

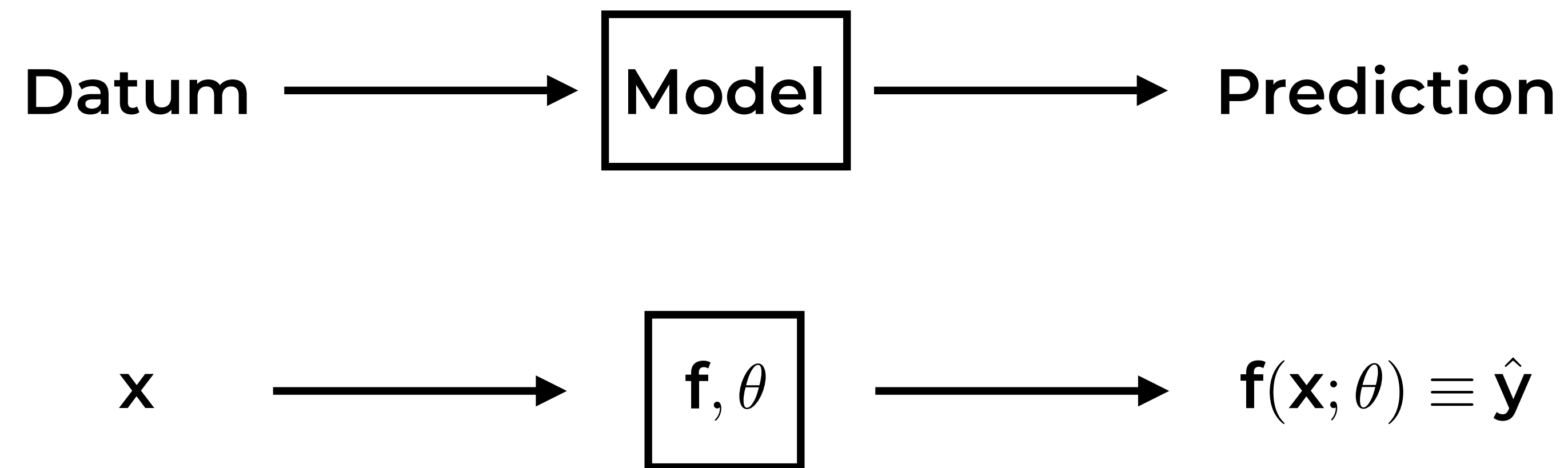
Machine Learning I
MATH80629A

Apprentissage Automatique I
MATH80629

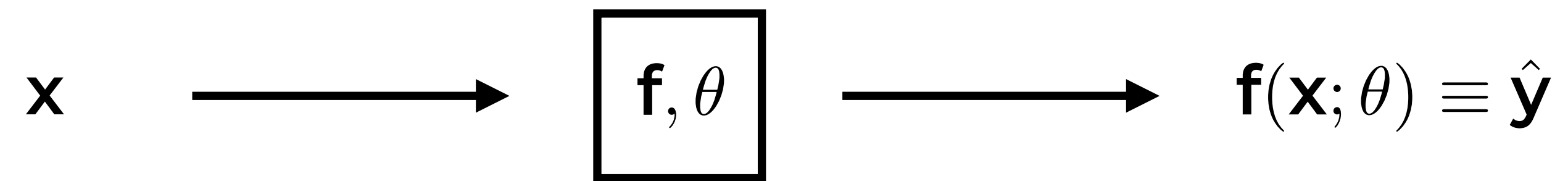
“Mid-term-ish” summary

- **Brief summary of what we have seen so far**
- **Explain concepts within a single framework**
- **Focus on a few more advanced concepts**

Supervised Machine Learning

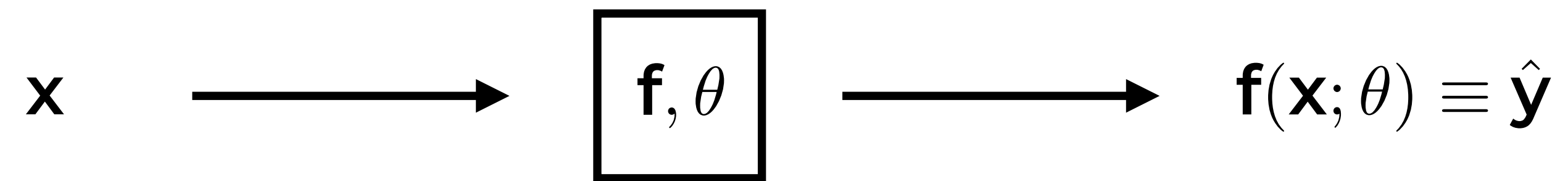


Loss function

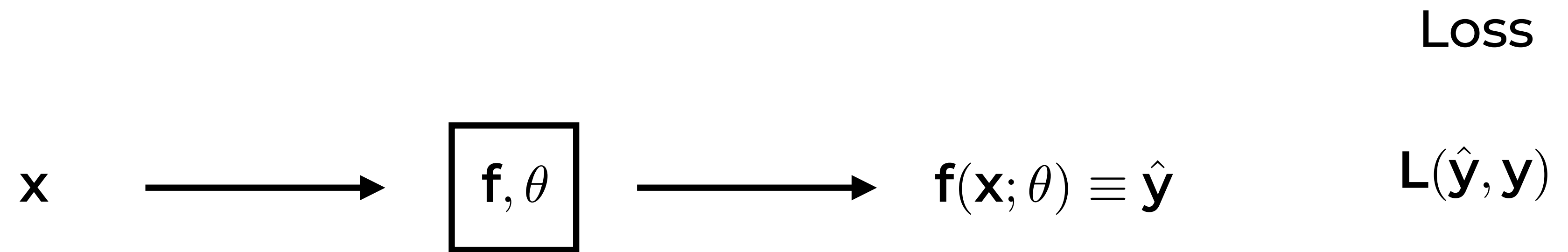


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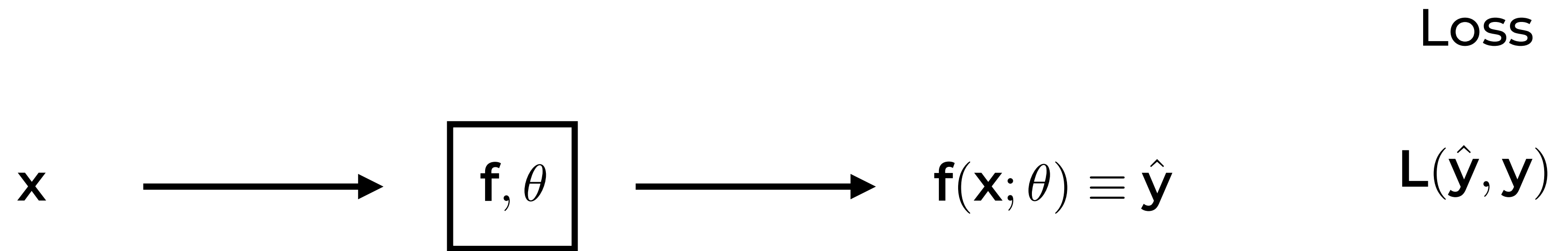
Loss



Loss function



Loss function



Different losses for different types of y 's

$y \in \mathcal{R}$

y categorical e.g., {cat, dog, bird}

$y \in \{0, 1\}$

Regression

Classification

Binary Classification

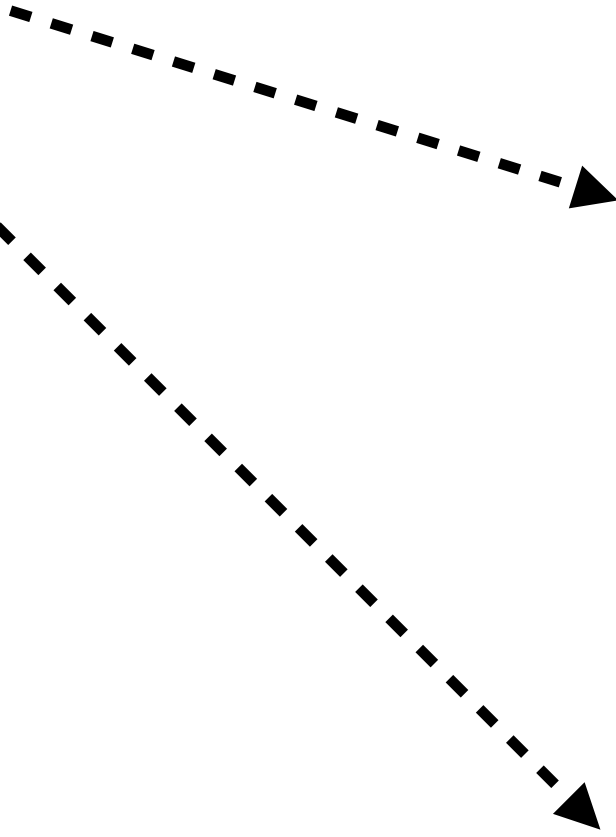
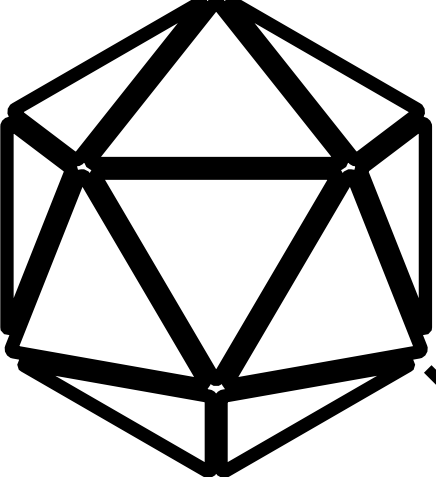
$(\hat{y} - y)^2$

accuracy

AUC

Learning Process

Distribution
over (x,y) :
 $P(x,y)$



X_{train}



f, θ



\hat{Y}_{train}

Loss
 $L(\hat{Y}_{\text{train}}, Y_{\text{train}})$

X_{test}



$f, \hat{\theta}$



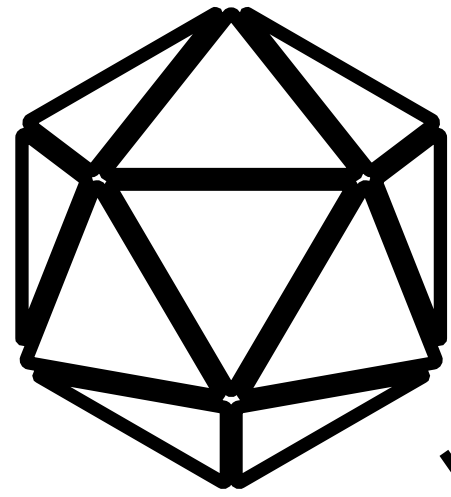
\hat{Y}_{test}

$L(\hat{Y}_{\text{test}}, Y_{\text{test}})$

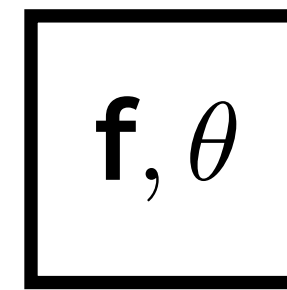
Learning Process

In practice

Distribution
over (x,y) :
 $P(x,y)$



X_{train}

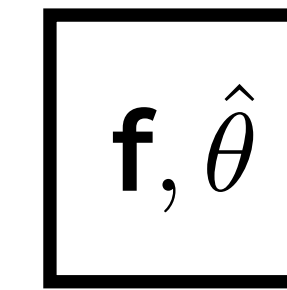


\hat{Y}_{train}

Loss

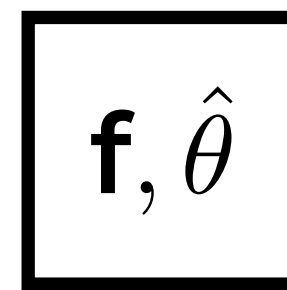
$$L(\hat{Y}_{\text{train}}, Y_{\text{train}})$$

X_{valid}



\hat{Y}_{valid}

X_{test}



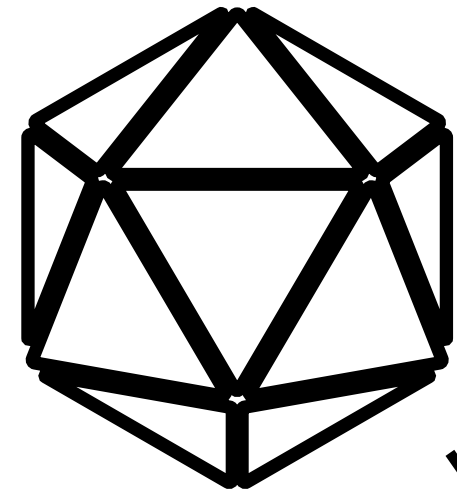
\hat{Y}_{test}

$$L(\hat{Y}_{\text{test}}, Y_{\text{test}})$$

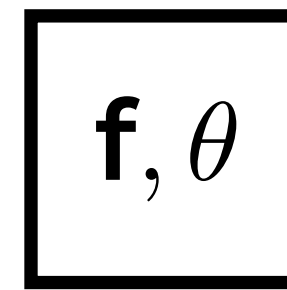
Learning Process

In practice

Distribution
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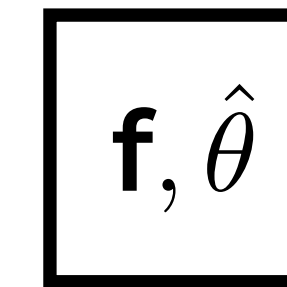


\hat{Y}_{train}

Loss

$$L(\hat{Y}_{\text{train}}, Y_{\text{train}})$$

X_{valid}

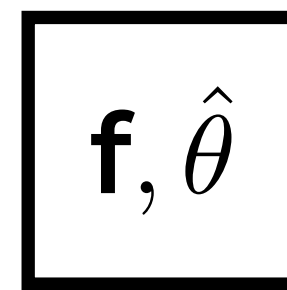


\hat{Y}_{valid}

Useful:

- to select hyper-parameters
- To pick the best model

X_{test}

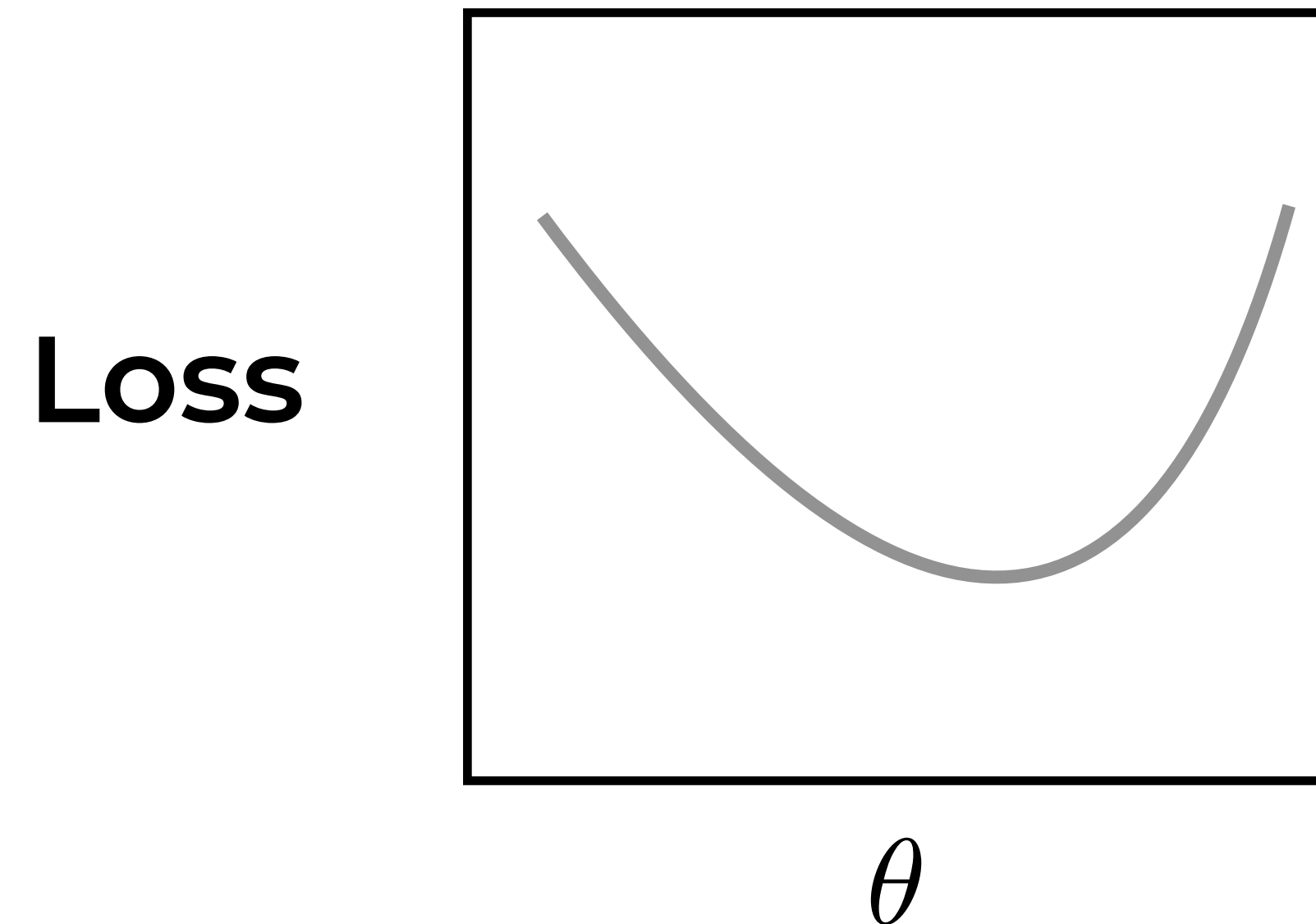


\hat{Y}_{test}

$$L(\hat{Y}_{\text{test}}, Y_{\text{test}})$$

Learning

- Learn: Change the parameters to obtain better predictions



- In other words: change the parameters to minimize the loss
- Take the derivative of the loss wrt the parameter: $\frac{d \text{ Loss}}{d\theta}$

Different models

- **f: linear regression, θ has a closed-form solution**
- **f: neural network, θ does not have a closed-form solution. Gradient descent is used**

- Given a training set: $\{(\mathbf{x}_{\text{train}}, \mathbf{y}_{\text{train}})\}$

- Initialize $\hat{\theta}_1$ randomly

for $t = 1, 2, \dots$ (epochs) **do**

for $i = 1, 2, \dots$ (datum) **do**

 - Obtain the predictions $\{\mathbf{f}(\mathbf{x}_{\text{train}}; \hat{\theta}_t)\}$ (Forward propagation)

 - Compute the Loss: $\text{Loss}_{ti} := L(\mathbf{f}(\mathbf{x}_i; \hat{\theta}_t), \mathbf{y}_i)$

 - Find the derivative of the loss: $\frac{d \text{Loss}_{ti}}{d \hat{\theta}_t}$

 - Update parameters: $\hat{\theta}_{t+1} = \hat{\theta}_t - \alpha \frac{d \text{Loss}_{ti}}{d \hat{\theta}_t}$

 - If $\|\hat{\theta}_{t+1} - \hat{\theta}_t\|_2^2 < \epsilon$ then stop

end for

end for

- Given a training set: $\{(\mathbf{x}_{\text{train}}, \mathbf{y}_{\text{train}})\}$

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Stochastic Gradient Descent



for $t = 1, 2, \dots$ (epochs) **do**

for $i = 1, 2, \dots$ (datum) **do**

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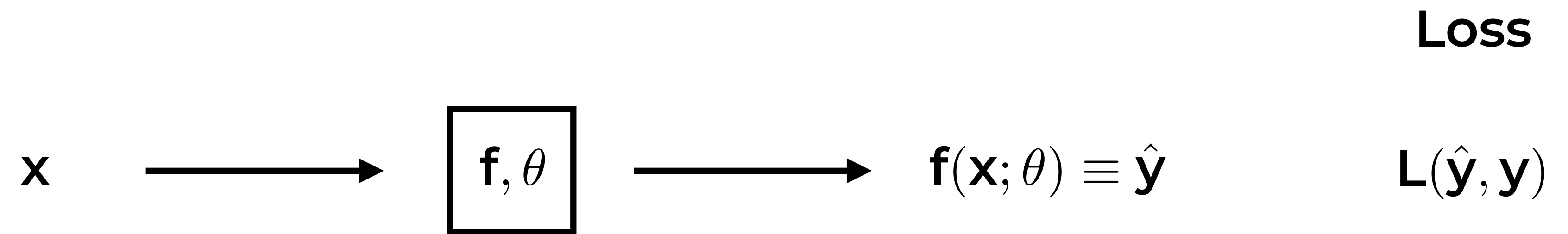
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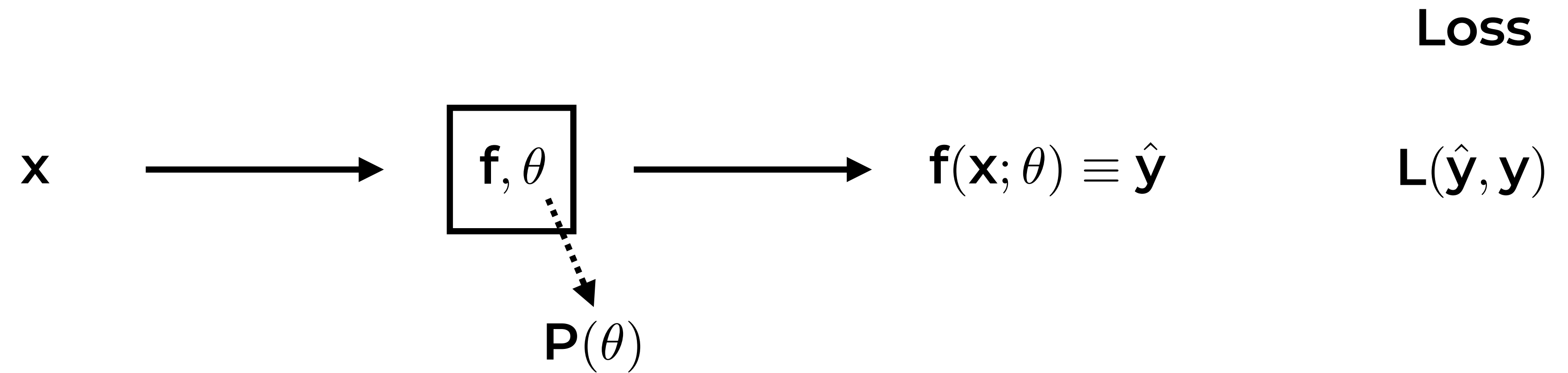
end for

end for

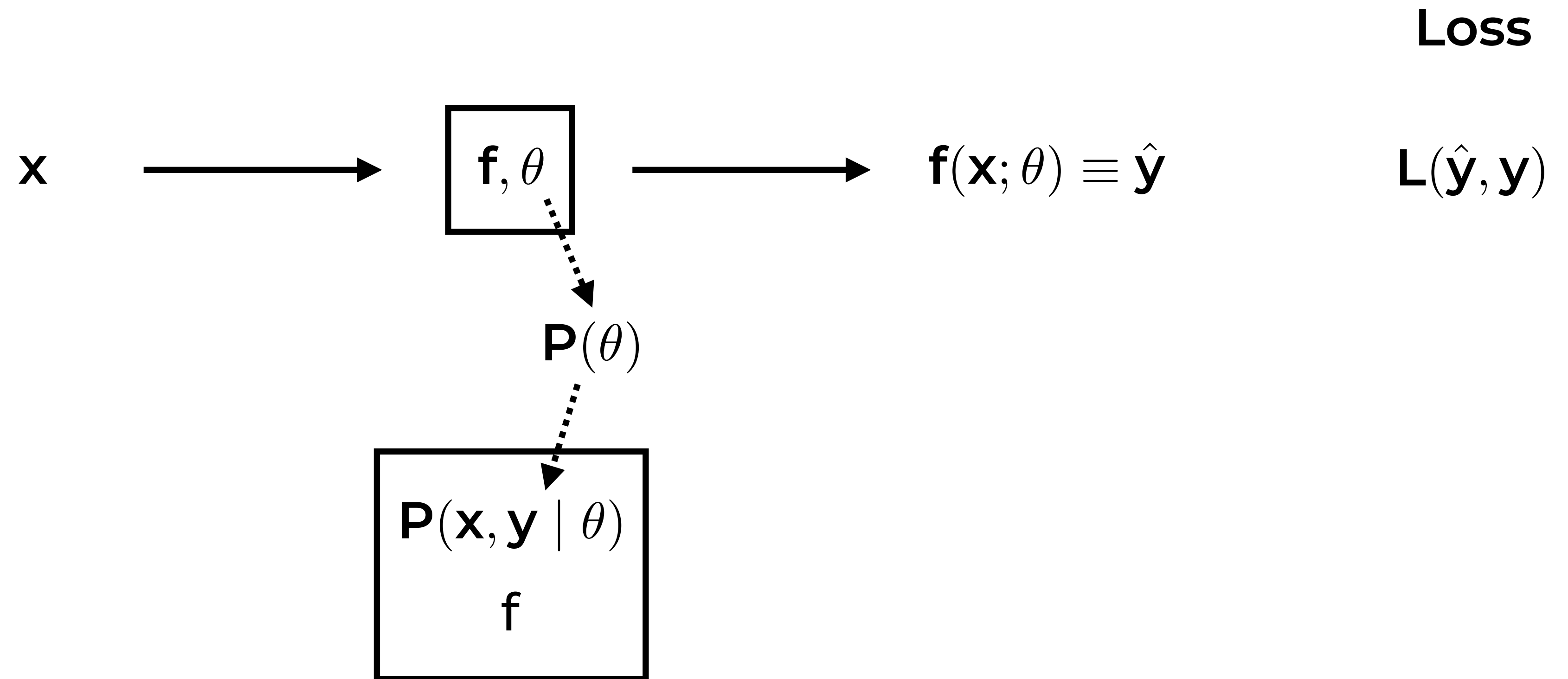
Probabilistic Models



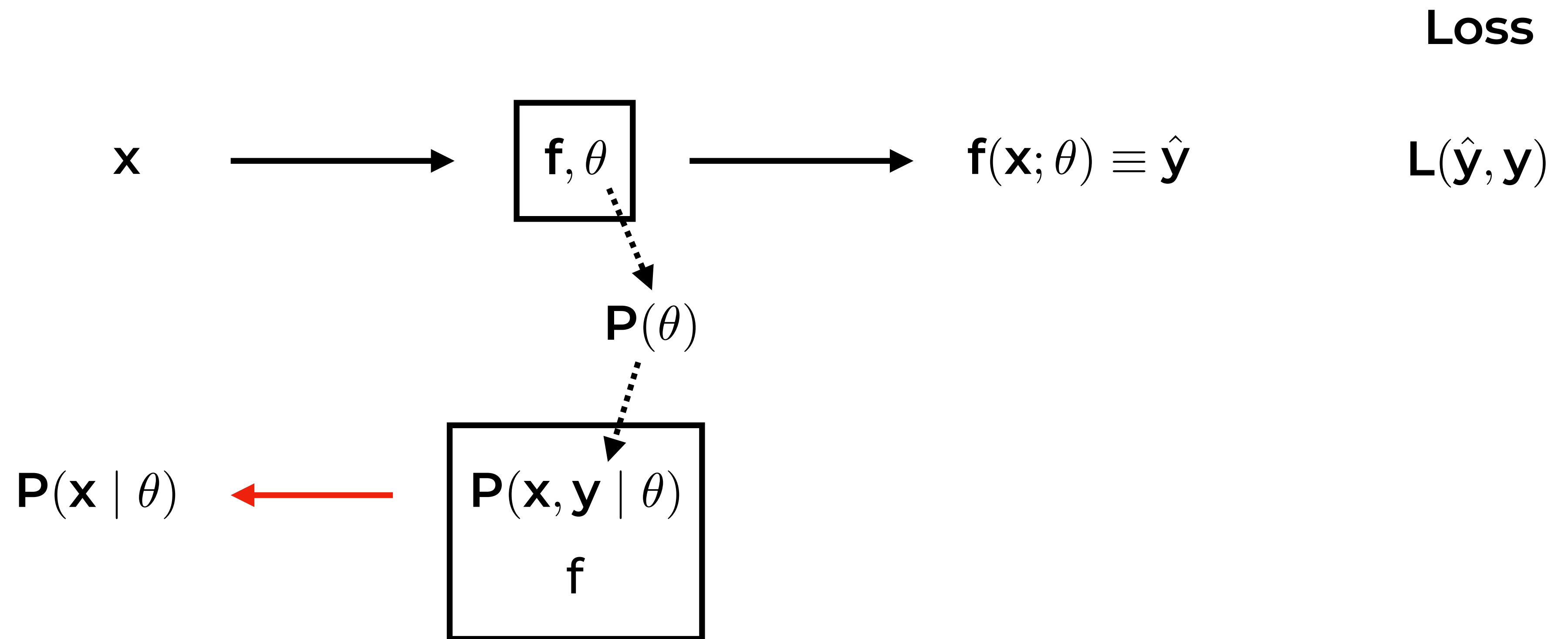
Probabilistic Models



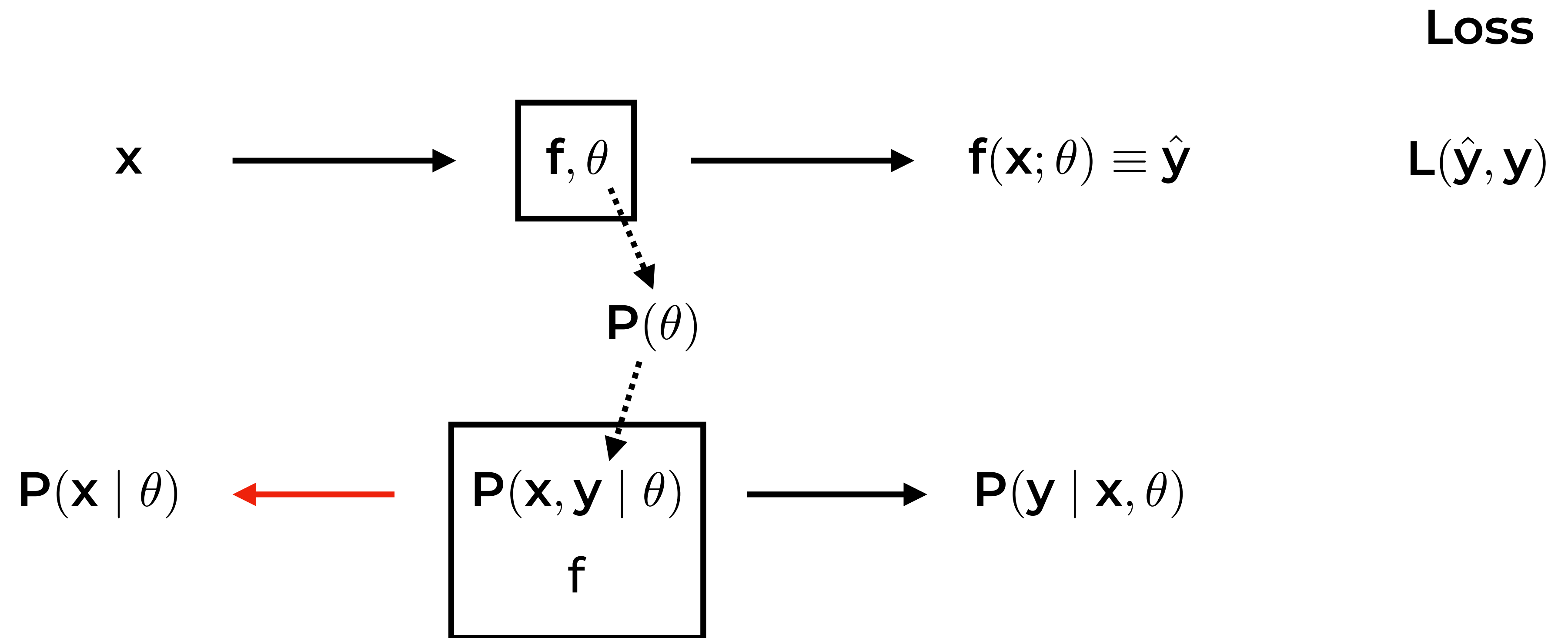
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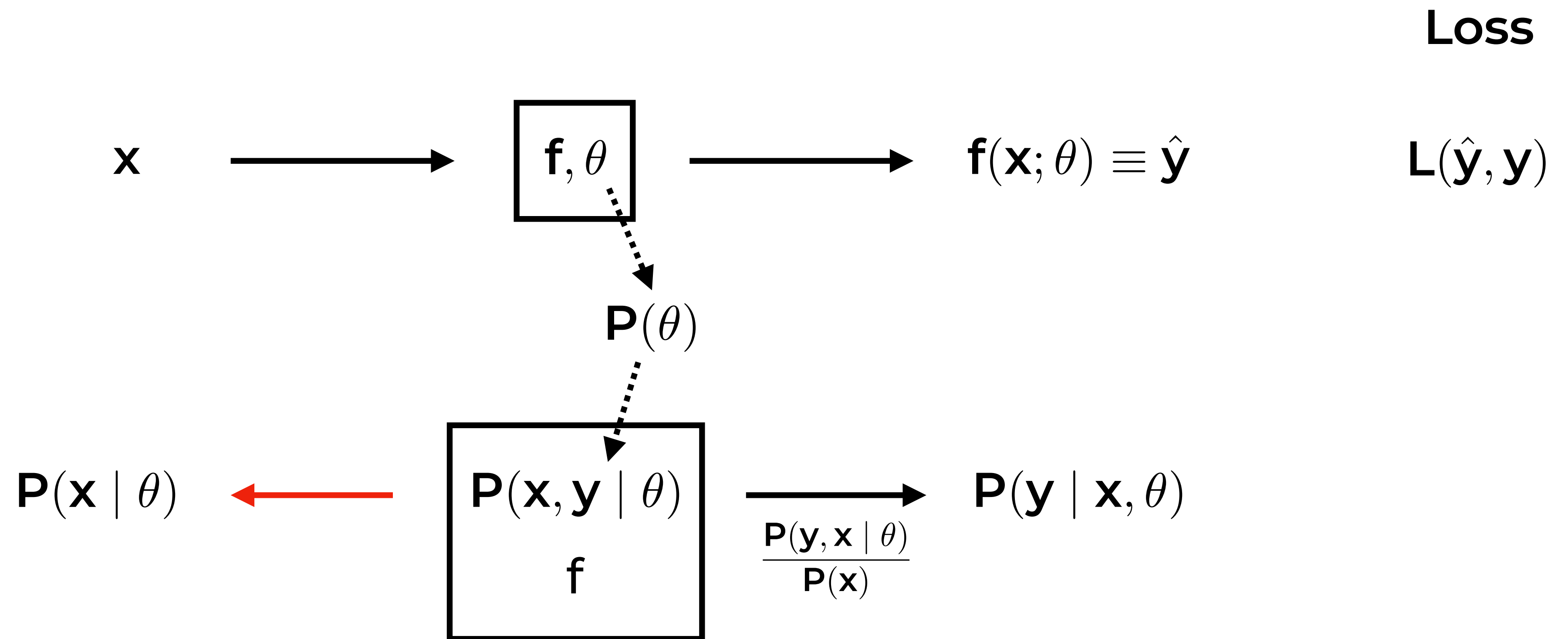
Probabilistic Models



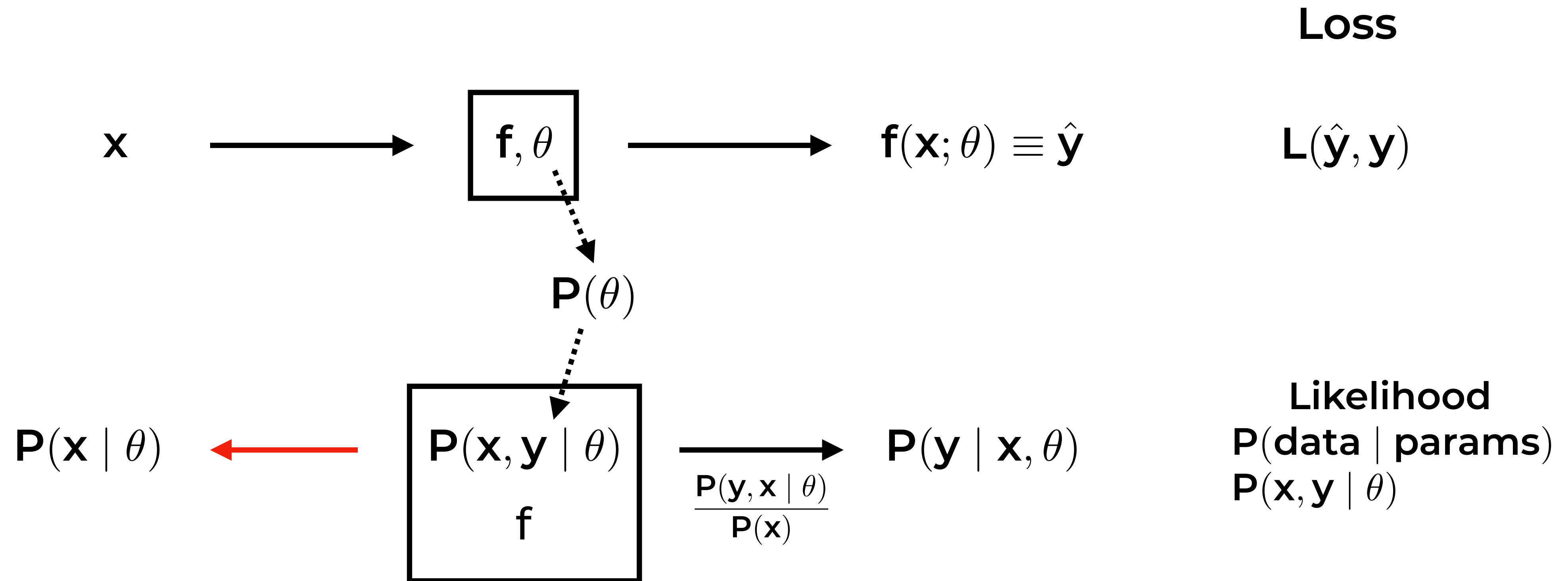
Probabilistic Models



Probabilistic Models



Probabilistic Models



Example

Data: 952 1064 965 1037 871 1029 1138 (unsupervised problem)

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$$\text{Likelihood}(x | \mu, 1) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x - \mu)^2}{2}\right)$$

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Log-Likelihood

$$= \log \frac{1}{\sqrt{2\pi}} \exp - \frac{(x - \mu)^2}{2}$$

$$= \log 1 - \frac{1}{2} \log 2\pi - \frac{(x - \mu)^2}{2}$$

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What value of μ maximizes it?

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$$\begin{aligned} &\frac{d \text{Log-Likelihood}}{d \mu} \\ &= \frac{d \frac{(x - \mu)^2}{2}}{d \mu} \\ &= (x - \mu) \\ &\text{set to 0} \\ &\mu = x \end{aligned}$$

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$$= (x - \mu)$$

set to 0

$$\mu = x = 952$$

Data: (x,y)
Naive Bayes

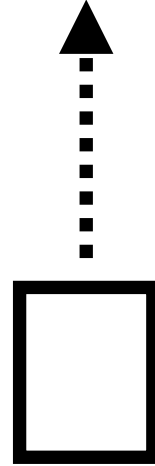


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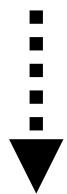
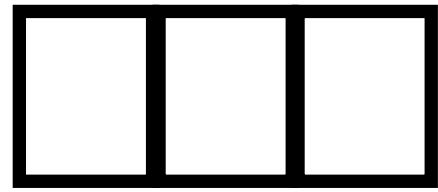
Model : $P(\mathbf{x}, \mathbf{y} \mid \theta) = P(\mathbf{x} \mid \mathbf{y}, \theta)P(\mathbf{y} \mid \theta)$

Data: (x,y)
Naive Bayes

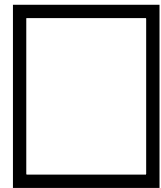
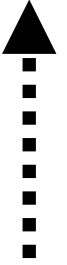
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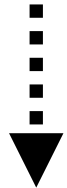
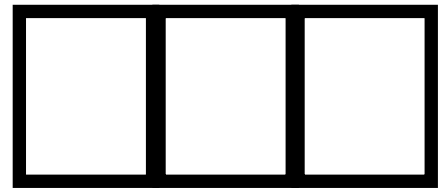
Data: (x,y) Naive Bayes



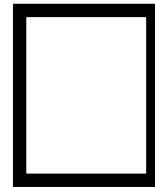
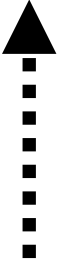
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Data: (x,y)
Naive Bayes

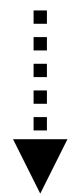
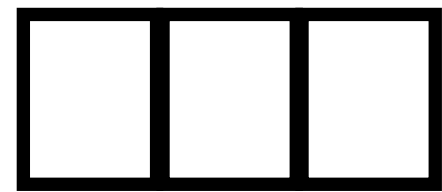


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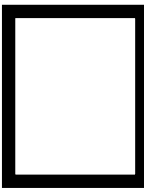


Data: x
Gaussian Mixture Models

Data: (x,y)
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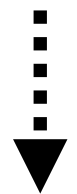
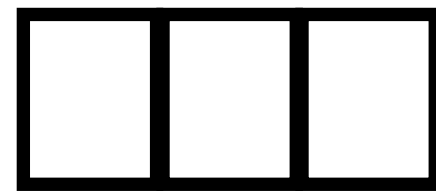
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Model : $P(\mathbf{x} \mid \theta) = \sum_{k=1}^K P(\theta_{\mathbf{x}} = \mathbf{k}) \underbrace{P(\mathbf{x} \mid \theta_{\mathbf{k}})}_{\mathcal{N}(\mathbf{x} \mid \mu_{\mathbf{k}}, \Sigma_{\mathbf{k}})}$ (K components)

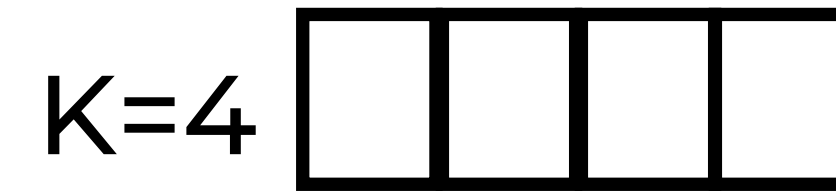
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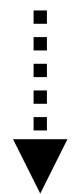
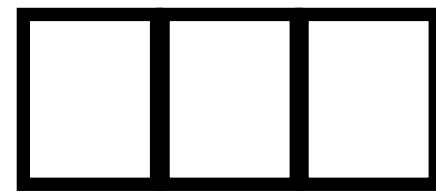


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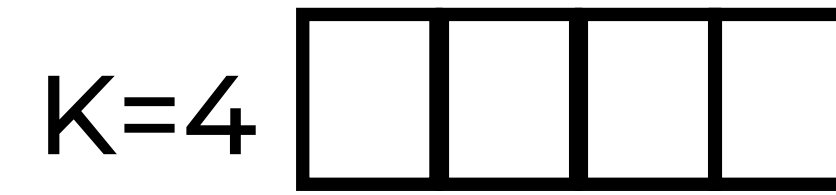
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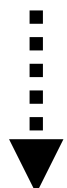
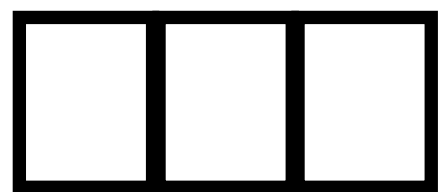
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Gaussian Mixture Models



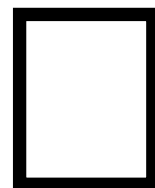
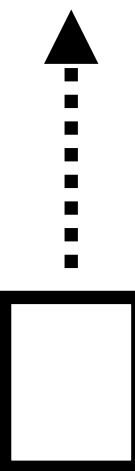
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Max. likelihood (MLE) : $\hat{\theta}_{\text{MLE}} = \arg \max_{\theta} P(\mathbf{x} \mid \theta)$

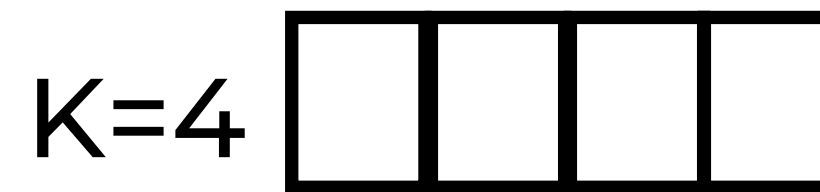
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Data: x
Gaussian Mixture Models



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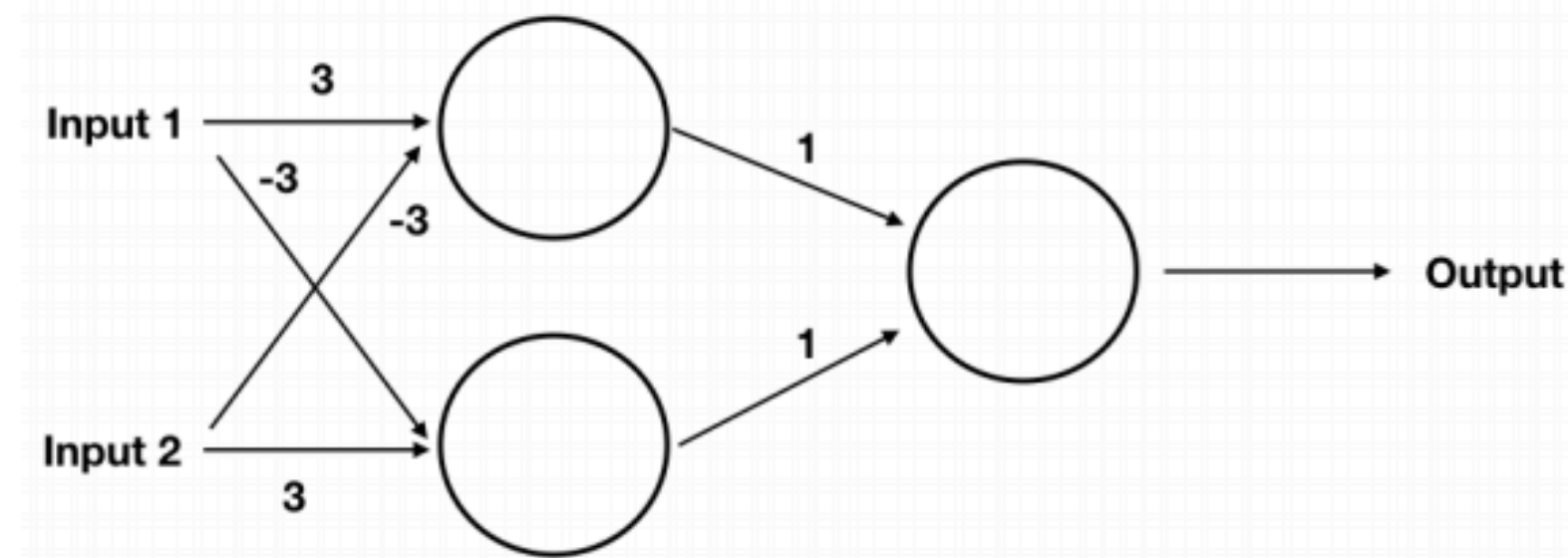
Max. a posteriori (MAP) : $\hat{\theta}_{\text{MAP}} = \arg \max_{\theta} P(\theta \mid \mathbf{x}, \gamma) = \arg \max_{\theta} \frac{P(\mathbf{x} \mid \theta)P(\theta \mid \gamma)}{P(\mathbf{x})}$

MLPs / RNNs / CNNs

- **MLPs: layers are fully-connected to the next layer**
- **RNNs: inputs at each layer**
 - **Typical application: time-series modelling**
- **CNNs: replace matrix multiplications by convolutions (sparse connections, weight sharing) + pooling**
 - **Typical application: object recognition in images**

MLPs

- (e) (4 points) Consider the neural network below. We have estimated its parameters (shown next to their corresponding arrows).



The activation function of each unit in the network is a simple thresholding function:

$$\text{threshold}(x) = \begin{cases} 0 & \text{if } x \leq 0, \\ 1 & \text{if } x > 0. \end{cases} \quad (1)$$

For each of these four sets of inputs write down the network's output (i.e., its prediction) in the "Output" column of the table below.

Input 1	Input 2	Output
0	0	
1	1	
0	1	
1	0	