CSC 311: Introduction to Machine Learning

Lecture 2 - Decision Trees & Bias-Variance Decomposition

Rahul G. Krishnan

University of Toronto, Fall 2023

Outline

Goal of machine learning (supervised) is to model

$p(y|x)$?

y: labels

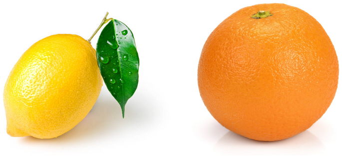
x: inputs

1. Introduction
2. Decision Trees
3. Bias-Variance Decomposition

Today

- Announcement: HW1 released this week
- Decision Trees
  - Simple but powerful learning algorithm
  - Used widely in Kaggle competitions
  - Lets us motivate concepts from information theory (entropy, mutual information, etc.)
- Bias-variance decomposition
  - Concept to motivate combining different classifiers.
- Ideas we will need in today's lecture
  - Trees [from algorithms]
  - Expectations, marginalization, chain rule [from probability]

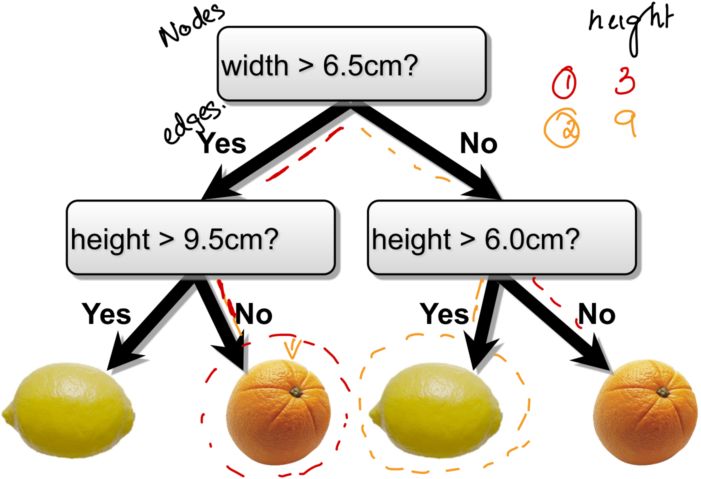
Lemons or Oranges



Scenario: You run a sorting facility for citrus fruits

- Binary classification: lemons or oranges
- Features measured by sensor on conveyor belt: height and width

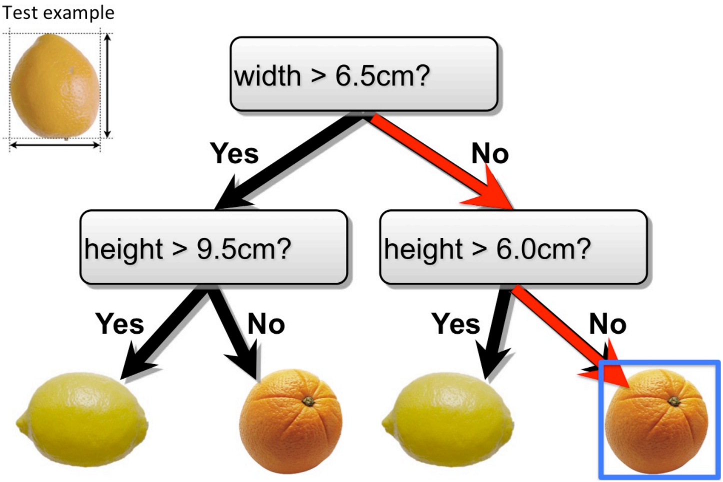
- Make predictions by splitting on features according to a tree structure.



	height	width.
1	3	10
2	9	3

Decision Trees

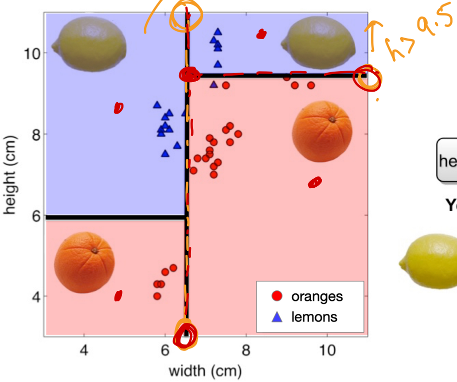
- Make predictions by splitting on features according to a tree structure.

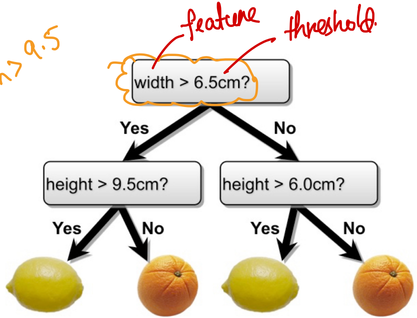


Decision Trees—Continuous Features

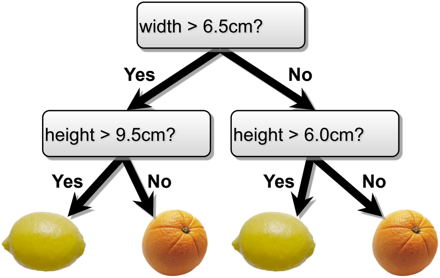
- Split *continuous features* by checking whether that feature is greater than or less than some threshold.
- Decision boundary is made up of axis-aligned planes.

training points at the leaf node.





Decision Trees



- Internal nodes test a feature
- Branching is determined by the feature value
- Leaf nodes are outputs (predictions)

Question: What are the hyperparameters of this model?

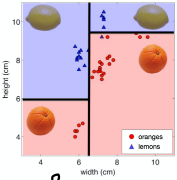
Decision Trees—Classification and Regression

- Each path from root to a leaf defines a region R_m of input space
- Let $\{(x^{(m_1)}, t^{(m_1)}), \ldots, (x^{(m_k)}, t^{(m_k)})\}$ be the training examples that fall into R_m
- $m = 4$ on the right and k is the same across each region

\# leafs

\# training points within the leaf region for a tree.

1 2



3 4.

m = 4

Decision Trees—Classification and Regression

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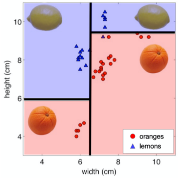
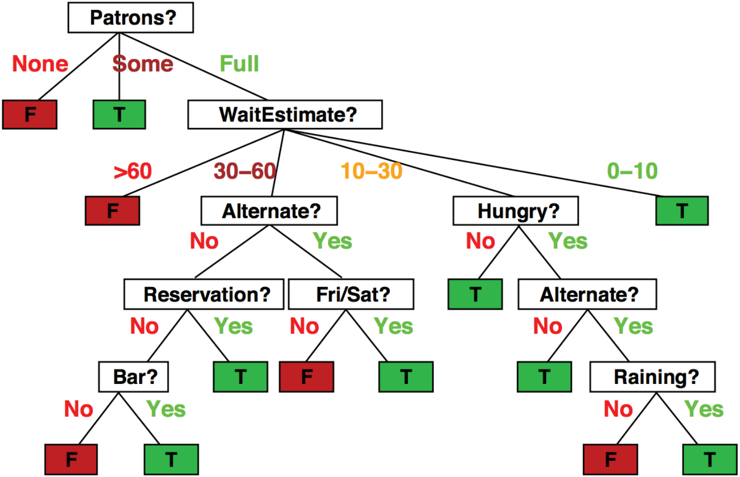


- Regression tree:
  - continuous output
  - leaf value y^m typically set to the mean value in $\{t^{(m_1)}, \ldots, t^{(m_k)}\}$
- Classification tree (we will focus on this):
  - discrete output
  - leaf value y^m typically set to the most common value in $\{t^{(m_1)}, \ldots, t^{(m_k)}\}$

Decision Trees—Discrete Features

- Will I eat at this restaurant?



Decision Trees—Discrete Features

- Split *discrete features* into a partition of possible values.

binary feature

categorical feature

Example	Input Attributes										Goal
	Alt	*Bar*	*Fri*	*Hun*	*Pat*	*Price*	*Rain*	*Res*	*Type*	*Est*	*WillWait*
$\mathbf{x}_1$	Yes	No	No	Yes	Some	$$$	No	Yes	French	0–10	$y_1 =$ Yes
$\mathbf{x}_2$	Yes	No	No	Yes	Full	$	No	No	Thai	30–60	$y_2 =$ No
$\mathbf{x}_3$	No	Yes	No	No	Some	$	No	No	Burger	0–10	$y_3 =$ Yes
$\mathbf{x}_4$	Yes	No	Yes	Yes	Full	$	Yes	No	Thai	10–30	$y_4 =$ Yes
$\mathbf{x}_5$	Yes	No	Yes	No	Full	$$$	No	Yes	French	>60	$y_5 =$ No
$\mathbf{x}_6$	No	Yes	No	Yes	Some	$$	Yes	Yes	Italian	0–10	$y_6 =$ Yes
$\mathbf{x}_7$	No	Yes	No	No	None	$	Yes	No	Burger	0–10	$y_7 =$ No
$\mathbf{x}_8$	No	No	No	Yes	Some	$$	Yes	Yes	Thai	0–10	$y_8 =$ Yes
$\mathbf{x}_9$	No	Yes	Yes	No	Full	$	Yes	No	Burger	>60	$y_9 =$ No
$\mathbf{x}_{10}$	Yes	Yes	Yes	Yes	Full	$$$	No	Yes	Italian	10–30	$y_{10} =$ No
$\mathbf{x}_{11}$	No	No	No	No	None	$	No	No	Thai	0–10	$y_{11} =$ No
$\mathbf{x}_{12}$	Yes	Yes	Yes	Yes	Full	$	No	No	Burger	30–60	$y_{12} =$ Yes

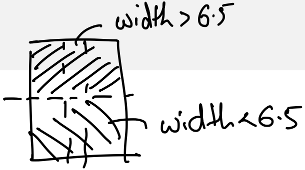
Features:

1.	Alternate: whether there is a suitable alternative restaurant nearby.
2.	Bar: whether the restaurant has a comfortable bar area to wait in.
3.	Fri/Sat: true on Fridays and Saturdays.
4.	Hungry: whether we are hungry.
5.	Patrons: how many people are in the restaurant (values are None, Some, and Full).
6.	Price: the restaurant's price range ($, $$, $$$).
7.	Raining: whether it is raining outside.
8.	Reservation: whether we made a reservation.
9.	Type: the kind of restaurant (French, Italian, Thai or Burger).
10.	WaitEstimate: the wait estimated by the host (0-10 minutes, 10-30, 30-60, >60).

Learning Decision Trees

- Decision trees are universal function approximators.
  - For any training set we can construct a decision tree that has exactly the one leaf for every training point, but it probably won't generalize.
  - Example - If all D features were binary, and we had $N = 2^D$ unique training examples, a **Full Binary Tree** would have one leaf per example.
- Finding the smallest decision tree that correctly classifies a training set is NP complete.
  - If you are interested, check: Hyafil & Rivest'76.
- So, how do we construct a useful decision tree?

Learning Decision Trees



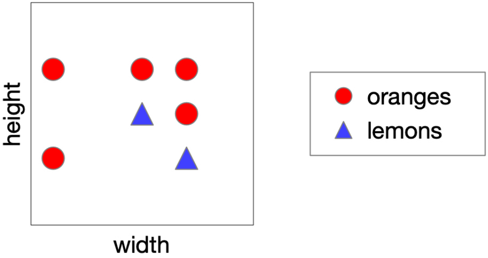
- Resort to a greedy heuristic:
  - Start with the whole training set and an empty decision tree.
  - Pick a feature and candidate split that would most reduce a loss
  - Split on that feature and recurse on subpartitions.

will come up again!

- What is a loss?
  - When learning a model, we use a scalar number to assess whether we're on track
  - Scalar value: low is good, high is bad
- Which loss should we use?

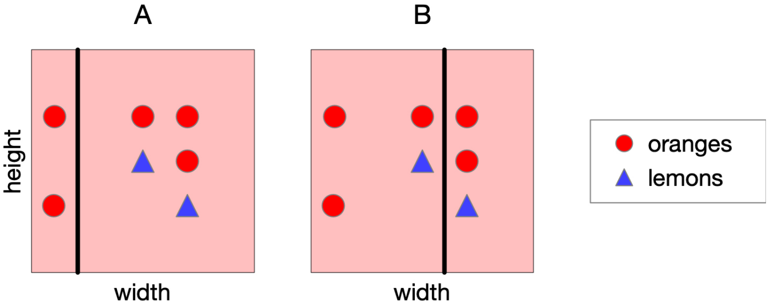
Choosing a Good Split

- Consider the following data. Let's split on width.
- Classify by majority.



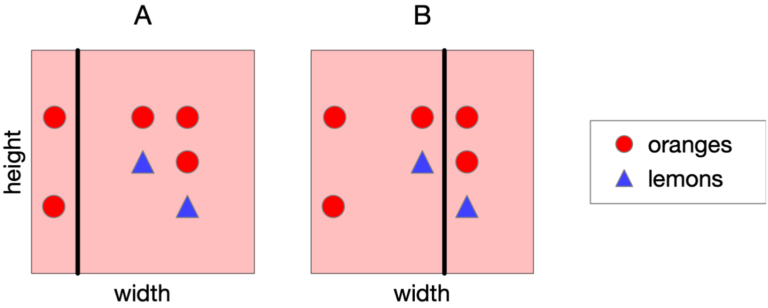
Choosing a Good Split

- Which is the best split? Vote!



Choosing a Good Split

- A feels like a better split, because the left-hand region is very certain about whether the fruit is an orange.
- Can we quantify this?



Choosing a Good Split

- How can we quantify uncertainty in prediction for a given leaf node?
  - If all examples in leaf have same class: good, low uncertainty
  - If each class has same amount of examples in leaf: bad, high uncertainty
- **Idea:** Use counts at leaves to define probability distributions; use a probabilistic notion of uncertainty to decide splits.
- A brief detour through information theory...

Note: We will consistently borrow tools from probability theory to model phenomena in data.

Entropy - Quantifying uncertainty

- You may have encountered the term entropy quantifying the state of chaos in chemical and physical systems,
- In statistics, it is a property of a random variable,
- The entropy of a discrete random variable is a number that quantifies the uncertainty inherent in its possible outcomes.
- The mathematical definition of entropy that we give in a few slides may seem arbitrary, but it can be motivated axiomatically.
  - If you're interested, check: *Information Theory* by Robert Ash or Elements of Information Theory by Cover and Thomas.
- To explain entropy, consider flipping two different coins...

We Flip Two Different Coins

Each coin is a binary random variable with outcomes 1 or 0:

Sequence 1:
`0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 1 0 0 ... ?`

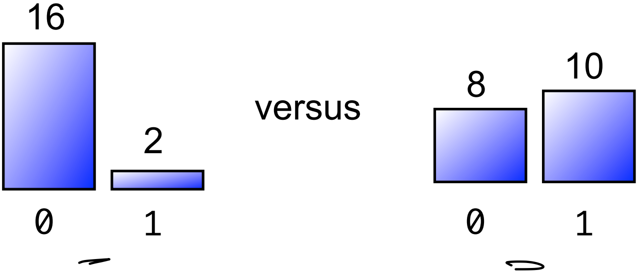
Sequence 2:
`0 1 0 1 0 1 1 1 0 1 0 0 1 1 0 1 0 1 ... ?`

We Flip Two Different Coins

Each coin is a binary random variable with outcomes 1 or 0:

Sequence 1:
0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 1 0 0 ... ?

Sequence 2:
0 1 0 1 0 1 1 1 0 1 0 0 1 1 0 1 0 1 ... ?



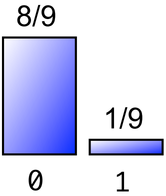
Quantifying Uncertainty

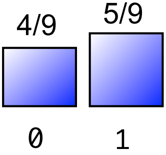
- The entropy of a loaded coin with probability p of heads is given by

$$-p\log_2(p) - (1-p)\log_2(1-p)$$

p = 8/9

p = 4/9





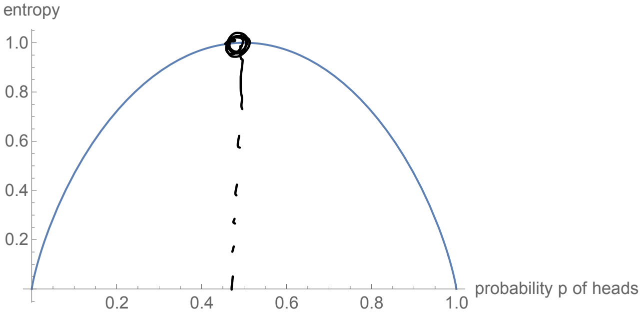
$$-\frac{8}{9}\log_2\frac{8}{9} - \frac{1}{9}\log_2\frac{1}{9} \approx \frac{1}{2}$$

$$-\frac{4}{9}\log_2\frac{4}{9} - \frac{5}{9}\log_2\frac{5}{9} \approx 0.99$$

- Notice: the coin whose outcomes are more certain has a lower entropy.
- In the extreme case $p = 0$ or $p = 1$, we were certain of the outcome before observing. So, we gained no certainty by observing it, i.e., entropy is 0.

Quantifying Uncertainty

- Can also think of entropy as the expected information content of a random draw from a probability distribution.



- Claude Shannon showed: you cannot store the outcome of a random draw using fewer expected bits than the entropy without losing information.
- So units of entropy are bits; a fair coin flip has 1 bit of entropy.

Entropy

- More generally, the entropy of a discrete random variable Y is given by

$$H(Y) = -\sum_{y \in Y} p(y) \log_2 p(y)$$

1	2	3
0.3	0.2	0.5

log 0.3 log 0.2 log 0.5

$H(Y) = -\big(0.3 \log 0.3 + 0.2 \log 0.2 + 0.5 \log 0.5 \big)$

- **"High Entropy"**:
  - Variable has a uniform like distribution over many outcomes
  - Flat histogram
  - Values sampled from it are less predictable

e.g $Y \in \{0, 1, 2\}$

$P(Y=0) = 0.3$

$P(Y=1) = 0.3$

$P(Y=2) = 0.3$

[Slide credit: Vibhav Gogate]

Entropy

- More generally, the entropy of a discrete random variable Y is given by

$$H(Y) = -\sum_{y \in Y} p(y) \log_2 p(y)$$

- **"High Entropy"**:
  - Variable has a uniform like distribution over many outcomes
  - Flat histogram
  - Values sampled from it are less predictable
- **"Low Entropy"**
  - Distribution is concentrated on only a few outcomes
  - Histogram is concentrated in a few areas
  - Values sampled from it are more predictable

e.g $Y \in \{0, 1, 2\}$ & $P(Y=0) = 0.8$

$P(Y=1) = 0.15$

$P(Y=2) = 0.05$

[Slide credit: Vibhav Gogate]

Entropy

- Suppose we observe partial information X about a random variable Y
  - For example, $X = \text{sign}(Y)$.
- We want to work towards a definition of the expected amount of information that will be conveyed about Y by observing X.
  - Or equivalently, the expected reduction in our uncertainty about Y after observing X.

Entropy of a Joint Distribution

- Example: $X = \{\text{Raining, Not raining}\}$, $Y = \{\text{Cloudy, Not cloudy}\}$

Y

X	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

$$
\begin{aligned}
H(X,Y) &= \boxed{-\sum_{x \in X} \sum_{y \in Y} p(x,y) \log_2 p(x,y)} \\
&= -\frac{24}{100}\log_2\frac{24}{100} - \frac{1}{100}\log_2\frac{1}{100} - \frac{25}{100}\log_2\frac{25}{100} - \frac{50}{100}\log_2\frac{50}{100} \\
&\approx \underline{1.56\text{bits}}
\end{aligned}
$$

Conditional Entropy

- Example: $X = \{\text{Raining, Not raining}\}$, $Y = \{\text{Cloudy, Not cloudy}\}$

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

Marginal of x
$p(x = \text{raining})$
$= 24/100 + 1/100$
$= 25/100$

- What is the entropy of cloudiness Y, **given that it is raining**?

$$H(Y|X=x) = \boxed{-\sum_{y \in Y} p(y|x) \log_2 p(y|x)}$$
$$= -\frac{24}{25}\log_2\frac{24}{25} - \frac{1}{25}\log_2\frac{1}{25}$$
$$\approx 0.24\text{bits}$$

- We used: $\boxed{p(y|x) = \frac{p(x,y)}{p(x)},}$ and $\boxed{p(x) = \sum_y p(x,y)}$ (sum in a row)

Conditional Entropy

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

- The expected conditional entropy:

$$
\begin{aligned}
H(Y|X) &= \mathbb{E}_x[H[Y|x]] \\
&= \sum_{x \in X} p(x) H(Y|X=x) \\
&= -\sum_{x \in X} \sum_{y \in Y} p(x,y) \log_2 p(y|x)
\end{aligned}
$$

$H(Y|X=\text{rain}) \cdot P(X=\text{rain}) + H(Y|X=\text{no rain}) \cdot P(X=\text{no rain})$

Conditional Entropy

- Example: $X = \{\text{Raining, Not raining}\}$, $Y = \{\text{Cloudy, Not cloudy}\}$

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

Note the difference relative to $H(Y|X=x)$

- What is the entropy of cloudiness, given the knowledge of whether or not it is raining?

$$
\begin{aligned}
H(Y|X) &= \sum_{x \in X} p(x) H(Y|X=x) \\
&= \underbrace{\tfrac{1}{4}}_{p(\text{rain})} H(\text{cloudy}|\text{is raining}) + \underbrace{\tfrac{3}{4}}_{p(\text{not raining})} H(\text{cloudy}|\text{not raining}) \\
&\approx 0.75 \text{ bits}
\end{aligned}
$$

Conditional Entropy

Entropy → Joint distribution of R.Vs → Conditional Entropy → Expected C. Entropy

- Some useful properties:
  - H is always non-negative
  - Chain rule: $H(X,Y) = H(X|Y) + H(Y) = H(Y|X) + H(X)$
  - If X and Y independent, then X does not affect our uncertainty about Y: $H(Y|X) = H(Y)$
  - But knowing Y makes our knowledge of Y certain: $H(Y|Y) = 0$
  - By knowing X, we can only decrease uncertainty about Y: $H(Y|X) \leq H(Y)$

Information Gain

	Cloudy	Not Cloudy
Raining	24/100	1/100
Not Raining	25/100	50/100

- How much more certain am I about whether it's cloudy if I'm told whether it is raining? My uncertainty in Y minus my expected uncertainty that would remain in Y after seeing X.
- This is called the information gain $IG(Y|X)$ in Y due to X, or the mutual information of Y and X

$$IG(Y|X) = H(Y) - H(Y|X) \tag{1}$$

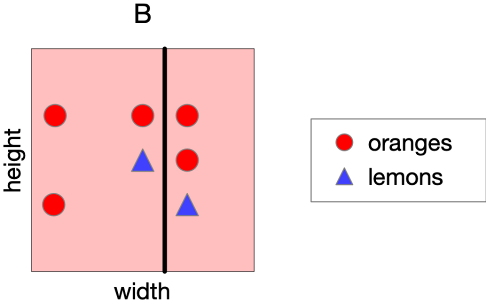
- If X is completely uninformative about Y: $IG(Y|X) = 0$
- If X is completely informative about Y: $IG(Y|X) = H(Y)$

Revisiting Our Original Example

- Information gain measures the informativeness of a variable, which is exactly what we desire in a decision tree split!
- The information gain of a split: how much information (over the training set) about the class label Y is gained by knowing which side of a split you're on.

Information Gain of Split B

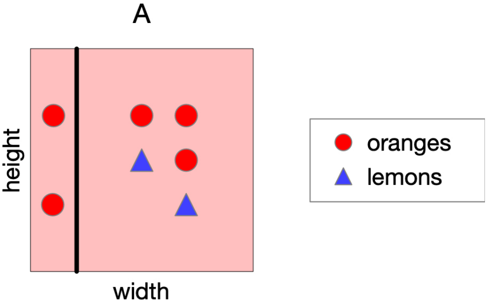
- What is the information gain of split B? Not terribly informative...



- Entropy of class outcome before split:
  $H(Y) = -\frac{2}{7}\log_2(\frac{2}{7}) - \frac{5}{7}\log_2(\frac{5}{7}) \approx 0.86$
- Conditional entropy of class outcome after split:
  $H(Y|left) \approx 0.81$, $H(Y|right) \approx 0.92$
- $IG(split) \approx 0.86 - (\frac{4}{7} \cdot 0.81 + \frac{3}{7} \cdot 0.92) \approx 0.006$

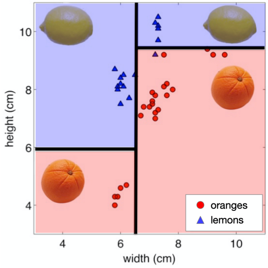
Information Gain of Split A

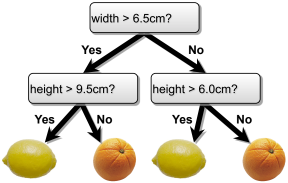
- What is the information gain of split A? Very informative!



- Entropy of class outcome before split:
  $H(Y) = -\frac{2}{7}\log_2(\frac{2}{7}) - \frac{5}{7}\log_2(\frac{5}{7}) \approx 0.86$
- Conditional entropy of class outcome after split:
  $H(Y|left) = 0$, $H(Y|right) \approx 0.97$
- $IG(split) \approx 0.86 - (\frac{2}{7}\cdot 0 + \frac{5}{7}\cdot 0.97) \approx 0.17!!$

Constructing Decision Trees





- At each level, one must choose:
    1. Which feature to split.
    2. Possibly where to split it.
- Choose them based on how much information we would gain from the decision! (choose feature that gives the highest gain)

Decision Tree Construction Algorithm

- Simple, greedy, recursive approach, builds up tree node-by-node
  1. pick a feature to split at a non-terminal node
  2. split examples into groups based on feature value
  3. for each group:
     - if no examples – return majority from parent
     - else if all examples in same class – return class
     - else loop to step 1
- Terminates when all leaves contain only examples in the same class or are empty.
- Questions for discussion:
  - How do you choose the feature to split on?
  - How do you choose the threshold for each feature?

Back to Our Example

Example	Input Attributes										Goal
	Alt	*Bar*	*Fri*	*Hun*	*Pat*	*Price*	*Rain*	*Res*	*Type*	*Est*	*WillWait*
$\mathbf{x}_1$	Yes	No	No	Yes	Some	$$$	No	Yes	French	0–10	$y_1 =$ Yes
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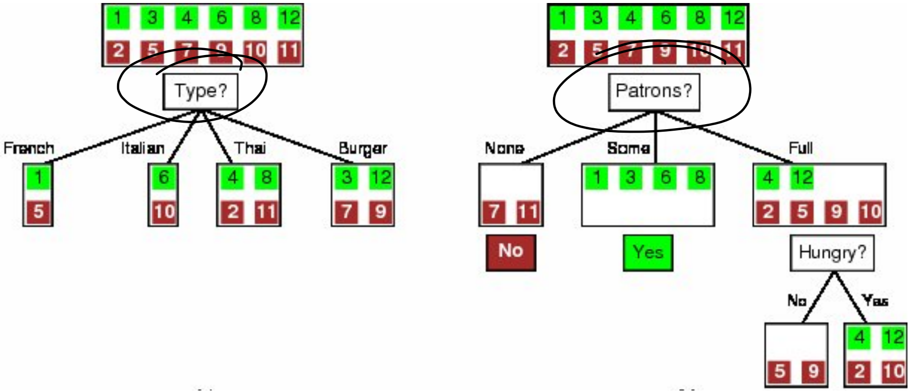
$\mathbf{x}_9$	No	Yes	Yes	No	Full	$	Yes	No	Burger	>60	$y_9 =$ No
$\mathbf{x}_{10}$	Yes	Yes	Yes	Yes	Full	$$$	No	Yes	Italian	10–30	$y_{10} =$ No
$\mathbf{x}_{11}$	No	No	No	No	None	$	No	No	Thai	0–10	$y_{11} =$ No
$\mathbf{x}_{12}$	Yes	Yes	Yes	Yes	Full	$	No	No	Burger	30–60	$y_{12} =$ Yes

Features:

1.	Alternate: whether there is a suitable alternative restaurant nearby.
2.	Bar: whether the restaurant has a comfortable bar area to wait in.
3.	Fri/Sat: true on Fridays and Saturdays.
4.	Hungry: whether we are hungry.
5.	Patrons: how many people are in the restaurant (values are None, Some, and Full).
6.	Price: the restaurant's price range ($, $$, $$$).
7.	Raining: whether it is raining outside.
8.	Reservation: whether we made a reservation.
9.	Type: the kind of restaurant (French, Italian, Thai or Burger).
10.	WaitEstimate: the wait estimated by the host (0-10 minutes, 10-30, 30-60, >60).

[from: Russell & Norvig]

Feature Selection

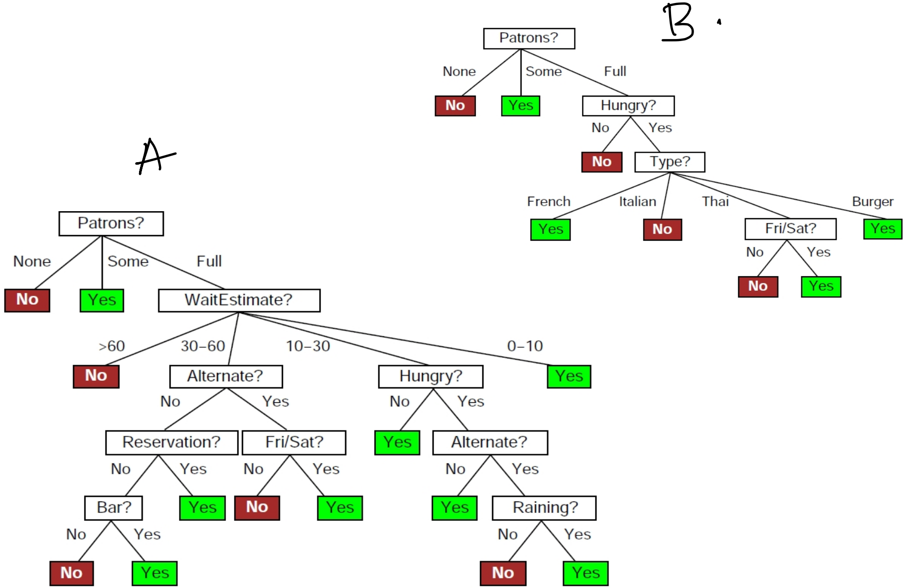


$$IG(Y) = H(Y) - H(Y|X)$$

$$IG(type) = 1 - \left[\frac{2}{12}H(Y|\text{Fr.}) + \frac{2}{12}H(Y|\text{It.}) + \frac{4}{12}H(Y|\text{Thai}) + \frac{4}{12}H(Y|\text{Bur.})\right] = 0$$

$$IG(Patrons) = 1 - \left[\frac{2}{12}H(0,1) + \frac{4}{12}H(1,0) + \frac{6}{12}H(\frac{2}{6}, \frac{4}{6})\right] \approx 0.541$$

Which Tree is Better? Vote!



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- We desire small trees with informative nodes near the root

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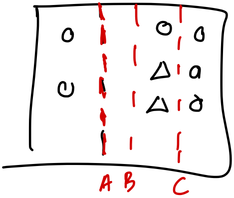

A & B will have the same IG

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- Decision trees can also be used for regression on real-valued outputs. Choose splits to minimize squared error, rather than maximize information gain.

KNN versus Decision Trees

Advantages of decision trees over KNNs

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Advantages of KNNs over decision trees

- Few hyperparameters
- Can incorporate interesting distance measures (e.g. shape contexts)

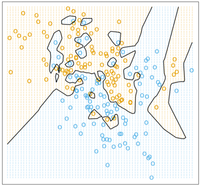
- We've seen many classification algorithms.
- We can combine multiple classifiers into an ensemble, which is a set of predictors whose individual decisions are combined in some way to classify new examples
  - E.g., (possibly weighted) majority vote
- For this to be nontrivial, the classifiers must differ somehow, e.g.
  - Different algorithm
  - Different choice of hyperparameters
  - Trained on different data
  - Trained with different weighting of the training examples
- Next lecture, we will study some specific ensembling techniques.

- Today, we deepen our understanding of generalization through a bias-variance decomposition.
  - This will help us understand ensembling methods.
- What is generalization?
  - Ability of a model to correctly classify/predict from unseen examples (from the same distribution that the training data was drawn from).
  - **Why does this matter?** Gives us confidence that the model has correctly captured the right patterns in the training data and will work when deployed.

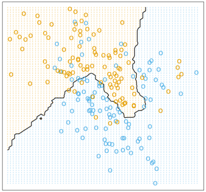
Bias-Variance Decomposition

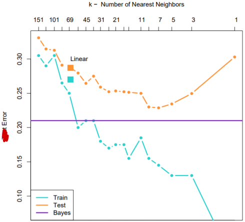
- Overly simple models underfit the data, and overly complex models overfit.
- We can quantify underfitting and overfitting in terms of the bias/variance decomposition.

k=1



k=15





Basic Setup for Classification

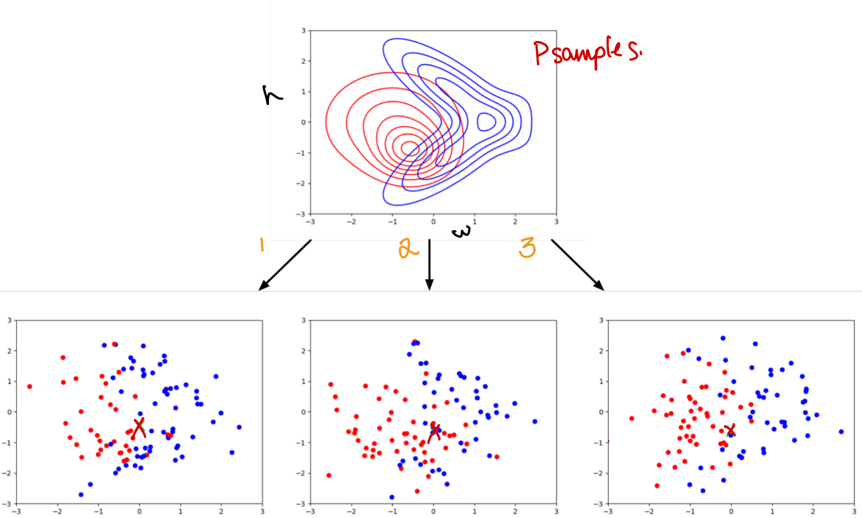
Unknown process that dictates how labels are generated ~ a function of inputs.

$p(t|x)$ - label distribution

- p_{sample} is a $\boxed{\text{data generating distribution}}$.
  For lemons and oranges, p_{sample} characterizes heights and widths.
- Pick a fixed query point $\mathbf{x}$ (denoted with a green x).
  We want to get a prediction y at $\mathbf{x}$.
- A training set $\mathcal{D}$ consists of pairs $(\mathbf{x}_i, t_i)$ sampled independent and identically distributed (i.i.d.) from p_{sample}.
- We can sample lots of training sets independently from $\boxed{p_{\text{sample}}}$.

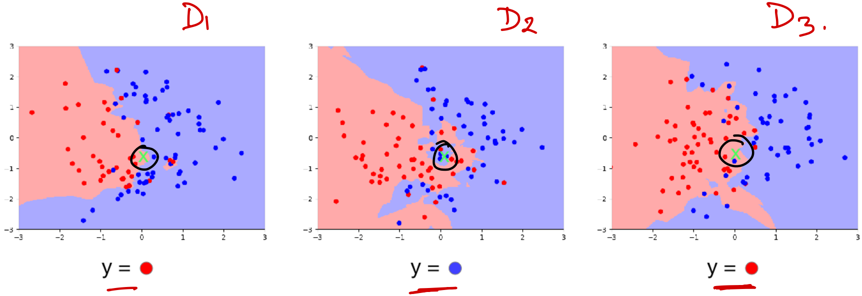
Typically no other knowledge of this but we'll pretend we can sample from this.

Basic Setup for Classification

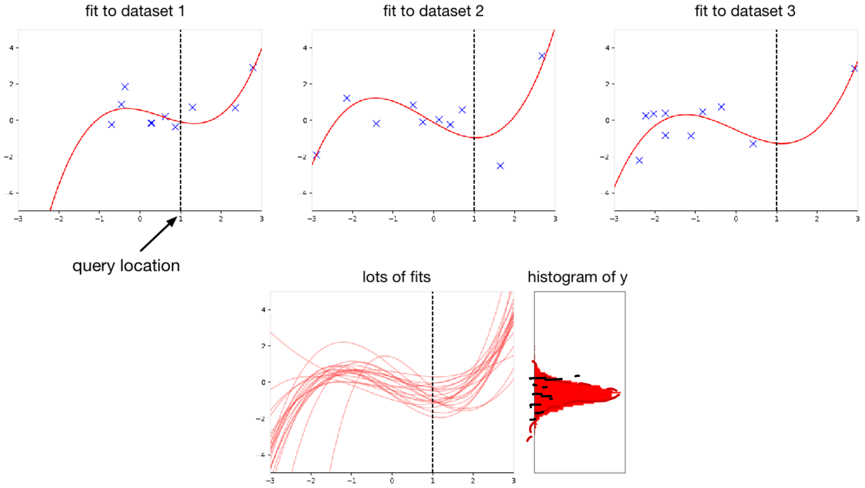


Basic Setup for Classification

- Run our learning algorithm on each training set, and compute its prediction y at the query point $\mathbf{x}$.
- We can view y as a random variable, where the randomness comes from the choice of training set.
- The classification accuracy is determined by the distribution of y.
- Since y is a random variable, we can compute its expectation, variance, etc.



Basic Setup for Regression



Basic Setup

- Fix a query point $\mathbf{x}$.
- Repeat:
  - Sample a random training dataset $\mathcal{D}$ i.i.d. from the data generating distribution p_{sample}.
  - Run the learning algorithm on $\mathcal{D}$ to get a prediction y at $\mathbf{x}$.
  - Sample the (true) target from the conditional distribution $p(t|\mathbf{x})$.
  - Compute the loss $\boxed{L(y, t).}$ - How close is my prediction to the ground truth.

Comments:

- Notice: y is independent of t. (Why?)

Basic Setup

- Fix a query point $\mathbf{x}$.
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Comments:

- Notice: y is independent of t. (Why?)
- This gives a distribution over the loss at $\mathbf{x}$, with expectation $\mathbb{E}[L(y,t) \,|\, \mathbf{x}]$.
- For each query point $\mathbf{x}$, the expected loss is different. We are interested in minimizing the expectation of this with respect to $\mathbf{x} \sim p_{\text{sample}}$.

Choosing a prediction y

- Consider squared error loss, $L(y,t) = \frac{1}{2}(y-t)^2$.
- Suppose that we knew the conditional distribution $p(t \mid \mathbf{x})$. What value of y should we predict?
  - Treat t as a random variable and choose y.

Choosing a prediction y

- Consider squared error loss, $L(y, t) = \frac{1}{2}(y - t)^2$.
- Suppose that we knew the conditional distribution $p(t \mid \mathbf{x})$. What value of y should we predict?
  - Treat t as a random variable and choose y.
- **Claim:** $y_* = \mathbb{E}[t \mid \mathbf{x}]$ is the best possible prediction.
- **Proof:**

$$
\begin{aligned}
\mathbb{E}_t[(y - t)^2 \mid \mathbf{x}] &= \mathbb{E}[y^2 - 2yt + t^2 \mid \mathbf{x}] && \text{(open up square)} \\
&= y^2 - 2y\mathbb{E}[t \mid \mathbf{x}] + \mathbb{E}[t^2 \mid \mathbf{x}] && \text{(linearity of expectation)} \\
&= y^2 - 2y\mathbb{E}[t \mid \mathbf{x}] + \mathbb{E}[t \mid \mathbf{x}]^2 + \mathrm{Var}[t \mid \mathbf{x}] && \star \\
&= y^2 - 2yy_* + y_*^2 + \mathrm{Var}[t \mid \mathbf{x}] && \text{(set } y^* = \mathbb{E}[t \mid x]\text{)} \\
&= (y - y_*)^2 + \mathrm{Var}[t \mid \mathbf{x}] && \text{(complete the square)}
\end{aligned}
$$

$\mathrm{Var}[t \mid x] = \mathbb{E}[t^2 \mid x] - (\mathbb{E}[t \mid x])^2$ $\star$

Bayes Optimality

$$\mathbb{E}[(y-t)^2 \mid \mathbf{x}] = (y-y_*)^2 + \mathrm{Var}[t \mid \mathbf{x}]$$

- The first term is nonnegative, and can be made 0 by setting $y = y_*$.
- The second term is the Bayes error, or
  the noise or inherent unpredictability of the target t.
  - An algorithm that achieves it is Bayes optimal.
  - This term doesn't depend on y.
  - Best we can ever hope to do with any learning algorithm.
- This process of choosing a single value y_* based on $p(t \mid \mathbf{x})$ is an example of decision theory.

Decomposition Continued

- Now let's treat y as a random variable (where the randomness comes from the choice of dataset).
- We can decompose the expected loss further (suppressing the conditioning on $\mathbf{x}$ for clarity):

$$
\begin{aligned}
\mathop{\mathbb{E}}_{t,y}[(y-t)^2] &= \mathop{\mathbb{E}}_{y}[(y-y_\star)^2] + \mathrm{Var}(t) \\
&= \mathbb{E}[y_\star^2 - 2y_\star y + y^2] + \mathrm{Var}(t) \\
&= y_\star^2 - 2y_\star \mathbb{E}[y] + \mathbb{E}[y^2] + \mathrm{Var}(t) \\
&= y_\star^2 - 2y_\star \mathbb{E}[y] + \mathbb{E}[y]^2 + \mathrm{Var}(y) + \mathrm{Var}(t) \\
&= \underbrace{(y_\star - \mathbb{E}[y])^2}_{\text{bias}} + \underbrace{\mathrm{Var}(y)}_{\text{variance}} + \underbrace{\mathrm{Var}(t)}_{\text{Bayes error}}
\end{aligned}
$$

Bayes Optimality

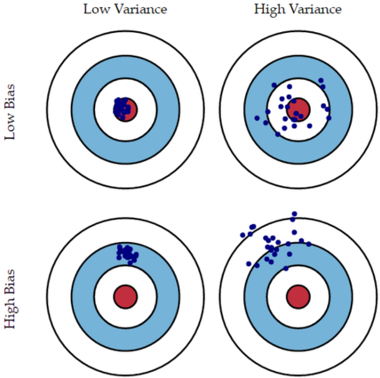
$$\mathbb{E}[(y-t)^2] = \underbrace{(y_\star - \mathbb{E}[y])^2}_{\text{bias}} + \underbrace{\mathrm{Var}(y)}_{\text{variance}} + \underbrace{\mathrm{Var}(t)}_{\text{Bayes error}}$$

We split the expected loss into three terms:

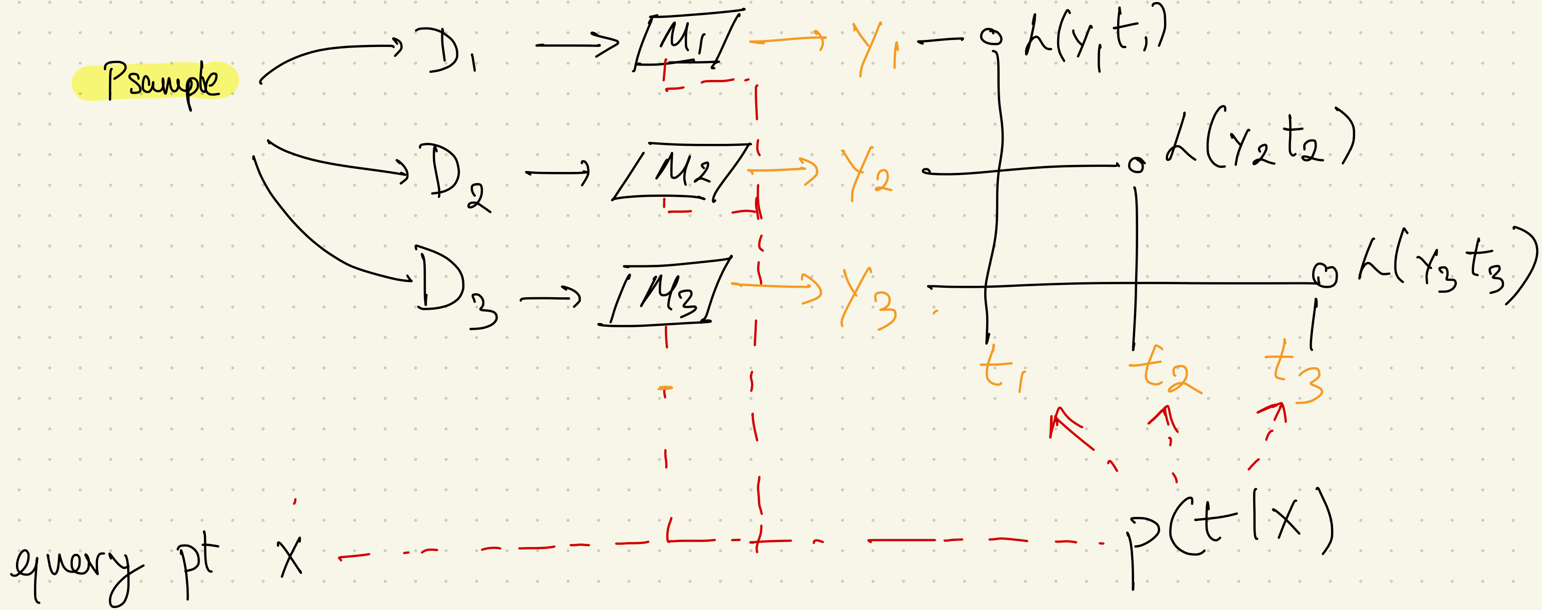
- bias: how wrong the expected prediction is (corresponds to underfitting)
- variance: the amount of variability in the predictions (corresponds to overfitting)
- Bayes error: the inherent unpredictability of the targets

Bias and Variance

- Throwing darts = predictions for each draw of a dataset



- Be careful, what doesn't this capture?
  - We average over points $\mathbf{x}$ from the data distribution.



Flow diagram for bias variance decomposition.