

**Worst-case Time Complexity: Proving Asymptotic Bounds.**

Let  $t(x)$  be the number of steps taken by algorithm  $\mathcal{A}$  on input  $x$ .

Let  $T(n)$  be the *worst-case* time complexity of algorithm  $\mathcal{A}$ :

$$T(n) = \max_{\text{all inputs } x \text{ of size } n} t(x) = \max \{t(x) : x \text{ is an input of size } n\}$$

1. To prove that  $T(n)$  is  $O(g(n))$ , one must show that there is a constant  $c > 0$ , and an input size  $n_0 > 0$ , such that for all  $n \geq n_0$ :

$$\begin{aligned} T(n) &\leq c \cdot g(n) \\ \Leftrightarrow &\max \{t(x) : x \text{ is an input of size } n\} \leq c \cdot g(n) \\ \Leftrightarrow &\text{For every input } x \text{ of size } n, t(x) \leq c \cdot g(n) \\ \Leftrightarrow &\text{For every input of size } n, \mathcal{A} \text{ takes at most } c \cdot g(n) \text{ steps} \end{aligned}$$

2. To prove that  $T(n)$  is  $\Omega(g(n))$ , one must show that there is a constant  $c > 0$ , and an input size  $n_0 > 0$ , such that for all  $n \geq n_0$ :

$$\begin{aligned} T(n) &\geq c \cdot g(n) \\ \Leftrightarrow &\max \{t(x) : x \text{ is an input of size } n\} \geq c \cdot g(n) \\ \Leftrightarrow &\text{For some input } x \text{ of size } n, t(x) \geq c \cdot g(n) \\ \Leftrightarrow &\text{For some input of size } n, \mathcal{A} \text{ takes at least } c \cdot g(n) \text{ steps} \end{aligned}$$

**IN SUMMARY:**

Let  $T(n)$  be the *worst-case* time complexity of algorithm  $\mathcal{A}$ .

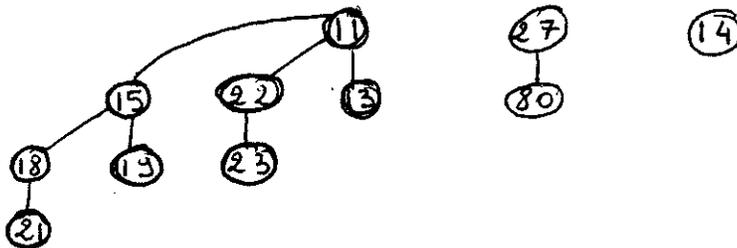
1.  $T(n)$  is  $O(g(n))$  iff  $\exists c > 0, \exists n_0 > 0$ , such that  $\forall n \geq n_0$ :  
for every input of size  $n$ ,  $\mathcal{A}$  takes at most  $c \cdot g(n)$  steps.
2.  $T(n)$  is  $\Omega(g(n))$  iff  $\exists c > 0, \exists n_0 > 0$ , such that  $\forall n \geq n_0$ :  
for some input of size  $n$ ,  $\mathcal{A}$  takes at least  $c \cdot g(n)$  steps.
3.  $T(n)$  is  $\Theta(g(n))$  iff  $T(n)$  is  $O(g(n))$  and  $T(n)$  is  $\Omega(g(n))$ .

*Handwritten note:*  $T(n)$  is  $\Theta(g(n))$  iff  $\exists c_1, c_2 > 0, \exists n_0 > 0$ , such that  $\forall n \geq n_0$ :  
 $c_1 g(n) \leq T(n) \leq c_2 g(n)$

# DELETE\_MIN(T)

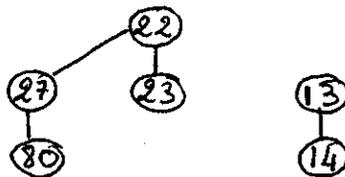
Example :

T =



- Delete\_MIN(T) :
1. Scan roots to find smallest element
  2. Delete element
  3. Merge resulting BQ's.

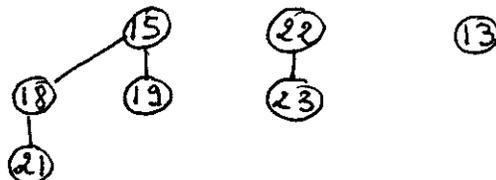
Carry :



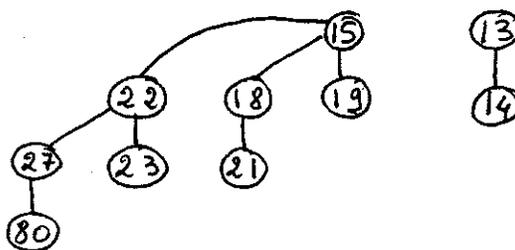
$$T_1 = T - S_3$$

+

$$T_2 = S_3 - \{x\}$$



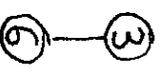
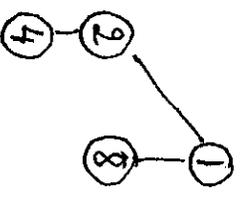
$$T \leftarrow \text{UNION}(T_1, T_2)$$



Implementation:

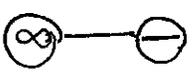
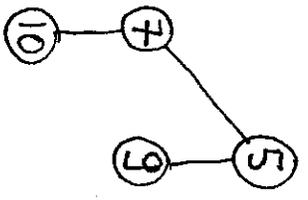


EXAMPLE OF BINOMIAL TREE MERGE



Carry

Total of  
5 edges



6

:

6

+

3

:

T

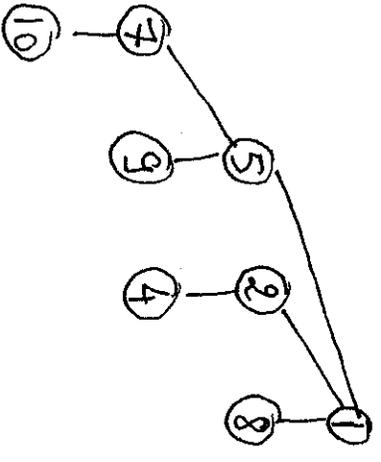
Total of

8 edges

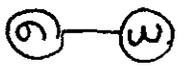
Merge took

$8 - 5 = 3$

key comparisons



X



X

ADT

Descrip

DT

priority Queue

- Set  $S$  with elem<sup>t</sup>/keys
- insert ( $S, x$ )
- max ( $s$ )
- extract max ( $s$ )

- unordered ll
  - ins  $\in \Theta(1)$
  - ex. max  $\in \Theta(n)$
- ordered ll
  - ins  $\in \Theta(n)$
  - ex. max  $\in \Theta(1)$
- heap (max, min)
  - ins, exmax  $\in \Theta(\lg n)$

Mergeable PQ

u

- union ( $S, T$ )

- binomial heap
  - ins  $\in \Theta(\lg n)$
  - ex. min  $\in \Theta(\lg n)$
  - union  $\in \Theta(\lg n)$

Dictionary

- Set
- 

- BST
  - ?  $\Theta(n)$
- balanced BST
  - ↳ AVL - tree
  -

DT: <sup>max</sup> binary heap: CBT (  ) + max heap property

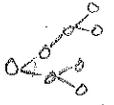
~~C[heap] = C[min-heap] + C[max-heap]~~ 

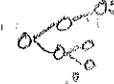
BH  $\subset$  H, BH = minBH  $\cup$  maxBH, H = minH  $\cup$  maxH

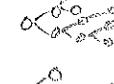
binomial tree  $S_k = \begin{cases} 0 & \text{if } k=0 \\ \Delta_{S_{k-1}} & \text{if } k>0 \end{cases}$

(  $2^k$  nodes,  $\binom{k}{d}$  at depth  $d$  )

binomial forest  $BF_m = (S_k \mid \cup S_k = m)$

BT  $\rightarrow$   | total order over in order

BST  $\rightarrow$  

CBT  $\rightarrow$  

FBT  $\rightarrow$  

---

AA, AVL, red-black, 2-3-4

selfbalancing

sb-bst

# Data structures

**ADT**: descrip<sup>o</sup> of object and ops

**DS**: specific implementa<sup>o</sup> of ADT

e.g. Priority Queues  $\rightarrow$  obj: set  $S$  of elem<sup>t</sup> w/ keys  
 $\rightarrow$  ops: insert( $S, x$ ): ( $S \leftarrow S \cup \{x\}$ )  
 max( $S$ ):  $x \leftarrow \text{max}(S)$   
 extract\_max( $S$ ):  $x \leftarrow \text{max}(S)$   
 ( $S \leftarrow S - \{x\}$ )

$\rightarrow$  DT for PQ

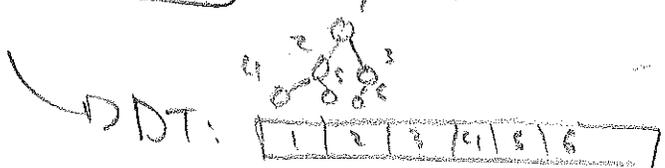
e.g. unordered linked list  
 ordered  $\checkmark$   
 heap

ins( $S, x$ )	extract_max( $S$ )
$\Theta(1)$	$\Theta(n)$
$\Theta(n)$	$\Theta(1)$
$\Theta(\log n)$	$\Theta(\log n)$

**CBT**:



**Max-Heap**: CBT, s.t.  $\forall n \in \text{CBT}, \text{value}(n) \geq \text{value}(\text{child}(n))$   
 $\geq \text{value}(\text{rchild}(n))$



max heap property

heapsize =  $n$   
 Rchild of  $A[i]$  is  $A[2i]$  (parent:  $A[\lfloor \frac{i}{2} \rfloor]$ )  
 Rchild  $A[2i+1]$

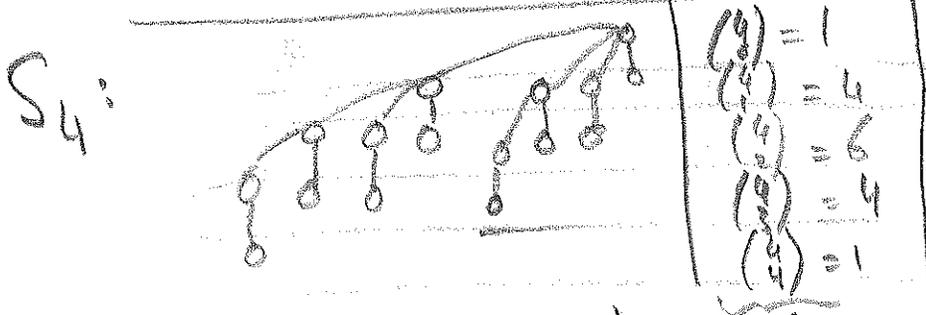
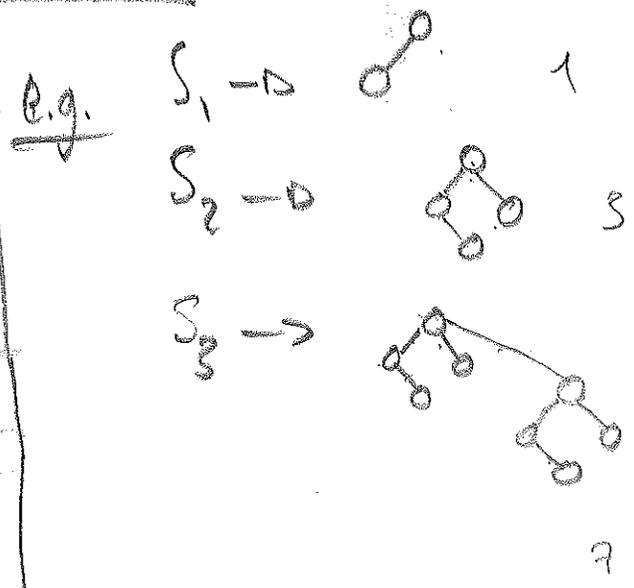
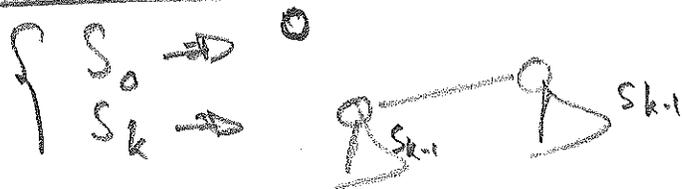
height of ~~tree~~ is length of longest path from root to leaf -

$\rightarrow$  Heap Ops: 1. Get CBT shape right  
 constraints 2. Get maxheap. right

insert: put at last pos then swaps (max: height)  
 extract\_max: swap last pos with root  
 decrease heapsize  
 heapify (swap, compare w/ heapsize)

ADT	ops	DS	CSC 263 COG 250 CSC 321 MAT 224 CSC 363 PSY 270 CSC 2534 ECE 516
priority Q	<ul style="list-style-type: none"> <li>insert</li> <li>max</li> <li>extract-max</li> </ul>	Heap (CRSB)	CBT based on bin-forest
mergeable priority Q	All above + Union (S, T)	Binomial Heaps	

### $S_k$ -Trees



$S_k$ -tree has  $2^k$  nodes — and  $\binom{k}{d}$  nodes at depth  $d$ .

### Binomial Forest

A binomial forest of size  $n$  ( $BF_n$ ) is a sequence of  $S_k$ -trees w/ decreasing  $k$ 's and  $s$  nodes.

- eg.
- ①  $BF_7 = \langle S_2, S_1, S_0 \rangle$
  - ②  $BF_9 = \langle S_3, S_0 \rangle$

A  $BF_n$  with  $n = \langle b_{l-1}, \dots, b_0 \rangle_2$  nodes

$BF_n = \langle \text{all } S_k \text{ trees s.t. } b_k = 1 \rangle$

- ① Largest tree in  $BF_n$  is  $S_l$  with  $l = \lfloor \log_2 n \rfloor$
- ② Let  $\alpha(n) = \#$  of 1's in the binary rep of  $n$

- (a)  $BF_n$  has  $\alpha(n)$  trees
- (b)  $BF_n$  has  $n - \alpha(n)$  edges

A (min) binomial heap of  $n$  elements with keys is a  $BF_n$  s.t.

- (a) Each node of  $BF_n$  stores 1 element
- (b) Each  $S_k$ -tree of  $BF_n$  is (min) heap-ordered

$S_k$  tree  
 has a root node w/ exact  $k$  children

- ①  $S \leftarrow \text{UNION}(S, T)$   $\rightarrow$  binary addi<sup>o</sup>
- ② insert  $\rightarrow$  for  $\{x\} \rightarrow S_0: (x) \rightarrow$  Union
- ③  $\text{MIN}(T) \rightarrow$  look at roots ( $O(\log n)$ )
- ④ Extract-min / Delete-min

e.g.  $|T| = 27 \rightarrow \langle S_4, S_3, S_2, S_0 \rangle$  (11011)

$\rightarrow 27 - 4 = 23$  edges

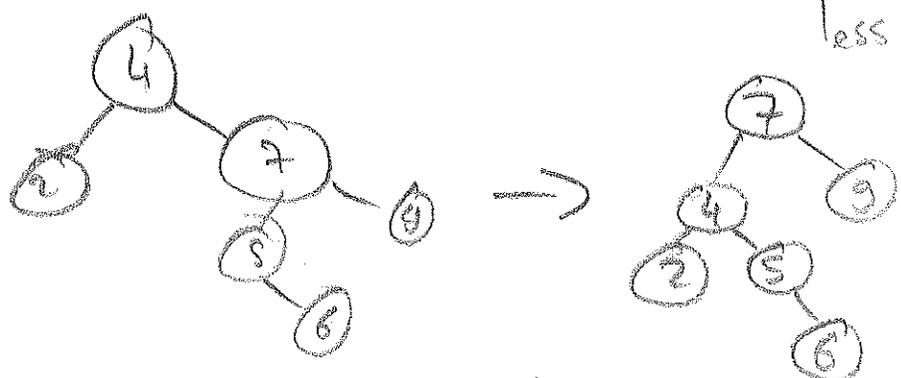
insert  $\{x\}$ :  $+ \begin{array}{r} 11011 \\ 11100 \\ \hline \end{array}$  } 2 key comps  $\Rightarrow$  2 new edges

$\Rightarrow 25$  edges (check:  $28 - 3 = 25$ )  
(23+2)

$\rightarrow$  Bin heap: since based on bin addi<sup>o</sup>

$\rightarrow$  when insertions  $> \log n \Rightarrow$  avg insert is cost  
less than  $\frac{1}{2}$

BST rota<sup>o</sup>

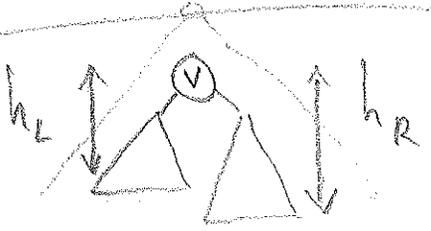


Priority Queues implemented with heaps (and used almost always for that purpose) -

$$\frac{\log i}{\log 2} \approx i \cdot e^{-2}$$

ADT	OPS	Data Structures
Dictionary	Insert, Delete, Search	BST
		Balanced BST <ul style="list-style-type: none"> <li>- 2-3 trees</li> <li>- Red-black trees</li> <li>- AVL-trees</li> <li>(...)</li> </ul>

Balanced trees



$$BF(v) = h_R - h_L$$

height right subtree - height left subtree

AVL-tree == BST s.t.  $\forall v \in AVL, BF(v) = -1 || 0 || +1$

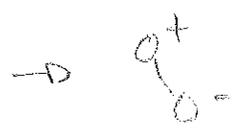
height of AVL : with  $n$  nodes have height  $O(\log n)$

$$\left[ \leq 1.44 \log(n+2) \right]$$

→ Can do inserts and deletes while Maintaining the balance

insert( $T, x$ )

- insert as in any BST,  $x$  == leaf
- go up to root # notice: if encounter 0, no need to go up any more #
- rotate if needed

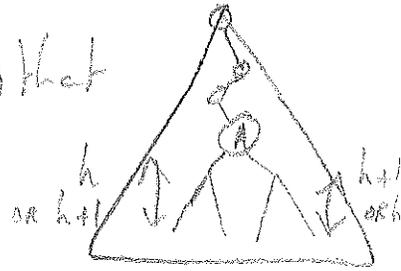


After Rotation:

- (1) rebalanced
- (2) BST property
- (3) height same as before (bonus)

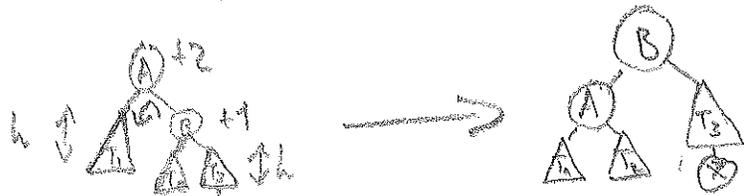
# Rebalancing

Let  $A$  be the first node on path  $R \rightarrow \text{root}(T)$  that becomes unbalanced.



wlog  $A \rightarrow +1 \rightarrow +2$  (sym.  $A \rightarrow -1 \rightarrow -2$ )

case (1).1



case (1).2



# Deletion

No bonus

Article on Sorting + DS

2368206  $\rightarrow$  263 SLOG

TSP

aloph — 1/2  
 baeb gimed dalek  
 he jav zayin  
 let — 1/3/7  
 tek d h kamed  
 mem — 0/0  
 nuw — 5/1  
 samekh ayin  
 9/9/9  
 sadke — 5/7  
 qof reek shin  
 tav — 1/1  
 N Z λ T Π I P Π U' E S H J V Y G Y P T E A  
 A B Γ Δ E Z H Θ I K Λ M N Ξ O Π P Σ T Y Φ X Ψ Ω  
 α β γ δ ε ζ η θ κ λ μ ν ξ ο π ρ σ τ υ φ χ ψ ω

# Summary

1	Priority Qs	Heaps
2	mergeable priority Qs	Binomial Heaps
3	Dictionary	BST, AVL

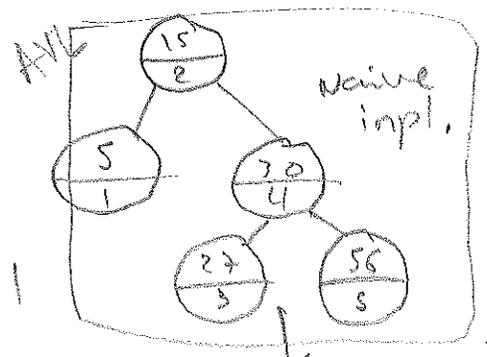
## Augmenting Data Structures

E.g. Dynamic Order Statistics

- set  $S$  of  $n$  elements with keys
- ops: insert, delete, search
- $select(k)$ : return the element of rank  $k$
- $rank(v)$ : returns the rank of  $v$ .

$k$ th one in sorted order

e.g.  $S = \{5, 15, 27, 30, 56\}$   
 $select(4) = 30$   
 $rank(15) = 2$

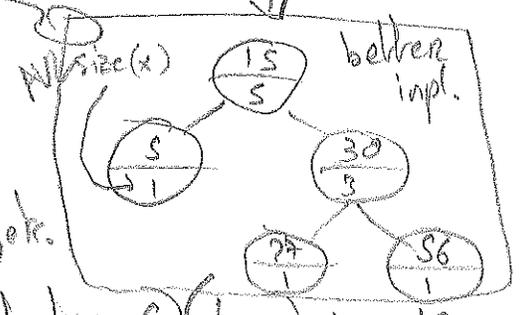


$$size(v) = size(left(v)) + S(R(x)) + 1$$

relative ranking

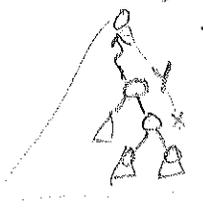
$$RR(x) = size(left(x)) + 1$$

$select(k) \Rightarrow$  to find  $k$ th rank,  
 if  $k < RR(x)$ , find  $k$ th rank of  $left(x)$ , etc.



$\Rightarrow$  (since AVL tree),  $select(k)$  takes  $O(\log n)$  in WC.

$rank(k) \Rightarrow$  determine  $RR(x)$  in  $x$ -subtree.  
 in every node from path  $x \rightarrow$  root, determine  $RR(y)$  in  $y$ -subtree:  
 $RR(x) = \begin{cases} RR(x) & \text{if } x \text{ is left child} \\ RR(x) + RR(y) & \text{if } x \text{ is right child} \end{cases}$



$\Rightarrow$  (---),  $rank(k)$  takes  $O(\log n)$  in WC.

Naive ranking

# Maintaining size info

## insert(x):

- x ends up a leaf  $\Rightarrow$  size(x) := 1
  - add 1 to size(y) for all y  $\in$  path x  $\rightarrow$  root
  - proceed (as usual in AVL) from x  $\rightarrow$  root updating Balance Factors and rebalancing.
- $\Rightarrow$  takes  $O(\log n)$  if a rota<sup>n</sup> is done, then update sizes!

## Average / Expected Complexity

e.g. implementing a dictionary with keys  $k \in U$ ,  $U = \{0, 1, \dots, u-1\}$

1 - u is small, use a direct access table

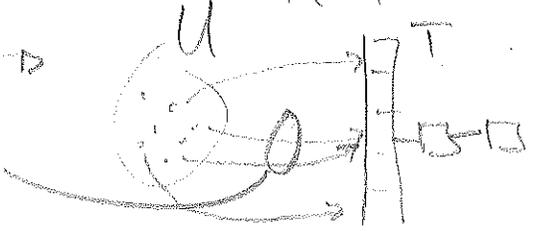


2 - u is very large, use a hash table

- let  $k \in U$  and  $T$  (hash table),  $|T| = m$  (i.e.  $[0, \dots, m-1]$ )
- hash function  $h: U \rightarrow T$
- $e \mapsto h(e) = i, i \in \{0, \dots, m-1\}$  if  $i \in T$

## Hashing w/ Chaining

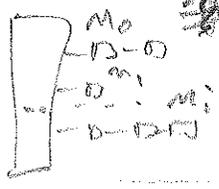
collision  $\Rightarrow$  linked list (LIFO)



WC is  $O(m)$  (if  $h()$  leads to many collisions)

## Simple Uniform Hashing Assumption (SUHA)

Any key  $k$  is equally likely to hash into any of  $m$  slots of  $T$ .  
 Assumption relies on  $h()$  and dist. of  $k \in U$ .



$$\Rightarrow P(h(k) = i) = \frac{1}{m} \quad (i \in \{0, \dots, m-1\})$$

proof  $E(m_0 + \dots + m_{m-1}) = \sum_{i=0}^{m-1} (E(m_i))$

By SUHA,  $\forall i, j, E(m_i) = E(m_j)$

$\Rightarrow m E(m_i) = m \Rightarrow E(m_i) = \frac{m}{m} = \alpha$  load factor

Additional assumption:  $m \in \Theta(n) \Rightarrow \alpha \in \Theta(1)$

→ Worst Case Cost of  $QRS(S)$  is  $\Theta(m^2)$

AKO, HOPCROFT, ULLMAN

## Analysis of QRS

- 2 keys compared iff 1 is a pivot
- 2 keys can be compared at most once.
- 2 keys split apart by pivot are never compared.

Fix  $|S| = m$ . cost of  $QRS = \#$  key comps.

WC:  $C = \Theta(m^2)$

AC:  $E(C) = ?$

•  $S$  has  $m$  keys:  $z_1 < z_2 < \dots < z_i < \dots < z_j < \dots < z_m$

•  $c_{ij} = \begin{cases} 1 & \text{if } z_i \text{ comp to } z_j \\ 0 & \text{if } \dots \end{cases}$

$$\Rightarrow E(C) = E\left[\sum_{i < j} c_{ij}\right] = \sum_{i < j} E(c_{ij})$$

$$E(c_{ij}) = 1 \times \Pr[c_{ij} = 1] + 0 \times \Pr[c_{ij} = 0] = \Pr[c_{ij} = 1]$$

Consider  $Z_{ij} \subseteq Z$  (cont'd  $S$ ),  $|Z_{ij}| = j - i + 1$

• initially  $Z_{ij} \subseteq Z = S$

•  $QRS$  keeps selecting pivots

→ as long as they aren't in  $Z_{ij}$ ,  $Z_{ij}$  remains <sup>subinterval of a subarray</sup>

→ at some pt,  $QRS(S)$  must select a pivot within  $Z_{ij}$

• case 1:  $z_i < p < z_j \Rightarrow z_i$  is never comp to  $z_j$

• case 2:  $p = (z_i \vee z_j) \Rightarrow$  prob of that is  $\frac{2}{j-i+1}$

$$\Rightarrow E(C) = \sum_{i=1}^j \sum_{j=2}^m \frac{2}{j-i+1} = \sum_{i=1}^{m-1} \sum_{j=i+1}^m \frac{2}{j-i+1}$$

$$= \sum_{i=1}^{m-1} \sum_{k=1}^{m-i} \frac{2}{k+1} < 2 \sum_{i=1}^m \sum_{k=1}^m \frac{1}{k+1}$$

$$\Rightarrow E(C) \leq 2m H_m \wedge H_m \in O(\ln m)$$

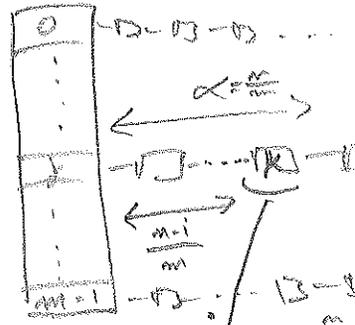
$$E(C) \in O(m \log m)$$

# Hashing cond'

SUHA:  $\forall 0 \leq j < m-1, \Pr[h(k)=j] = \frac{1}{m}$

①  $k \notin T: E \approx \alpha$

②  $k \in T: E \approx \frac{\alpha}{2}$



↳ Assume that  $\Pr[k=k_i] = \frac{1}{m}$

"k is equally likely to be any of the m keys inserted in T."

⇒ Expected cost:  $E = \frac{1}{m} \sum_{i=1}^m [\frac{m-i}{m} + 1]$

$= \frac{1}{m} (\frac{1}{m} \sum_{i=1}^m [m-i] + m)$

$= \frac{1}{m} \frac{1}{m} \frac{m(m-1)}{2} + 1$

$= \frac{\alpha}{2} - \frac{1}{2m} + 1$

↳ connecting factor intro.

⇒ if k was ith key to be inserted, expected # comps is  $[\frac{m-i}{m} + 1]$ .

distribute k in m slots:  $\frac{k}{m}$  and half:  $\frac{1}{2}$

e.g.  $\begin{cases} m=2000 \\ m-1 \text{ is prime} \\ k(k) = k \bmod m \\ E(\text{search}(k)) \approx 3 \end{cases}$

$\Rightarrow \alpha \leq 3 \Rightarrow m \geq \frac{2000}{3} \Rightarrow m > 666 \Rightarrow m = 701$

## Probabilistic algorithm

↳ Assumes input is random → input follows some 'nice' dist. e.g. hashing with SUHA

⑦

## Randomized algorithm

↳ Uses nondeterminism

e.g. Randomized Quick sort (recursive guy)

input: set of n distinct keys  
output: sorted keys

RQS(S): if  $S = \emptyset$ , then return

• if  $|S| = 1$ , then output key and return.

• if  $|S| \geq 2$ , then: select pivot  $p$  uniformly at random.

• by comparing  $p$  with every other key in  $S$ , split  $S$  into:  $S_L = \{s \in S / s < p\}$

$S_R = \{s \in S / s > p\}$

•  $RQS(S_L)$ , output  $p$ ,  $RQS(S_R)$

# Disjoint Sets

25 years for analysis!  
 → 64-73-79-89

- $m$  distinct elements
- initially each is in its own set:
- each set has a representative
- $S_x = \text{set rep. by } x$

$S_1 = \{1\}, S_2 = \{2\} \dots S_m = \{m\}$

- operations:
  - + UNION( $S_x, S_y$ ): replaces sets  $S_x$  and  $S_y$  by  $S = S_x \cup S_y$
  - + FIND( $z$ ): finds  $S$ , s.t.  $z \in S$

	$S_1$	$S_2$	$S_3$	$S_4$	$S_5$
eg:	{1}	{2}	{3}	{4}	{5}

- At most  $m-1$  UNIONS possible
- $\sigma = \text{seq of } m-1 \text{ UNIONS}$  mixed w/  $m \geq m$  finds
- how to minimize the cost of executing  $\sigma$  seqs?

U( $S_3, S_4$ )		{3,4}	X	
F(4) = $S_3$				
U( $S_1, S_5$ )	{1,5}			X
U( $S_1, S_3$ )	{1,3,4}		X	
F(4) = $S_1$				

→ impl: linked list whose head is the rep of the set



DT for  $m \ll$

→ cost of UNION:  $O(1)$   
 → cost of FIND:  $O(m)$   
 }  $xm$  ⇒ cost( $\sigma$ ) =  $O((m+1)m)$

• augmented linked list



→ cost:  $O(m)$   
 → cost:  $O(1)$   
 }  $xm$  ⇒  $O(m \log m)$

• w/ weighted UNION rule

→ ANALYSIS in TUTORIAL  
 $O(m \log m)$

• forest DT



→ cost 1:  $O(1)$   
 → cost 1:  $O(1 + \text{len of FIND path})$

how to reduce?

① Weighted UNION [by size] CLRS: Rank



With WU rule (by size) any tree of height  $h$  created during the exec of

of seq  $\sigma$  has at least  $2^h$  nodes, i.e.  $|T| \geq 2^h$

proof (induct on height of T: h)

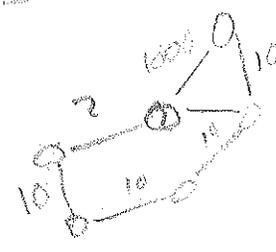
- Basis: When a tree of height  $h = 0$  is created it has  $2^0 = 1$  node.
- IS: Assume the lemma holds for  $h$

Consider the next time a tree  $T$  of height  $h+1$  is created.

By IH:  $|A| \geq 2^h$

By WU:  $|B| \geq |A| \geq 2^h$

$\Rightarrow |T| = |A| + |B|$   
 $|T| \geq 2^h + 2^h \geq 2^{h+1}$



$\rightarrow$  Thus, by lemma:  $2^h \leq |T| \leq m \Rightarrow h \leq \log m$   
 with WU,  $\text{cost}(\sigma) = O(m + m \log m)$

② Path compression rule

PC: at each FIND, chg plus of all nodes to pt to root

$\rightarrow$  with WU & PC,  $\text{cost}(\sigma) = O(m \log^* m)$

\*  $\hookrightarrow 2 \uparrow \uparrow m : \begin{cases} 2 \uparrow \uparrow 0 = 1 \\ 2 \uparrow \uparrow (m+1) = 2^{2 \uparrow \uparrow m} \end{cases}$   
 $\hookrightarrow \log^* m = \min \{k \mid 2 \uparrow \uparrow k \geq m\}$

$2 \uparrow \uparrow 0 = 1$
$2 \uparrow \uparrow 1 = 2$
$2 \uparrow \uparrow 2 = 4$
$2 \uparrow \uparrow 3 = 16 = 2^{2^2}$
$2 \uparrow \uparrow 4 = 65536 = 2^{2^{2^2}}$
$2 \uparrow \uparrow 5 = 2^{65536} \approx 10^{19728}$
$2 \uparrow \uparrow 6 = \text{Lantern}$

1973: proof of  $O(m \log^* m)$  (cf paper)

1975: tarjan: proof of  $O(m \alpha^{-1}(m, m))$  where  $\alpha$  is the ackermann func

1979: tarjan:  $\Omega(\dots)$  under same assump

$\rightarrow$  Double recursion in ackermann func impl. in Machine Swiches (p. 100) by S. M.

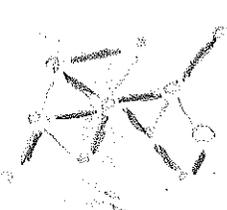
1989: same w/out assump  
 Any alg that solves Disjoint Set Unification pb is  $\Theta(m \alpha^{-1}(m, m))$

Minimum cost spanning tree

$2^3 = 2 \times 2 \times 2$ ,  $2 \uparrow \uparrow 3 = 2^{2^2}$ ,  $2 \uparrow \uparrow \uparrow 3 = 2 \uparrow \uparrow 2 \uparrow \uparrow 2$   
 $= 2 \uparrow \uparrow (2^{2^2})$

TUTORIAL

no unives: 1 obj / set  
 $= 2^{2^{2^2}}$  times



set of edges s.t. cost is minimized & all cities are connected

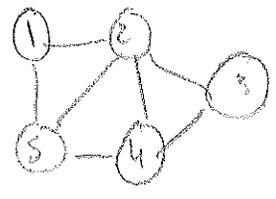
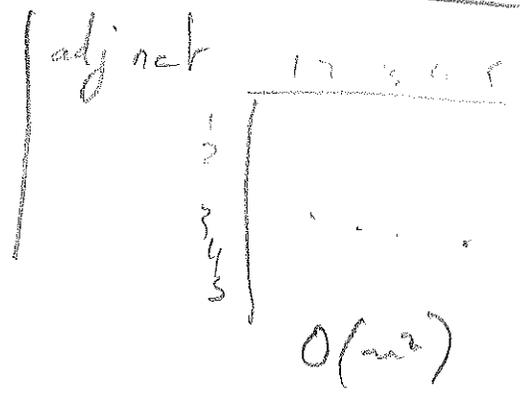
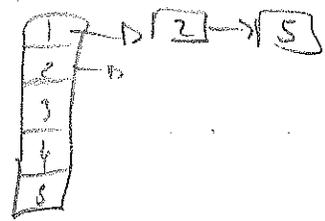
$\Rightarrow 2^k = m \Rightarrow k = \log m$  (Kruskal's alg.)



# Graphs $G = (V, E)$ , $|V| = n$ , $|E| = m$

CSC263

adjacency list



## BFS

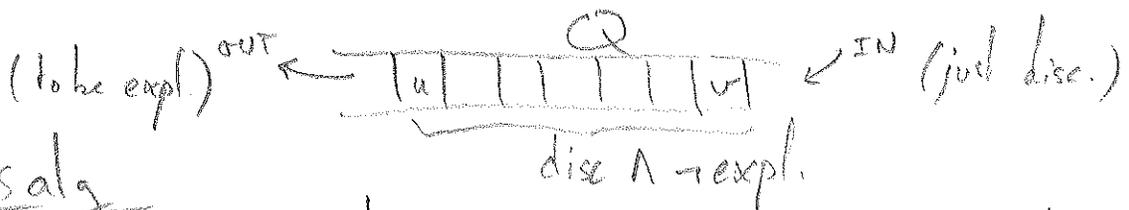
start  $s \in V$  explore all neighbours

- colour  $(v)$  = white  $\rightarrow V$  is undiscovered
- grey  $\rightarrow V$  was disc. but not explored
- black  $\rightarrow V$  was disc and expl.

length of disc. path  $= d[v]$   
 $s \rightarrow \dots \rightarrow u \rightarrow v$   
 $d[v] = d[u] + 1$

$P[v] = u$  : "u disc. v"

$\rightarrow$  BFS tree is graph induced by all edges  $(u, v)$  s.t.  $P[v] = u$



## BFS alg

initialization

- colour  $[s] \leftarrow$  grey,  $d[s] \leftarrow 0$ ,  $P[s] \leftarrow$  NIL
- $\forall v \in V, v \neq s$ , colour  $[v] \leftarrow$  white,  $d[v] \leftarrow \infty$ ,  $P[v] \leftarrow$  NIL
- $Q \leftarrow$  EMPTY, ENQ  $(Q, s)$

code

```

while Q  $\neq$   $\emptyset$ 
{
  u  $\leftarrow$  DEQ(Q)
  for each (u, v)  $\in$  E do
  {
    if colour(v) = white do
    {
      colour(v)  $\leftarrow$  grey
      P[v]  $\leftarrow$  u
      d[v]  $\leftarrow$  d[u] + 1
      ENQ(Q, v)
    }
  }
  colour[u]  $\leftarrow$  BLACK
}
    
```

WC-complexity:  $O(m+n)$   
 let  $\delta(s, v) \triangleq$  length of shortest path  $s \rightarrow v$  in  $G$   
 $\Rightarrow \delta(s, v) \leq d[v]$

WC-complexity of BFS (graph-disc.) is  $O(m+n)$

L0  $\delta(s, v) \leq d[v]$



L1  $u$  enters  $Q$  before  $v$  during  $BFS(s) \Rightarrow d[u] \leq d[v]$

proof Suppose ~~by~~ contra that L1 is FALSE before v entered Q  
for

Let  $v$  be the 1<sup>st</sup> node that enters  $Q$  s.t.  $d[u] > d[v]$  for some  $u$  that  $u \neq s$  bcs  $d[s] = 0$ ,  $v \neq s$  bcs  $s$  is the 1<sup>st</sup>.

$u$  and  $v$  entered  $Q$  during explora<sup>n</sup> of some nodes  $u'$  and  $v'$  resp.  
 $d[u] = d[u'] + 1$        $d[v] = d[v'] + 1$       since  $d[v] \neq d[u] \Rightarrow u' \neq v'$

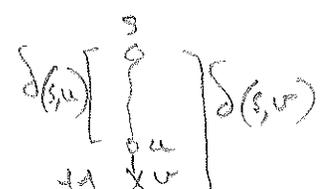
since  $u$  entered  $Q$  before  $v$ ,  $u'$  was expl. before  $v'$ ,  $u'$  entered  $Q$  before  $v'$  entered  $Q$ . By def,  $d[u'] \leq d[v']$   
 $d[u'] + 1 \leq d[v'] + 1$   
 $d[u] \leq d[v]$   $\rightarrow$  contradictio

Theorem After  $BFS(s)$ ,  $\forall v \in V, d[v] \stackrel{\delta}{=} \delta(s, v)$

proof Suppose for contra,  $\exists x \in V, d[x] \neq \delta(s, x)$

Shortest

Let  $v$  be closest node from  $s$  s.t.  $d[v] \neq \delta(s, v)$ .



(Clearly,  $d[v] > \delta(s, v)$ ) (1)

Consider a shortest path from  $s \rightsquigarrow v$

$\delta(s, v) = \delta(s, u) + 1$  (2)

$d[v] > d[u] + 1$   
 $\star$

Since  $u$  is closer than  $v$  to  $s$ , it must be that  $\delta(s, u) = \delta(s, v) - 1$  (3)

$d[v] > \delta(s, v) = \delta(s, u) + 1 = d[u] + 1$

- $\circ$  Consider the colour of  $v$  just before  $u$  is expl.
- (a)  $v$  is white:  $u$  expl.  $v \Rightarrow d[v] = d[u] + 1$  — contra to  $\star$
- (b)  $v$  is black:  $v$  was expl. bef.  $u$ ,  $v$  ent.  $Q$  bef.  $u$ .  
 by L1  $\Rightarrow d[v] \leq d[u]$  —  $\star$

(c)  $V$  is grey/gray, some  $w$  disc.  $v$  bef.  $u$  is expl.

$\Rightarrow w$  expl. bef  $u$  expl.

$\Rightarrow w$  enters  $Q$  bef  $u$  enters  $Q$

$\Rightarrow d[w] \leq d[u], d[w]+1 \leq d[u]+1 \Rightarrow d[v] \leq d[u]+1$   
 — constraint



## Depth First Search

Same as in BFS: colours,  $P[v] = u$  iff " $u$  disc.  $v$ "

DFS:  
last

Different from BFS: global var for time (counter)  
 $d[u]$ : time when  $u$  was disc.  
 $f[u]$ :  $u$ 's expl. was compl.

### alg. DFS( $G$ )

[For each  $w \in V$   
 colour  $[w] \leftarrow w; d[w] \leftarrow \infty; f[w] \leftarrow \infty; P[w] \leftarrow NIL$   
 time  $\leftarrow 0$   
 For each  $v \in V$   
 if colour  $[v] = w$ , then DFS-explone( $G, v$ )

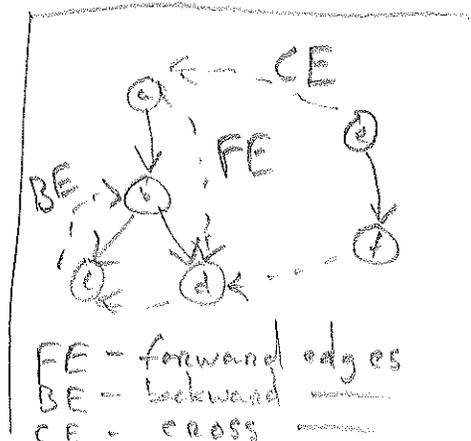
### DFS-explone( $G, u$ )

colour  $[u] \leftarrow$  grey  
 time  $\leftarrow$  time + 1;  $d[u] \leftarrow$  time



[For each edge  $(u, v) \in E$   
 if colour  $[v] =$  white then /\*  $u$  disc.  $v$  \*/  
 $P[v] \leftarrow u$   
 DFS-explone( $G, v$ )

colour  $[u] \leftarrow$  black  
 time  $\leftarrow$  time + 1;  $f[u] \leftarrow$  time



$\rightarrow$  DFS forest

$a \rightsquigarrow d \quad \forall (a, d), a :: \text{ancestor}, d :: \text{descendant}$  CSC 263

$$d[a] < d[d] < f[d] < f[a]$$

~~2011/11/11~~

Claim 1

$v$  is a DESC. of  $u$  in DFS forest iff  
 $d[u] < d[v] < f[v] < f[u]$

Claim 2

For any 2 nodes,  $u$  and  $v$ , we cannot have  
 $d[u] < d[v] < f[u] < f[v]$   
 overlapping disc. intervals are imp.

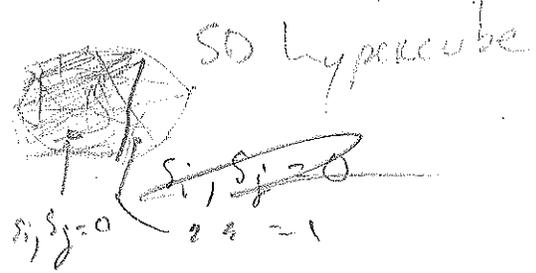
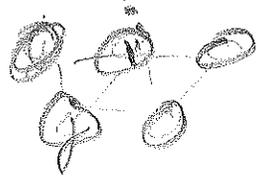
Claim 3

if  $(u, v) \in E$ , then  $d[v] < f[u]$

Applica. of BFS: use to find # comp. (and nature)

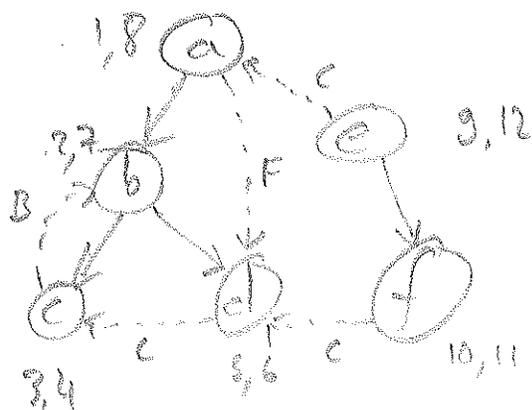
No cycles  $\Leftrightarrow |E| = |V| - 1$  comp

GBM - 10



# DFS cont'd

CS663



- C1:  $u$  is ancestor of  $v$  in the DFS of  $G$  iff  $d[u] < d[v] < f[v] < f[u]$
- C2: for any  $u$  and  $v$ , we cannot have  $d[u] < d[v] < f[u] < f[v]$
- C3: if  $(u,v) \in E$  [that is,  $u \rightarrow v$  in  $G$ ] then  $d[v] < f[u]$

A DFS of a directed graph  $G$  classifies its edges as follows:  
 $(u,v) \in E$  is a:

- ① true edge iff  $u$  is parent of  $v$  in DFS of  $G$
- non-tree edges:
  - ② forward edge iff  $u$  is ancestor of  $v$
  - ③ back edge iff  $u$  is descendant of  $v$
  - ④ cross edge otherwise

→ Claim:  $(u,v) \in E$  is of type

- ① or ② iff  $d[u] < d[v] < f[v] < f[u]$
- ③ iff  $d[v] < d[u] < f[u] < f[v]$
- ④ iff  $d[v] < f[v] < d[u] < f[u]$

## Applications of DFS

→ White Path Theorem (CLRS 22.9)

$\forall e \in E, \forall$  DFS of  $G, v$  becomes a descendant of  $u$  iff at the same time  $d[u]$  (the DFS disc.  $u$ ), there is a path from  $u$  to  $v$  in  $G$  that consists entirely of white nodes.

proof

①  $\Rightarrow$

Suppose  $v$  is a descendant of  $u$  in the DFS at  $d[u]$ .  
not yet discovered so they are all white.

②  $\Leftarrow$

Suppose at the time  $d[u]$ ,  $u \xrightarrow{\text{white}} w \xrightarrow{\text{white}} z \xrightarrow{\text{white}} v$   
Suppose for contradiction, that  $\exists$  a node in the white path that is not a descendant of  $u$ . Let  $z$  be the closest such node to  $u$  in that path.  
Then  $w = u$  or  $w$  is descendant of  $u$ !

- $d[u] < d[z]$  #  $z$  is white at time  $d[u]$
- $d[z] < f[w]$  # by  $z \in B$ .
- $f[w] \leq f[u]$  # because  $w = u$  or  $w$  desc. of  $u$ .

$\Rightarrow d[u] < d[z] < f[z] < f[u]$

$\Rightarrow z$  is disc during expl. interval  $(d[u], f[u])$

$\Rightarrow z$  is a descendant of  $u$

$\Rightarrow$  contra!

$\Rightarrow \forall \text{ node } \in \text{white Path, node is desc. of } u$

Theorem (CLRS 22.11)

$\forall$  directed  $G$ ,  $\forall$  DFS of  $G$ :

$G$  has a cycle  $\Leftrightarrow$  DFS of  $G$  has a back edge

proof ①  $\Leftarrow$

Suppose DFS of  $G$  finds a back edge  $(v, u)$   
then  $u \xrightarrow{\text{white}} v \xrightarrow{\text{white}} u$ , so  $G$  has a cycle

②  $\Rightarrow$

Suppose  $G$  has a cycle  $C$

Let  $u$  be the 1st node in  $C$  DFS discovers

Let  $v$  be the guy before  $u$  in  $C$ .

By WPT,  $v$  is a desc. of  $u$  in the DFS

$\Rightarrow$  back edge by def



# Problem Complexity

CSC263

Let  $P$  be a pb. e.g.  $P$ : "Sorting  $n \#$ "

① -> Alg complexity: given specific alg  $A$ , to solve  $P$  (e.g. Heapsort...)  
what is the cost of solving  $P$  using  $A$ .

② -> Pf complexity: what is the cost of solving  $P$ .

intuitively: By the best possible alg.

-> Decision Tree model:

This can be used to model comparison-based algs. that work by doing comparisons only.  $\Rightarrow$  height of tree is WC.

For each permutation  $\pi$  of  $n$ ; any decision tree for sorting  $n \#$  has at least 1 leaf corresponding to the inverse permutation  $\pi^{-1}$  that 'sorts' input  $\pi$ .  $\Rightarrow$  the tree has at least  $n!$  leaves.

Theorem: Every comparison-based sorting alg  $A$  for sorting  $n \#$  requires at least  $\Omega(n \log n)$  comparisons in the WC.

proof Let  $A$  be any comp.-based alg for sorting  $n \#$ ;  $T_A$  be decision tree.

Let  $h = \text{height}(T_A)$

note in WC,  $A$  takes  $h$  comps!

claim:  $h$  is  $\Omega(n \log n)$

proof of claim:

①  $T_A$  has at least  $n!$  leaves (one for each permutation)

②  $T_A$  is a binary tree of height  $h$ , so it has at most  $2^h$  leaves  $\Rightarrow 2^h \geq n! \Rightarrow h \geq \lg(n!)$  which is  $\Omega(n \log n)$

-> Adversary Approach

e.g.  $P =$  "Find both max & min of Set  $S$  of  $n$  distinct elements"

Naive alg scan  $S$  twice

•  $n-1$  comps

then  $n-2$  comps

} total:  $2n-3$  comps -

## Better alg

Divide  $S$  into  $\frac{n}{2}$  pairs

-> Find max, min of each pair.  $n/2$

-> Scan  $\frac{n}{2}$  maxes to find max:  $n/2 - 1$

-> Scan  $\frac{n}{2}$  mins to find min:  $n/2 - 1$

} tot:  $\frac{3}{2}n - 2$  comps.

Theorem Any comp-based alg for min-max pb takes at least  $\frac{3}{2}n - 2$  comps in WC.

proof of pic -

Starting from initial state  $[n, 0, 0, 0]$

① The alg must create  $n-2$  "M".

To create each "M", it needs to do 1 comp in \*

$\Rightarrow$  alg needs to do at least  $n-2$  comps of type \*

② The alg must also create

.  $n-2$   $\rightarrow$  W or L that becomes M

. 1  $\rightarrow$  W that remains W until the end

. 1  $\rightarrow$  L  $\quad \quad \quad$  L  $\quad \quad \quad$

$\Rightarrow$  alg must create at least  $n$  "L" or "W"

$\Rightarrow$  alg needs at least  $\frac{n}{2}$  comps to create them.

# Minimum Spanning Tree

CSC263

A tree is a connected undirected graph with no cycles.

tree = undirected acyclic connected graph

spanning tree of  $G$  (undirected, connected) = tree  $T = (V, E')$ , s.t.  $E' \subseteq E$

spanning forest = pieces of spanning tree:  $F = \cup T_i$   
( $T_i = (V_i, E_i)$ ) s.t.  $\cup V_i = V$ ,  $\cup E_i \subseteq E$ ,  $V_i \cap V_j = \emptyset$

A Minimum Spanning Tree of  $G$  is s.t.  $\sum w(t)$  is minimized

Num of spanning trees in a clique size  $n$  is

$n^{n-2} \Rightarrow$  brute force approach is exponential time

## Kruskal's MST alg

sort edges alpha + weight and build forest of trees

Given a <sup>implementable</sup> connected undirected weighted graph  $G = (V, E)$  <sup>array</sup>

code:

Build MinHeap( $E$ ) # linear time

Forest  $\leftarrow \{ \{i\}, \dots, \{n\} \}$  # makeSet( $V$ )

MST-edges  $\leftarrow \emptyset$

while  $|(MST-edges)| < n-1$ , do

$(u, v) \leftarrow \text{Extract\_min}(E)$

$T_u \leftarrow \text{Find}(u)$ ;  $T_v \leftarrow \text{Find}(v)$

    if  $T_u \neq T_v$ , then

        | Union( $T_u, T_v$ )

        | MST-edges  $\leftarrow$  MST-edges  $\cup \{(u, v)\}$

End

loop invariant:  
MST-edges are  
contained in  
some MST of  $G$ .

WC - Kruskal :  $O(m) + O(m) + \underbrace{O(m \log m) + O(m \log^* m)}_{\text{dominating term}}$   
 $m \neq O(m^2) \Rightarrow O(m \log m)$

## Traveling Salesman Problem

$G$  : completely connected w/ nonnegative edge weights.

Tour of  $G$  : visit every node exactly once -

TSP tour of  $G$  : min-cost tour -

TSP -> find a TSP tour of  $G$  -

-> brute force : exponential time  $\rightarrow O(n!)$  -> bounded by  $O(2^n)$   
 -> polytime alg  $\Rightarrow O(n^k)$

TSP is NP-complete -

->  $\Delta$ TSP : assume that weights satisfy the triangular inequality  
 i.e.  $\forall u, v, w : c(u, v) \leq c(u, w) + c(w, v)$    
 $\Delta$ TSP is NP-complete -

### Core Lemma

Let TSP be any opt tour of  $G$

Let MST be any MST of  $G$

Then  $\text{cost}(\text{MST}) \leq \text{cost}(\text{TSP})$

proof.

$\forall e$ ,  $\text{cost}(ST) \leq \text{cost}(\text{TSP})$

$\text{cost}(\text{MST}) \leq \text{cost}(ST)$

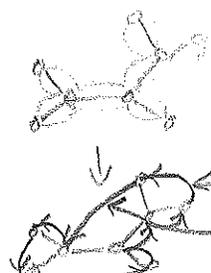
remove 1 edge from

### Approx alg for $\Delta$ TSP with

1. Find MST of  $G$

2. Do a full walk on it  $\rightarrow$  

$\Rightarrow$  cycle  $C$   
 3. Transform  $C$  into a tour  $C^*$



gives a cycle that traverses every edge exactly twice

use triangular inequality!

# Time Complexity

Worst case asymptotic analysis  $O(f(n))$

$\exists c, \exists m_0$  (constant effect),  $n > m_0 \rightarrow f(n) \leq c g(n)$  - not strict  $\leq$  'at some point bounded by'

$\forall c, \exists m_0$  (for every scaling),  $n > m_0 \Rightarrow f(n) < c g(n)$  - strict  $<$  'always asymptotically dominates'

$\rightarrow f \in O(g) \rightarrow f \notin o(f) \rightarrow f \in o(g) \Leftrightarrow \lim_{n \rightarrow \infty} \frac{f}{g} = 0$

Time complexity class:  $\text{TIME}(t(n)) = \{L \mid L \text{ is decidable by some } O(t(n)) \text{ TM}\}$   
 note: single tape TM is polynomially equivalent to multitape TM  
 $\forall$  multitape TM,  $\text{TM} \in O(t(n)) \Rightarrow \exists$  single tape TM'  $\in O(t^2(n))$  equiv. to TM

Non-deterministic TM has runtime  $f(n) = \text{max length of branch of computation}$   
 $\rightarrow$  constrained to being a decider (arbitrariness?)  
 $\forall$  nd TM,  $\text{TM} \in O(t(n)) \Rightarrow \exists$  d TM',  $\text{TM}' \in O(2^{O(t(n))})$  equiv. to TM

Chaper: all reasonable models of comp are poly equivalent  $\rightarrow$  that are equally powerful

$f(n) \in o(n \log n) \Rightarrow \text{TIME}(f(n)) \subseteq \text{REG}$

$P = \bigcup_k \text{TIME}(n^k) \rightarrow$  invariant for models of comp 'reasonable'  
 $\rightarrow$  most problems in reality aren't very poly big ( $n^{100+}$  is rare)

$NP = \bigcup_k \text{NTIME}(n^k) \rightarrow \text{NTIME}(t(n)) = \{L \mid L \text{ is decided by a } O(t(n)) \text{ nd TM}\}$

$NP = \{L \mid L \text{ has a polytime verifier}\}$   $\rightarrow$  alg V is a verifier for L iff  $L = \{w \mid \exists c \in \{0,1\}^*$  V accepts  $\langle w, c \rangle\}$

$\text{CFL} \subsetneq P \quad \text{CSL? NP}$

$\text{PATH} \in P, \text{COPRIME} = \text{RELPRIME} \in P$

$\rightarrow$  L is polynomially verifiable iff it has a polytime verifier  
 $\rightarrow$  measured only in terms of input  $w$