#### CSC304 Lecture 4

### Game Theory (Cost sharing & congestion games, Potential function, Braess' paradox)

## Recap

- Nash equilibria (NE)
  - > No agent wants to change their strategy
  - > Guaranteed to exist if mixed strategies are allowed
  - Could be multiple
- Pure NE through best-response diagrams
- Mixed NE through the indifference principle

## Worst and Best Nash Equilibria

- What can we say after we identify all Nash equilibria?
   Compute how "good" they are in the best/worst case
- How do we measure "social good"?
  - Game with only rewards?
    Higher total reward of players = more social good
  - Game with only penalties?
    Lower total penalty to players = more social good
  - Game with rewards and penalties? No clear consensus...

## Price of Anarchy and Stability

• Price of Anarchy (PoA)

"Worst NE vs optimum"

Max total reward Min total reward in any NE

or

Max total cost in any NE

Min total cost

• Price of Stability (PoS)

"Best NE vs optimum"

Max total reward Max total reward in any NE

or

Min total cost in any NE Min total cost

 $PoA \ge PoS \ge 1$ 

# **Revisiting Stag-Hunt**

Hunter 2 Hunter 1	Stag	Hare
Stag	(4 , 4)	(0 , 2)
Hare	(2 , 0)	(1 , 1)

- Max total reward = 4 + 4 = 8
- Three equilibria

> (Stag, Stag) : Total reward = 8  
> (Hare, Hare) : Total reward = 2  
> 
$$\binom{1}{3}$$
 Stag  $-\frac{2}{3}$  Hare,  $\frac{1}{3}$  Stag  $-\frac{2}{3}$  Hare)  
 $\circ$  Total reward =  $\frac{1}{3} * \frac{1}{3} * 8 + (1 - \frac{1}{3} * \frac{1}{3}) * 2 \in (2,8)$ 

• Price of stability? Price of anarchy?

## **Revisiting Prisoner's Dilemma**

John Sam	Stay Silent	Betray
Stay Silent	(-1 , -1)	(-3 , 0)
Betray	(0 , -3)	(-2 , -2)

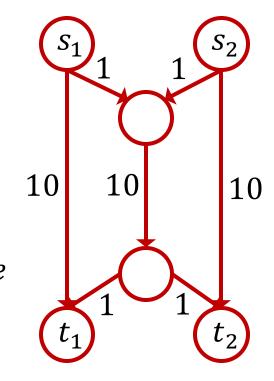
- Min total cost = 1 + 1 = 2
- Only equilibrium:

> (Betray, Betray) : Total cost = 2 + 2 = 4

• Price of stability? Price of anarchy?

# **Cost Sharing Game**

- n players on directed weighted graph G
- Player *i* 
  - > Wants to go from  $s_i$  to  $t_i$
  - > Strategy set  $S_i = \{ \text{directed } s_i \rightarrow t_i \text{ paths} \}$
  - > Denote his chosen path by  $P_i \in S_i$
- Each edge e has cost c<sub>e</sub> (weight)
   ➤ Cost is split among all players taking edge e
   ➤ That is, among all players i with e ∈ P<sub>i</sub>

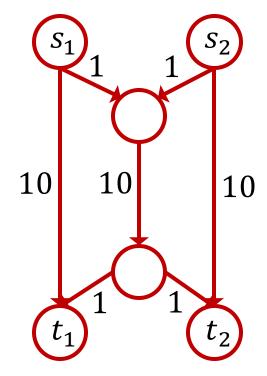


## Cost Sharing Game

• Given strategy profile  $\vec{P}$ , cost  $c_i(\vec{P})$  to player *i* is sum of his costs for edges  $e \in P_i$ 

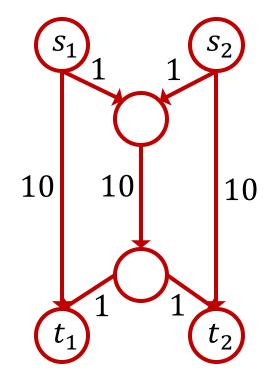
• Social cost 
$$C(\vec{P}) = \sum_i c_i(\vec{P})$$

• Note: 
$$C(\vec{P}) = \sum_{e \in E(\vec{P})} c_e$$
, where...  
>  $E(\vec{P})$ ={edges taken in  $\vec{P}$  by at least one player}  
> Why?



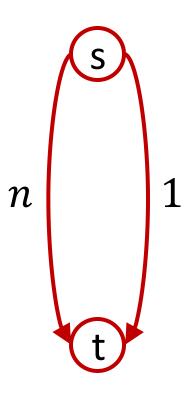
# **Cost Sharing Game**

- In the example on the right:
  - > What if both players take direct paths?
  - > What if both take middle paths?
  - What if one player takes direct path and the other takes middle path?
- Pure Nash equilibria?



# Cost Sharing: Simple Example

- Example on the right: *n* players
- Two pure NE
  - > All taking the n-edge: social cost = n
  - All taking the 1-edge: social cost = 1
    - Also the social optimum
- Price of stability: 1
- Price of anarchy: *n* 
  - ➤ We can show that price of anarchy ≤ n in every cost-sharing game!



# Cost Sharing: PoA

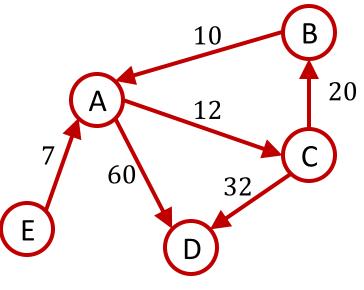
- Theorem: The price of anarchy of a cost sharing game is at most *n*.
- Proof:
  - > Suppose the social optimum is  $(P_1^*, P_2^*, ..., P_n^*)$ , in which the cost to player *i* is  $c_i^*$ .
  - > Take any NE with cost  $c_i$  to player i.
  - > Let  $c'_i$  be his cost if he switches to  $P_i^*$ .
  - > NE  $\Rightarrow c'_i \ge c_i$  (Why?)
  - > But :  $c'_i \leq n \cdot c^*_i$  (Why?)
  - >  $c_i \leq n \cdot c_i^*$  for each  $i \Rightarrow$  no worse than  $n \times$  optimum

# **Cost Sharing**

- Price of anarchy
  - > Every cost-sharing game:  $PoA \le n$
  - > Example game with PoA = n
  - $\succ$  Bound of *n* is tight.
- Price of stability?
  - > In the previous game, it was 1.
  - > In general, it can be higher. How high?
  - > We'll answer this after a short detour.

# **Cost Sharing**

- Nash's theorem shows existence of a mixed NE.
  - Pure NE may not always exist in general.
- But in both cost-sharing games we saw, there was a PNE.
  - > What about a more complex game like the one on the right?



10 players:  $E \rightarrow C$ 27 players:  $B \rightarrow D$ 19 players:  $C \rightarrow D$ 

## Good News

- Theorem: Every cost-sharing game have a pure Nash equilibrium.
- Proof:
  - > Via "potential function" argument

### Step 1: Define Potential Fn

- Potential function:  $\Phi : \prod_i S_i \to \mathbb{R}_+$ 
  - > This is a function such that for every pure strategy profile  $\vec{P} = (P_1, ..., P_n)$ , player *i*, and strategy  $P'_i$  of *i*,

$$c_i(P'_i, \vec{P}_{-i}) - c_i(\vec{P}) = \Phi(P'_i, \vec{P}_{-i}) - \Phi(\vec{P})$$

- When a single player i changes her strategy, the change in potential function equals the change in cost to i!
- In contrast, the change in the social cost C equals the total change in cost to all players.

 $\circ$  Hence, the social cost will often not be a valid potential function.

#### Step 2: Potential $F^n \rightarrow pure Nash Eq$

- A potential function exists  $\Rightarrow$  a pure NE exists.
  - > Consider a  $\vec{P}$  that minimizes the potential function.
  - Deviation by any single player i can only (weakly) increase the potential function.
  - > But change in potential function = change in cost to i.
  - > Hence, there is no beneficial deviation for any player.
- Hence, every pure strategy profile minimizing the potential function is a pure Nash equilibrium.

#### Step 3: Potential F<sup>n</sup> for Cost-Sharing

- Recall:  $E(\vec{P}) = \{ edges taken in \vec{P} by at least one player \}$
- Let  $n_e(\vec{P})$  be the number of players taking e in  $\vec{P}$

$$\Phi(\vec{P}) = \sum_{e \in E(\vec{P})} \sum_{k=1}^{n_e(\vec{P})} \frac{c_e}{k}$$

• Note: The cost of edge *e* to each player taking *e* is  $c_e/n_e(\vec{P})$ . But the potential function includes all fractions:  $c_e/1$ ,  $c_e/2$ , ...,  $c_e/n_e(\vec{P})$ .

#### Step 3: Potential F<sup>n</sup> for Cost-Sharing

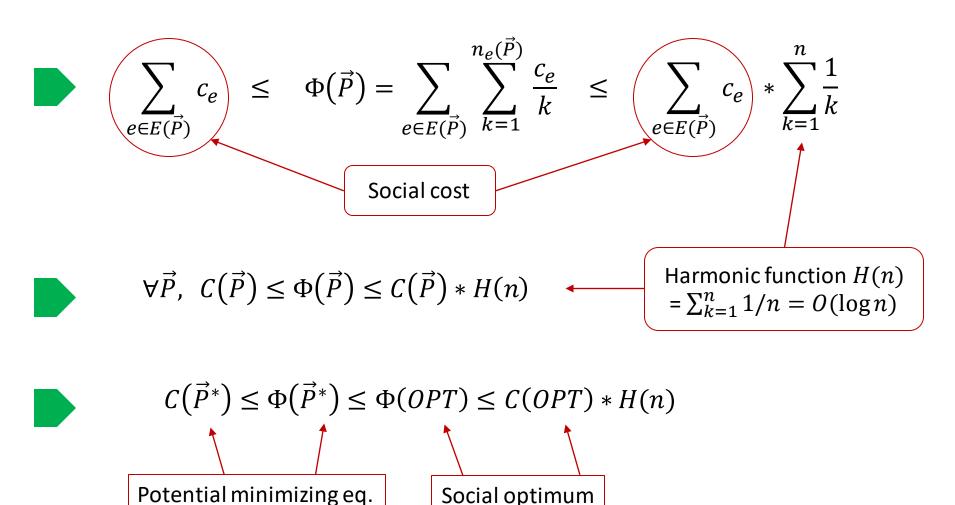
$$\Phi(\vec{P}) = \sum_{e \in E(\vec{P})} \sum_{k=1}^{n_e(\vec{P})} \frac{c_e}{k}$$

- Why is this a potential function?
  - > If a player changes path, he pays  $\frac{c_e}{n_e(\vec{P})+1}$  for each new edge e, gets back  $\frac{c_f}{n_f(\vec{P})}$  for each old edge f.
  - > This is precisely the change in the potential function too. > So  $\Delta c_i = \Delta \Phi$ .

# Potential Minimizing Eq.

- Minimizing the potential function gives some pure Nash equilibrium
  - > Is this equilibrium special? Yes!
- Recall that the price of anarchy can be up to *n*.
  - > That is, the worst Nash equilibrium can be up to n times worse than the social optimum.
- A potential-minimizing pure Nash equilibrium is better!

### Potential Minimizing Eq.



# Potential Minimizing Eq.

Potential-minimizing PNE is O(log n)-approximation to the social optimum.

- Thus, in every cost-sharing game, the price of stability is O(log n).
  - $\succ$  Compare to the price of anarchy, which can be n

## **Congestion Games**

- Generalize cost sharing games
- *n* players, *m* resources (e.g., edges)
- Each player *i* chooses a set of resources  $P_i$  (e.g.,  $s_i \rightarrow t_i$  paths)
- When  $n_j$  player use resource j, each of them get a cost  $f_j(n_j)$
- Cost to player is the sum of costs of resources used

## **Congestion Games**

- Theorem [Rosenthal 1973]: Every congestion game is a potential game.
- Potential function:

$$\Phi(\vec{P}) = \sum_{j \in E(\vec{P})} \sum_{k=1}^{n_j(\vec{P})} f_j(k)$$

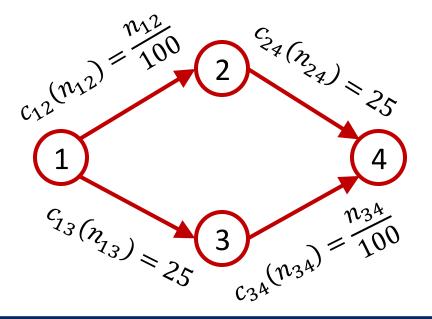
• Theorem [Monderer and Shapley 1996]: Every potential game is equivalent to a congestion game.

### **Potential Functions**

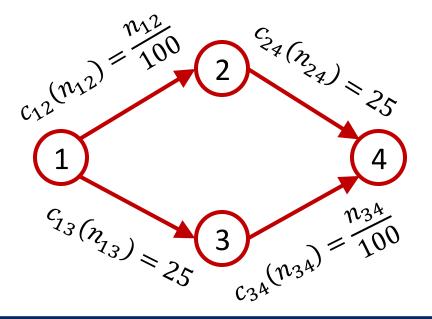
- Potential functions are useful for deriving various results
  - > E.g., used for analyzing amortized complexity of algorithms
- Bad news: Finding a potential function that works may be hard.

- In cost sharing,  $f_i$  is decreasing
  - > The more people use a resource, the less the cost to each.
- f<sub>i</sub> can also be increasing
  - > Road network, each player going from home to work
  - > Uses a sequence of roads
  - The more people on a road, the greater the congestion, the greater the delay (cost)
- Can lead to unintuitive phenomena

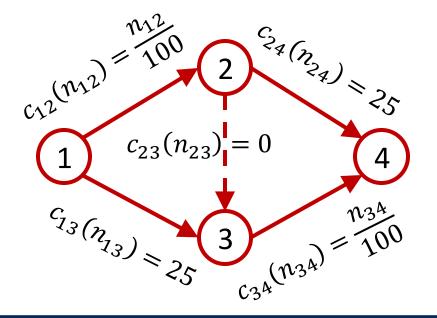
- Parkes-Seuken Example:
  - > 2000 players want to go from 1 to 4
  - $\succ$  1  $\rightarrow$  2 and 3  $\rightarrow$  4 are "congestible" roads
  - $\succ 1 \rightarrow 3 \text{ and } 2 \rightarrow 4 \text{ are "constant delay" roads}$



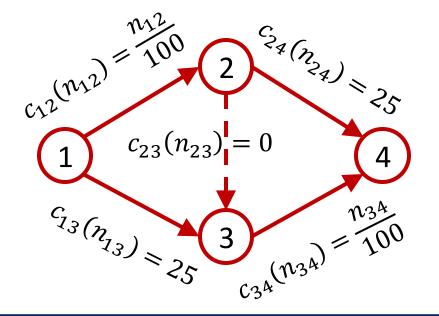
- Pure Nash equilibrium?
  - > 1000 take  $1 \rightarrow 2 \rightarrow 4$ , 1000 take  $1 \rightarrow 3 \rightarrow 4$
  - > Each player has cost 10 + 25 = 35
  - > Anyone switching to the other creates a greater congestion on it, and faces a higher cost



- What if we add a zero-cost connection  $2 \rightarrow 3$ ?
  - > Intuitively, adding more roads should only be helpful
  - In reality, it leads to a greater delay for everyone in the unique equilibrium!



- Nobody chooses  $1 \rightarrow 3$  as  $1 \rightarrow 2 \rightarrow 3$  is better irrespective of how many other players take it
- Similarly, nobody chooses  $2 \rightarrow 4$
- Everyone takes  $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$ , faces delay = 40!



- In fact, what we showed is:
  - > In the new game,  $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$  is a strictly dominant strategy for each player!

