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## Notes for Q+A Session 7 (Monday, March 30)

$$P_K = -r_K + B_K P_{K-1} \quad (5.13)$$

Recall  $r_K = Ax_K - b$  ( $r_K$  is the "residual" associated with  $x_K$ )

Recall also that

$$\phi(x) = \frac{1}{2} x^T A x - b^T x$$

$$\therefore \nabla \phi(x) = Ax - b$$

$$\therefore r_K = Ax_K - b = \nabla \phi(x_K)$$


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Want  $P_K$  &  $P_{K-1}$  conjugate:  $P_{K-1}^T A P_K = 0$

So from (5.13)

$$\begin{aligned} 0 &= P_{K-1}^T A P_K = P_{K-1}^T A (-r_K + B_K P_{K-1}) \\ &= -P_{K-1}^T A r_K + B_K P_{K-1}^T A P_{K-1} \end{aligned}$$

$$\Rightarrow B_K = \frac{P_{K-1}^T A r_K}{P_{K-1}^T A P_{K-1}} = \frac{r_K^T A P_{K-1}}{P_{K-1}^T A P_{K-1}}$$

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$$\text{Claim: } \alpha_K = \frac{\mathbf{r}_K^T \mathbf{r}_K}{\mathbf{P}_K^T \mathbf{A} \mathbf{P}_K}$$

$$\text{Alg. S.1} \quad \alpha_K = \frac{-\mathbf{r}_K^T \mathbf{P}_K}{\mathbf{P}_K^T \mathbf{A} \mathbf{P}_K}$$

$$\begin{aligned} -\mathbf{r}_K^T \mathbf{P}_K &= -\mathbf{r}_K^T (-\mathbf{r}_K + \mathbf{B}_K \mathbf{P}_{K-1}) \quad (\text{by (S.14e)}) \\ &= \mathbf{r}_K^T \mathbf{r}_K - \mathbf{B}_K \mathbf{r}_K^T \mathbf{P}_{K-1} \end{aligned}$$

$$\text{But } \mathbf{r}_K^T \mathbf{P}_{K-1} = 0 \quad \text{by (S.11) in Thm S.2}$$

$$\therefore -\mathbf{r}_K^T \mathbf{P}_K = \mathbf{r}_K^T \mathbf{r}_K$$

$$\therefore \alpha_K = \frac{-\mathbf{r}_K^T \mathbf{P}_K}{\mathbf{P}_K^T \mathbf{A} \mathbf{P}_K} = \frac{\mathbf{r}_K^T \mathbf{r}_K}{\mathbf{P}_K^T \mathbf{A} \mathbf{P}_K}$$

Note:  $\alpha_K = 0 \Rightarrow \mathbf{r}_K \neq 0 \Rightarrow \nabla \varphi(\mathbf{x}_K) = 0$   
 $\mathbf{r}_K \neq 0 \Rightarrow \mathbf{x}_K$  is the minimizer  
of  $\varphi(\mathbf{x})$  so stop.

If we don't stop,  $\alpha_K \neq 0$

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Claim:

$$\beta_{k+1} = \frac{v_{k+1}^T v_{k+1}}{v_k^T v_k}$$

Alg 5-1:  $\beta_{k+1} = \frac{v_{k+1}^T A P_k}{P_k^T A P_k}$

$$v_{k+1} = v_k + \alpha_k A P_k \Rightarrow A P_k = \frac{v_{k+1} - v_k}{\alpha_k} \quad (\alpha_k \neq 0)$$

$$\therefore v_{k+1}^T A P_k = v_{k+1}^T \left( \frac{v_{k+1} - v_k}{\alpha_k} \right) = v_{k+1}^T v_{k+1} \quad \left( \text{since } v_{k+1}^T v_k = 0 \text{ by (5.15)} \right)$$

$$= \frac{v_{k+1}^T v_{k+1}}{\alpha_k} \quad \left( \begin{array}{l} \text{since } v_{k+1}^T v_k = 0 \\ \text{by (5.16)} \end{array} \right)$$

$$P_k^T A P_k = P_k^T \left( \frac{v_{k+1} - v_k}{\alpha_k} \right)$$

$$= - \frac{P_k^T v_k}{\alpha_k} \quad \left( \begin{array}{l} \text{since } P_k^T v_{k+1} = 0 \\ \text{by (5.11)} \end{array} \right)$$

$$= - \frac{(-v_k + \beta_k P_{k-1})^T v_k}{\alpha_k} \quad (\text{by (5.14e)})$$

$$= \frac{P_{k-1}^T v_k}{\alpha_k} \quad \left( \begin{array}{l} \text{since } P_{k-1}^T v_k = 0 \\ \text{by (5.11)} \end{array} \right)$$

$$\therefore \beta_{k+1} = \frac{v_{k+1}^T A P_k}{P_k^T A P_k} = \frac{v_{k+1}^T v_{k+1} / \alpha_k}{v_k^T v_k / \alpha_k} = \frac{v_{k+1}^T v_{k+1}}{v_k^T v_k}$$

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$$\text{Claim: } \frac{1}{2} \|x - x^*\|_A^2 = \frac{1}{2} (x - x^*)^T A (x - x^*) = \varphi(x) - \varphi(x^*)$$

∴ where  $x^*$  is the minimizer of  $\varphi(x)$

$$\Rightarrow \nabla \varphi(x^*) = 0 \Rightarrow A x^* = b$$

$$\frac{1}{2} (x - x^*)^T A (x - x^*) = \varphi(x) - \varphi(x^*)$$

$$= \frac{1}{2} x^T A x - x^T A x^* + \frac{1}{2} (x^*)^T A x^*$$

$$= \left( \frac{1}{2} x^T A x - b^T x \right) + \left( \frac{1}{2} (x^*)^T A x^* - b^T x^* \right)$$

$$= -x^T A x^* + \frac{1}{2} (x^*)^T A x^* + b^T x + \frac{1}{2} (x^*)^T A x^* - b^T x^*$$

$$= -x^T A x^* + \frac{1}{2} (x^*)^T A x^* + b^T x$$

(replace  $A x^*$  by  $b$ )

$$= -x^T b + \frac{1}{2} (x^*)^T b + b^T x + \frac{1}{2} (x^*)^T b - b^T x^*$$

$$= 0$$

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$$x_{K+1} = \arg \min_{x \in X_0 + \text{Span}\{p_0, p_1, \dots, p_K\}} \varphi(x)$$

$$= \arg \min_{x \in X_0 + \text{Span}\{p_0, p_1, \dots, p_K\}} \frac{1}{2} \|x - x^*\|_A^2$$

$$= \arg \min_{x \in X_0 + \text{Span}\{p_0, p_1, \dots, p_K\}} \|x - x^*\|_A$$

$$= \arg \min_{x \in X_0 + \text{Span}\{r_0, Ar_0, \dots, A^K r_0\}} \|x - x^*\|_A$$

$$= \arg \min_{P_K \in \mathcal{P}_K} \|x_0 + P_K(A)r_0 - x^*\|_A$$

$\mathcal{P}_K$  a polynomial of degree  $\leq K$

$$\text{Now note } r_0 = Ax_0 - b = Ax_0 - Ax^* = A(x_0 - x^*)$$

$$\therefore x_0 + P_K(A)r_0 - x^* = (I + P_K(A)A)(x_0 - x^*)$$

$$\therefore x_{K+1} = \arg \min_{P_K \in \mathcal{P}_K} \|P_K(A)(x_0 - x^*)\|_A$$

$\mathcal{P}_K = \left\{ \text{polynomials of the form } 1 + \gamma_0 P_K(x) \text{ where } P_K(x) \text{ is a polynomial of deg } \leq K \right\}$

$$1 + \gamma_0 P_K(x) = 1 + \gamma_0 x + \dots + \gamma_K x^{K+1}$$

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A SPD eigenvalues  $0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$   
 orthonormal eigenvectors  $v_1, v_2, \dots, v_n$

$$A v_i = \lambda_i v_i \quad v_i^T v_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

Essentially same as  $Q^T A Q = \Lambda = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix}$   
 $Q = \{v_1, v_2, \dots, v_n\}$

Outer product form

$$A = \sum_{i=1}^n \lambda_i v_i v_i^T$$

Why:  $A v_k = \lambda_k v_k$   $\downarrow = \begin{cases} 1 & \text{if } i=k \\ 0 & \text{if } i \neq k \end{cases}$

$$\left( \sum_{i=1}^n \lambda_i v_i v_i^T \right) v_k = \sum_{i=1}^n \lambda_i v_i (v_i^T v_k) = \lambda_k v_k$$

If  $A v_i = B v_i$  for  $i=1, \dots, n$

and  $\{v_1, v_2, \dots, v_n\}$  is a basis for  $\mathbb{R}^n$

then must have  $Ax = Bx$  for all  $x \in \mathbb{R}^n$

$$\Rightarrow A = B$$

Note eigenvalues  $\{v_1, v_2, \dots, v_n\}$  is a basis for  $\mathbb{R}^n$ .

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$$P_K(A) v_i = P_K(\lambda_i) v_i \quad \text{for eigenvector } v_i \text{ of } A$$

$$Av_i = \lambda_i v_i$$

Why? First note  $A^j v_i = \lambda_i^j v_i$

$P_K(A)$  Induction on  $j$

$$j=1 \quad A v_i = \lambda_i v_i$$

Assume true for  $j$  and consider  $Av_i = \lambda_i v_i$

$$\begin{aligned} A^{j+1} v_i &= A (A^j v_i) = A(\lambda_i^j v_i) = \lambda_i^j A v_i \\ &= \lambda_i^j (\lambda_i v_i) \\ &= \lambda_i^{j+1} v_i \end{aligned}$$

$$\therefore P_K(A) v_i = \left( \sum_{j=0}^K \alpha_j A^j \right) v_i$$

In general,  $A^j v_i = \lambda_i^j v_i$

$$= \sum_{j=0}^K \alpha_j A^j v_i$$

$$= \sum_{j=0}^K \alpha_j \lambda_i^j v_i$$

$$= \left( \sum_{j=0}^K \alpha_j \lambda_i^j \right) v_i$$

$$= P_K(\lambda_i) v_i$$

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$$x_{k+1} - x^* = (\mathbb{I} + P_K^*(A)A)(x_0 - x^*) \quad (5-30)$$

Let  $x_0 - x^* = \sum_{i=1}^n \xi_i v_i$

$$\begin{aligned} x_{k+1} - x^* &= (\mathbb{I} + P_K^*(A)A)(x_0 - x^*) \\ &= (\mathbb{I} + P_K^*(A)A) \sum_{i=1}^n \xi_i v_i \\ &= \sum_{i=1}^n \xi_i (\mathbb{I} + P_K^*(A)A) v_i \\ &= \sum_{i=1}^n (\mathbb{I} v_i + P_K^*(A)v_i) \xi_i \\ &= \sum_{i=1}^n (v_i + P_K^*(\lambda_i) \lambda_i v_i) \xi_i \\ &= \sum_{i=1}^n (1 + P_K^*(\lambda_i) \lambda_i) \xi_i v_i \end{aligned}$$

$$\begin{aligned} \|z\|_A^2 &= z^T A z = z^T \left( \sum_{i=1}^n \lambda_i v_i v_i^T \right) z \\ &= \sum_{i=1}^n \lambda_i (z^T v_i) (v_i^T z) \\ &= \sum_{i=1}^n \lambda_i (v_i^T z)^2 \end{aligned}$$

$$\begin{aligned} \therefore \|x_{k+1} - x^*\|_A^2 &= (x_{k+1} - x^*)^T A \underbrace{(x_{k+1} - x^*)}_{= z} = \sum_{i=1}^n (1 + P_K^*(\lambda_i) \lambda_i) \xi_i^2 v_i^2 \end{aligned}$$

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$$\|x_{k+1} - x^*\|_A^2 = \min_{P_k} \sum_{i=1}^n (1 + P_k(\lambda_i) \lambda_i)^2 \lambda_i \xi_i^2$$

$$\leq \min_{P_k} \max_{1 \leq i \leq n} (1 + P_k(\lambda_i) \lambda_i)^2 \sum_{i=1}^n \lambda_i \xi_i^2$$

$$\text{Recall } x_0 - x^* = \sum_{i=1}^n \xi_i v_i = z$$

$$\begin{aligned} \|x_0 - x^*\|_A^2 &= (\sum_{i=1}^n \xi_i v_i)^T A (\sum_{i=1}^n \xi_i v_i) \\ &= (\sum_{i=1}^n \xi_i v_i)^T (\sum_{i=1}^n \xi_i A v_i) \\ &= (\sum_{i=1}^n \xi_i v_i)^T (\sum_{i=1}^n \xi_i \lambda_i v_i) \\ &= \sum \lambda_i \xi_i^2 \end{aligned}$$

$$\therefore \|x_{k+1} - x^*\|_A^2 \leq \left( \min_{P_k} \max_{1 \leq i \leq n} (1 + P_k(\lambda_i) \lambda_i)^2 \right) \|x_0 - x^*\|_A^2$$

(5.33) in book

This is the key result.

Speed of Convergence of CG depends on

$$\min_{P_k} \max_{1 \leq i \leq n} (1 + P_k(\lambda_i) \lambda_i)^2$$