Education	PhD, Computer ScienceJan 2017 - May 2021University of Toronto, Ontario, Canada, Cumulative GPA: 4.00/4.00Supervised by Prof. Raquel Urtasun	
	• Research Focus: Multi-sensor lane detection, panoptic segmentation, multi-object tracking, 3D LiDAR segmentation	
	<ul> <li>MSc., Computer Science Sep 2015 - Jan 2017</li> <li>University of Toronto, Ontario, Canada, Cumulative GPA: 3.95/4.00</li> <li>Supervised by Prof. Raquel Urtasun</li> <li>Research Focus: Optical flow estimation, instance level segmentation</li> </ul>	
	<b>BASc., Electrical Engineering</b> Sep 2008 - May 2013University of Waterloo, Ontario, Canada, Cumulative GPA: 93% (3.94/4.00)	
Selected Publications	• Z. Zhang, M. Bai, E. Li, <i>Self-Supervised Pretraining for Large-Scale Point Clouds</i> , accepted at NeuRIPS 2022	
	<ul> <li>B. Yang, M. Bai, M. Liang, W. Zeng, R. Urtasun, Auto4D: Learning to Label 4D Objects from Sequential Point Clouds, submitted to IROS 2021</li> <li>M. Bai, S. Wang, K. Wong, E. Yumer, R. Urtasun, Non-Parametric Memory for Spatio-Temporal Segmentation of Construction Zones for Self-Driving, submitted to IROS 2019.</li> </ul>	
	<ul> <li>M. Bai*, G. Mattyus*, N. Homayounfar, S. Wang, S. K. Lakshmikanth, R. Urtasun, <i>Deep Multi-Sensor Lane Detection</i>, in IROS 2018. * denotes equal contributions.</li> <li>S. Wang, M. Bai, G. Mattyus, H. Chu, W. Luo, B. Yang, J. Liang, J. Cheverie, S. Fidler, R. Urtasun, <i>TorontoCity: Seeing the World with a Million Eyes</i>, in</li> </ul>	
	<ul> <li>ICCV 2017 (spotlight).</li> <li>M. Bai, R. Urtasun, Deep Watershed Transform for Instance Segmentation, in CVPR 2017.</li> </ul>	
	• M. Bai <sup>*</sup> , W. Luo <sup>*</sup> , K. Kundu, R. Urtasun, <i>Exploiting Semantic Information and Deep Matching for Optical Flow</i> , in ECCV 2016. * denotes equal contributions.	
Industry	Applied Scientist	
Experience	<ul> <li>Amazon Web Services, New York, NY June 2021 - Present</li> <li>Design and prototype 2D / 3D computer vision algorithms to accelerate creation of high quality labels for autonomous driving perception (object detection, segmentation, lane boundaries, etc)</li> <li>Conduct scientific research in 2D / 3D self-supervised learning, domain adapta-</li> </ul>	
	<ul> <li>tion, and assistive labeling (see publications)</li> <li>Contribute to science expertise of AWS SageMaker Ground Truth team through giving tutorials, talks, technical consultations, and patent filings</li> </ul>	
	<ul> <li>Research Scientist</li> <li>Uber Inc. Advanced Technologies Group, Toronto, Ontario May 2017 - Feb 2021</li> <li>Develop and prototype new computer vision and machine learning models for parts of the autonomous-driving software stack (see publications)</li> <li>Design and provide guidance for creation and curation of various large scale datasets including 3D lane annotation, 2D / 3D semantic and instance segmentation, construction zones</li> </ul>	

	• Assist software engineering team in integrating new t driving platform	echnologies into autonomous-
	Wireless Systems Engineer Apple Inc., Cupertino, CA	May 2013 - Jul 2015
<ul> <li>Performed radiated power, receiver sensitivi using anechoic chambers, cell emulators, spec</li> <li>Set up, modified, and maintained anechoic c ibration and verification of measurement ant ment, and software automation suites</li> </ul>		d throughput measurements analyzers, VNAs er test systems including cal- switching paths, test equip-
Services	Conference reviewer for CVPR, ICCV, ECCV, WACV, I	CRA, IROS
Skills	Python, MATLAB, C++, Pytorch, TensorFlow, scikit-lea	arn, numpy, opencv