# CSC 411 Lecture 09: Generative Models for Classification II

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- Classification Multi-dimensional (Gaussian) Bayes classifier
- Estimate probability densities from data

- Generative models model  $p(\mathbf{x}|t = k)$
- Instead of trying to separate classes, try to model what each class "looks like".
- Recall that  $p(\mathbf{x}|t = k)$  may be very complex

$$p(x_1,\cdots,x_d,y)=p(x_1|x_2,\cdots,x_d,y)\cdots p(x_{d-1}|x_d,y)p(x_d,y)$$

- Naive bayes used a conditional independence assumption. What else could we do? Choose a simple distribution.
- Today we will discuss fitting Gaussian distributions to our data.

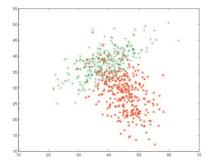
## **Bayes** Classifier

- Let's take a step back...
- Bayes Classifier

$$h(\mathbf{x}) = \arg \max p(t = k | \mathbf{x}) = \arg \max \frac{p(\mathbf{x} | t = k)p(t = k)}{p(\mathbf{x})}$$
$$= \arg \max p(\mathbf{x} | t = k)p(t = k)$$

• Talked about Discrete x, what if x is continuous?

• Observation per patient: White blood cell count & glucose value.



• How can we model p(x|t = k)? Multivariate Gaussian

### Gaussian Discriminant Analysis (Gaussian Bayes Classifier)

- Gaussian Discriminant Analysis in its general form assumes that  $p(\mathbf{x}|t)$  is distributed according to a multivariate normal (Gaussian) distribution
- Multivariate Gaussian distribution:

$$p(\mathbf{x}|t=k) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}_k|^{1/2}} \exp\left[-(\mathbf{x} - \boldsymbol{\mu}_k)^T \boldsymbol{\Sigma}_k^{-1} (\mathbf{x} - \boldsymbol{\mu}_k)\right]$$

where  $|\Sigma_k|$  denotes the determinant of the matrix, and d is dimension of **x** 

- Each class k has associated mean vector  $\mu_k$  and covariance matrix  $\Sigma_k$
- $\Sigma_k$  has  $\mathcal{O}(d^2)$  parameters could be hard to estimate (more on that later).

- Multiple measurements (sensors)
- *d* inputs/features/attributes
- N instances/observations/examples

$$\mathbf{X} = \begin{bmatrix} x_1^{(1)} & x_2^{(1)} & \cdots & x_d^{(1)} \\ x_1^{(2)} & x_2^{(2)} & \cdots & x_d^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(N)} & x_2^{(N)} & \cdots & x_d^{(N)} \end{bmatrix}$$

Mean

$$\mathbb{E}[\mathbf{x}] = [\mu_1, \cdots, \mu_d]^T$$

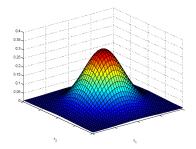
Covariance

$$\Sigma = Cov(\mathbf{x}) = \mathbb{E}[(\mathbf{x} - \mu)^{T}(\mathbf{x} - \mu)] = \begin{bmatrix} \sigma_{1}^{2} & \sigma_{12} & \cdots & \sigma_{1d} \\ \sigma_{12} & \sigma_{2}^{2} & \cdots & \sigma_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{d1} & \sigma_{d2} & \cdots & \sigma_{d}^{2} \end{bmatrix}$$

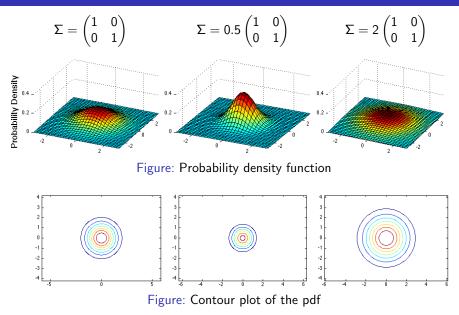
• For Gaussians - all you need to know to represent! (not true in general)

#### Multivariate Gaussian Distribution

•  $\mathbf{x} \sim \mathcal{N}(\mu, \Sigma)$ , a Gaussian (or normal) distribution defined as  $p(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp\left[-(\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu)\right]$ 



- Mahalanobis distance (x μ<sub>k</sub>)<sup>T</sup>Σ<sup>-1</sup>(x μ<sub>k</sub>) measures the distance from x to μ in terms of Σ
- It normalizes for difference in variances and correlations



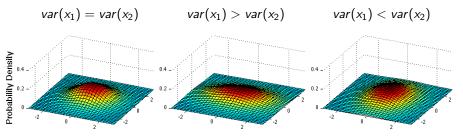
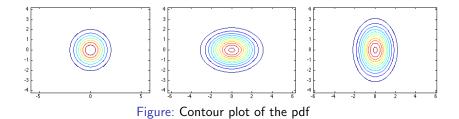
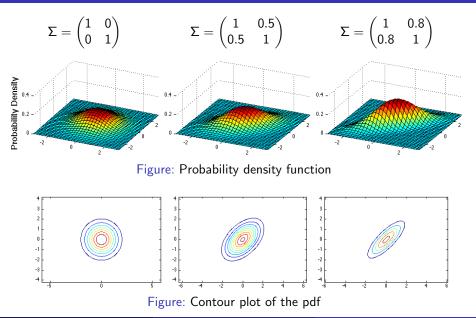
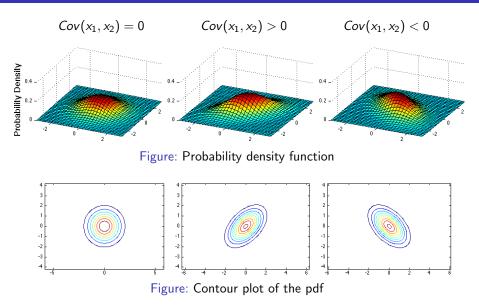


Figure: Probability density function



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#### Gaussian Discriminant Analysis (Gaussian Bayes Classifier)

• GDA (GBC) decision boundary is based on class posterior:

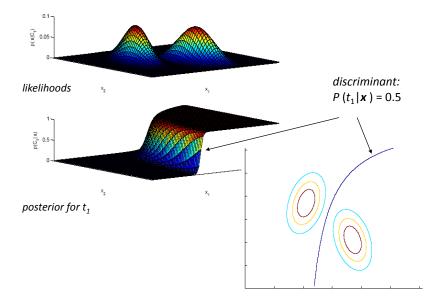
$$\begin{split} \log p(t_k | \mathbf{x}) &= \log p(\mathbf{x} | t_k) + \log p(t_k) - \log p(\mathbf{x}) \\ &= -\frac{d}{2} \log(2\pi) - \frac{1}{2} \log |\Sigma_k^{-1}| - \frac{1}{2} (\mathbf{x} - \mu_k)^T \Sigma_k^{-1} (\mathbf{x} - \mu_k) + \\ &+ \log p(t_k) - \log p(\mathbf{x}) \end{split}$$

• Decision boundary:

$$(\mathbf{x} - \mu_k)^T \Sigma_k^{-1} (\mathbf{x} - \mu_k) = (\mathbf{x} - \mu_\ell)^T \Sigma_\ell^{-1} (\mathbf{x} - \mu_\ell) + Const$$
$$\mathbf{x}^T \Sigma_k^{-1} \mathbf{x} - 2\mu_k^T \Sigma_k^{-1} \mathbf{x} = \mathbf{x}^T \Sigma_\ell^{-1} \mathbf{x} - 2\mu_\ell^T \Sigma_\ell^{-1} \mathbf{x} + Const$$

- Quadratic function in x
- What if  $\Sigma_k = \Sigma_\ell$ ?

#### **Decision Boundary**





#### Learning

- Learn the parameters for each class using maximum likelihood
- Assume the prior is Bernoulli (we have two classes)

$$p(t|\phi) = \phi^t (1-\phi)^{1-t}$$

• You can compute the ML estimate in closed form

$$\phi = \frac{1}{N} \sum_{n=1}^{N} \mathbb{1}[t^{(n)} = 1]$$
  

$$\mu_{k} = \frac{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k] \cdot \mathbf{x}^{(n)}}{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k]}$$
  

$$\Sigma_{k} = \frac{1}{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k]} \sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k] (\mathbf{x}^{(n)} - \mu_{t^{(n)}}) (\mathbf{x}^{(n)} - \mu_{t^{(n)}})^{T}$$

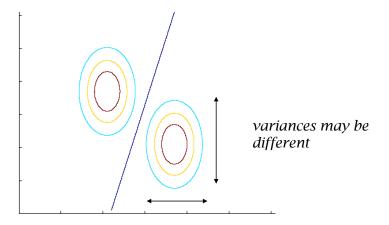
What if **x** is high-dimensional?

- For Gaussian Bayes Classifier, if input **x** is high-dimensional, then covariance matrix has many parameters
- Save some parameters by using a shared covariance for the classes
- Any other idea you can think of?
- MLE in this case:

$$\Sigma = rac{1}{N} \sum_{n=1}^{N} (\mathbf{x}^{(n)} - \mu_{t^{(n)}}) (\mathbf{x}^{(n)} - \mu_{t^{(n)}})^T$$

• Linear decision boundary.

## Decision Boundary: Shared Variances (between Classes)



• Binary classification: If you examine  $p(t = 1|\mathbf{x})$  under GDA and assume  $\Sigma_0 = \Sigma_1 = \Sigma$ , you will find that it looks like this:

$$p(t|\mathbf{x}, \phi, \mu_0, \mu_1, \Sigma) = \frac{1}{1 + \exp(-\mathbf{w}^T \mathbf{x})}$$

where **w** is an appropriate function of  $(\phi, \mu_0, \mu_1, \Sigma)$ ,  $\phi = p(t = 1)$ 

- Same model as logistic regression!
- When should we prefer GDA to LR, and vice versa?

- GDA makes stronger modeling assumption: assumes class-conditional data is multivariate Gaussian
- If this is true, GDA is asymptotically efficient (best model in limit of large N)
- But LR is more robust, less sensitive to incorrect modeling assumptions (what loss is it optimizing?)
- Many class-conditional distributions lead to logistic classifier
- When these distributions are non-Gaussian (a.k.a almost always), LR usually beats GDA
- GDA can handle easily missing features (how do you do that with LR?)

• Naive Bayes: Assumes features independent given the class

$$p(\mathbf{x}|t=k) = \prod_{i=1}^{d} p(x_i|t=k)$$

- Assuming likelihoods are Gaussian, how many parameters required for Naive Bayes classifier?
- Equivalent to assuming  $\Sigma_k$  is diagonal.

#### Gaussian Naive Bayes

• Gaussian Naive Bayes classifier assumes that the likelihoods are Gaussian:

$$p(x_i|t=k) = rac{1}{\sqrt{2\pi}\sigma_{ik}}\exp\left[rac{-(x_i-\mu_{ik})^2}{2\sigma_{ik}^2}
ight]$$

(this is just a 1-dim Gaussian, one for each input dimension)

- Model the same as Gaussian Discriminative Analysis with diagonal covariance matrix
- Maximum likelihood estimate of parameters

$$\mu_{ik} = \frac{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k] \cdot x_i^{(n)}}{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k]}$$
  
$$\sigma_{ik}^2 = \frac{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k] \cdot (x_i^{(n)} - \mu_{ik})^2}{\sum_{n=1}^{N} \mathbb{1}[t^{(n)} = k]}$$

• What decision boundaries do we get?

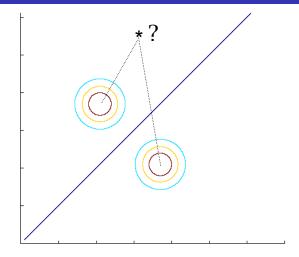
- In this case:  $\sigma_{i,k} = \sigma$  (just one parameter), class priors equal (e.g.,  $p(t_k) = 0.5$  for 2-class case)
- Going back to class posterior for GDA:

$$\log p(t_k | \mathbf{x}) = \log p(\mathbf{x} | t_k) + \log p(t_k) - \log p(\mathbf{x}) = -\frac{d}{2} \log(2\pi) - \frac{1}{2} \log |\Sigma_k^{-1}| - \frac{1}{2} (\mathbf{x} - \mu_k)^T \Sigma_k^{-1} (\mathbf{x} - \mu_k) + \log p(t_k) - \log p(\mathbf{x})$$

where we take  $\Sigma_k = \sigma^2 I$  and ignore terms that don't depend on k (don't matter when we take max over classes):

$$\log p(t_k | \mathbf{x}) = -\frac{1}{2\sigma^2} (\mathbf{x} - \mu_k)^T (\mathbf{x} - \mu_k)$$

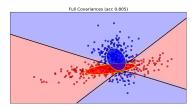
#### Decision Boundary: isotropic



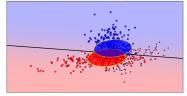
• Same variance across all classes and input dimensions, all class priors equal

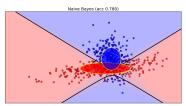
• Classification only depends on distance to the mean. Why?

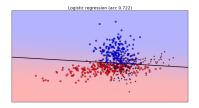
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Shared Covariance (acc 0.717)







- GDA quadratic decision boundary.
- With shared covariance "collapses" to logistic regression.
- Generative models:
  - Flexible models, easy to add/remove class.
  - Handle missing data naturally
  - More "natural" way to think about things, but usually doesn't work as well.
- Tries to solve a hard problem in order to solve a easy problem.