Signals

Haviland – Ch. 6

Signals

- Unexpected/unpredictable asynchronous events
  - floating point error
  - death of a child
  - interval timer expired (alarm clock)
  - control-C (termination request)
  - control-Z (suspend request)
- Events are called interrupts
- When the kernel recognizes an event, it sends a signal to the process.
- Normal processes may send signals.

What are signals for?

- When a program forks into 2 or more processes, rarely do they execute independently.
- The processes usually require some form of synchronization, often handled by signals.
- To transfer data between processes, we will use pipes and sockets (coming soon).
- Signals are generated by
  - machine interrupts
  - the program itself, other programs or the user.

Software Interrupts

- <sys/signal.h> lists the signal types on CDF.
- “man 7 signal” (“man 5 signal” on Solaris) gives some description of various signals
  - `SIGTERM, SIGABRT, SIGKILL`
  - `SIGSEGV, SIGBUS`
  - `SIGSTOP, SIGCONT`
  - `SIGCHLD`
  - `SIGPIPE`
  - `SIGUSR1, SIGUSR2`

Signal handlers

- When a C program receives a signal, control is immediately passed to a function called a signal handler.
- The signal handler function can execute some C statements and exit in 3 different ways:
  - return control to the place in the program which was executing when the signal occurred.
  - return control to some other point in the program.
  - terminate the program by calling exit.

Default actions

- Each signal has a default action:
  - terminate
  - stop
  - ignore
- The default action can be changed for most signal types using the `sigaction()` function. The exceptions are SIGKILL and SIGSTOP.

Signal table

- For each process, Unix maintains a table of actions that should be performed for each kind of signal.
- Here are a few…

Signal	Default Action	Comment
SIGINT	Terminate	Interrupt from keyboard
SIGSEGV	Terminate/Dump core	Invalid memory reference.
SIGKILL	Terminate (cannot ignore)	Kill
SIGCHLD	Ignore	Child stopped or terminated.
SIGSTOP	Stop (cannot ignore)	Stop process.
SIGCONT		Continue if stopped.

`sigaction()`

- Install a signal handler, `act`, for the signal `sig`.

```
int sigaction(int sig,
      const struct sigaction *act,
      struct sigaction *oldact);
```

- Struct defined in <signal.h> to fill in to pass in for `act`.

```
struct sigaction {
  /* SIG_DFL, SIG_IGN, or pointer to function */
  void (*sa_handler)(int);
  sigset_t sa_mask; /*Signals to block during handler*/
  int sa_flags; /* flags and options */
};
```

- You may come across various extensions, including another field in the sigaction struct for a function to catch signals.

sigaction() example

```
int i = 0;
/* signal handling function */
void quit(int code) {
  fprintf(stderr, "\nInterrupt (code=%d, i=%d)\n",
         code, i);
  exit(1);
}
int main() {
  struct sigaction newact;
  /* fill in newact */
  newact.sa_handler = quit; newact.sa_flags = 0;
  if(sigaction(SIGINT, &newact, NULL) == -1) exit(1);
  /* compute for a while */
  for(;;)
      if ((i++ % 50000000) == 0)
          fprintf(stderr,".");
}
```

• Run the program and try sending different signals to it.

Sending a signal

- From the command line use

  `kill [-signal] pid [pid]…`
- If no signal is specified, kill sends the TERM signal to the process.
- signal can be specified by the number or name without the SIG.
- Examples:

```
kill -QUIT 8883
kill -STOP 78911
kill -9 76433     (9 == KILL)
```


Signalling between processes

- One process can send a signal to another process using the misleadingly named function call.

  `kill(int pid, int sig);`
- This call sends the signal `sig` to the process `pid`
- Signalling between processes can be used for many purposes:
  - kill errant processes
  - temporarily suspend execution of a process
  - make a process aware of the passage of time
  - synchronize the actions of processes.

Timer signals

- Three interval timers are maintained for each process:
  - `SIGALRM` (real-time alarm, like a stopwatch)
  - `SIGVTALRM` (virtual-time alarm, measuring CPU time)
  - `SIGPROF` (used for profilers)
- Useful functions to set and get timer info:
  - `sleep()` – cause calling process to suspend.
  - `usleep()` – like sleep() but at a finer granularity.
  - `alarm()` – sets SIGALRM
  - `pause()` – suspend until next signal arrives
  - `setitimer(), getitimer()`
- `sleep()` and `usleep()` are interruptible by other signals.

Blocking Signals

- Signals can arrive at any time.
- To temporarily prevent a signal from being delivered we block it.
- The signal is held until the process unblocks the signal.
- When a process ignores a signal, it is thrown away.

Groups of signals

- Signal masks are used to store the set of signals that are currently blocked.
- Operations on sets of signals:

```
int sigemptyset(sigset_t *set);
int sigfillset(sigset_t *set);
int sigaddset(sigset_t *set, int signo);
int sigdelset(sigset_t *set, int signo);
int sigismember(const sigset_t *set,
                int signo);
```


sigprocmask()

```
int sigprocmask(int how,
            const sigset_t *set,
            sigset_t *oset);
```

- how indicates how the signal will be modified
  - SIG_BLOCK: add to those currently blocked
  - SIG_UNBLOCK: delete from those currently blocked
  - SIG_SETMASK: set the collection of signals being blocked
- set points to the set of signals to be used for modifying the mask
- oset on return holds the set of signals that were blocked before the call.