

University of Toronto  
Department of Computer Science  
CSC418/2504: Computer Graphics

Midterm exam  
Fall 2005

Duration: 50 minutes  
No aids allowed

There are 4 pages total (including this page)

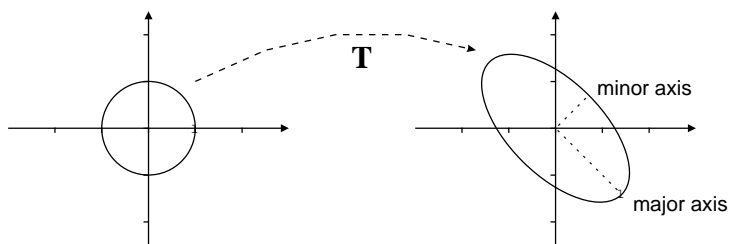
Family name: \_\_\_\_\_

Given names: \_\_\_\_\_

Student number: \_\_\_\_\_

Question	Marks
1	_____
2	_____
3	_____
4	_____
5	_____
Total	_____

1. [8 marks] Let  $C$  be a circle in 2D with radius one, centered at the origin as shown in Figure 1. Define a transformation matrix  $\mathbf{T}$  that transforms the circle to an ellipse rotated clockwise by  $45^\circ$ , with major axis of length 2 and minor axis length 1, as shown in Figure 1. (You may define  $\mathbf{T}$  as a composition of elementary transformation matrices).



2. [10 marks] Suppose we define a 3D plane in parametric form as  $\vec{p}(\alpha, \beta) = \vec{p}_0 + \alpha\vec{a} + \beta\vec{b}$ . As usual,  $\vec{a}$  and  $\vec{b}$  are vectors, and  $\vec{p}_0$  is a point. Further, let  $\vec{r}(\lambda) = \vec{r}_0 + \lambda\vec{d}$  be a 3D ray with  $\lambda \geq 0$ , where  $\vec{r}_0$  is a point, and  $\vec{d}$  is a vector. Derive formulae to determine whether the ray intersects the plane, and, if it does, to compute the intersection point.

3. [8 marks] Let  $S$  be a 3D surface made up of points  $\bar{p} = (x, y, z)$  that satisfy the implicit equation

$$x^2 + 3y^2 + 2xz - 4 = 0 .$$

Find a vector that is normal to  $S$  at point  $(1, 1, 0)$ . Show and explain your work.

4. [8 marks] Assume we have defined a camera in terms of  $\bar{e}$ ,  $\vec{u}$ ,  $\vec{v}$ , and  $\vec{w}$ , where  $\bar{e}$  denotes the eye location (the center of projection), and the vectors  $\vec{u}$ ,  $\vec{v}$  and  $\vec{w}$  form a right-handed coordinate frame (i.e.,  $\vec{u}$ ,  $\vec{v}$  and  $\vec{w}$  provide the directions of the camera's  $x$ ,  $y$ , and  $z$  axes in the world coordinate frame). Let  $\bar{p}^c$  be the representation of a point in camera-centered coordinates. Derive the homogeneous form of the transformation that maps the point  $\bar{p}^c$  into its representation in world-centered coordinates, denoted  $\bar{p}^w$ .

5. [11 marks] (a) In words, what is a *backface*?

(b) Explain (mathematically) how to perform backface culling for a triangle with vertices  $\bar{p}_1$ ,  $\bar{p}_2$  and  $\bar{p}_3$  and outward-facing normal  $\vec{n}$ , where the eye of the camera is at location  $\bar{e}$  with a gaze direction of  $\vec{g}$ .

(c) Sketch a simple diagram to show one example in which a triangle is not visible but would not be removed by backface culling.