

Additive Models with Exponential Loss

Now that obtained h_m , we want to find α : Define the weighted classification error:

$$\text{err}_m = \frac{\sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h_m(\mathbf{x}^{(i)}) \neq t^{(i)}\}}{\sum_{i=1}^N w_i^{(m)}}$$

With this definition and

$\min_{h \in \mathcal{H}} \sum_{i=1}^N w_i^{(m)} \exp(-\alpha h(\mathbf{x}^{(i)})t^{(i)}) = \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h_m(\mathbf{x}^{(i)}) \neq t_i\}$, we have

$$\begin{aligned} & \min_{\alpha} \min_{h \in \mathcal{H}} \sum_{i=1}^N w_i^{(m)} \exp(-\alpha h(\mathbf{x}^{(i)})t^{(i)}) = \\ & \min_{\alpha} \left\{ (e^{\alpha} - e^{-\alpha}) \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h_m(\mathbf{x}^{(i)}) \neq t_i\} + e^{-\alpha} \sum_{i=1}^N w_i^{(m)} \right\} \\ & = \min_{\alpha} \left\{ (e^{\alpha} - e^{-\alpha}) \text{err}_m \left(\sum_{i=1}^N w_i^{(m)} \right) + e^{-\alpha} \left(\sum_{i=1}^N w_i^{(m)} \right) \right\} \end{aligned}$$

Take derivative w.r.t. α and set it to zero. We get that

$$e^{2\alpha} = \frac{1 - \text{err}_m}{\text{err}_m} \Rightarrow \alpha = \frac{1}{2} \log \left(\frac{1 - \text{err}_m}{\text{err}_m} \right).$$

Additive Models with Exponential Loss

The updated weights for the next iteration is

$$\begin{aligned}w_i^{(m+1)} &= \exp\left(-H_m(\mathbf{x}^{(i)})t^{(i)}\right) \\&= \exp\left(-\left[H_{m-1}(\mathbf{x}^{(i)}) + \alpha_m h_m(\mathbf{x}^{(i)})\right]t^{(i)}\right) \\&= \exp\left(-H_{m-1}(\mathbf{x}^{(i)})t^{(i)}\right) \exp\left(-\alpha_m h_m(\mathbf{x}^{(i)})t^{(i)}\right) \\&= w_i^{(m)} \exp\left(-\alpha_m h_m(\mathbf{x}^{(i)})t^{(i)}\right) \\&= w_i^{(m)} \exp\left(-\alpha_m \left(2\mathbb{I}\{h_m(\mathbf{x}^{(i)}) = t^{(i)}\} - 1\right)\right) \\&= \exp(\alpha_m) w_i^{(m)} \exp\left(-2\alpha_m \mathbb{I}\{h_m(\mathbf{x}^{(i)}) = t^{(i)}\}\right).\end{aligned}$$

The term $\exp(\alpha_m)$ multiplies the weight corresponding to all samples, so it does not affect the minimization of h_{m+1} or α_{m+1} .

Additive Models with Exponential Loss

To summarize, we obtain the additive model $H_m(x) = \sum_{i=1}^m \alpha_i h_i(\mathbf{x})$ with

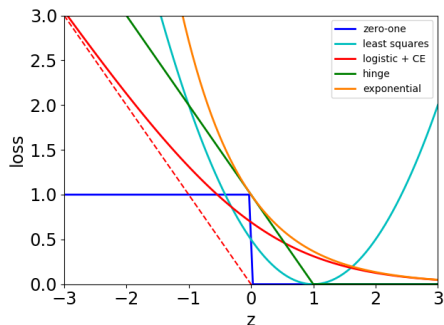
$$h_m \leftarrow \operatorname{argmin}_{h \in \mathcal{H}} \sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h(\mathbf{x}^{(i)}) \neq t_i\},$$

$$\alpha = \frac{1}{2} \log \left(\frac{1 - \operatorname{err}_m}{\operatorname{err}_m} \right), \quad \text{where } \operatorname{err}_m = \frac{\sum_{i=1}^N w_i^{(m)} \mathbb{I}\{h_m(\mathbf{x}^{(i)}) \neq t^{(i)}\}}{\sum_{i=1}^N w_i^{(m)}},$$

$$w_i^{(m+1)} = w_i^{(m)} \exp \left(-\alpha_m h_m(\mathbf{x}^{(i)}) t^{(i)} \right).$$

We derived the AdaBoost algorithm!

Revisiting Loss Functions for Classification



- If AdaBoost is minimizing exponential loss, what does that say about its behavior (compared to, say, logistic regression)?
- This interpretation allows boosting to be generalized to lots of other loss functions!