Computer Graphics

CSC 418/2504

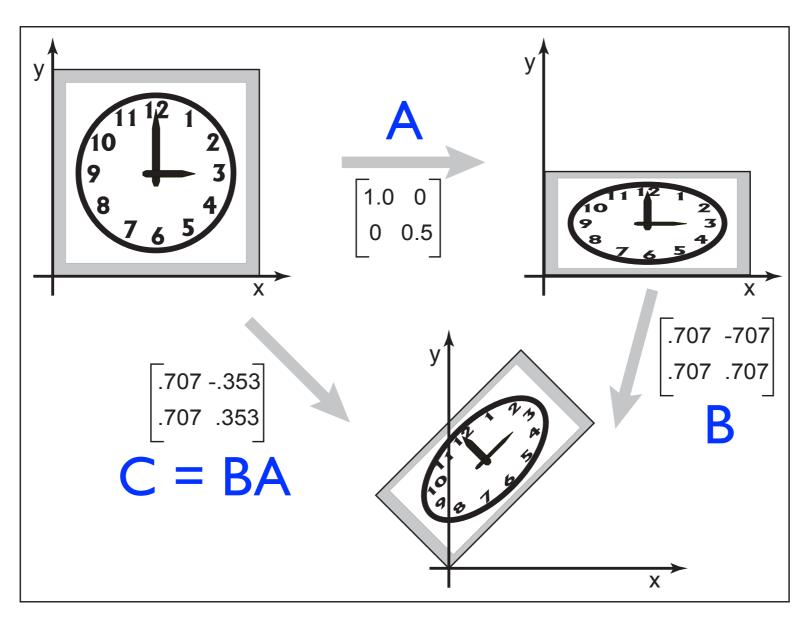
Patricio Simari September 28, 2011

Coordinate-free geometry slides courtesy of Patrick Coleman Composition figure courtesy of Peter Shirley

Today

- Homogeneous coordinates
- Coordinate-free geometry
- 3D geometric primitives

Composition



$$B(Ax) = (BA)x = Cx$$

Translation: Special Case

$$\begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} t_x \\ t_y \end{bmatrix}$$

```
\begin{bmatrix} & \mathbf{I} & \mathbf{0} & t_x \\ & \mathbf{0} & \mathbf{I} & t_y \\ & \mathbf{0} & \mathbf{0} & \mathbf{I} \end{bmatrix} \begin{bmatrix} & x \\ & y \\ & \mathbf{I} \end{bmatrix} = \begin{bmatrix} & x + t_x \\ & y + t_y \\ & \mathbf{I} \end{bmatrix}
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$$rotate(\phi) = \begin{bmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

```
\begin{bmatrix} a_{11} & a_{12} & t_x \\ a_{21} & a_{22} & t_y \\ 0 & 0 & I \end{bmatrix} \begin{bmatrix} x \\ y \\ I \end{bmatrix} = \begin{bmatrix} a_{11}x + a_{12}y + t_x \\ a_{21}x + a_{22}y + t_y \\ I \end{bmatrix}
```

Coordinate Free Geometry

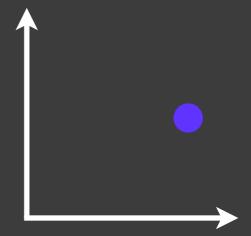
A style of expressing geometric computations that avoids explicit use of coordinates

Easier derivations

Far simpler code

CFG Quantities

Point: location in space



Vector: direction in space

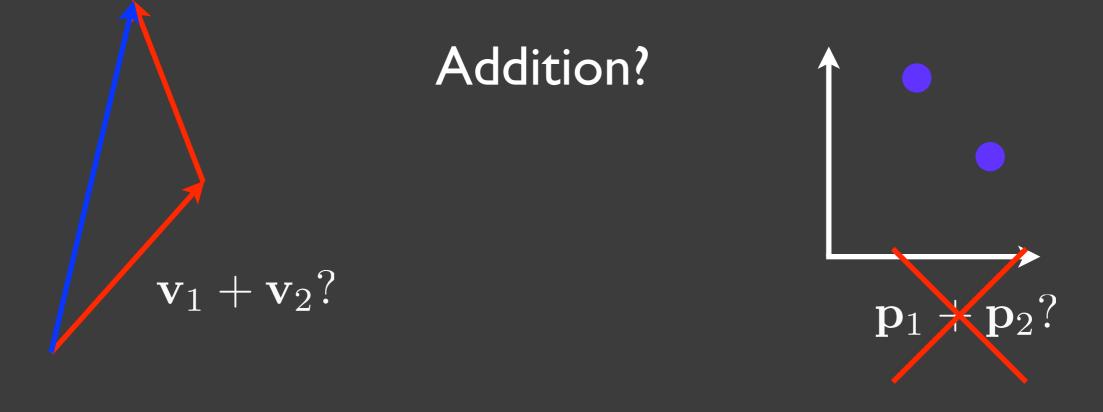
Scalar: real number

Points vs. Vectors

A point is not a vector.

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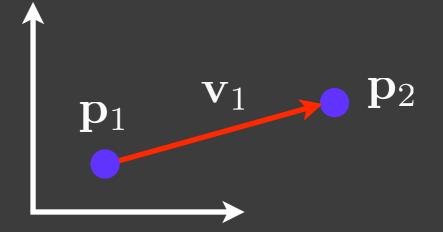


Magnitude of a vector

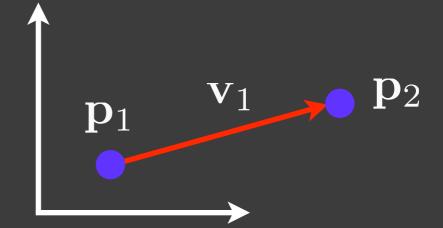
 $||\mathbf{v}||$

Point-vector addition

$$\mathbf{p}_1 + \mathbf{v}_1 = \mathbf{p}_2$$

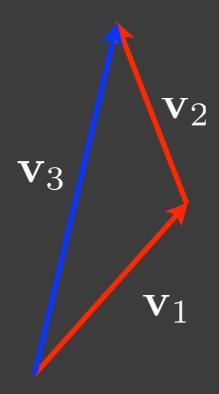


$$\mathbf{p}_2 - \mathbf{p}_1 = \mathbf{v}_1$$



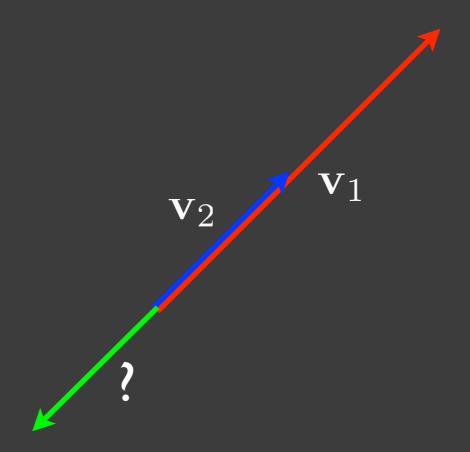
Vector addition

$$\mathbf{v}_1 + \mathbf{v}_2 = \mathbf{v}_3$$



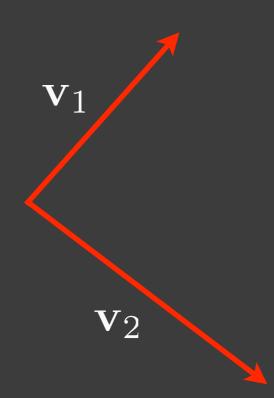
Vector scaling

$$\alpha \mathbf{v}_1 = \mathbf{v}_2$$



Dot product

$$\mathbf{v}_1 \cdot \mathbf{v}_2$$



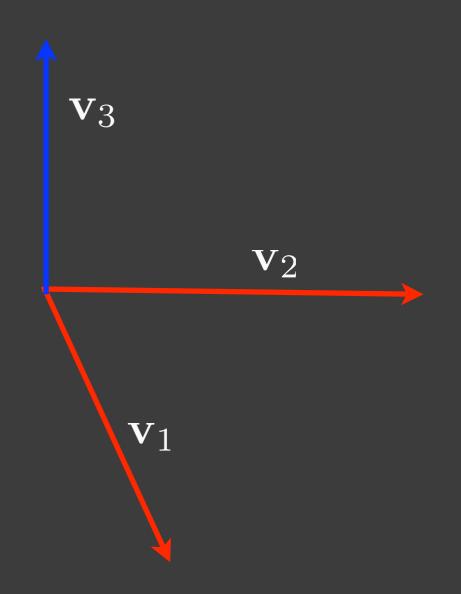
$$\mathbf{v}_1 \cdot \mathbf{v}_2 = \mathbf{v}_1^T \mathbf{v}_2 = ||\mathbf{v}_1|| \ ||\mathbf{v}_2|| \cos(\theta)$$

Cross product (3D)

$$\mathbf{v}_1 imes \mathbf{v}_2 = egin{bmatrix} \mathbf{x} & \mathbf{y} & \mathbf{z} \ x_1 & y_1 & z_1 \ x_2 & y_2 & z_2 \ \end{bmatrix}$$

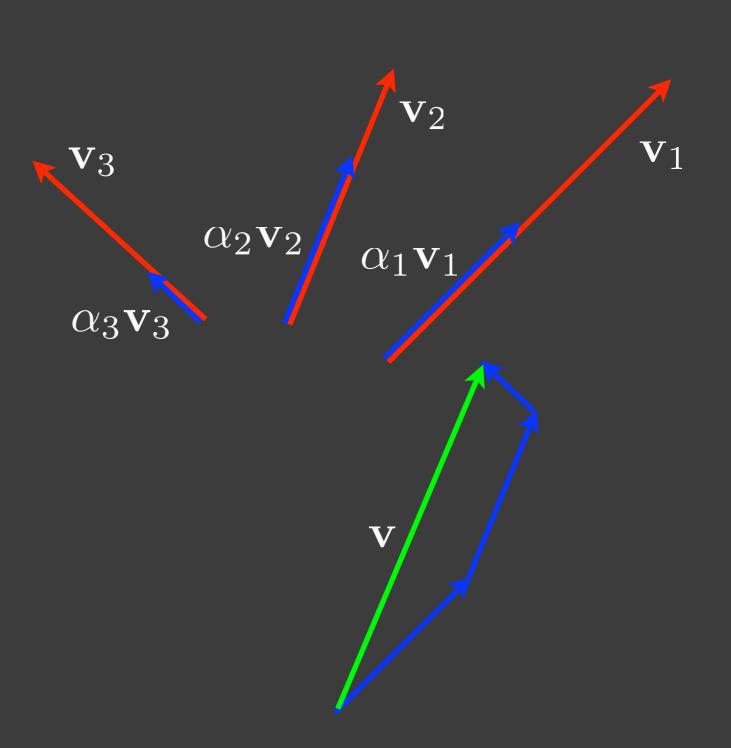
$$||\mathbf{v}_1 \times \mathbf{v}_2|| = ||\mathbf{v}_1|| ||\mathbf{v}_2|| \sin(\theta)$$

Right hand rule



Linear combination of vectors

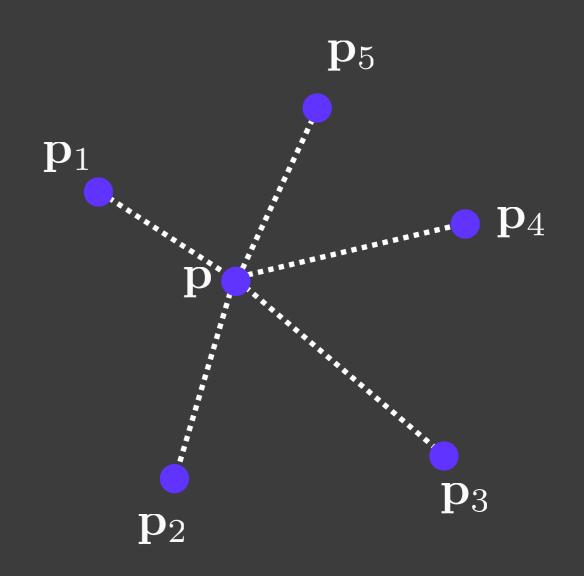
$$\sum_{i} \alpha_{i} \mathbf{v}_{i} = \mathbf{v}$$



Affine combination of points

$$\sum_{i} \alpha_{i} \mathbf{p}_{i} = \mathbf{p}$$

where
$$\sum_{i} \alpha_{i} = 1$$



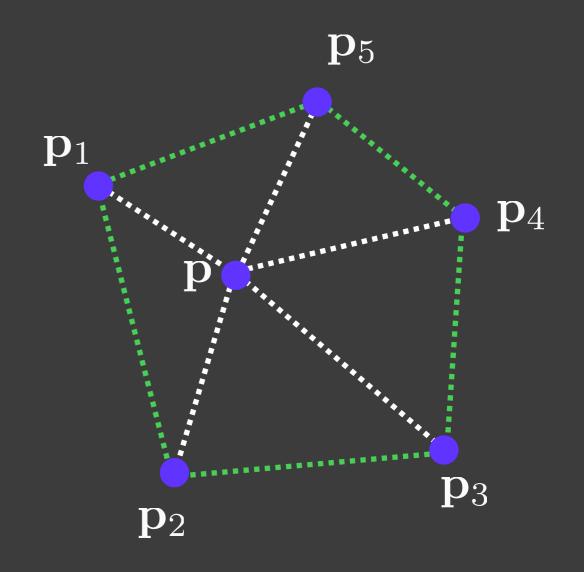
Affine combination of points

$$\sum_{i} \alpha_{i} \mathbf{p}_{i} = \mathbf{p}$$

where
$$\sum_{i} \alpha_{i} = 1$$

$$\alpha_3 = 1$$

$$lpha_3=1$$
 ? $lpha_i>=0$?

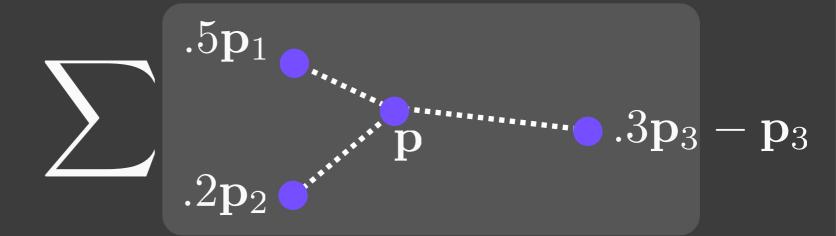


Vectors as restricted point combination

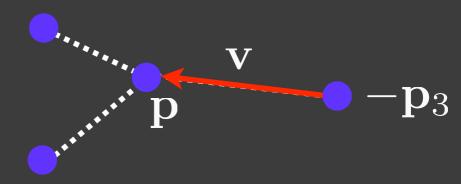
$$\sum_{i=1}^{n} \frac{1}{2\mathbf{p}_2} \mathbf{p}_2 \mathbf{$$

$$\sum_{i} \alpha_{i} \mathbf{p}_{i} = \mathbf{v}$$

where $\sum_{i} \alpha_{i} = 0$



Example...



Everything Else

Undefined

CFG Reasoning Example

$$\mathbf{p}_1$$
 $\mathbf{p}_m = ?$
 $\mathbf{p}_m = \frac{1}{2} \left(\mathbf{p}_1 + \mathbf{p}_2 \right)$
 $\mathbf{p}_m = \frac{1}{2} \mathbf{p}_1 + \frac{1}{2} \mathbf{p}_2$

$$\mathbf{p}_{m} = ?$$
 $\mathbf{p}_{m} = \mathbf{p}_{1} + \frac{1}{2} \left(\mathbf{p}_{2} - \mathbf{p}_{1} \right)$

3D Geometric Primitives

To the Board