ABSTRACT
The past decade has witnessed a rapid growth of research on fairness in machine learning. In contrast, fairness has been formally studied for almost a century in microeconomics in the context of resource allocation, during which many general-purpose notions of fairness have been proposed. This paper explores the applicability of two such notions — envy-freeness and equitability — in machine learning. We propose novel relaxations of these fairness notions which apply to groups rather than individuals, and are compelling in a broad range of settings. Our approach provides a unifying framework by incorporating several recently proposed fairness definitions as special cases. We provide generalization bounds for our approach, and theoretically and experimentally evaluate the tradeoff between loss minimization and our fairness guarantees.

CSCS CONCEPTS
\begin{itemize}
  \item Computing methodologies \rightarrow Machine learning
  \item Applied computing \rightarrow Economics
\end{itemize}

KEYWORDS
Group envy-freeness, group equitability, fairness, generalization

1 INTRODUCTION
Machine learning algorithms are now ubiquitously used to automate decisions which affect human lives (e.g. deciding credit ratings, filtering resumes of job applicants, or making decisions regarding bail or loan applications). Their proliferation raises concerns that these algorithms might amplify human biases or introduce new sources of unfairness [6]. Such concerns have led to a recent explosion in research on fairness in machine learning [10, 14, 17, 22, 27, 28].

While yielding insights on how to make algorithms fairer, it has also led to plethora of fairness definitions [32], many of which are incompatible [14, 27]. There is a general lack of consensus on which is the right definition, and this choice is often application-dependent [25]. Further, most popular definitions such as statistical parity [10, 17] and equalized odds [22] only apply to restrictive binary settings (e.g. where a loan application can be either approved or rejected); there are few definitions or general frameworks for considering fairness across a broad range of settings [24].

While fairness in machine learning is a recent phenomenon, fairness has been formally studied in microeconomics (especially in fair resource allocation) since almost a century [37]. Initiated by studying the canonical cake-cutting setting, it has since focused on proposing general-purpose definitions such as proportionality [37], envy-freeness [19], equitability, the core [41], and Rawlsian egalitarian fairness [34], which apply to a broad range of settings. For example, the core is not only applicable in cake-cutting [41], but also in participatory budgeting [18], housing markets [36], matching markets [20], public goods allocation [18], and even clustering [13].

Recently, a number of papers emerged using these definitions to design fair machine learning algorithms [5, 40, 43]. One central fairness notion adopted by them all is envy-freeness, which mandates that no individual should envy another individual. Formally, this is written as $\forall i, j : u_i(o_i) \geq u_i(o_j)$, where $u_i$ is the utility function of individual $i$ and $o_i$ is the outcome experienced by her.

Envy-freeness is compelling because it is simple, intuitive, and requires no information beyond individuals’ utility functions, which can be easily learned easily from their actions [4, 12]; this is in contrast to definitions like individual fairness [17], which requires access to a task-specific similarity metric between people. However, it has a significant drawback. While it can be exactly satisfied in classic resource allocation settings like cake-cutting [38] or rent division [39], it is often too stringent for many machine learning applications. For example, in binary settings with only two outcomes where all individuals prefer the same outcome (e.g. prefer receiving a loan/bail than not receiving it), envy-freeness would require that all individuals receive the same outcome. In applications like targeted advertising where people have heterogeneous preferences, envy-freeness is less restrictive, but only when randomized assignments are allowed [5].

Almost all of this discussion applies to another key fairness definition, equitability, which is formally stated as $\forall i, j : u_i(o_i) = u_j(o_j)$. That is, all individuals must have the same utility for their own outcome. To illustrate its distinction from envy-freeness, consider a hypothetical setting where individual 1 has utility 1 for outcome A but 0 for outcome B, while individual 2 has utility 1 for B but 0 for A. Assigning outcome B to both individuals is envy-free (indeed, individual 1 does not envy individual 2 as they both receive the same outcome), but not equitable (individual 1 receives utility 0 whereas individual 2 receives utility 1).

The research question we address in this paper is: Are there relaxations of envy-freeness and equitability which are more appropriate for machine learning settings?

1.1 Our Contributions
We propose novel relaxations of envy-freeness and equitability in style of classical group fairness notions in machine learning. We are interested in ensuring fairness between a pair of groups $(G, \bar{G})$, where groups are defined as arbitrary subsets of individuals. A classifier is group envy-free if this pair of groups if, on average, individuals in $G$ have no less utility for their own classification outcome than for the outcomes of individuals in $\bar{G}$. For the classifier to be group equitable for this pair of groups, the average utility of individuals in $G$ for their own outcome should equal the average utility of individuals in $\bar{G}$ for their own outcome.

Section 4 shows that both these notions capture several prior fairness notions such as statistical parity, equal opportunity, equalized
odds, and equalized financial impact, as special cases, and extend them beyond binary classification. For equalized odds, Hardt et al. [22] show that a non-discriminatory classifier can be post-processed to satisfy equalized odds without access to feature vectors. We show such post-processing is not generally possible in our setting without access to utility functions (which depend on feature vectors).

Section 5 provides generalization error bounds for both our fairness notions using Rademacher complexity. We show that these classifiers that provide good fairness guarantees on polynomially large training set can also provide good fairness guarantees on the population, even when the pairs of groups for which fairness is sought is exponential.

In Section 6, we show that in the worst case, fairness and loss minimization are not very compatible: simply minimizing the empirical loss without any regards to group envy-freeness or group equitability can quite unfair, whereas imposing either fairness requirement can significantly increase the loss of the classifier.

Section 7 qualifies these observations by performing simulations in the targeted advertising setting. First, we derive efficient methods for training classifiers with low violations of group envy-freeness and group equitability constraints. Next, we observe that our method provides a good tradeoff between empirical risk minimization (which has very low loss but highly unfair) and trivial methods for achieving fairness (which is highly fair, but has very high loss). We also observe that empirically, group envy-freeness is much less imposing than group equitability or (individual) envy-freeness, indicating it may be better suited for practical applications.

1.2 Related Work

Envy-freeness in machine learning. Closely related to ours is the work of Balcan et al. [5], who consider envy-free classifiers in targeted advertising context. As described above, envy-freeness is a stringent constraint for machine learning; we also empirically observe this in our experiments (Section 7). Further, envy-freeness places a constraint for every pair of individuals, thus generating an extremely large number of constraints.

Envy-freeness with decoupled classifiers. Zafar et al. [43] and Ustun et al. [40] also adapt envy-freeness to the machine learning context. Though they define a notion of envy-freeness among groups that is similar to our group envy-freeness notion, there is a key difference. They work with group-conditional or decoupled classifiers, where the principal trains a potentially different classifier \( h_G \) for each group \( G \). Then, it is said that group \( G \) does not envy group \( \bar{G} \) if \( \mathbb{E}_{x \sim G} u(x, h_{\bar{G}}(x)) - u(x, h_G(x)) \leq 0 \). That is, on average, an individual \( x \) from group \( G \) should prefer the outcome of \( h_G \) on \( x \) than the outcome of \( h_{\bar{G}} \) on \( x \). We argue that this can allow the principal to satisfy the fairness requirement without actually being fair to groups. For example, consider a scenario in which all individuals prefer class 1 over class 0. The principal trains \( (h_G, h_{\bar{G}}) \) such that \( h_G \) assigns class \( 0 \) to everyone in group \( G \), whereas \( h_{\bar{G}} \) assigns class \( 1 \) to everyone in group \( \bar{G} \). When both groups are equally deserving of class 1, this is clearly unfair. However, \( h_{\bar{G}} \) may be a classifier which, when applied on any individual \( x \) from group \( G \), detects membership in \( G \) using the feature vector and returns class \( 0 \) in that case. Then, these decoupled classifiers will satisfy envy-freeness according to the definitions of Ustun et al. [40], Zafar et al. [43].

In contrast, note that we require that individuals in group \( G \) not prefer the classification given to individuals in group \( \bar{G} \) (and not just the classification that would be given to them if the classifier for group \( \bar{G} \) were used for them). Hence, these unfair classifiers would significantly violate our group envy-freeness notion. We also note that auditing for fairness is much more difficult under their notion than ours. Checking group envy-freeness under our notion simply requires knowing the classification outcomes, which is often public information, whereas checking it under their notion requires access to the actual classifiers, which are often kept private [25].

Welfare-equalizing fairness. Concurrently to (and independently of) our work, Ben-Porat et al. [8] propose welfare-equalizing fairness, which coincides with our group equitability notion. They also argue that this subsumes classic fairness notions like statistical parity, equal opportunity, and equalized odds like we do for both group envy-freeness and group equitability in Section 4. However, their main focus is observing that equalized odds may harm even the disadvantaged group when utilities are not considered [24], whereas this cannot happen under group equitability, lending it further credibility. They also identify the structure of optimal group equitable classifiers in a certain context. Although one of our notions coincides with their proposal, our contribution is entirely different. We provide generalization error bounds for our fairness notions, and theoretically and empirically evaluate the tradeoff between loss minimization and fairness, which they do not do.

Fair division. Envy-freeness originated in microeconomics literature on fair allocation of resources [19]. In that context, envy-freeness is easy to achieve either exactly [41] or approximately [9, 11, 29]. Hence, the literature has focused on group-level notions of fairness which strengthen (i.e. logically imply) envy-freeness, such as group envy-freeness [7] or group fairness [15]. These should not be confused with our notion of group envy-freeness, which is a relaxation of individual envy-freeness. We term it group envy-freeness because in machine learning, notions that relax individual-level fairness to groups are referred to as group fairness notions, and there are no notions that strengthen individual fairness because individual fairness is already severely restrictive.

In classical fair division, fairness notions which average utilities across individuals are usually not considered as individual utilities can be on different scales (or expressed in different units). Interpersonal comparisons of utilities is thus avoided [30]; an exception to this is the work of Aleksandrov and Walsh [2]. In machine learning contexts, however, utility can often be interpreted in terms of the probability of receiving the preferred outcome [43] or financial impact [33], and thus can be on the same scale.

We also remark that there is significant potential of importing further ideas from this literature. For example, the recent work of Gölz et al. [21] considers the implications of requiring monotonicity axioms from fair division in the classification context, and show that some axioms are easy to guarantee in conjunction with equalized odds, while others are effectively incompatible.

Generalization. In proving generalization of our notions, we use the Rademacher complexity framework, but tie it to the Natarajan dimension of the family of multiclass classifiers. Balcan et al. [5] also used the Natarajan dimension when analyzing generalization of envy-freeness. However, they only establish that a large
fraction of constraints will be approximately satisfied with high probability, whereas in our setting, all constraints are approximately satisfied with high probability.\footnote{This is because in an infinite population, envy-freeness imposes infinitely many constraints, whereas our approach imposes finitely many constraints.} We also note that our approach can provide fairness across exponentially many pairs of arbitrarily defined groups with polynomially many training data points; similar approaches in the literature for providing fairness across exponentially many groups require the family of groups to have “low complexity” in a certain sense \cite{23, 26}.

2 PRELIMINARIES

For a natural number $k \in \mathbb{N}$, define $[k] = \{1, \ldots, k\}$. For a set $T$, let $\Lambda(T)$ denote the set of all distributions over $T$.

We are interested in a classification setting where the task is to learn to classify individuals into appropriate classes. Typically, an individual is represented by a feature vector $x \in \mathcal{X} \subseteq \mathbb{R}^m$, which is accessible to the classifier. In some classification settings, there is also side information (e.g. a ground truth label $y^*$ for each individual), which, while not available to the classifier, could be used as part of training. To capture this general setting, we represent individuals by the extended feature vector $x^* = (x, y^*) \in \mathcal{X}^*$, where $y^*$ is any side information. We use this abstract notation to convey the fact that our definitions and framework apply to machine learning settings with a ground truth (e.g. the loan or bail setting) as well as those without (e.g. the targeted ad setting). Let $\mathcal{P}^{\mathcal{X}^*}$ denote a distribution over individuals.

Let there be a finite set of classes (a.k.a. labels) $\mathcal{Y} = [d]$. Note throughout the paper, we consider multiclass classifiers. As before, let $\mathcal{P}^{\mathcal{Y}} \in \Lambda(\mathcal{Y})$ denote a distribution over classes.

Classifiers: A deterministic classifier $h_d : \mathcal{X} \rightarrow \mathcal{Y}$ assigns a class to each individual. A randomized classifier $h_r : \mathcal{X} \rightarrow \Lambda(\mathcal{Y})$ assigns a distribution over classes to each individual. We use $\mathcal{H}$ to denote a family of classifiers. For a family $\mathcal{H}$ of deterministic classifiers, we use $\Delta(\mathcal{H})$ to denote the family of randomized classifiers which can be expressed as a mixture over $k$ deterministic classifiers from $\mathcal{H}$, i.e., $\Delta^k(\mathcal{H})$ is the set of all $h_r = \sum_{t=1}^k \eta_t h^t_d$ for some $h_1^d, \ldots, h_k^d \in \mathcal{H}$ and $\eta_1, \ldots, \eta_k \in [0, 1]$ with $\sum_{t=1}^k \eta_t = 1$.

Loss functions: A loss function $\ell : \mathcal{X}^* \times \mathcal{Y} \rightarrow [0, 1]$, where $\ell(x^*, y)$ return the loss in predicting label $y$ for individual $x^*$.

Given a loss function $\ell$ and a finite dataset $S \subseteq \mathcal{X}^*$, the empirical risk of a classifier $h$ is given by $R_S(h) = \frac{1}{|S|} \sum_{x^* \in S} \ell(x^*, h(x^*))$.

The classifier which minimizes this empirical risk is termed the empirical risk minimizer (ERM). The expected loss of the classifier on the population, defined by a distribution $\mathcal{P}^{\mathcal{X}^*}$ over individuals, is $R(h) = \mathbb{E}_{x^* \sim \mathcal{P}^{\mathcal{X}^*}}[\ell(x^*, h(x^*))]$.

Utility: A utility function is given by $u : \mathcal{X}^* \times \mathcal{Y} \rightarrow [0, 1]$, where $u(x^*, y)$ encodes the utility of individual $x^*$ being assigned class $y$.\footnote{The loss must be bounded, but the restriction to $[0, 1]$ is without loss of generality.} We assume that individual utilities are normalized: for each $x^* \in \mathcal{X}^*, \sum_{y \in \mathcal{Y}} u(x^*, y) = 1$. Again, with a slight abuse of notation, we define $u(x^*, \mathcal{P}^{\mathcal{Y}}) = \mathbb{E}_{y \sim \mathcal{P}^{\mathcal{Y}}} [u(x^*, y)]$.

Note that we allow the utility function of an individual represented by $x^*$ to depend on the side information (such as a ground truth label for the individual). That said, we assume that utility function of an individual only depends on features captured by $x^*$.

In practice, two individuals with identical $x^*$ may have slightly different utilities, but our results hold approximately if a close approximation of their individuals’ utility functions can be found which depend only on $x^*$.

3 GROUP ENVY-FREENESS AND GROUP EQUITABILITY

Our main conceptual contribution in this work is to propose two group fairness notions for machine learning, inspired by the literature on fair division. For this, we first define the notion of groups.

Groups: Unlike much prior literature on fairness in machine learning where groups are defined based on certain sensitive attribute (e.g. race, gender, ethnicity, etc.), our framework allows groups to be defined arbitrarily. A group of individuals $G$ is identified by a subset of extended feature vectors, i.e., $G \subseteq \mathcal{X}^*$. Our fairness guarantees apply to pairs of groups. Let $\mathcal{G}$ denote a set of pairs of groups; we want to ensure fairness across all pairs of groups $(G, \tilde{G}) \in \mathcal{G}$. We are now ready to define our group fairness notions.

Group envy-freeness: In the fair division literature, envy-freeness is a notion of individual fairness, which requires that no individual should envy any other individual. This was adapted to the classification context by Balcan et al. \cite{5}, and formally translates to the following: a classifier $h$ is envy-free if $\forall x^*, \tilde{x}^* \in \mathcal{X}^* : u(x^*, h(x^*)) \geq u(\tilde{x}^*, h(\tilde{x}^*))$. Another way of viewing the envy-freeness is that the envy of any individual for any other individual is non-negative: $u(x^*, h(x)) - u(\tilde{x}^*, h(\tilde{x})) \geq 0, \forall x^*, \tilde{x}^* \in \mathcal{X}^*$. As argued in the introduction, this is a very stringent requirement in most applications. For example, in the loan/bail domain, this requires either granting all loan/bail applications or denying them all.\footnote{Once again, the utility must be bounded, but the restriction to $[0, 1]$ is without loss of generality.} For the targeted advertisement domain, this translates to showing each individual her most preferred ad out of all ads shown to anyone.\footnote{The requirement becomes a bit less stringent for randomized classifiers, as observed by Balcan et al. \cite{5}.}

We propose a group-level relaxation of this constraint, following a similar relaxation proposed by Aleksandrov and Walsh \cite{2}. Instead of mandating each individual prefer their outcome to anyone else’s, we require that the average preference (i.e. utility) of individuals in a group for their outcome be higher than their average preference for outcomes given to another group. Formally, given a pair of groups $G, \tilde{G} \subseteq \mathcal{X}^*$, a dataset $S \subseteq \mathcal{X}^*$, and $\epsilon \geq 0$, we say that classifier $h$ is empirically $\epsilon$-group-envy-free on $(G, \tilde{G})$ with respect to $S$ if

\begin{equation}
\frac{1}{|S^G| \cdot |S^{\tilde{G}}|} \sum_{x^* \in S^G} u(x^*, h(\tilde{x})) - u(x^*, h(x)) \leq \epsilon.
\end{equation}

where $S^G = S \cap G$ and $S^{\tilde{G}} = S \cap \tilde{G}$ represent restrictions of $S$ to groups $G$ and $\tilde{G}$, respectively. We refer to the maximum\footnote{We do this because negative envy is not specifically desired.} of

\begin{equation}
\max_{(G, \tilde{G}) \in \mathcal{G}} \text{max}_{S \subseteq \mathcal{X}^*} \epsilon(G, \tilde{G}, S)
\end{equation}
the difference on LHS and 0 as the empirical group envy of $\mathcal{G}$ for $\mathcal{G}$ on $S$. When $\epsilon = 0$, we simply refer to this as empirical group envy-freeness. Note that while we want the group envy to be non-negative (or minimally positive), having large negative group envy is not necessarily desirable. Also, like envy-freeness, group envy-freeness is not symmetric: group envy-freeness on $(G, \bar{G})$ does not imply group envy-freeness on $(\bar{G}, G)$. In fact, as we argue in Section 8, in certain applications it may be desirable to impose asymmetric group envy-freeness constraints.

The population version is simply given by the expectation over a distribution of individuals $\mathcal{P}^X$: we say that classifier $h$ is population $\epsilon$-group-envy-free on $(G, \bar{G})$ if

$$\mathbb{E} \left[ u(x^+, h(\bar{x})) - u(x^+, h(x)) \right]_{x^+ \in G, \bar{x}^+ \in \bar{G}} \leq \epsilon.$$ 

Again, when $\epsilon = 0$, we simply refer to this as population group-envy-freeness.

Our goal is to ensure that this style of group fairness is maintained across a set of pairs of groups $\mathcal{G}$. We say that $h$ is empirically (resp. population) $\epsilon$-group-envy-free on $\mathcal{G}$ with respect to $S$ (resp. $\mathcal{P}^X$) if it is $\epsilon$-group-envy-free on $(G, \bar{G})$ with respect to $S$ (resp. $\mathcal{P}^X$) for all $(G, \bar{G}) \in \mathcal{G}$.

**Group equitability**: In the classical fair division literature, equitability requires that all agents have identical utility for their outcomes. This translates to the following definition in our classification context: a classifier $h$ is **equitable** if $\forall x^+, \bar{x}^+: u(x^+, h(x)) = u(\bar{x}^+, h(\bar{x}))$. Unfortunately, this too is a stringent requirement in machine learning contexts similarly to envy-freeness.

We relax this to a group setting by requiring the average utility of individuals in a group for their outcome be equal across all groups. Formally, given a pair of groups $G, \bar{G} \subseteq X^*$, a dataset $S \subseteq X^*$, and $\epsilon \geq 0$, we say that classifier $h$ is empirically $\epsilon$-group-equitable on $(G, \bar{G})$ with respect to $S$ if

$$\frac{1}{|G^+|} \sum_{x^+ \in G^+} u(x^+, h(x)) - \frac{1}{|\bar{G}^+|} \sum_{\bar{x}^+ \in \bar{G}^+} u(\bar{x}^+, h(\bar{x})) \leq \epsilon.$$ 

We refer to this difference as the empirical group equitability violation between $G$ and $\bar{G}$ on $S$. When $\epsilon = 0$, we simply refer to this as empirical group equitability. Given a distribution of individuals $\mathcal{P}^X$, we say that classifier $h$ is population $\epsilon$-group-equitable on $(G, \bar{G})$ if

$$\mathbb{E} \left[ u(x^+, h(x)) \right]_{x^+ \in G} - \mathbb{E} \left[ u(\bar{x}^+, h(\bar{x})) \right]_{\bar{x}^+ \in \bar{G}} \leq \epsilon.$$ 

Again, when $\epsilon = 0$, we simply refer to this as population group-equitability.

Given a set of pairs of groups $\mathcal{G}$, we say that $h$ is empirically (resp. population) $\epsilon$-group-equitable on $\mathcal{G}$ with respect to $S$ (resp. $\mathcal{P}^X$) if it is $\epsilon$-group-equitable on $(G, \bar{G})$ with respect to $S$ (resp. $\mathcal{P}^X$) for all $(G, \bar{G}) \in \mathcal{G}$. Lastly, we note that unlike group envy free, group equitability is symmetric: group equitable on $(G, \bar{G})$ implies group equitable on $(\bar{G}, G)$.

### 4 Classical Fairness Notions as Special Cases

In this section, we discuss the connection of group envy-freeness and group equitability to several classical notions of fairness proposed in the fair machine learning literature.

#### 4.1 Statistical Parity, Equal Opportunity, and Equalized Odds

First, we show that three popular group fairness notions for binary classification — statistical parity, equal opportunity, and equalized odds — are special cases of our definitions. Thus, our definitions provide a unifying framework for viewing classical definitions under one umbrella and generalizing them to multiclass classification.

Recall the binary classification framework. Each individual $x$ also has a ground truth label $y$. Recall that $y_0$ denotes the class assigned to the individual. When the individual is sampled from population, we use $X$, $Y^*$, and $Y$ to denote the corresponding random variables. In this setting, there is a positive class (say $y = 1$), which is preferred by all individuals. For example, this may correspond to receiving a loan or bail. Given a pair of groups $(G, \bar{G})$, the three aforementioned notions of fairness — which treat both groups symmetrically — are defined as follows.

- **Statistical parity** demands an equal probability of getting a positive classification, regardless of group identity: $\Pr[Y = 1 \mid X \in G] = \Pr[Y = 1 \mid X \in \bar{G}]$.
- **Equal opportunity** is similar to statistical parity, except that we now condition on both group identity and positive ground truth class: $\Pr[Y = 1 \mid X \in G, Y^* = 1] = \Pr[Y = 1 \mid X \in \bar{G}, Y^* = 1]$.
- **Equalized odds** is similar to equal opportunity, except that we seek fairness across both positive and negative ground truth classes: $\Pr[Y = 1 \mid X \in G, Y^* = a] = \Pr[Y = 1 \mid X \in \bar{G}, Y^* = a]$ for all $a \in \{0, 1\}$.

**Theorem 1.** Given a pair of groups $(G, \bar{G})$, there is a set $\mathcal{G}$ of pairs of groups and individual utility functions such that group envy-freeness and group equitability with respect to $\mathcal{G}$ coincide with statistical parity with respect to $(G, \bar{G})$. The same holds for equal opportunity and equalized odds.

**Proof.** Let all individuals have utility 1 for the preferred class, and 0 for the less preferred one. That is, $u(x^+, 1) = 1$ and $u(x^+, 0) = 0$. Then, for a random class $Y$, we have $u(x^+, Y) = \Pr[Y = 1]$. For a pair of groups $(G, \bar{G})$, a classifier $h$ is group envy-free with respect to $(G, \bar{G})$ if

$$\mathbb{E} \left[ \Pr[h(\bar{x}) = 1] - \Pr[h(x) = 1] \right]_{x^+ \in G, \bar{x}^+ \in \bar{G}} \leq 0$$

$$\Rightarrow \Pr[Y = 1 \mid X \in \bar{G}] \leq \Pr[Y = 1 \mid X \in G].$$

Hence, the classifier is group envy-free with respect to both $(G, \bar{G})$ and $(\bar{G}, G)$ if and only if $\Pr[Y = 1 \mid X \in G] = \Pr[Y = 1 \mid X \in \bar{G}]$, which is the condition for the classifier to satisfy statistical parity with respect to $(G, \bar{G})$. Hence, $\mathcal{G} = \{(G, \bar{G}), (\bar{G}, G)\}$ suffices.

It is easy to see that for equitability, simply $\mathcal{G} = (G, \bar{G})$ suffices as equitability is already a symmetric condition.
Finally, equal opportunity with respect to \((G, \tilde{G})\) is simply statistical parity with respect to \((G_1, \tilde{G}_1)\), where \(G_\alpha = G \cap \{ x^+ \in X^+ : y = \alpha \}, \alpha \in \{0, 1\} \). Hence, given the above proof, this can be obtained as group envy-freeness with respect to \(S = \{(G_1, \tilde{G}_1), (\tilde{G}_2, G_2)\} \) and group equitability with respect to \(S = \{(G_1, \tilde{G}_1), (\tilde{G}_2, G_2)\} \). Similarly, equalized odds with respect to \((G, \tilde{G})\) is simply statistical parity with respect to both \((G_1, \tilde{G}_1)\) and \((G_0, \tilde{G}_0)\), which is group envy-freeness with respect to \(S = \{(G_1, \tilde{G}_1), (G_0, \tilde{G}_0)\} \) and group equitability with respect to \(S = \{(G_1, \tilde{G}_1), (G_0, \tilde{G}_0)\} \). \[\square\]

While we provide a proof for equivalence of the population versions of these notions, it is easy to see that the equivalence also holds for the empirical versions defined on a training set. Similarly, our definitions can also capture statistical parity, equal opportunity, or equalized odds with respect to multiple pairs of groups.

The fact that these three classical fairness definitions are subsumed by group envy-freeness and group equitability has two key implications. First, our framework provides a methodical approach to extend these fairness definitions from binary classification to multi-class classification. Second, our generalization guarantee from Section 5 using the Rademacher complexity provides a single generalization proof for all three classic fairness definitions. This is similar to the approach and generalization proof of Agarwal et al. \[1\]; however, their framework is limited to binary classification.

### 4.2 Equalized Financial Impact

Sometimes, even in binary classification, simply equalizing error rates across subpopulations defined by sensitive attributes (possibly the ground truth classes) may not be sufficient. Ramnarayan \[33\] considers the loan setting, and argues that the financial impact of an error made by the classifier (i.e., where the outcome differs from the ground truth label) may vary across individuals within a group depending on their wealth, and proposes equalizing the financial impact rather than error rates across the protected groups. This is similar to the harm-reduction approach of Altman et al. \[3\].

Formally, let \(h(x^+)\) denote some measure of wealth of an individual represented by \(x^+\), and let \(\psi(b(x^+))\) denote the financial impact when individual \(x^+\) receives a loan. Ramnarayan \[33\] assumes that \(h(x^+)\) is simply one of the features; however, our approach allows \(b\) to be any function of the features. Then, a classifier satisfies equalized financial impact with respect to a pair of groups \((G, \tilde{G})\) if \(\mathbb{E}[\Pr[Y = 0 \mid \psi(b(X))] \mid X \in G, Y^+ = 1] = \mathbb{E}[\Pr[Y = 0 \mid \psi(b(X))] \mid X \in \tilde{G}, Y^+ = 1]\). Similarly to Theorem 1, it is easy to see that this is also a special case of group envy-freeness and group equitability, where \(\psi\) defines the utility functions.

**Theorem 2.** Given a pair of groups \((G, \tilde{G})\), there is a set \(S\) of pairs of groups and utility functions \(\psi\) such that group envy-freeness and group equitability with respect to \(S\) coincide with equalized financial impact with respect to \((G, \tilde{G})\).

### 4.3 Impossibility of Post-Processing

Hardt et al. \[22\] show that given any (possibly discriminatory) binary classifier, one can derive from it a binary classifier satisfying equalized odds (or equal opportunity) using a simple post-processing step. This post-processing step does not require access to any feature vector information from the training data except for group membership and ground truth labels. It achieves fairness by simply taking an appropriate convex combination of the given classifier, its inverse (which flips the prediction on each individual), and trivial constant classifiers.

While such post-processing is clearly desirable, we show that when we move beyond the binary classification setting, we cannot hope to post-process an arbitrary given classifier and achieve fairness. For example, if we start from the empirical risk minimizer (ERM) which is obtained without accessing utilities, and perform a post-processing step which also does not access utilities, then any classifier derived is ultimately obtained without accessing utilities. We show that such classifiers can only guarantee group envy-freeness or group equitability in trivial cases. For these results, we assume that group membership is exclusive, i.e., we want to ensure fairness with respect to a pair of groups \((G, \tilde{G})\) where \(G \cap \tilde{G} = \emptyset\); note that we do not generally require this in our framework, although this is a common use case.

**Theorem 3.** Suppose \(h\) is a (possibly randomized) classifier obtained without access to utilities, \((G, \tilde{G})\) is a pair of groups with \(G \cap \tilde{G} = \emptyset\), and \(S\) is a finite set of individuals. Then:

1. \(h\) is guaranteed to be empirically group envy-free on \(S\) with respect to \((G, \tilde{G})\) if and only if \(h(x)\) is identical for all \(x^+ \in S^G\), given by the following equation:

   \[
   \Pr[h(x) = c] = \frac{1}{|S^G|} \cdot \sum_{\tilde{x}^+ \in S^\tilde{G}} \Pr[h(\tilde{x}) = c], \forall x^+ \in S^G, c \in \mathcal{Y}.
   \]

2. \(h\) is guaranteed to be empirically group equitable on \(S\) with respect to \((G, \tilde{G})\) if and only if for all \(x^+ \in S^G\) and \(\tilde{x}^+ \in S^\tilde{G}\), we have that \(h(x) = h(\tilde{x}) = \mathcal{U}(\mathcal{Y})\), where \(\mathcal{U}(\mathcal{Y})\) represents the uniform distribution over the set of classes \(\mathcal{Y}\).

**Proof.** Let us first consider group envy-freeness. For any \(h\) satisfying the equation given in part (1), we can see that the average empirical envy of any \(x^+ \in S^G\) towards \(\tilde{G}\) is

\[
\frac{1}{|S^G|} \cdot \sum_{\tilde{x}^+ \in S^{G\tilde{G}}} u(x^+, h(\tilde{x})) - u(x^+, h(x))
\]

\[
= \frac{1}{|S^G|} \cdot \sum_{\tilde{x}^+ \in S^{G\tilde{G}}} \sum_{c \in \mathcal{Y}} u(x^+, c) \cdot (\Pr[h(\tilde{x}) = c] - \Pr[h(x) = c])
\]

\[
= \sum_{c \in \mathcal{Y}} u(x^+, c) \cdot \left( \frac{1}{|S^G|} \cdot \sum_{\tilde{x}^+ \in S^{G\tilde{G}}} \Pr[h(\tilde{x}) = c] - \Pr[h(x) = c] \right) = 0,
\]

where the last equality uses the condition in part (1). Since this holds for all \(x^+ \in S^G\), clearly \(h\) is empirically group envy-free with respect to \((G, \tilde{G})\).

To see the converse, suppose for contradiction that there exists \(x^+_i \in S^G\) violating the condition in part (1). Then, there exists \(c_i \in \mathcal{Y}\) such that \(\Pr[h(x_i)] = c_i\) if \(\frac{1}{|S^G|} \cdot \sum_{\tilde{x}^+ \in S^{G\tilde{G}}} \Pr[\tilde{h}(\tilde{x}) = c_i]\). Since \(h\) was constructed without access to utility functions, the underlying utilities could have been such that \(u(x^+_i, c_i) = 1, u(x^+_i, c) = 0\) for all \(c \in \mathcal{Y} \setminus \{c_i\}\), and \(u(x^+, c) = 1/|\mathcal{Y}|\) for all \(x^+ \in S^G \setminus \{x^+_i\}, c \in \mathcal{Y}\).
Then, the group envy of $G$ towards $\widehat{G}$ is
\[
\frac{1}{|S^G| \cdot |S^G|} \sum_{x^+ \in S^G, \tilde{x}^+ \in S^G} u(x^+, h(\tilde{x})) - u(x^+, h(x))
\]
\[
= \frac{1}{|S^G| \cdot |S^G|} \sum_{x^+ \in S^G} u(x^+_i, h(\tilde{x})) - u(x^+_i, h(x))
\]
\[
= \frac{1}{|S^G| \cdot |S^G|} \sum_{x^+ \in S^G} (\Pr[h(\tilde{x}) = c_i] - \Pr[h(x_i) = c_i])
\]
\[
= \frac{1}{|S^G|} \left( \sum_{x^+ \in S^G} \Pr[h(\tilde{x}) = c_i] - \Pr[h(x_i) = c_i] \right) > 0,
\]
where the first transition follows from the fact that $u(x^+, \mathcal{P}Y) = 1/d$ for every $x^+ \in S^G \setminus \{x^+_i\}$ and every classification $\mathcal{P}Y$, and the last transition follows from the way $x^+_i$ was constructed.

For group envy-freeness, note that the condition in part (2) is very strong. If $h$ satisfies this condition, then $u(x^+, h(x)) = u(\tilde{x}^+, h(\tilde{x})) = 1/d$, where $d = |Y|$. Hence, group envy-freeness is trivially satisfied. We now show that this is also necessary. For each $x^+_i \in S^G$, define $i^\text{min}_i = \min_{h \in \mathcal{H}} \Pr[h(x_i) = c]$. For each $x^+_i \in S^G$, define $i^\text{max} = \max_{h \in \mathcal{H}} \Pr[h(x_i) = c]$. Note that for each $x^+_i \in S^G$, $\Pr[h(x_i) = i^\text{min}_i] \leq 1/d$, and for each $\tilde{x}^+_i \in S^G$, $\Pr[h(\tilde{x}_i) = i^\text{max}] \geq 1/d$.

Now, consider the following utilities: $\forall x^+_i \in S^G : u(x^+_i, i^\text{min}_i) = 1$ and $u(x^+_i, c) = 0$ for all $c \neq i^\text{min}_i$, and $\forall x^+_i \in S^G$, $u(x^+_i, i^\text{max}) = 1$ and $u(x^+_i, c) = 0$ for all $c \neq i^\text{max}$. Under these utilities, it is easy to check that $h$ is empirically group envy-fair on $S$ with respect to $(G, \widehat{G})$ if and only if $(1/|S^G|) \sum_{x^+_i \in S^G} \Pr[h(x_i) = i^\text{min}_i] = (1/|S^G|) \sum_{x^+_i \in S^G} \Pr[h(\tilde{x}_i) = i^\text{max}]$. However, this requires $\Pr[h(x_i) = i^\text{min}_i] = \Pr[h(\tilde{x}_i) = i^\text{max}] = 1/d$ for each $x^+_i \in S^G$, $\tilde{x}^+_i \in S^G$. By the definitions of $i^\text{min}_i$ and $i^\text{max}$, we get that $h(x_i) = h(\tilde{x}_i) = \mathcal{U}(\mathcal{P}Y)$ for all $x^+_i \in S^G$, $\tilde{x}^+_i \in S^G$, as desired.

Note that if we require the classifier $h$ to be empirically group envy-free on $S$ with respect to both $(G, \widehat{G})$ and $(\overline{G}, \overline{\widehat{G}})$ (to make the requirement symmetric between the groups), then we obtain that $h(x) = h(\tilde{x})$ must hold for all $x^+ \in S^G$, $\tilde{x}^+ \in S^G$. Though less strict than the requirement for group envy-freeness, it is still too restrictive in practice. Hence, post-processing cannot produce reasonable classifiers in our more general setting, without accessing individual utilities. We remark that even in the binary classification setting with homogenous preferences, it has been observed that any post-processing which does not access the features can be very suboptimal in performance [42].

### 5 GENERALIZATION

Our learning problem seeks a classifier that has low empirical risk and satisfies (or minimally violates) group envy-freeness or group envy-freeness against the training data. However, this classifier is then used to classify all individuals in the population. Hence, it is crucial that our fairness definitions generalize well. That is, we seek to establish that classifiers which are approximately fair on training data are also approximately fair on the population according to our fairness definitions. For this purpose, we use the Rademacher complexity approach.

Let $G$ denote a finite set of groups. Let us denote the $k$th pair by $(G_{k,1}, G_{k,2})$. Let $b_k$ denote the corresponding membership function: for a pair of individuals $z = (x^+_i, x^+_j)$, we have the indicator $b_k(z) = b_k(x^+_i, x^+_j) = 1$ if $x^+_i \in G_{k,1}$ and $x^+_j \in G_{k,2}$.

Let $\mathcal{B} = \{b_1, \ldots, b_{|G|}\}$ denote the family of membership functions, with $|\mathcal{B}| = |G|$. Let $\mathcal{P}^{X^+ \times X^+}$ denote any joint distribution over pairs of individuals, and let $S$ denote a finite training set of iid pairs $z_i = (x^+_i, x^+_j)$ sampled from this joint distribution and $|S| = n^6$.

Let us now define empirical and population violations of group envy-freeness and group envy-freeness constraints in this framework. For this, we need the following quantities. For $a, b \in \{1, 2\}$, $i \in \{1, \ldots, |G|\}$, and classifier $h$, let
\[
U_{ab}^S(h, b_k) = \frac{1}{|S|} \sum_{(x^+_i, x^+_j) \in S} u(x^+_i, h(b_k)) \cdot b_k(x^+_i, x^+_j),
\]
\[
U_{ab}(h, b_k) = \mathbb{E}_{(x^+_i, x^+_j) \sim \mathcal{P}^{X^+ \times X^+}} \left[ u(x^+_i, h(b_k)) \cdot b_k(x^+_i, x^+_j) \right].
\]
Note that $U_{ab}^S(h, b_k)$ (resp. $U_{ab}(h, b_k)$) effectively measures the average (resp. expected) utility of an individual in group $G_{k,1}$ for the classification given to an individual in group $G_{k,2}$. Similarly, $U_{ab}^S(h, b_k)$ and $U_{ab}^S(h, b_k)$ (resp. $U_{ab}(h, b_k)$ and $U_{ab}(h, b_k)$) effectively measure the average (resp. expected) utility of individuals in groups $G_{k,1}$ and $G_{k,2}$.

We can now define the empirical and population group envy-freeness and group envy-freeness violations in terms of these quantities. Hereinafter, we focus on group envy-freeness. The definitions and proofs for group envy-freeness are almost identical. Let the empirical and population group envy-freeness be defined as $\mathcal{V}^S(h, b_k) = U_{ab}^S(h, b_k) - U_{ab}^S(h, b_k)$ and $\mathcal{V}(h, b_k) = U_{ab}(h, b_k) - U_{ab}(h, b_k)$. To establish generalization, our goal is to show that given a sufficiently large training dataset $S$, with high probability, the difference $|\mathcal{V}(h, b_k) - \mathcal{V}(h, b_k)|$ is small for all $h$ and all $b_k$.

We first introduce two necessary definitions.

**Definition 1.** For a function class $\mathcal{F}$ containing functions mapping $X^+ \times X^+ \rightarrow \mathbb{R}$ and a set $S = \{z_1, \ldots, z_m\}$, the **Rademacher complexity** is $\mathcal{R}(\mathcal{F} \circ S) = \mathbb{E}_{\sigma \in \{-1, 1\}^n} \sup_{f \in \mathcal{F}} \sum_{i=1}^n \sigma_i \cdot f(z_i)$, where $\sigma = (\sigma_1, \ldots, \sigma_m)$ and each $\sigma_i$ is an independent random variable with $Pr[\sigma_i = 1] = Pr[\sigma_i = -1] = 1/2$. For simplicity of notation, we omit $S$ and simply denote this as $\mathcal{R}(\mathcal{F})$.

**Definition 2.** A set $S = \{z_1, \ldots, z_m\}$ is multi-class shattered by a function class $\mathcal{F}$, if there exist two functions $f_1$ and $f_2$ such that: (1) $\forall z \in S$, $f_1(z) \neq f_2(z)$ and (2) for every $b \subseteq S$, there exists a function $f \in \mathcal{F}$ such that $f(z) = f(z)$ for all $z \in b$ and $f(z) = f(z)$ for all $z \in S \setminus b$. The **Natarajan dimension** of $\mathcal{F}$ is the cardinality of the largest set of points that can be multi-class shattered by $\mathcal{F}$.

---

1 In this section, we switch from $(G, \widehat{G})$ to $(G_{k,1}, G_{k,2})$ for notational convenience.

2 When the training data consists of $n$ individuals sampled iid from a distribution $\mathcal{P}^{X^+}$, we can simply pair up individuals to create a dataset consisting of $n/2$ pairs sampled iid from the product distribution $\mathcal{P}^{X^+ \times X^+}$.

3 Note that in $U_{ab}^S(h, b_k) - U_{ab}^S(h, b_k)$, the denominator of both terms is $|S|$, and in the numerator, we measure the envy for every $z$ with $b_k(z) = 1$ and ignore the term corresponding to every $z$ with $b_k(z) = 0$. Hence, this difference is proportional to the group envy that $G_{k,1}$ has towards $G_{k,2}$. For group envy-freeness, we would need to consider both $U_{ab}^S(h, b_k) - U_{ab}^S(h, b_k)$ and $U_{ab}^S(h, b_k) - U_{ab}^S(h, b_k)$ for bounding the empirical violation, and the two similar quantities for bounding the population violation.
Let $\mathcal{H}$ be a family of deterministic classifiers and recall that $\Delta^k(\mathcal{H})$ contains all randomized classifiers that are mixtures of $k$ classifiers from $\mathcal{H}$. To obtain generalization, we need to bound the Rademacher complexity of

$$\{g: g(x^+_d, x^-_d) = u(x^+_d, h(x_d)) \cdot b_k(x^+_d, x^-_d), h \in \Delta^k(\mathcal{H}), b_k \in \mathcal{B}\}.$$  

Our approach is as follows. First, in Lemma 1, we eliminate the dependence on $b_k$ in the product $u(x^+_d, h(x_d)) \cdot b_k(x^+_d, x^-_d)$. Next, in Lemma 2, we eliminate the dependence on both $u$ and the randomized nature of $h \in \Delta^k(\mathcal{H})$, and express our bound directly in terms of $\mathcal{R}(\mathcal{H})$. Finally, we observe in Theorem 5 that function classes with low Natarajan dimension have low Rademacher complexity. In particular, we show that linear one-vs-all classifiers generalize well. We begin with the first result.

**Lemma 1.** Given a function class $\mathcal{F}$ containing functions mapping $X^+ \times X^- \to \mathbb{R}$ and a binary function $b : X^+ \times X^- \to \{0, 1\}$, define $\mathcal{F}_b = \{f_b : f_b(z) = f(z) \cdot b(z), f \in \mathcal{F}\}$. Then $\mathcal{R}(\mathcal{F}_b) \leq \mathcal{R}(\mathcal{F})$.

**Proof.** For each $\sigma$, let $f^*_\sigma \in \mathcal{F}$ be where $\sup_{f \in \mathcal{F}} \sum \sigma_i f_i(z) b_i(z)$ is attained (if the supremum is not reached, we can take a sequence of $f^*_\sigma$ that converge to the supremum) and define $\bar{\sigma}$ where $\bar{\sigma}_i = \sigma_i$ if $b_i(z) = 1$ and $\bar{\sigma}_i = 0$ otherwise. Then, we can write

$$\mathcal{R}(\mathcal{F}_b) = \mathbb{E}_\sigma \left[ \sum \sigma_i f^*_\sigma(z_i) b_i(z_i) \right] = \mathbb{E}_\sigma \left[ \sum \sigma_i f^*_\sigma(z_i) \right] = \mathbb{E}_\sigma \left[ \sum \bar{\sigma}_i f^*_\bar{\sigma}(z_i) \right] \leq \mathbb{E}_\sigma \left[ \sup_{f \in \mathcal{F}} \sum \bar{\sigma}_i f_i(z_i) \right] = \mathcal{R}(\mathcal{F}),$$

where the third transition holds because $\sup_{f \in \mathcal{F}} \sum \sigma_i f_i(z) b_i(z) = \sup_{f \in \mathcal{F}} \sum \bar{\sigma}_i f_i(z_i)$ only depends on the values of $\bar{\sigma}_i$ where $b_i(z_i) = 1$, and the fourth transition holds because the expected value of the term corresponding to each $i$ with $b_i(z_i) = 0$ is 0 (this is because $\sigma_i$ takes values +1 and −1 with probability 1/2 each, while $f_\bar{\sigma}$ does not change). \qed

Using Lemma 1, we are now express our desired Rademacher complexity directly in terms of the complexity of $\mathcal{H}$, eliminating the dependence on utilities, group membership functions, and randomization over deterministic classifiers. However, classifiers from $\mathcal{H}$ act on individuals, whereas training set $\mathcal{S}$ consists of pairs of individuals. Hence, we define $\mathcal{H}_b = \{h_b : h_b(x_1, x_2) = h(x_d) \in \mathcal{H}\}$, where $b \in \{1, 2\}$. Now, $\mathcal{R}(\mathcal{H}_b) \leq \mathcal{R}(\mathcal{H})$ is well-defined.

**Lemma 2.** Given a family of deterministic classifiers $\mathcal{H}$, function $b_k : X^+ \times X^- \to \{0, 1\}$, and $a, b \in \{1, 2\}$, define

$$\mathcal{F} = \{f : f(x^+_d, x^-_d) = u(x^+_d, h(x_d)) \cdot b_k(x^+_d, x^-_d); h \in \Delta^k(\mathcal{H})\}. $$

Then, $\mathcal{R}(\mathcal{F}) \leq \mathcal{R}(\mathcal{H}_b)$.

**Proof.** Let $\mathcal{F}_b = \{f : f(x^+_d, x^-_d) = u(x^+_d, h(x_d)) : h \in \Delta^k(\mathcal{H})\}$. By Lemma 1, we have that $\mathcal{R}(\mathcal{F}) \leq \mathcal{R}(\mathcal{F}_b)$. For a mixture $h = \sum_{k=1}^K \eta_k h^*_k$, note that $u(x^+_d, h(x_d)) = \sum_{k=1}^K \eta_k u(x^+_d, h^*_k(x_d))$, which is in the convex hull of $\{u(x^+_d, h_d(x_d)) : h_d \in \mathcal{H}\}$. Because the Rademacher complexity of the convex hull of a set is equal to that of the set $[35]$, we obtain

$$\mathcal{R}(\mathcal{F}_b) \leq \mathbb{E}_{\sigma} \left[ \sup_{h_d \in \mathcal{H}} \sum \sigma_i \cdot u(x^+_{i,a}, h_d(x_i,b)) \right].$$

Recall that $h_d : X \to [d]$. To apply the contraction lemma [35], we need $u$ to be Lipschitz continuous in its second argument. For this, we extend $u$ to a surrogate $\mathbb{U}$ as follows. For all $y \in [1, d]$, $\mathbb{U}((x^+_d, x^-_d), y) = u(x^+_d, h(x_d)) + u(x^+_{i,a}, y) - u(x^+_{i,a}, y)) \cdot (y - |y|).$ (4)

Note that $\mathbb{U}$ is 1-Lipschitz in its second argument (because utilities sum to 1), and matches $u$ when $y \in [d]$. As such, we can replace $u$ with $\mathbb{U}$ in Equation (3), and applying the contraction lemma [35], obtain: $\mathcal{R}(\mathcal{F}_b) \leq \mathbb{E}_{\sigma} \left[ \sup_{h_d \in \mathcal{H}_b} \sum \sigma_i h_d(x_i, b) \right] = \mathcal{R}(\mathcal{H}_b).$ \qed

With the help of these two lemmas, we now present the following generalization theorem:

**Theorem 4.** Let $\mathcal{H}$ be a family of deterministic classifiers, $S$ be a finite training set such that $\mathcal{R}(\mathcal{H}_b \circ S) \leq \epsilon/8$ for each $b \in \{1, 2\}$, and $\delta > 0$. If $|S| \geq 512 \ln(8\mathbb{U}(\mathcal{V}))/\epsilon^2$, then with probability at least $1 - \delta$, we have $\sup_{h \in \Delta^k(\mathcal{H}_b)} \mathbb{U}(\mathcal{V}(h, b)) - \mathbb{V}(h, b_k) \leq \epsilon.$

**Proof.** By expanding $\mathcal{V}$ and $\mathcal{U}$, we have

$$\mathbb{E}_{\sigma} \left[ \sup_{h \in \Delta^k(\mathcal{H}_b), b \in \mathcal{B}} \mathbb{U}(\mathcal{V}(h, b_k)) - \mathbb{V}(h, b_k) \right] \geq \epsilon$$

where the last transition follows from the triangle inequality and the union bound.

Let $\mathcal{F} = \{g : g(x^+_d, x^-_d) = u(x^+_d, h(x_d)) \cdot b_k(x^+_d, x^-_d); h \in \Delta^k(\mathcal{H})\}$. From Lemma 2, we have $\mathcal{R}(\mathcal{F}) \leq \mathcal{R}(\mathcal{H}_b)$. Using the standard generalization bound for Rademacher complexity [35],

$$\mathbb{E}_{\sigma} \left[ \sup_{h \in \Delta^k(\mathcal{H})} \mathbb{U}(\mathcal{V}(h, b_k)) - \mathbb{V}(h, b_k) \right] \leq \epsilon$$

where the last inequality holds because we are given $\mathcal{R}(\mathcal{H}_b) \leq \epsilon/8$. The same argument applies to the second term in Equation (5).

Hence, the probability in Equation (5) is at most $8\mathbb{U}(\mathcal{V}) \cdot e^{-|S|\epsilon^2}/512$. Setting this to $\delta$ and solving for $|S|$ completes the proof. \qed

Theorem 4 implies that regardless of the classifier trained, with high probability, the difference between group envy-freeness (or group equitability) violation between training and test will be small.

Finally, note that Theorem 4 requires $|S|$ to be large enough such that $\mathcal{R}(\mathcal{H}_b \circ S) \leq \epsilon/8$ for each $b \in \{1, 2\}$. Hence, for small $|S|$ to suffice, we also seek a family of deterministic classifiers $\mathcal{H}$ for which the Rademacher complexity quickly vanishes as $|S|$ grows.
We show that the family of linear one-vs-all classifiers that we use in our experiments has this property.

**Theorem 5.** Let $\mathcal{H}$ be the family of linear one-vs-all classifiers given by $h = \{ h_{x} : h_{x}(x) = \arg \max_{y \in [d]} w_{y}^{T} x ; w_{y} \in \mathbb{R}^{m} \}$. If $|S| \geq \frac{10^{4} d^{2} m^{2} \log(6|m|/\varepsilon)}{\varepsilon^{2}}$, then $\mathcal{A}(H_{b} \circ S) \leq \varepsilon/8$ for each $b \in \{1, 2\}$.

**Proof.** It is well-known that the Natarajan dimension of $\mathcal{H}$ is at most $md$ [35]. Using the version of Sauer’s lemma for Natarajan dimension [35], we get that the number of possible labelings of $S$ is at most $|S|^{md} e^{2md}$. Fix $b \in \{1, 2\}$. Then, $\|\{h_{x}(z_{1}), \ldots, h_{x}(z_{|S|})\}\|_{2} \leq \sqrt{|S|}$. Hence, using Massart’s lemma [35], we get $\mathcal{A}(H_{b}) \leq \frac{2d}{|S|^{d}} \sqrt{|S|} md \log(|S|d)$. Using simple algebra, it can be checked that our lower bound on $|S|$ is sufficient to get $\mathcal{A}(H_{b}) \leq \varepsilon/8$.

Combining Theorems 4 and 5, we get that when learning a mixture of linear one-vs-all classifiers, training set of size $|S| = O\left(\log(|G|)/\delta + d^{2} m \log(m)/\varepsilon\right)$ suffices to get generalization error bound of $\varepsilon$ with respect to $G$ with probability at least $1 - \delta$.

Note that our sample complexity scales logarithmically with $|G|$, which allows achieving fairness with respect to exponentially many pairs of groups with only polynomial training sample size. This is reminiscent of similar results due to Hébert-Johnson et al. [23], Kearns et al. [26]. However, crucially, their approach requires the groups over which fairness is desired to be of small complexity or computable via small circuits. In contrast, our approach works with arbitrarily defined groups, and is therefore significantly stronger. Note that we do not place any assumptions on the groups (e.g. that they be defined based on certain sensitive attributes) or pairs of groups (e.g. that they be disjoint) involved in our constraints.

### 6.1 Unfairness of Loss Minimization

First, we analyze the worst-case violation of group envy-freeness and group equitability that vanilla ERM can produce. Specifically, we let $h_{\text{ERM}}$ denote the ERM classifier. Then, we are interested in total the violations $T_{\text{envy}}(h_{\text{ERM}})$ and $T_{\text{eq}}(h_{\text{ERM}})$, which are the sum of empirical group envy-freeness and group equitability violations defined by Equations (1) and (2), across all pairs of groups. Note that the lowest possible values of $T_{\text{envy}}$ and $T_{\text{eq}}$ are 0; due to Theorem 3, trivial group envy-free and group equitability classifiers always exist. We show that in the worst case, $T_{\text{envy}}$ and $T_{\text{eq}}$ can be as high as $\Theta(g^{2})$ for $h_{\text{ERM}}$, which is an upper bound for any classifier $h$.

**Theorem 6.** Let $h_{\text{ERM}}$ denote an empirical risk minimizer. Then, with $g \geq 2$ groups, we have $T_{\text{envy}}(h_{\text{ERM}}) = \Theta(g^{2})$ and $T_{\text{eq}}(h_{\text{ERM}}) = \Theta(g^{2})$ in the worst case.

**Proof.** Since there are $O(g^{2})$ pairwise constraints, and violation of each constraint is bounded by 1, we have that $T_{\text{envy}}$ and $T_{\text{eq}}$ are trivially bounded by $O(g^{2})$ for any classifier.

To show that this bound is tight, we now construct an explicit instance that achieves it. Let the groups be denoted $G_{1}, \ldots, G_{g}$. Let there be $d = 2$ classes. Every individual in group $G_{i}$ where $i \leq |g/2|$ has utility 1 for class 1 and 0 for class 2. Let the loss for such an individual be $1$ for class 1 and 0 for class 2. Similarly, every individual in group $G_{i}$ where $i > |g/2|$ has utility 1 for class 2 and 0 for class 1. Let the loss for such an individual be $1$ for class 2 and 0 for class 1. In this instance, it is evident that $h_{\text{ERM}}$ assigns class 2 to every individual in group $G_{i}$ for $i \leq |g/2|$ and class 1 to all remaining individuals. However, for every $(i, j)$ with $i \leq |g/2|$ and $j > |g/2|$, every individual in group $G_{i}$ envy $j$ for such an individual be $1$ and vice-versa. Hence, all such $O(g^{2})$ pairs result in empirical group envy-freeness violation of 1, yielding the desired bound.

To show that the bound for $T_{\text{eq}}$ is tight, we construct the following instance. As before, let there be $d = 2$ classes and the groups be denoted $G_{1}, \ldots, G_{g}$. For each individual in group $G_{i}$, where $i \leq |g/2|$, let the utility be 0 for class 1 and 1 for class 2. For every individual in group $G_{i}$, where $i > |g/2|$, let the utility be 1 for class 1 and 0 for class 2. For all individuals, let the loss be 0 for class 1 and 1 for class 2. Then, it is evident that $h_{\text{ERM}}$ assigns class 1 to all individuals, giving individuals in group $G_{i}$ utility 1 when $i \leq |g/2|$ and utility 0 when $i > |g/2|$. Thus, this results in group equitability violation of 1 for every constraint $(G_{i}, G_{j})$ where $i \leq |g/2|$ and $j > |g/2|$, or $O(g^{2})$ in total.

### 6.2 Inefficiency of Fair Classifiers

We now examine the worst-case increase in loss due to imposition of group envy-freeness and group equitability constraints. Let $S$ denote a finite training set with $n$ data points, and $\ell^{2}(h)$ denote empirical loss of classifier $h$ on $S$. We are interested in $\ell^{2}(h) - \ell^{2}(h_{\text{ERM}})$ for group envy-free or group equitable classifier $h$. The next result shows that in the worst case, it could be $\Theta(n)$, which is the maximum possible for any classifier $h$.

**Theorem 7.** Let $h_{\text{ERM}}$ denote an empirical risk minimizer with respect to a training set $S$ of size $n$. With $g \geq 2$ groups, we have that in the worst case, $\ell^{2}(h) - \ell^{2}(h_{\text{ERM}})$ can be $\Theta(n)$ for every group envy-free or every group equitable classifier $h$.

**Proof.** $O(n)$ upper bound is trivial because $\ell^{2}$ is upper bounded by $n$.

For group envy-freeness lower bound, consider the following instance. Let there be $d = 2$ classes and two groups $G_{1}$ and $G_{2}$, each consisting of $n/2$ individuals. For every individual $x^{*} \in G_{1}$, we have $u(x^{*}, 1) = \ell(x^{*}, 1) = 1$ and $u(x^{*}, 2) = \ell(x^{*}, 2) = 0$. For every individual $x^{*} \in G_{2}$, we have the opposite: $u(x^{*}, 1) = \ell(x^{*}, 1) = 0$ and $u(x^{*}, 2) = \ell(x^{*}, 2) = 1$. For $a, b \in \{1, 2\}$, let $F_{a, b}$ denote the average probability of an individual in group $G_{a}$ receiving class $b$. Then, it is easy to check that for empirical group envy-freeness to hold with respect to both $(G_{1}, G_{2})$ and $(G_{2}, G_{1})$, we need $P_{1, 1} \geq P_{1, 2}$ and $P_{2, 2} \geq P_{1, 2}$. Taking the sum and adding $P_{1, 1} + P_{2, 2}$ on both sides, we get

$$2 \cdot (P_{1, 1} + P_{2, 2}) \geq P_{1, 1} + P_{1, 2} + P_{2, 1} + P_{2, 2} = 2 \Rightarrow P_{1, 1} + P_{2, 2} \geq 1.$$
We now propose a method for training (almost) group envy-free η which minimizes the empirical risk subject to group envy-freeness. This can be achieved by solving the following convex optimization problem:

\[
\min_{\eta \in \Delta^k} \frac{1}{|G|} \sum_{i=1}^{|G|} \eta_i \sum_{x \in S_{\eta}} \ell(x^+, \phi^i_d(x)) \quad \text{subject to} \quad \sum_{i=1}^{|G|} \eta_i = 1.
\]

where \( \lambda \) is a Lagrangian parameter.

For group equitability, we take the construction above, and simply illustrate the feasibility of training good classifiers subject to our fairness guarantees.

Formally, our goal is to learn a mixture \( \sum_{i=1}^k \eta_i h^i_d \in \Delta^k(\mathcal{H}) \) which minimizes the empirical risk subject to group envy-freeness or group equitability constraints. We use a similar convex relaxation approach to Balcan et al. [5] for envy-freeness. In all methods, we set the Lagrangian parameter to \( \lambda \) times the sum of all individual utilities, and add a penalty term encoding the violation and control its effect with a Lagrangian parameter \( \lambda \).

Second, for tractability, instead of enforcing group envy-freeness or group equitability as hard constraints, we add a penalty term encoding these violation and control its effect with a Lagrangian parameter \( \lambda \). Let \( T_{en} \) and \( T_{eq} \) respectively denote total empirical violations of group envy-freeness and group equitability constraints (Equations (1) and (2)) across all \((G, \hat{G}) \in G\). Then, we add \( \lambda \cdot T_{en} \) and \( \lambda \cdot T_{eq} \) penalty for group envy-freeness and group equitability. This yields unconstrained optimization problems, which are easier.

7 IMPLEMENTATION AND EXPERIMENTS

We now propose a method for training (almost) group envy-free and (almost) group equitable classifiers, and use it to empirically evaluate the tradeoff between our fairness desiderata and loss minimization. Our approach follows the convex relaxation approach proposed by Balcan et al. [5] for building (almost) envy-free classifiers. We emphasize that our approach is not the end-all solution; it simply illustrates the feasibility of training good classifiers subject to our fairness guarantees.

Formally, our goal is to learn a mixture \( \sum_{i=1}^k \eta_i h^i_d \in \Delta^k(\mathcal{H}) \) which minimizes the empirical risk subject to group envy-freeness or group equitability constraints. Let \( h = (h^1_d, \ldots, h^k_d) \in \mathcal{H}^k \) and \( \eta = (\eta^1, \ldots, \eta^k) \in \Delta^k \), where \( \Delta^k \) denotes the k-simplex containing probability distributions over k elements. Section 5 suggests when using the following family \( \mathcal{H} \) of linear one-vs-all multiclass classifiers, we obtain good generalization due to its low Natarajan dimension: \( \mathcal{H} = \{g_w : g_w(x) = \arg\max_{y \in [d]} w_y^T x ; \ w_y \in \mathbb{R}^m \} \).

Given this family, a finite training set \( S \), and a finite set of pairs of groups \( G \), our learning problem is the following. We only add one of the two constraints, depending on the fairness desired.

\[
\min_{h \in \mathcal{H}} \frac{1}{|S|} \sum_{i=1}^|S| \eta_i \sum_{x \in S_i} \ell(x^+, h^i_d(x)) \quad \text{subject to} \quad \sum_{i=1}^|S| \eta_i = 1.
\]

// for group envy-freeness, or

\[
\min_{h \in \mathcal{H}} \frac{1}{|S|} \sum_{i=1}^|S| \eta_i \sum_{x \in S_i} \ell(x^+, h^i_d(x)) + \lambda \sum_{i=1}^|S| \eta_i \sum_{x \in S_i} \ell(x^+, h^i_d(x)) - \lambda \sum_{i=1}^|S| \eta_i \sum_{x \in S_i} \ell(x^-, h^i_d(x)) \quad \text{subject to} \quad \sum_{i=1}^|S| \eta_i = 1.
\]

// for group equitability.

Convex relaxation of loss and utilities: Note that in Equation (6), \( \ell(x^+, h^i_d(x)) \) and \( u(x^+, h^i_d(x)) \) are neither convex nor differentiable due to the use of arg max in \( h^i_d \). As such, we consider the following multiclass-SVM-inspired convex relaxation, similarly to Balcan et al. [5]. For any \( e \in [d] \), \( \ell(x^+, h^i_d(x)) \leq \ell(x^+, h^i_d(x)) + w^T e x - w^T e x \). Thus, we get \( \ell(x^+, h^i_d(x)) \leq \max_{y \in [d]} \ell(x^+, y) + w^T e x - w^T e x \), which is a convex upper bound on \( \ell(x^+, h^i_d(x)) \). We use a similar convex upper bound on \( u(x^+, h^i_d(x)) \).

Training: Our problem is still not entirely convex due to the product of mixture probabilities with loss and utilities. To circumvent this, we use an iterative approach [5] whereby we first fix a default \( \eta \) and successively train for each \( h^i_d \) given previously learned \( h_d^{d-1}, \ldots, h_d^1 \), and after learning full \( h \), fix it and train for \( \eta \). Second, we consider the same process. We use a similar convex relaxation approach to Balcan et al. [5] for envy-freeness. In all methods, we set the Lagrangian parameter to \( \lambda = 10 \). We omit ERM-GroupEF solution from the bulk of our experiments because it does not scale well with the training sample size.
size. We instead show a separate comparison with this solution on smaller sample sizes.

7.2 Results of Experiments

We consider three key metrics: loss per individual, total group envy-freeness violation across all pairs of groups, and total group equitability violation across all pairs of groups.

Figure 1 shows the performance of ERM, ERM-Welfare, ERM-Group Envy Free, and ERM-Group Equitable with varying number of training samples. The number of groups is fixed to be 4. As expected, ERM attains the lowest loss, but at the cost of significant violation of group envy-freeness and group equitability. ERM-Welfare expectedly performs very well in terms of the fairness metrics, but at a significant cost in terms of the loss. ERM-GroupEF and ERM-GroupEQ provide reasonable tradeoffs, with the former achieving at least $\sim 50\%$ reduction in group envy-freeness violation compared to ERM and the latter achieving at least $\sim 30\%$ reduction in group equitability violation compared to ERM. Interestingly, ERM-GroupEF clearly outperforms ERM-GroupEQ for group envy-freeness, but the converse effect is less strong in group equitability.

We see a similar story in Figure 2, when we fix the training sample size to 100 but vary the number of groups. This time, ERM-GroupEF and ERM-GroupEQ, respectively, achieve at least $\sim 50\%$ and $\sim 40\%$ reduction in group envy-freeness and group equitability violations compared to ERM.

Finally, in Figure 3, we compare ERM-EF to ERM-GroupEF. Since individual envy-freeness is a stricter constraint than group envy-freeness, as expected, ERM-EF performs better in terms of the fairness metrics (both group envy-freeness and individual envy-freeness violations), whereas ERM-GroupEF performs better in terms of the loss. However, the difference is small, and both solutions perform very similarly. The biggest drawback of ERM-EF is the running time. As we can see, computing ERM-EF takes significantly longer than computing ERM-GroupEF or ERM-GroupEQ. Indeed, this is why we did not include ERM-EF in Figures 1 and 2, where training sample size was larger than what ERM-EF can handle.

8 DISCUSSION

This paper explores the applicability of two prominent fairness notions from the economic literature on fair division — envy-freeness and equitability — in machine learning. We proposed novel relaxations of these definitions in a group setting, unifying several previously proposed ones under a single framework and extending them beyond the binary classification setting.

Group envy-freeness, in particular, allows placing asymmetric constraints. A feature found in few fairness definitions in the literature, but one that could be useful in certain applications. For example, equalized odds demands that $\Pr[Y = 1|X \in G, Y^* = a] \geq \Pr[Y = 1|X \in \tilde{G}, Y^* = a]$ for all $a \in \{0, 1\}$, capturing the intuition that individuals in groups $G$ and $\tilde{G}$ with the same ground truth label deserve equal treatment. However, individuals with...
ground truth label 1 (e.g. individuals likely not to re-offend or likely to repay a loan) may also deserve treatment that is no worse than that given to individuals with ground truth label 0. Though it may emerge naturally from loss minimization, it can be imposed explicitly through group envy-freeness for appropriately defined pairs of groups.

Our approach leaves the choice of $G$, the set of pairs of groups across which fairness is desired, to the designer. This allows application-dependent definitions of protected groups, but also raises an interesting challenge. Consider a multi-class version of the loan setting, in which there are $d$ different types of loans (thus, $d + 1$ possible outcomes including "no loan"). In this case, it makes sense for the group ground truth label to also be a vector $Y^* \in \{0, 1\}^d$, where $Y^*_r$ denotes the individual’s ability to repay a loan of type $r$, if it were given to the individual. How should one subdivide protected groups based on vector-valued ground truth labels?

In our view, this work only scratches the surface of exploring how economic literature on fairness can be applied to machine learning; despite significant recent progress in this direction [24, 31], there is much left to explore and future work here can discover novel challenges for the machine learning community to address.

REFERENCES


