

Topic 9:

Lighting & Reflection models

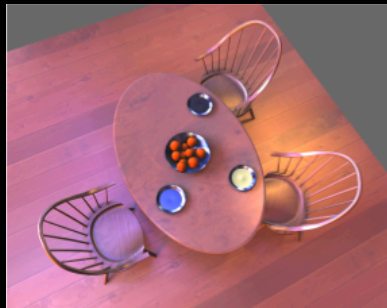
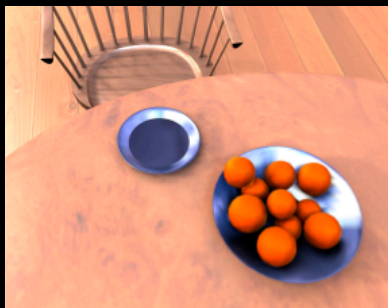
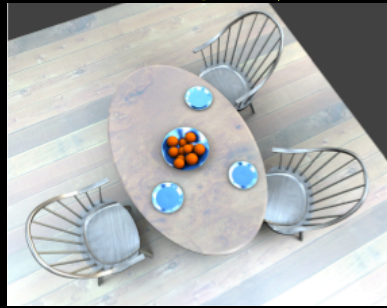
- Lighting & reflection
- The Phong reflection model
 - diffuse component
 - ambient component
 - specular component



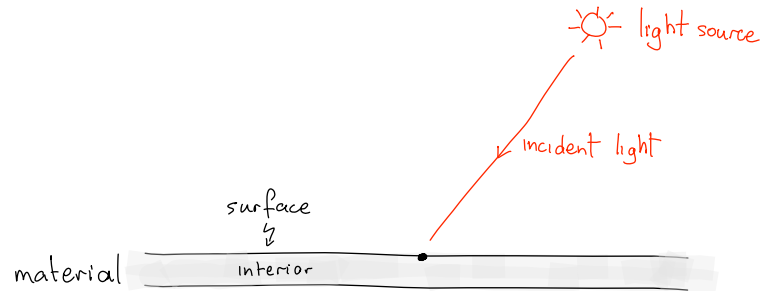
Ng et al, SIGGRAPH'04



Ng et al, SIGGRAPH'04

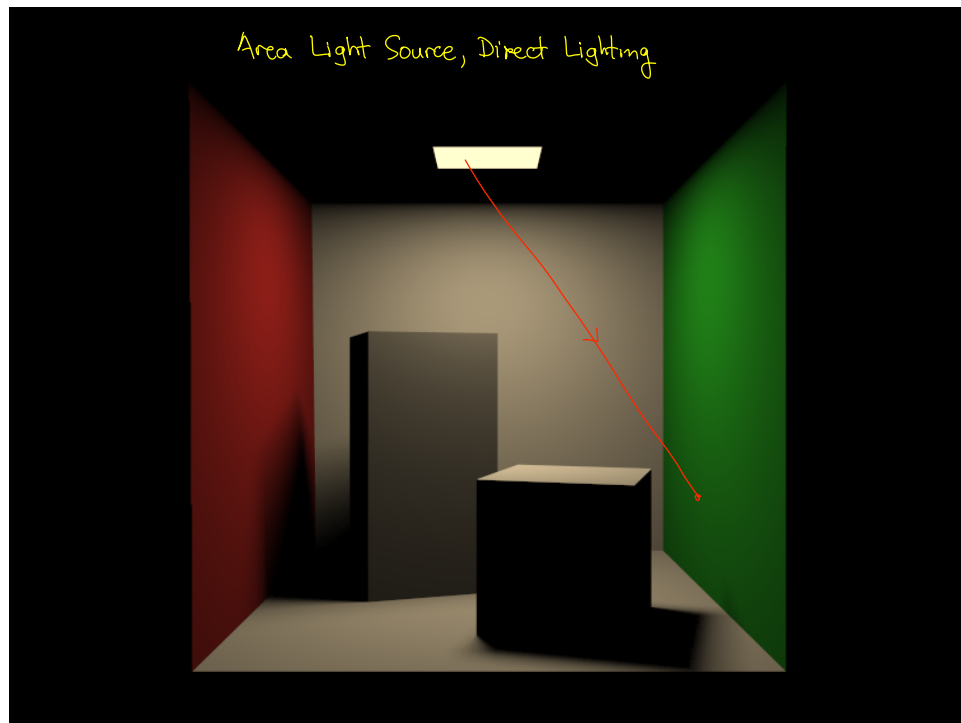


Light Sources

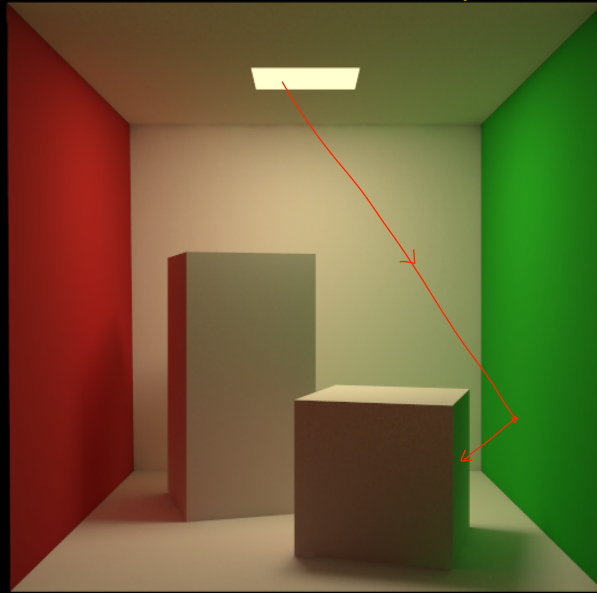


Main sources of light:

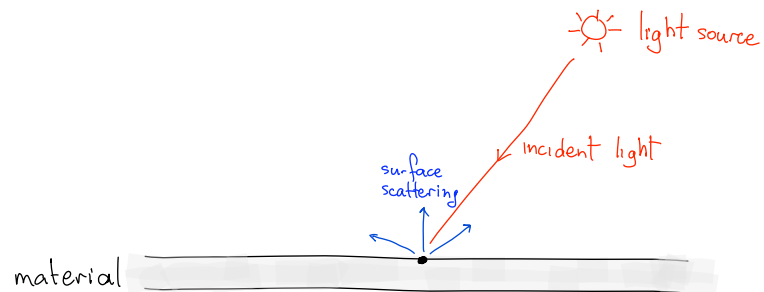
- point source
- distant source (spotlight)
- extended source (aka area light source)
- secondary reflection



Area Light Source, Indirect Lighting



Modeling Reflection: Diffuse Reflection

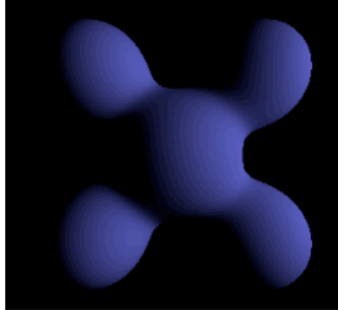


Diffuse reflection

- Represents "matte" component of reflected light
- Usually caused by "rough" surfaces (clay, eggshell, etc)

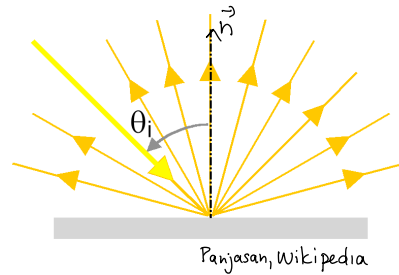
Modeling Reflection: Diffuse Reflection

Brad Smith, Wikipedia



Diffusely-shaded object

θ_i = angle of incidence

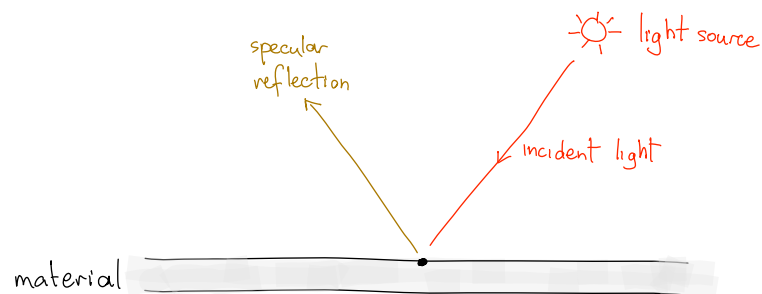


Panjasan, Wikipedia

Diffuse reflection

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Modeling Reflection: Specular Reflection



Specular reflection:

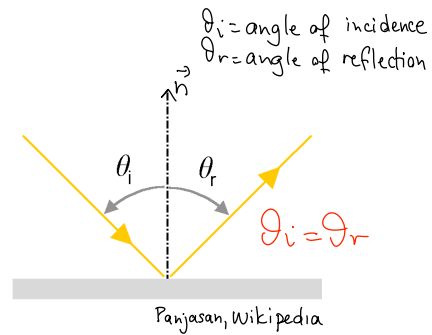
- Represents "shiny" component of reflected light
- Caused by mirror-like reflection off of smooth or polished surfaces (plastics, polished metal, etc)

Modeling Reflection: Specular Reflection

Romeiro et al, ECCV'08



mirror-like sphere

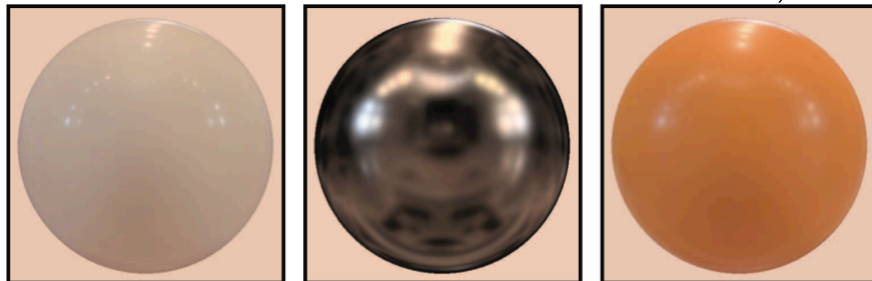


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Modeling Reflection: Specular Reflection

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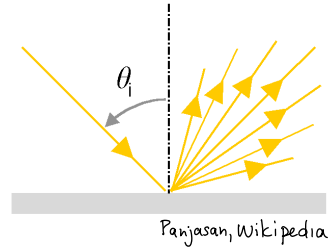


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Modeling Reflection: Specular Reflection

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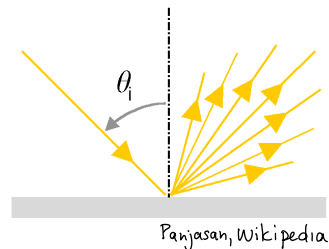
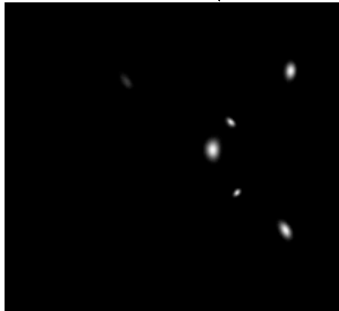


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Modeling Reflection: Specular Reflection

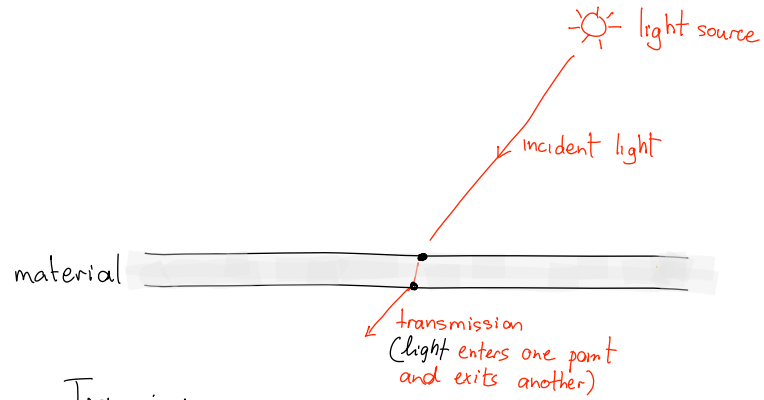
Brad Smith, Wikipedia



Specular reflection:

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Modeling Reflection: Transmission

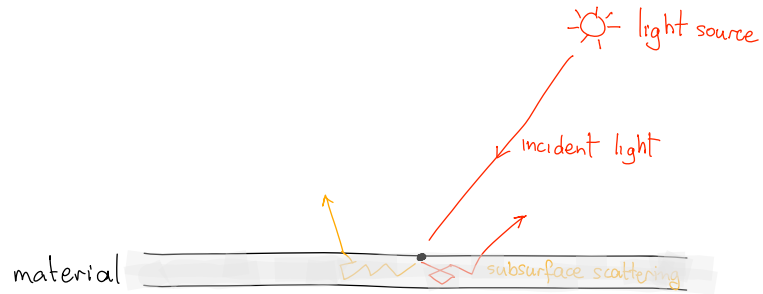


Transmission:

- Caused by materials that are not perfectly opaque
- Examples include glass, water and translucent materials such as skin



Modeling Reflection: Sub-surface Scattering



Subsurface scattering:

- Represents the component of reflected light that scatters in the material's interior (after transmission) before exiting again
- Examples include skin, milk, fog, etc.

Rendering w/ no subsurface scattering (opaque skin)



Jensen et al, SIGGRAPH'01

Rendering with subsurface scattering (translucent skin)



Jensen et al, SIGGRAPH'01

Rendering w/ no subsurface scattering (opaque milk)



Jensen et al, SIGGRAPH'01

Rendering with subsurface scattering (full milk)



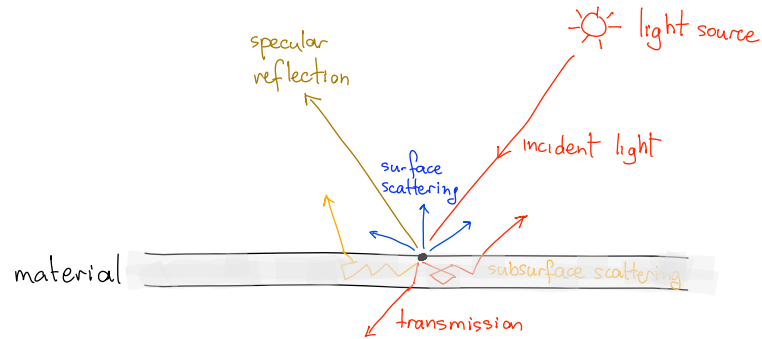
Jensen et al, SIGGRAPH'01

Rendering with subsurface scattering (skim milk)

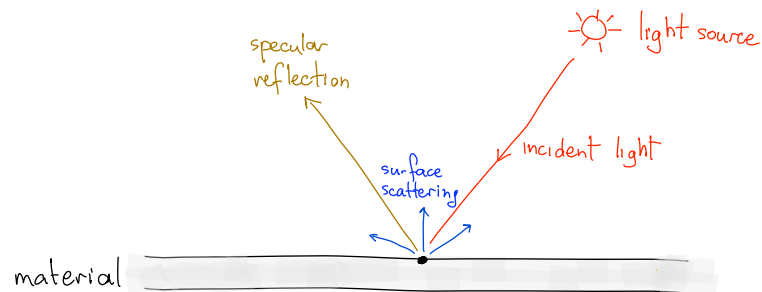


Jensen et al, SIGGRAPH'01

The Common Modes of "Light Transport"



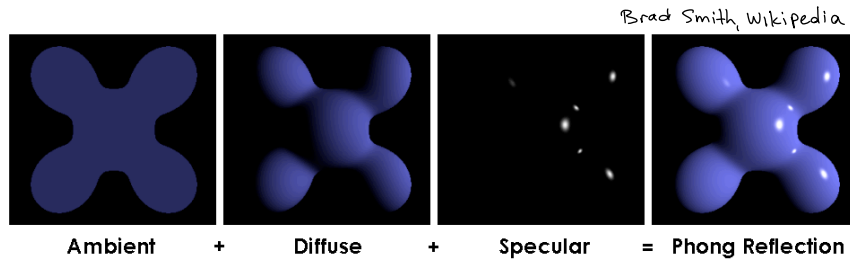
The Phong Reflectance Model



Phong model: A simple, computationally-efficient model that has 3 components:

- Diffuse
- Ambient
- Specular

The Phong Reflectance Model



Phong model: A simple, computationally-efficient model that has 3 components:

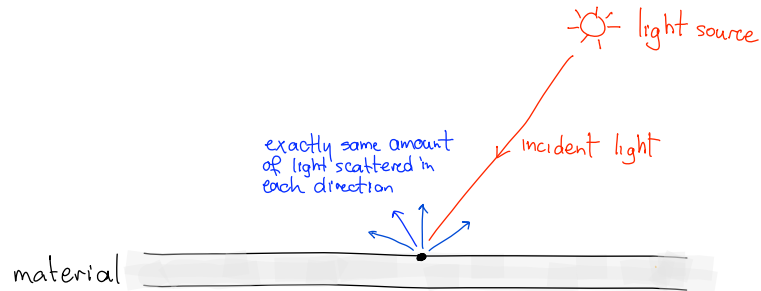
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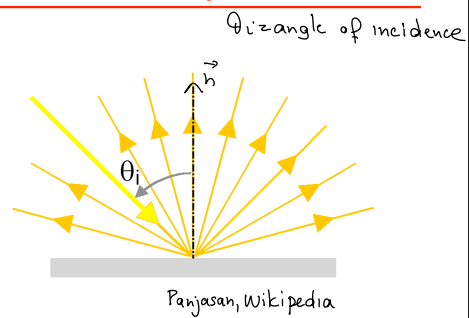
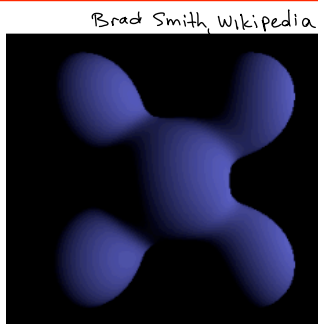
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Phong Reflection: The Diffuse Component



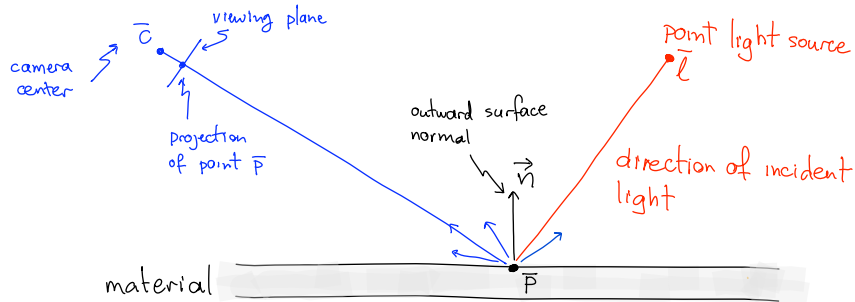
- A diffuse point looks the same from all viewing positions
- Simplest case: a single, point light source

Phong Reflection: The Diffuse Component



- A diffuse point looks the same from all viewing positions
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The Diffuse Component: Basic Equation

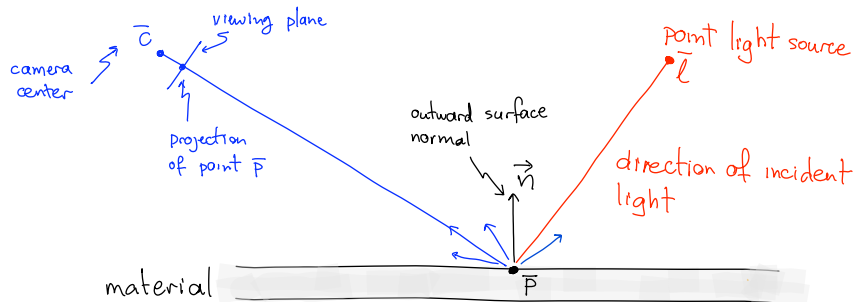


- A diffuse point looks the same from all viewing positions
- Simplest case: a single, point light source

$$I_{\bar{P}} = r_d \cdot I \cdot \max(0, \vec{S} \cdot \vec{n})$$

intensity at projection of \bar{P} fraction of light reflected intensity of source direction of light source outward unit surface normal $\vec{S} = \frac{\vec{l} - \bar{P}}{\|\vec{l} - \bar{P}\|}$

The Diffuse Component: Basic Equation



- A diffuse point looks the same from all viewing positions

$$I_{\bar{P}} = r_d \cdot I \cdot \max(0, \vec{S} \cdot \vec{n})$$

intensity at projection of \bar{P} independent of \bar{c} outward unit surface normal direction of light source $\vec{S} = \frac{\vec{l} - \bar{P}}{\|\vec{l} - \bar{P}\|}$

The Diffuse Component: Foreshortening

As the angle θ_i between \vec{s} and \vec{n} increases, the area of the surface around \bar{p} receiving light increases

⇒ the light intensity received per unit area decreases.

this is called foreshortening

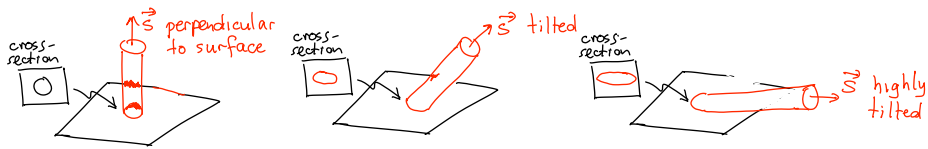
⇒ point \bar{p} will appear dimmer

suppose light propagates along a cylinder

point light source

direction of incident light

material



$$I_{\bar{p}} = r_d \cdot I \cdot \max(0, \vec{s} \cdot \vec{n})$$

accounts for dimming due to foreshortening

The Diffuse Component: Foreshortening

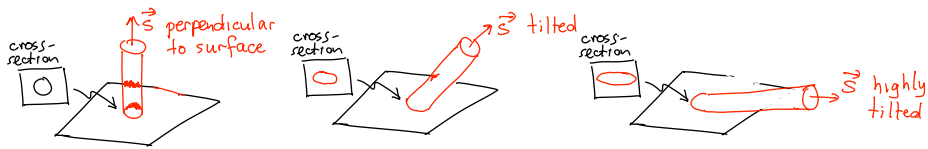
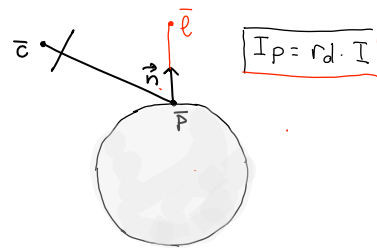
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Q: What is the intensity at \bar{p} 's projection?



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accounts for dimming due to foreshortening

The Diffuse Component: Foreshortening

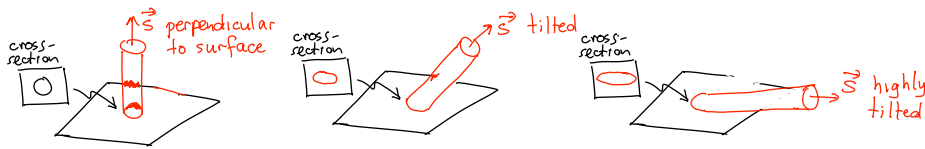
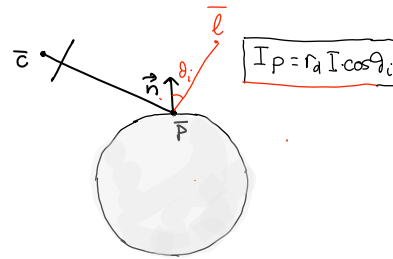
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The Diffuse Component: Foreshortening

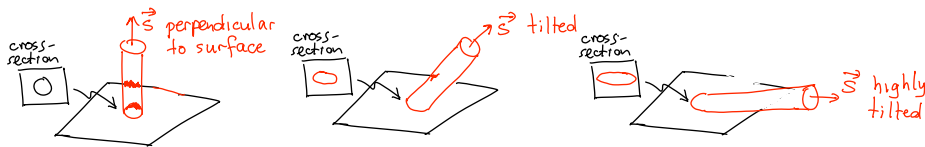
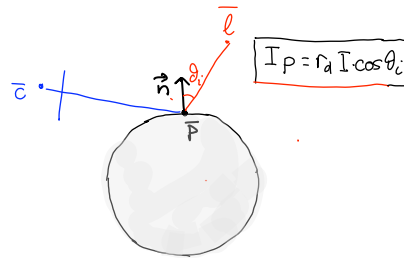
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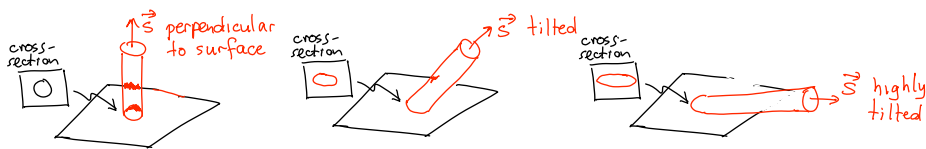
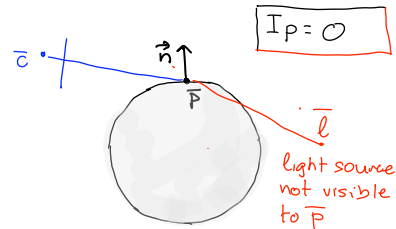
accounts for dimming due to foreshortening

The Diffuse Component: Self-Shading

As the angle θ_i between \vec{s} and \vec{n} increases, the area of the surface around \bar{p} receiving light increases

⇒ the light intensity received per unit area decreases.
this is called foreshortening
⇒ point \bar{p} will appear dimmer

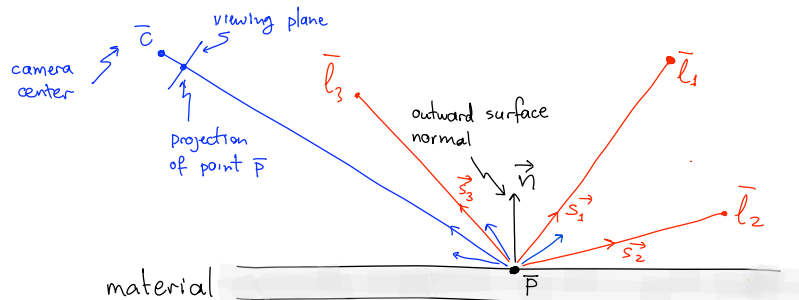
Q: What is the intensity at \bar{p} 's projection?



$$I_{\bar{p}} = r_d \cdot I \cdot \max(0, \vec{s} \cdot \vec{n})$$

accounts for cases where light source not visible

The Diffuse Component: Multiple Lights

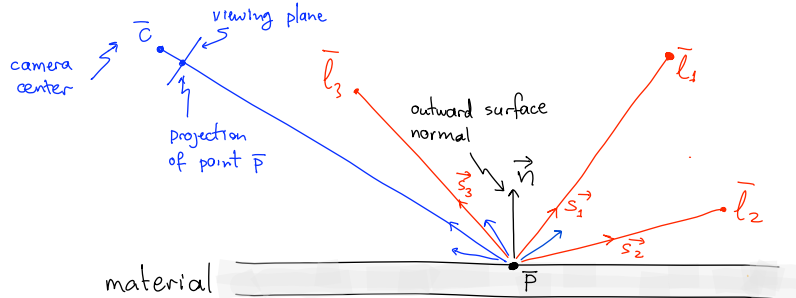


- A diffuse point looks the same from all viewing positions
- When the scene is illuminated by many point sources, we just sum their contributions to the diffuse component

$$I_{\bar{p}} = r_d \sum_i I_i \max(0, \vec{s}_i \cdot \vec{n})$$

intensity at projection of \bar{p} intensity of source i

The Diffuse Component: Incorporating Color



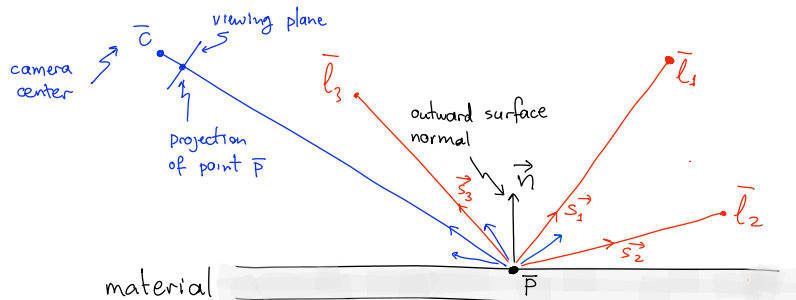
- A diffuse point looks the same from all viewing positions
- Colored sources and colored objects are handled by considering the R-G-B components of each color separately

$$I_{\vec{P},q} = r_{d,q} \sum_i I_{i,q} \max(0, \vec{s}_i \cdot \vec{n}) \quad q=R,G,B$$

intensity of color component q at projection of \vec{P}

intensity of color component q for light source i

The Diffuse Component: General Equation



Putting it all together:

$$I_{\vec{P},q} = r_{d,q} \sum_i I_{i,q} \max(0, \vec{s}_i \cdot \vec{n})$$

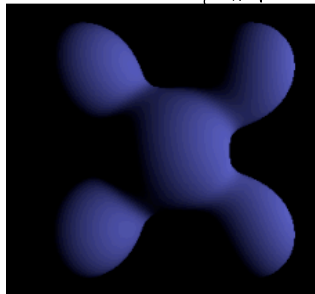
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Phong Reflection: Ambient Component

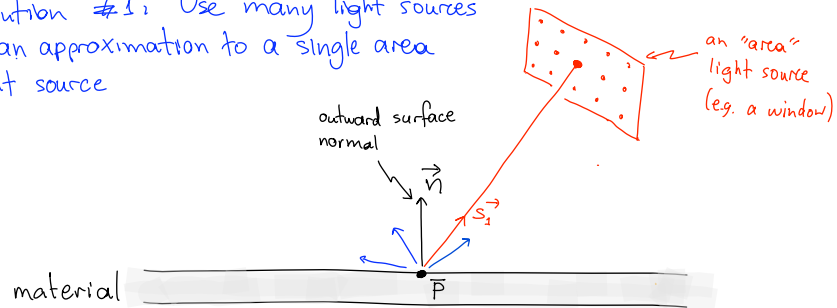
Brad Smith, Wikipedia



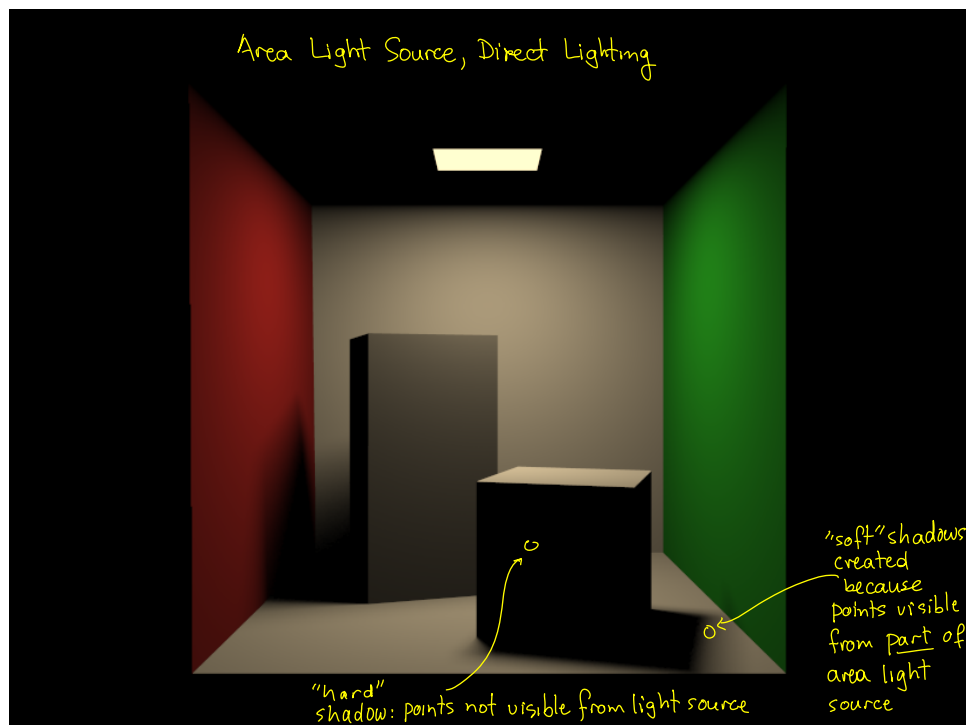
- Diffuse reflectance with a single point light source produces strong shadows
- Surface patches with $\vec{s} \cdot \vec{n} < 0$ are perfectly black
⇒ looks unnatural

Phong Reflection: Ambient Component

Solution #1: Use many light sources as an approximation to a single area light source



- Diffuse reflectance with a single point light source produces strong shadows
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⇒ looks unnatural



Phong Reflection: Ambient Component

Solution #2: (Simpler) Use an "ambient" term that is independent of any light source or surface normal

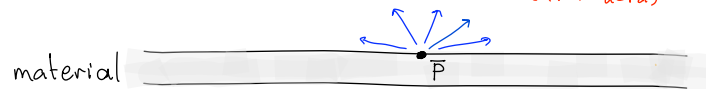
This term is not meaningful in terms of physics but improves appearance over pure diffuse reflection

can also have 3 such eqs for R, G, B components

$$I_{\bar{p}} = r_a \cdot I_a$$

ambient reflection coefficient (often $r_a = r_d$)

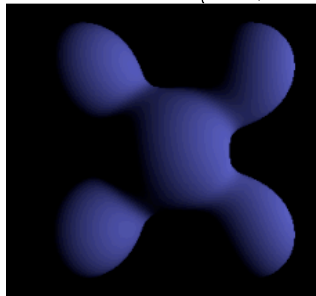
intensity of ambient illumination



- Diffuse reflectance with a single point light source produces strong shadows
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Phong Reflection: Ambient Component

Brad Smith, Wikipedia



Diffuse

Brad Smith, Wikipedia



Ambient

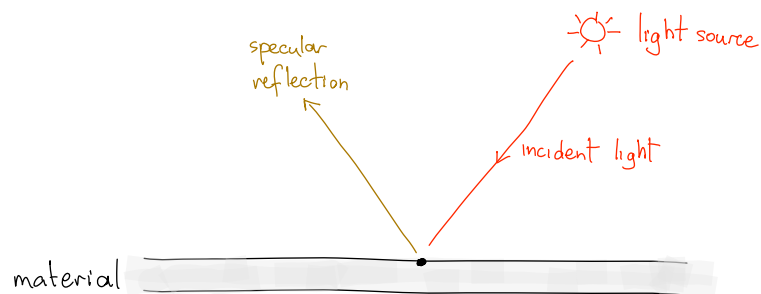
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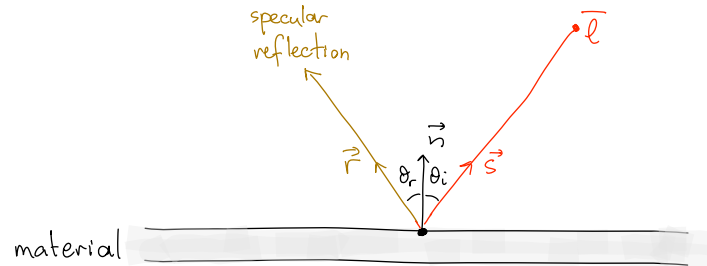
Phong Reflection: The Specular Component



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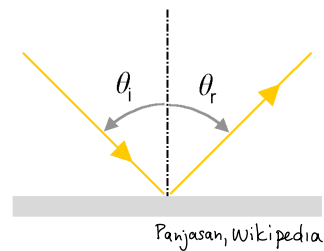
The Ideal Specular Component



- Idea: For each incident direction \vec{s} there is one emittant direction \vec{r}
- It is an idealization of a mirror:
 $\text{angle}(\vec{n}, \vec{s}) = \text{angle}(\vec{n}, \vec{r})$
 $\theta_i \qquad \theta_r$

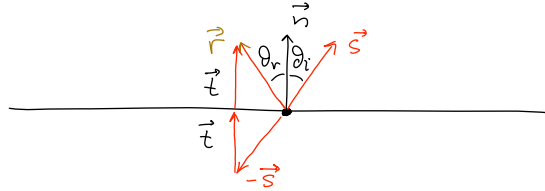
The Ideal Specular Component

Romeiro et al, ECV'08



- Idea: For each incident direction \vec{s} there is one emittant direction \vec{r}
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 $\text{angle}(\vec{n}, \vec{s}) = \text{angle}(\vec{n}, \vec{r})$
- Q: How can we express \vec{r} in terms of \vec{n}, \vec{s} ?

The Ideal Specular Component



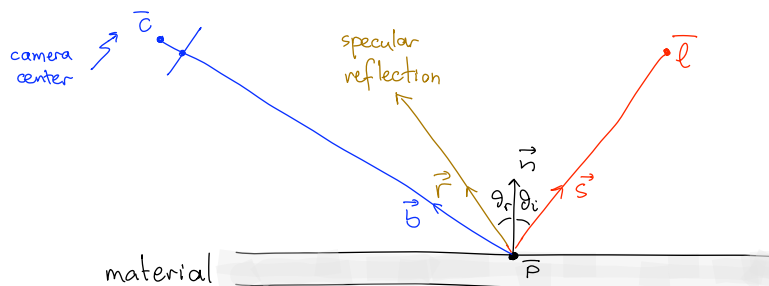
$$\vec{r} = -\vec{s} + 2\vec{t}$$

$$\begin{aligned} \vec{t} &= \text{projection of vector } \vec{s} \text{ onto} \\ &\text{vector } \vec{n} \\ &= (\vec{n} \cdot \vec{s}) \vec{n} \end{aligned}$$

$$\Rightarrow \boxed{\vec{r} = -\vec{s} + 2(\vec{n} \cdot \vec{s}) \vec{n}}$$

. Q: How can we express \vec{r} in terms of \vec{n}, \vec{s} ?

The Ideal Specular Component



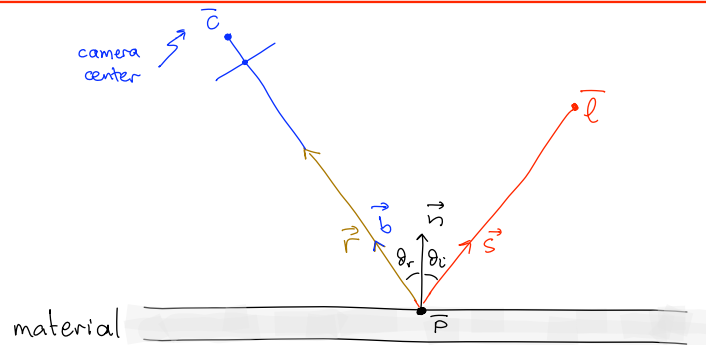
Ideal specular reflection term:

is 1 if and only if camera is along vector \vec{r}

$$I = r_s I_s \delta(\vec{r} \cdot \vec{b} - 1) \quad \text{where} \quad \delta(x) = \begin{cases} 1 & \text{if } x=0 \\ 0 & \text{otherwise} \end{cases}$$

r_s : specular reflection coefficient
 I_s : intensity of specular light source
 \vec{r} : unit vector in camera direction
 $\vec{b} = \frac{\vec{c} - \vec{p}}{\|\vec{c} - \vec{p}\|}$

The Ideal Specular Component



Ideal specular reflection term:

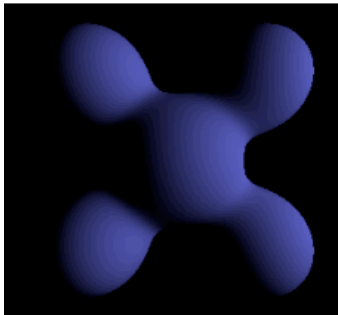
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The Ideal Specular Component

Brad Smith, Wikipedia



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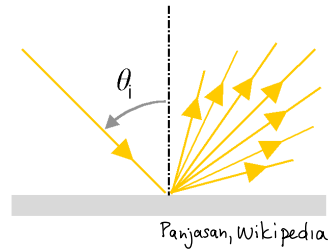
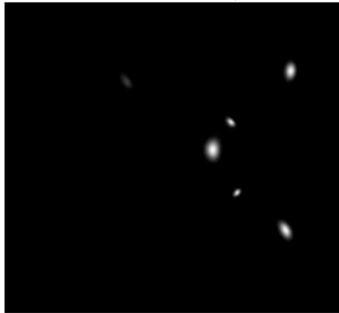
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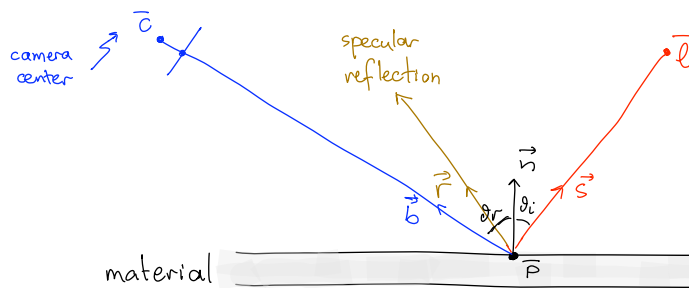
Phong Reflection: Off-Specular Reflection

Brad Smith, Wikipedia



Panjasan, Wikipedia

The Specular Component: Basic Equation



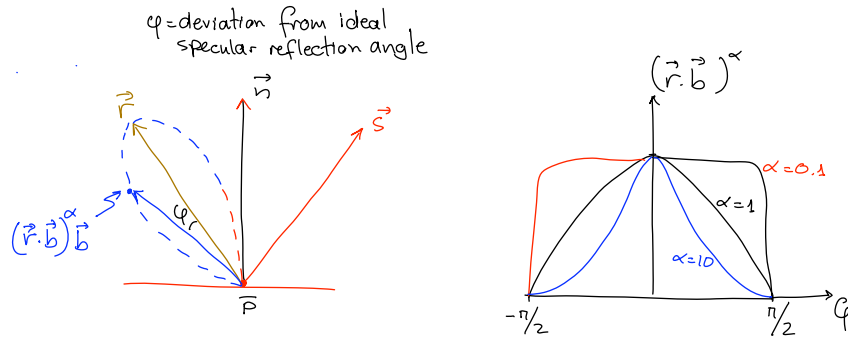
In reality, most specular surfaces reflect light into directions near the perfect mirror direction (eg. highlights in plastics, metals)

⇒ replace delta function by a cosine power:

$$I = r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha$$

← when $\alpha \rightarrow \infty$ term approaches ideal specular reflection term
 = 1 when $\vec{r} = \vec{b}$

The Specular Component: Visualization

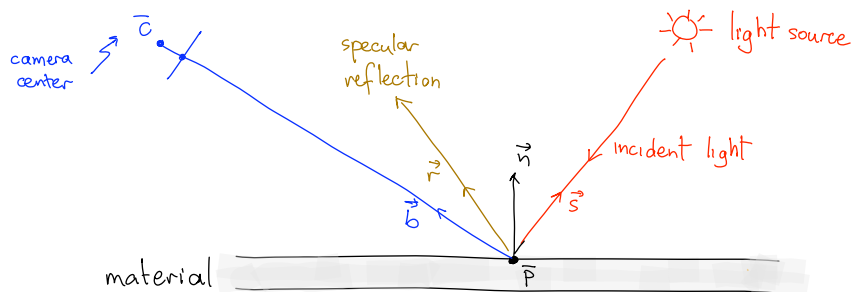


The length of vector $(\vec{r} \cdot \vec{b})^\alpha$ represents the contribution of the specular term when the camera is along \vec{b}

$$I = r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha$$

$\alpha \leftarrow$ when $\alpha \rightarrow \infty$ term approaches ideal specular reflection term
 $= 1$ when $\vec{r} = \vec{b}$

Phong Reflection: The General Equation

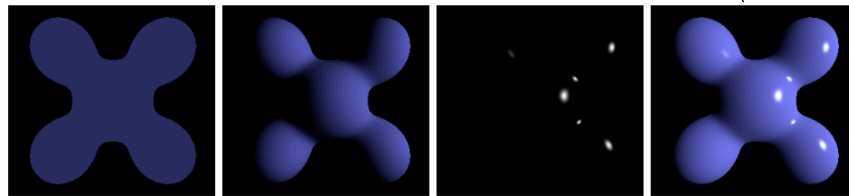


$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } \vec{P}} + \underbrace{r_d I_d}_{\text{ambient}} \max(0, \vec{n} \cdot \vec{s}) + \underbrace{r_s I_s}_{\text{diffuse}} \max(0, \vec{r} \cdot \vec{b})^\alpha$$

$\underbrace{\hspace{10em}}_{\text{specular}}$

Phong Reflection: The General Equation

Brad Smith, Wikipedia



Ambient + Diffuse + Specular = Phong Reflection

$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } \bar{p}} + \underbrace{r_d I_d \max(0, \vec{n} \cdot \vec{s})}_{\text{diffuse}} + \underbrace{r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha}_{\text{specular}}$$

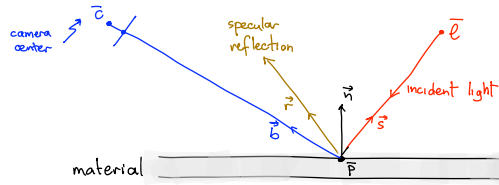
Topic 10:

Shading

- Introduction to Shading
- Flat Shading
- Interpolative Shading
 - Gouraud shading
 - Phong shading
 - Triangle scan-conversion with shading

Shading: Motivation

- Suppose we know how to compute the appearance of a point
- How do we shade a whole polygonal mesh?



Answer

assign intensities to every pixel at the mesh's projection in accordance with Phong reflection model

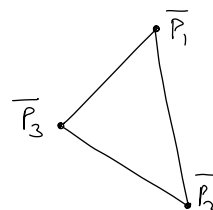
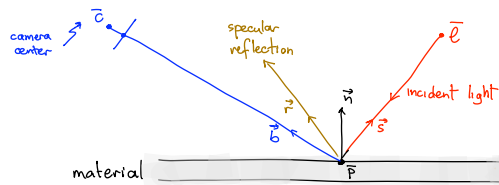
$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } P} + \underbrace{r_d I_d \max(0, \vec{n} \cdot \vec{s})}_{\text{ambient}} + \underbrace{r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha}_{\text{diffuse}} + \underbrace{\phantom{r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha}}_{\text{specular}}$$

Shading: Motivation

Given

- camera center (\vec{c})
- light source position (\vec{e})
- intensity of ambient, diffuse & specular sources (I_a, I_d, I_s)
- reflection coefficients (r_a, r_d, r_s)
- specular exponent (α)

Shade every pixel in triangle's projection

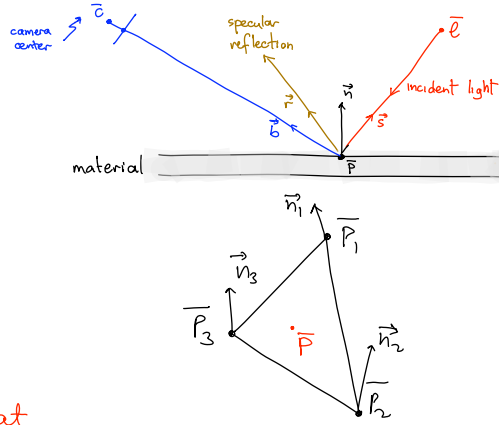


$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } P} + \underbrace{r_d I_d \max(0, \vec{n} \cdot \vec{s})}_{\text{ambient}} + \underbrace{r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha}_{\text{diffuse}} + \underbrace{\phantom{r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha}}_{\text{specular}}$$

Shading: Problem Definition

Given

- view { • camera center (\vec{c})
- scene { • light source position (\vec{e})
- intensity of ambient, diffuse & specular sources (I_a, I_d, I_s)
- material { • reflection coefficients (r_a, r_d, r_s)
- specular exponent (α)
- triangle { • normals at $\vec{P}_1, \vec{P}_2, \vec{P}_3$



Goal

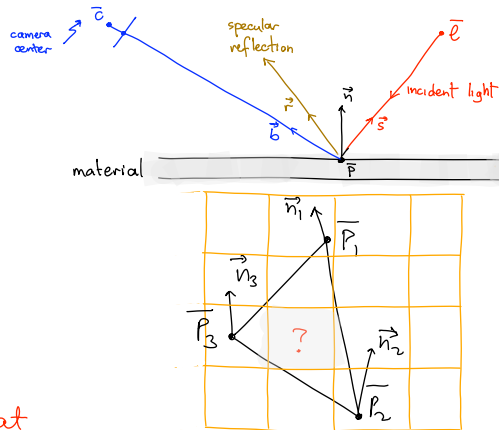
- compute color/intensity at an interior point

$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point P}} + \underbrace{r_d I_d \max(0, \vec{n} \cdot \vec{s})}_{\text{ambient}} + \underbrace{r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha}_{\text{diffuse}} + \underbrace{\quad}_{\text{specular}}$$

Shading: Problem Definition

Given

- view { • camera center (\vec{c})
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Goal

- compute color/intensity at an interior pixel

$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point P}} + \underbrace{r_d I_d \max(0, \vec{n} \cdot \vec{s})}_{\text{ambient}} + \underbrace{r_s I_s \max(0, \vec{r} \cdot \vec{b})^\alpha}_{\text{diffuse}} + \underbrace{\quad}_{\text{specular}}$$

Basic Approaches to Shading

Flat shading -

Draw all triangle points \bar{P} with identical color/intensity

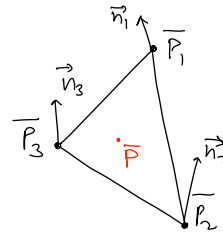
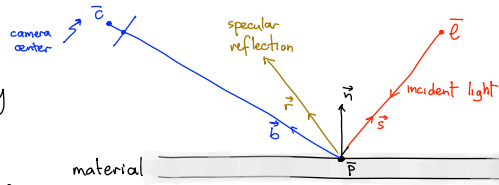
Gouraud shading -

- ① Compute $L_i = L(\vec{b}_i, \vec{n}_i, \vec{s}_i)$ for each vertex
- ② Interpolate the L_i 's to get value at \bar{P}

Phong shading -

- ① Interpolate $\vec{b}_i, \vec{n}_i, \vec{s}_i$ to get $\vec{b}, \vec{n}, \vec{s}$ at \bar{P}
- ② Compute $L(\vec{b}, \vec{n}, \vec{s})$

$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } \bar{P}} + \underbrace{r_d I_d \max(0, \vec{n} \cdot \vec{s})}_{\text{ambient}} + \underbrace{r_s I_s \max(0, \vec{r} \cdot \vec{b})^q}_{\text{diffuse}} + \underbrace{\quad}_{\text{specular}}$$



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Flat Shading: Main Idea

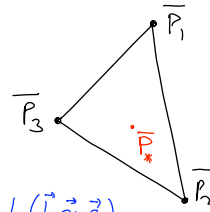
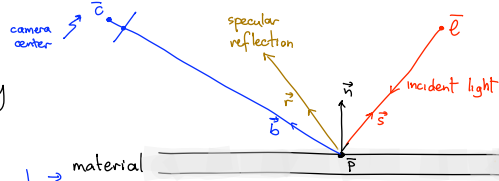
Flat shading—

Draw all triangle points \vec{P} with identical color/intensity

• All points have same normal \vec{n} (i.e. triangle is "flat")

• Phong model applied to center of triangle, $\vec{P}_* = \frac{1}{3}(\vec{P}_1 + \vec{P}_2 + \vec{P}_3)$ (i.e. \vec{b}, \vec{s} computed for \vec{P}_*)

• Triangle filled with color/intensity $L(\vec{b}, \vec{n}, \vec{s})$



$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point P}} + \underbrace{r_d I_d}_{\text{ambient}} \max(0, \vec{n} \cdot \vec{s}) + \underbrace{r_s I_s}_{\text{specular}} \max(0, \vec{r} \cdot \vec{b})^\alpha$$

Flat Shading: Main Idea

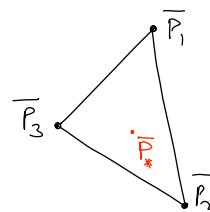
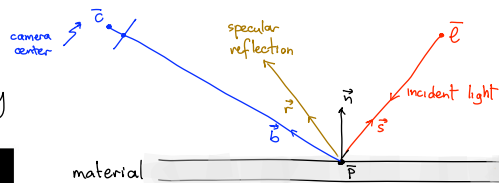
Flat shading—

Draw all triangle points \vec{P} with identical color/intensity

Sphere with flat shading



Jalo, wikipedia



$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point P}} + \underbrace{r_d I_d}_{\text{ambient}} \max(0, \vec{n} \cdot \vec{s}) + \underbrace{r_s I_s}_{\text{specular}} \max(0, \vec{r} \cdot \vec{b})^\alpha$$

Flat Shading: Key Issues

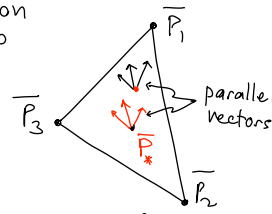
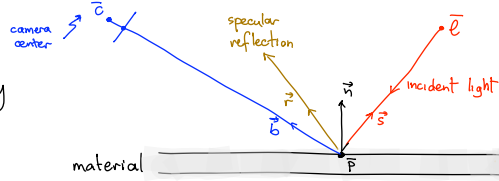
Flat shading

Draw all triangle points \bar{P} with identical color/intensity

Issues

- For large triangles:
 - specular term is poor approximation because highlights should be sharp (often better to drop this term)
 - flat shading essentially assumes a distant light source
- Triangle boundaries are usually visible (people very sensitive to intensity steps)

$$L(\bar{b}, \bar{n}, \bar{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } \bar{P}} + \underbrace{r_d I_d}_{\text{ambient}} \max(0, \bar{n} \cdot \bar{s}) + \underbrace{r_s I_s}_{\text{diffuse}} \max(0, \bar{r} \cdot \bar{b})^q$$



Flat Shading: Key Issues

Flat shading

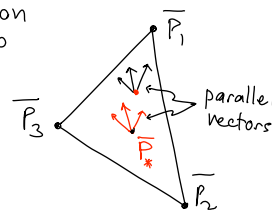
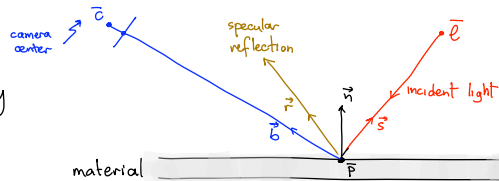
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Issues

- For large triangles:
 - specular term is poor approximation because highlights should be sharp (often better to drop this term)
 - flat shading essentially assumes a distant light source
- Triangle boundaries are usually visible (people very sensitive to intensity steps)

One solution

Since flat shading treats a triangle as a point, use small triangles!

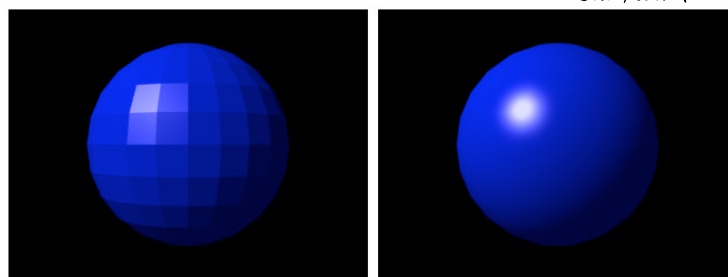


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Interpolated Shading



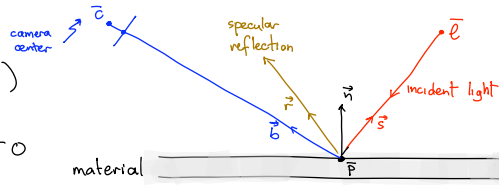
FLAT SHADING

PHONG SHADING

Interpolative Shading: Basic Approaches

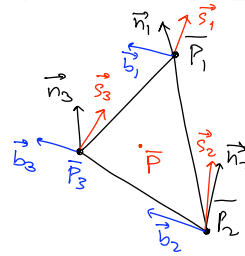
Gouraud shading -

- ① Compute $L_i = L(\vec{b}_i, \vec{n}_i, \vec{s}_i)$ for each vertex
- ② Interpolate the L_i 's to get value at \bar{P}



Phong shading -

- ① Interpolate $\vec{b}_i, \vec{n}_i, \vec{s}_i$ to get $\vec{b}, \vec{n}, \vec{s}$ at \bar{P}
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$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } \bar{P}} + \underbrace{r_d I_d}_{\text{ambient}} \max(0, \vec{n}_i \cdot \vec{s}_i) + \underbrace{r_s I_s}_{\text{diffuse}} \max(0, \vec{r}_i \cdot \vec{b}_i)^{\alpha}$$

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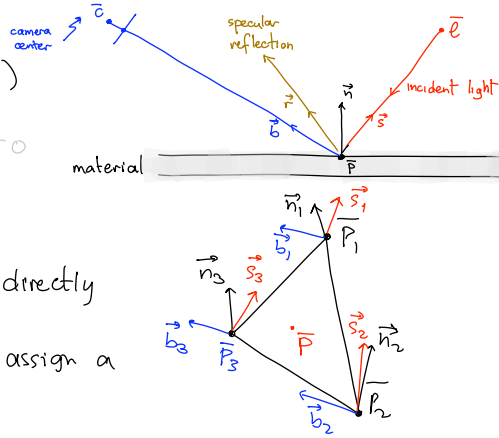
Gouraud Shading: Computation at Vertices

Gouraud shading -

- ① Compute $L_i = L(\vec{b}_i, \vec{n}_i, \vec{s}_i)$ for each vertex
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Notes

- Vectors \vec{b}_i, \vec{s}_i computed directly from \bar{P}_i, \bar{C} and \bar{E}
- Many possible ways to assign a normal to a vertex



$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } \bar{P}} + \underbrace{r_d I_d}_{\text{ambient}} \max(0, \vec{n} \cdot \vec{s}) + \underbrace{r_s I_s}_{\text{diffuse}} \max(0, \vec{r} \cdot \vec{b})^\alpha$$

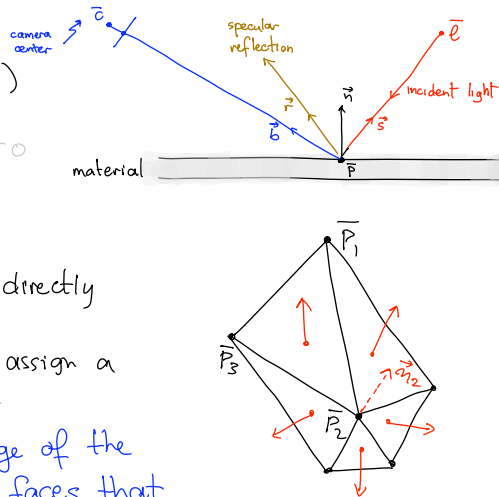
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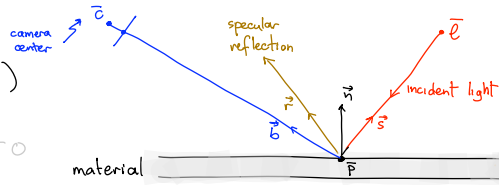
- Vectors \vec{b}_i, \vec{s}_i computed directly from \bar{P}_i, \bar{C} and \bar{E}
- Many possible ways to assign a normal to a vertex:
 - ① \vec{n}_j is the average of the normals of all faces that contain vertex \bar{P}_j



Gouraud Shading: Computation at Vertices

Gouraud shading -

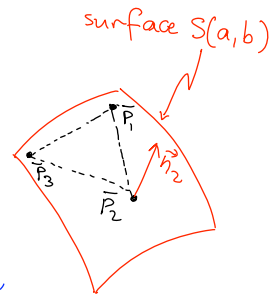
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- Vectors \vec{b}_i, \vec{s}_i computed directly from \bar{P}_i, \bar{c} and \bar{e}
- Many possible ways to assign a normal to a vertex:

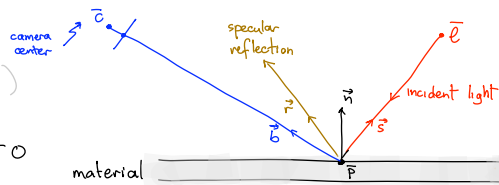
\vec{n}_j is the normal of a point sample on a parametric surface, computed when sampling points to create the original mesh



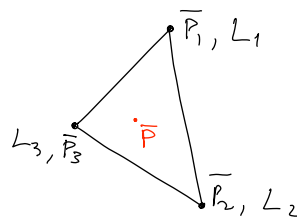
Gouraud Shading: Computation at Pixels

Gouraud shading -

- ① Compute $L_i = L(\vec{b}_i, \vec{n}_i, \vec{s}_i)$ for each vertex
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This step is integrated into the standard triangle-filling algorithm discussed in previous lecture

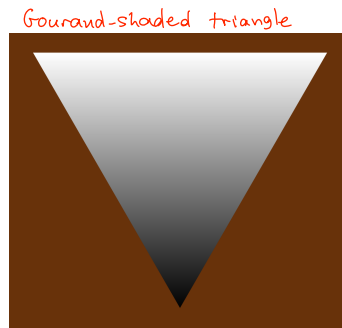
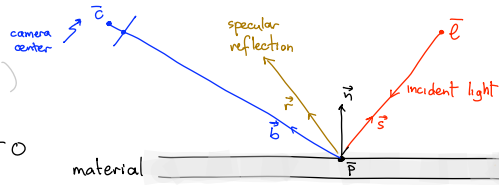


Gouraud Shading: Computation at Pixels

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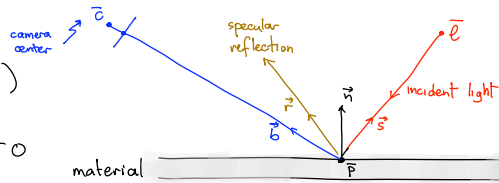


Yzmo, Wikipedia

Gouraud Shading: Comparisons

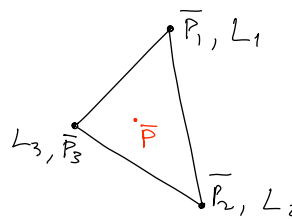
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Comparison to flat shading -

- ⊕ No visible seams between mesh triangles
- ⊕ Smooth, visually pleasing intensity variations that "mask" coarse geometry
- ⊖ Specular highlights still a problem for large triangles (why?)

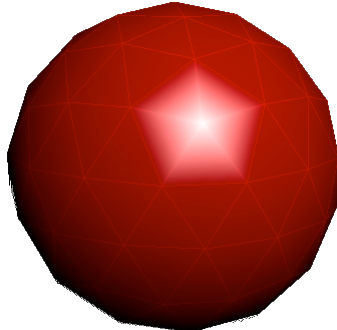


Gouraud Shading: Comparisons

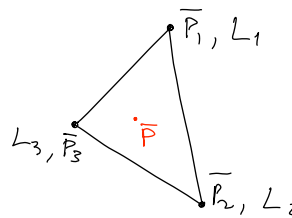
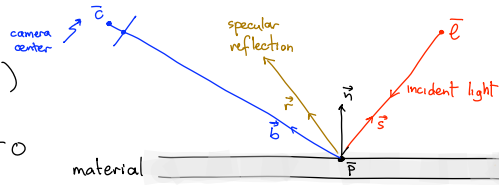
Gouraud shading -

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Gouraud-shaded specular sphere



Jalo, Wikipedia



Gouraud Shading: Comparisons

Gouraud shading -

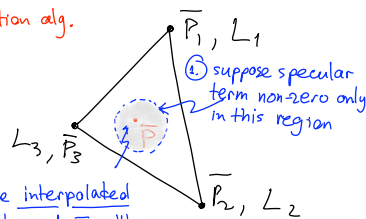
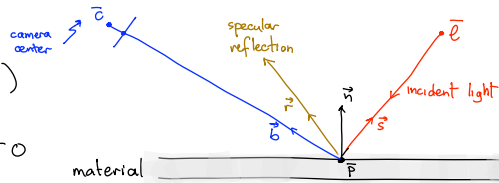
- ① Compute $L_i = L(\vec{b}_i, \vec{n}_i, \vec{s}_i)$ for each vertex
- ② Interpolate the L_i 's to get value at \vec{P} :

$$L = \beta L_1 + \gamma L_2 + \epsilon L_3$$

constants determined by interpolation alg.

Comparison to flat shading -

- ⊕ No visible seams between mesh triangles
- ⊕ Smooth, visually pleasing intensity variations that "mask" coarse geometry
- ⊖ Specular highlights still a problem for large triangles (why?)



③ the interpolated value at \vec{P} will erroneously not include a non-zero specular term

④ suppose specular term non-zero only in this region

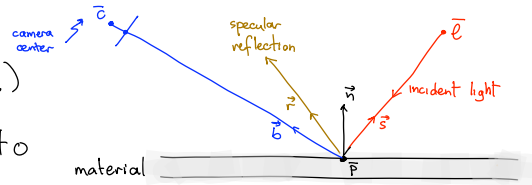
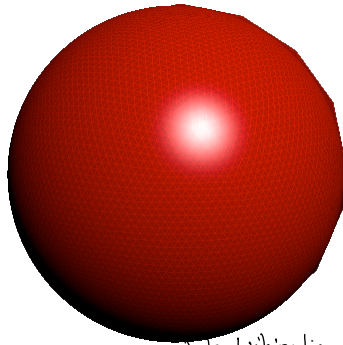
② then none of the L_i 's will include a non-zero specular term

Gouraud Shading: Comparisons

Gouraud shading -

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-
- ③ The interpolated value at \bar{P} will erroneously not include a non-zero specular term
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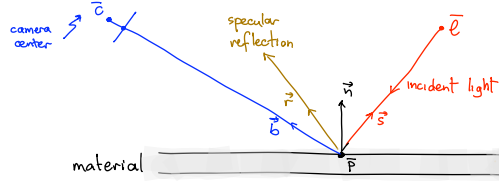
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Phong Shading: Main Idea

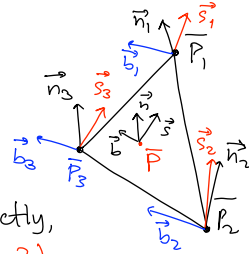
Phong shading -

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- ② Compute $L(\vec{b}, \vec{n}, \vec{s})$



Comparison to Gouraud shading -

- ⊕ Smooth intensity variations as in Gouraud shading
- ⊕ Handles specular highlights correctly, even for large triangles (Why?)

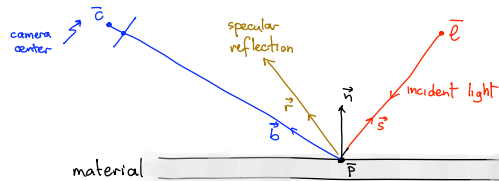


$$L(\vec{b}, \vec{n}, \vec{s}) = \underbrace{r_a I_a}_{\text{intensity at projection of point } \bar{P}} + \underbrace{r_d I_d}_{\text{ambient}} \max(0, \vec{n} \cdot \vec{s}) + \underbrace{r_s I_s}_{\text{diffuse}} \max(0, \vec{r} \cdot \vec{b})^q$$

Phong Shading: Comparisons

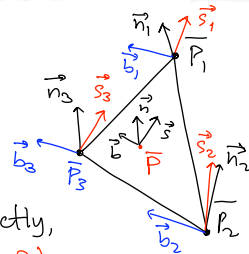
Phong shading -

- ① Interpolate $\vec{b}_i, \vec{n}_i, \vec{s}_i$ to get $\vec{b}, \vec{n}, \vec{s}$ at \bar{P}
- ② Compute $L(\vec{b}, \vec{n}, \vec{s})$



Comparison to Gouraud shading -

- ⊕ Smooth intensity variations as in Gouraud shading
- ⊕ Handles specular highlights correctly, even for large triangles (Why?)

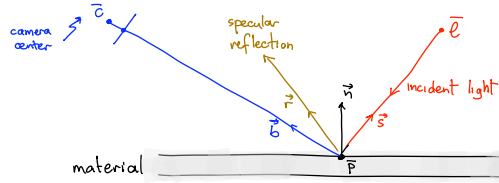


it is possible to have a significant specular component at \bar{P} even when all vertices have a negligible specular component

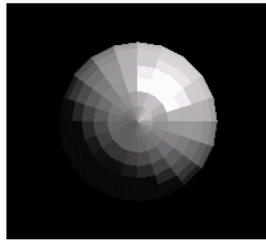
Phong Shading: Comparisons

Phong shading -

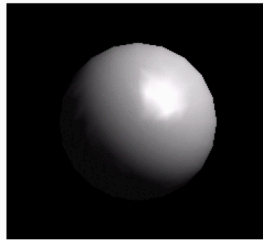
- ① Interpolate $\vec{b}_i, \vec{n}_i, \vec{s}_i$ to get $\vec{b}, \vec{n}, \vec{s}$ at \bar{P}
- ② Compute $L(\vec{b}, \vec{n}, \vec{s})$



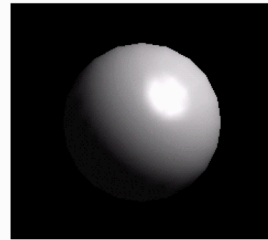
Hsien-Hsin Sean Lee, GaTech



Flat shading



Gouraud shading

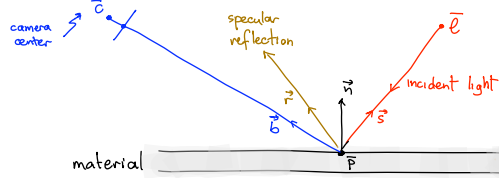


Phong shading

Phong Shading: Comparisons

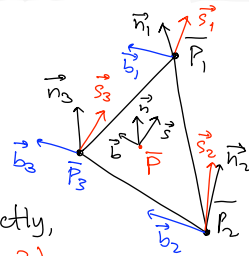
Phong shading -

- ① Interpolate $\vec{b}_i, \vec{n}_i, \vec{s}_i$ to get $\vec{b}, \vec{n}, \vec{s}$ at \bar{P}
- ② Compute $L(\vec{b}, \vec{n}, \vec{s})$



Comparison to Gouraud shading -

- ⊕ Smooth intensity variations as in Gouraud shading
- ⊕ Handles specular highlights correctly, even for large triangles (Why?)
- ⊖ Computationally less efficient (but ok on today's HW!)
(must interpolate 3 vectors & evaluate Phong reflection model at each triangle pixel)

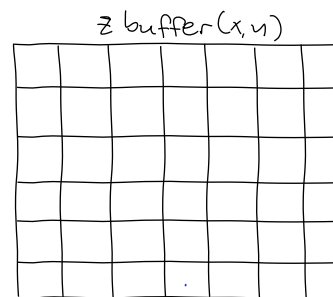
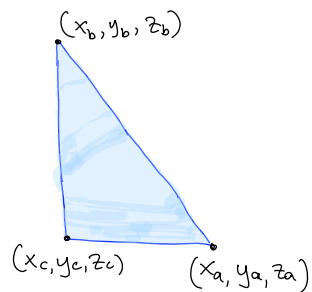


Topic 10:

Shading

- Introduction to Shading
- Flat Shading
- Interpolative Shading
 - Gouraud shading
 - Phong shading
- Triangle scan-conversion with shading

Scan Conversion with Z-Buffering & Shading



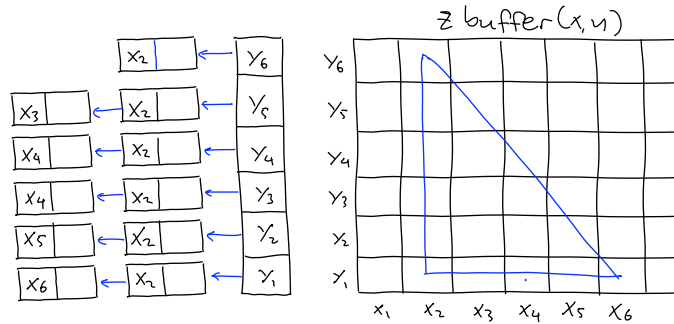
Step a: Build edge list

for each scanline,
store x-intersection,
pseudodepth and
 of each edge
pixel

Step b: Fill z-buffer & color at triangle pixels

for each triangle pixel in
scanline, interpolate
& pseudodepth & compare
to z-buffer

Scan Conversion with Z-Buffering & Shading



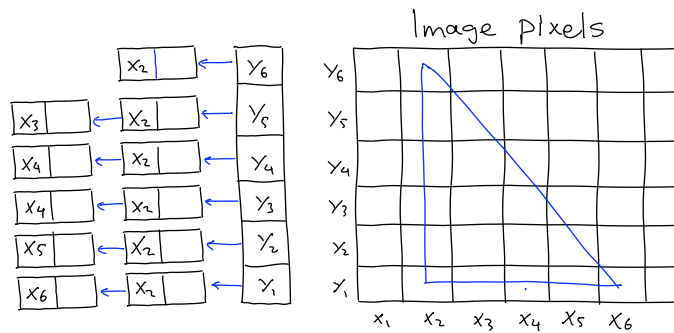
Step a: Build edge list

for each scanline, store x-intersection, pseudodepth and of each edge pixel

Step b: Fill zbuffer & color at triangle pixels

for each triangle pixel in scanline, interpolate & pseudodepth & compare to z-buffer

Scan Conversion with Gouraud Shading



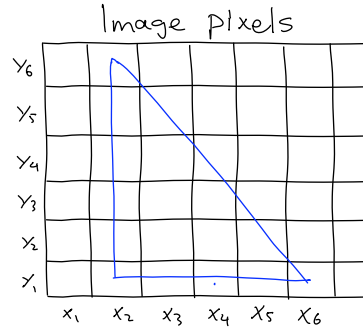
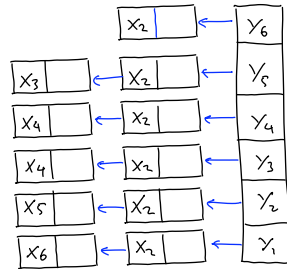
Step a: Build edge list

for each scanline, store x-intersection, pseudodepth and L value of each edge pixel

Step b: Fill zbuffer & color at triangle pixels

for each triangle pixel in scanline, interpolate L value & pseudodepth & compare to z-buffer

Scan Conversion with Phong Shading



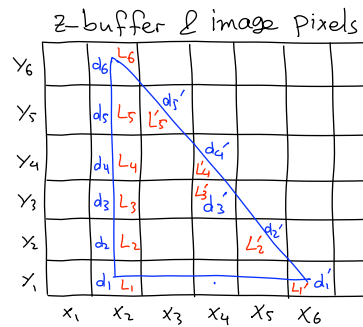
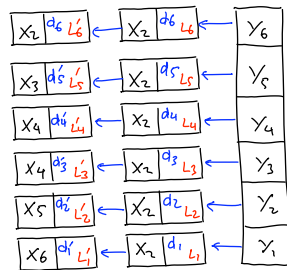
Step a: Build edge list

for each scanline,
store x-intersection,
pseudodepth and
 $(\vec{n}, \vec{s}, \vec{b})$ of each edge
pixel

Step b: Fill z-buffer &
color at triangle pixels

for each triangle pixel in
scanline, interpolate $(\vec{n}, \vec{s}, \vec{b})$
& pseudodepth & compare
to z-buffer

Edge List Construction (w/ Gouraud Shading)

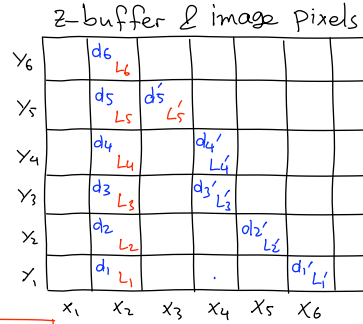
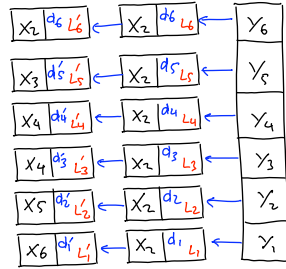


Step a: Build edge list

for each scanline,
store x-intersection,
pseudodepth and
 L value of each edge
pixel

for each edge $[(x_u, y_u, d_u), (x_e, y_e, d_e)]$
with $y_u > y_e$:
 $x = x_e, d = d_e, \Delta x = \frac{x_u - x_e}{y_u - y_e}, \Delta d = \frac{d_u - d_e}{y_u - y_e}$
 $\Delta L = \frac{L_u - L_e}{y_u - y_e}$
for $(y = y_e; y < y_u; y++)$
add (x, d) to list of scanline y
sort the list
 $x = x + \Delta x, d = d + \Delta d, L = L + \Delta L$

Scanline Filling with Z-Buffering & Gouraud



$\bar{y} = \min(y_a, y_b, y_c)$ $y^+ = \max(y_a, y_b, y_c)$
 for $(y = \bar{y}; y \leq y^+; y++)$
 get (x_e, d_e) and (x_u, d_u) from
 edge list of y , with $x_e < x_u$
 $\Delta d = \frac{d_u - d_e}{x_u - x_e}$ $\Delta L = \frac{L_u - L_e}{x_u - x_e}$
 for $(x = x_e, d = d_e, L = L_e; x \leq x_u; x++)$
 if $d < \text{zbuffer}(x, y)$
 put pixel (x, y, L) , $\text{zbuffer}(x, y) = d$
 $d = d + \Delta d$ $L = L + \Delta L$

Step 1: Fill zbuffer & color at triangle pixels

for each triangle pixel in scanline, interpolate L value & pseudodepth & compare to z-buffer