## CSC304

## Algorithmic Game Theory \& Mechanism Design

## Nisarg Shah

## Recap

- Iterated elimination
> Even when no player has a dominant action, we can iteratively eliminate dominated actions of players, which can make some previously undominated actions of other players dominated
> Two versions depending on strict/weak domination
- Nash equilibria
> Pure Nash equilibria via best response diagram
> Mixed Nash equilibria via the indifference principle


## Nash Equilibrium

- Nash Equilibrium
> A strategy profile $\vec{s}$ is in Nash equilibrium if $s_{i}$ is the best action for player $i$ given that other players are playing $\vec{s}_{-i}$

$$
u_{i}\left(s_{i}, \vec{s}_{-i}\right) \geq u_{i}\left(s_{i}^{\prime}, \vec{s}_{-i}\right), \forall s_{i}^{\prime}
$$


> Each player's strategy is only best given the strategies of others, and not regardless.
> You can't reason about a single player in isolation. You can only say whether you're in a NE after seeing the entire strategy profile.

## Recap: Attend or Not

| Professor | Attend | Be Absent |
| :---: | :---: | :---: |
| Atudents | $\mathbf{( 3 , 1 )} \rightleftarrows(\mathbf{1}, \mathbf{- 3})$ |  |
| Be Absent | $\mathbf{( - 1 , - 1 )} \longrightarrow \mathbf{( 0 , 0 )}$ |  |

- Pure Nash equilibria
> (Attend, Attend)
> (Be Absent, Be Absent)
- Not pure Nash equilibria
> (Attend, Be Absent)
> (Be Absent, Attend)


## Nash's Beautiful Result

- Nash's Theorem:
> Every normal form game has at least one (possibly mixed) Nash equilibrium.
- The Indifference Principle
> If $\left(s_{i}, \vec{s}_{-i}\right)$ is a Nash equilibrium and $s_{i}$ assigns a positive probability to the set of actions $T_{i}$ of player $i$, then...
...for all actions $a_{i}, a_{i}^{\prime} \in T_{i}$ and $a_{i}^{\prime \prime} \notin T_{i}$
Reward to $i$ for
playing $a_{i}$ w.p. 1 when others play $\vec{S}_{-i}$

$$
\begin{aligned}
& u_{i}\left(a_{i}, \vec{s}_{-i}\right)=u_{i}\left(a_{i}^{\prime}, \vec{s}_{-i}\right) \geq u_{i}\left(a_{i}^{\prime \prime}, \vec{s}_{-i}\right) \\
& \text { Must be indifferent } \\
& \text { between actions in } T_{i} \quad \text { in } T_{i} \text { to any others }
\end{aligned}
$$

## Applying Indifference Principle

- Let $S_{1}$ and $S_{2}$ denote the set of actions of players 1 and 2
- For every $T_{1} \subseteq S_{1}\left(T_{1} \neq \emptyset\right)$ and $T_{2} \subseteq S_{2}\left(T_{2} \neq \emptyset\right)$
> Write generic strategies $s_{1}$ and $s_{2}$ randomizing over $T_{1}$ and $T_{2}$
> Apply the indifference principle to player 1 to solve for $s_{2}$
> Apply the indifference principle to player 2 to solve for $s_{1}$
o Sometimes you obtain multiple (or even infinitely many) solutions, in which case all of them are mixed Nash equilibria


## Example

|  | Player 2 | L | R |
| :---: | :---: | :---: | :---: |
| Player 1 | (5,4) | $(0,2)$ |  |
| T | $(2,0)$ | $(4,1)$ |  |
| M | $(3,20)$ | $(1,50)$ |  |
|  |  |  |  |

- Case of $S_{1}=\{\mathrm{T}, \mathrm{M}\}$ and $S_{2}=\{\mathrm{L}, \mathrm{R}\}$

Let $s_{1}=(\mathrm{T}, \mathrm{M}, \mathrm{B})$ with probabilities $(p, 1-p, 0)$, where $p \in(0,1)$
$>$ Let $s_{2}=(\mathrm{L}, \mathrm{R})$ with probabilities $(q, 1-q)$, where $q \in(0,1)$
> We want to solve for possible values of $p$ and $q$ (if any) by applying the indifference principle

## Example

|  | Player 2 | $L$ |
| :---: | :---: | :---: |
| Player 1 | R |  |
| T | $(5,4)$ | $(0,2)$ |
| M | $(2,0)$ | $(4,1)$ |
| B | $(3,20)$ | $\mathbf{( 1 , 5 0 )}$ |

- Indifference principle to player 1
> $u_{1}\left(T, s_{2}\right)=u_{1}\left(M, s_{2}\right) \geq u_{1}\left(B, s_{2}\right)$
$>q \cdot 5+(1-q) \cdot 0=q \cdot 2+(1-q) \cdot 3 \geq q \cdot 3+(1-q) \cdot 1$
> $q=4 / 7$ works
- If player 2 plays (L,R) w.p. $(4 / 7,3 / 7)$, then playing (any) randomization between T and M would be best response for player 1


## Example

|  | Player 2 | $L$ |
| :---: | :---: | :---: |
| Player 1 | R |  |
| T | $(5,4)$ | $(0,2)$ |
| M | $(2,0)$ | $(4,1)$ |
| B | $(3,20)$ | $\mathbf{( 1 , 5 0 )}$ |

- Indifference principle to player 2
$>u_{2}\left(s_{1}, L\right)=u_{2}\left(s_{1}, R\right)$
$>p \cdot 4+(1-p) \cdot 0=p \cdot 2+(1-p) \cdot 1$
> $p=1 / 3$ works!
- If player 1 plays (T,M,B) w.p. $(1 / 3,2 / 3,0)$, then playing (any) randomization between $L$ and $R$ would be best response for player 2


## Exercise: Rock-Paper-Scissor

- Exercise: Solve for the "fully mixed" case where...
> P1 plays (R,P,S) w.p. $(p, q, 1-p-q)$, where $p>0, q>0, p+q<1$
> P2 plays (R,P,S) w.p. $(x, y, 1-x-y)$, where $x>0, y>0, x+y<1$
> Apply the indifference principle to P 1 to solve for $x$ and $y$
> Use symmetry to argue that the same calculations hold for $p$ and $q$
- Exercise: Check that other cases yield no equilibria

| P1 | P2 | Paper | Scissor |
| :---: | :---: | :---: | :---: |
| Rock | $(\mathbf{0}, \mathbf{0})$ | $(\mathbf{- 1}, \mathbf{1})$ | $\mathbf{( 1 , - 1 )}$ |
| Paper | $\mathbf{( 1 , - 1 )}$ | $(\mathbf{0}, \mathbf{0})$ | $\mathbf{( - 1 , 1 )}$ |
| Scissor | $\mathbf{( - 1 , 1 )}$ | $\mathbf{( 1 , - 1 )}$ | $\mathbf{( 0 , 0 )}$ |

## Exercise: Inspect Or Not

| Inspector | Inspect | Don't Inspect |
| :---: | :---: | :---: |
| Driver | $(-10,-1)$ | $\longrightarrow$ |
| Pay Fare | $\mathbf{( - 1 0 , 0 )}$ |  |
| Don't Pay Fare | $\mathbf{( 0 , - 3 0 )}$ |  |

- Game:
> Fare = 10
> Cost of inspection = 1
> Fine if fare not paid $=30$
> Total cost to driver if caught $=90$
- Pure and mixed Nash equilibria?


## Exercise: Cunning Airlines

- Two travelers lose their luggage.
- Airline agrees to refund up to $\$ 100$ to each.
- Policy:
> Both travelers would submit a number between 2 and 99 (inclusive).
$>$ If both report the same number, each gets this value.
> If one reports a lower number ( $s$ ) than the other ( $t$ ), the former gets $s+2$, the latter gets $s-2$.



## Exercise: Ice Cream Shop

- Two brothers, each wants to set up an ice cream shop on the beach [0,1]
- Reward structure:
$>$ If the shops are at $s, t$ (with $s \leq t$ ), the brother at $s$ gets the customers in $\left[0, \frac{s+t}{2}\right]$ and the other one gets the customers in $\left[\frac{s+t}{2}, 1\right]$
> Reward equals the length of the interval



## Computational Complexity

- Pure Nash equilibria
> Existence: Checking the existence of a pure Nash equilibrium can be NP-hard.
> Computation: Computing a pure NE can be PLS-complete, even in games in which a pure NE is guaranteed to exist.
- Mixed Nash equilibria
> Existence: Always exist due to Nash's theorem
> Computation: Computing a mixed NE is PPAD-complete.


## Nash Equilibria: Critique

- Noncooperative game theory provides a framework for analyzing rational behavior.
- But it relies on many assumptions that are often violated in the real world.
- Due to this, human actors are observed to play Nash equilibria in some settings, but play something far different in other settings.


## Nash Equilibria: Critique

- Assumptions:
> Rationality is common knowledge.
- All players are rational.
o All players know that all players are rational.
- All players know that all players know that all players are rational.
o ... [Aumann, 1976]
- Behavioral economics
> Rationality is perfect = "infinite wisdom"
- Computationally bounded agents
> Full information about what other players are doing.
- Bayes-Nash equilibria


## Nash Equilibria: Critique

- Assumptions:
> No binding contracts.
- Cooperative game theory
> No player can commit first.
- Stackelberg games (will study this in a few lectures)
> No external help.
- Correlated equilibria
> Humans reason about randomization using expectations.
- Prospect theory


## Nash Equilibria: Critique

- Also, there are often multiple equilibria, and no clear way of "choosing" one over another.
- For many classes of games, finding even a single Nash equilibrium is provably hard.
> Cannot expect humans to find it if your computer cannot.


## Nash Equilibria: Critique

- Conclusion:
> For human agents, take it with a grain of salt.
> For Al agents playing against Al agents, perfect!



# Prices of Anarchy \& Stability 

## Worst and Best Nash Equilibria

- What can we say after we identify all Nash equilibria?
> Compute how "good" they are in the best/worst case
- How do we measure "social good"?
> Game with only rewards?
Higher total reward of players = more social good
> Game with only penalties?
Lower total penalty to players = more social good
> Game with rewards and penalties? No clear consensus...


## Price of Anarchy and Stability

- Price of Anarchy (PoA) "Worst NE vs optimum"

Max total reward<br>Min total reward in any NE

- Price of Stability (PoS)
"Best NE vs optimum"

Max total reward<br>Max total reward in any NE

Min total cost in any NE
Min total cost

$$
\mathrm{PoA} \geq \mathrm{PoS} \geq 1
$$

## Revisiting Stag-Hunt

| Hunter 2 | Stag | Hare |
| ---: | :---: | :---: |
| Hunter 1 | $(\mathbf{4}, \mathbf{4 )}$ | $\mathbf{( 0 , 2 )}$ |
| Stag | $(\mathbf{2}, \mathbf{0})$ | $\mathbf{( 1 , 1 )}$ |

- Max total reward $=4+4=8$
- Three equilibria
> (Stag, Stag) : Total reward = 8
> (Hare, Hare) : Total reward = 2
$>(1 / 3$ Stag $-2 / 3$ Hare, $1 / 3$ Stag $-2 / 3$ Hare $)$
- Total reward $=\frac{1}{3} * \frac{1}{3} * 8+\left(1-\frac{1}{3} * \frac{1}{3}\right) * 2 \in(2,8)$
- Price of stability? Price of anarchy?


## Revisiting Prisoner's Dilemma

| Sam | Stay Silent | Betray |
| :---: | :---: | :---: |
| Stay Silent | $(-1,-1)$ | $(-3,0)$ |
| Betray | $(0,-3)$ | $(-2,-\mathbf{2})$ |

- $\operatorname{Min}$ total cost $=1+1=2$
- Only equilibrium:
$>($ Betray, Betray $):$ Total cost $=2+2=4$
- Price of stability? Price of anarchy?


## Cost Sharing Game

- $n$ players on directed weighted graph $G$
- Player $i$
> Wants to go from $s_{i}$ to $t_{i}$
> Strategy set $S_{i}=$ \{directed $s_{i} \rightarrow t_{i}$ paths \}
> Denote his chosen path by $P_{i} \in S_{i}$
- Each edge $e$ has cost $c_{e}$ (weight)
> Cost is split among all players taking edge $e$
$>$ That is, among all players $i$ with $e \in P_{i}$



## Cost Sharing Game

- Given strategy profile $\vec{P}$, cost $c_{i}(\vec{P})$ to player $i$ is sum of his costs for edges $e \in P_{i}$
- Social $\operatorname{cost} C(\vec{P})=\sum_{i} c_{i}(\vec{P})$
- Note: $C(\vec{P})=\sum_{e \in E(\vec{P})} c_{e}$, where...
$>E(\vec{P})=\{$ edges taken in $\vec{P}$ by at least one player $\}$
> Why?



## Cost Sharing Game

- In the example on the right:
> What if both players take direct paths?
> What if both take middle paths?
> What if one player takes direct path and the other takes middle path?
- Pure Nash equilibria?



## Cost Sharing: Simple Example

- Example on the right: $n$ players
- Two pure NE
> All taking the $n$-edge: social cost $=n$
> All taking the 1-edge: social cost = 1
- Also the social optimum
- Price of stability: 1
- Price of anarchy: $n$

> We can show that price of anarchy $\leq n$ in every costsharing game!


## Cost Sharing: PoA

- Theorem: The price of anarchy of a cost sharing game is at most $n$.
- Proof:
> Suppose the social optimum is $\left(P_{1}^{*}, P_{2}^{*}, \ldots, P_{n}^{*}\right)$, in which the cost to player $i$ is $c_{i}^{*}$.
> Take any NE with cost $c_{i}$ to player $i$.
> Let $c_{i}^{\prime}$ be his cost if he switches to $P_{i}^{*}$.
> $\mathrm{NE} \Rightarrow c_{i}^{\prime} \geq c_{i} \quad$ (Why?)
> But: $c_{i}^{\prime} \leq n \cdot c_{i}^{*}$ (Why?)
$>c_{i} \leq n \cdot c_{i}^{*}$ for each $i \Rightarrow$ no worse than $n \times$ optimum


## Cost Sharing

- Price of anarchy
> Every cost-sharing game: PoA $\leq n$
- Example game with PoA $=n$
$>$ Bound of $n$ is tight.
- Price of stability?
$>$ In the previous game, it was 1 .
$>$ In general, it can be higher. How high?
> We'll answer this after a short detour.


## Cost Sharing

- Nash's theorem shows existence of a mixed NE.
> Pure NE may not always exist in general.
- But in both cost-sharing games we saw, there was a PNE.
> What about a more complex game like the one on the right?


10 players: $E \rightarrow C$
27 players: $B \rightarrow D$
19 players: $C \rightarrow D$

