

Solutions for Tutorial Exercise 11: Approximation Algorithms

1. **Q5, Chp 11, Kleinberg and Tardos.** The first algorithm presented in the lecture notes for Load Balancing is an on-line algorithm, that is, the jobs can be processed as soon as they arrive. We refer to it as the **FirstArrival** algorithm. While the LPT algorithm obtains a better approximation ratio, it does not have this on-line property. Here we show that the **FirstArrival** algorithm can have an approximation ratio that is less than the worst case of 2 if the mix of jobs that it is asked to schedule is somehow restricted.

For example, suppose that you have 10 machines, and need to schedule N jobs, where the n^{th} such job takes time t_n . In addition, you know the total time required for all the jobs is $T = \sum_{n=1}^N t_n = 3000$, and the time required for each individual job satisfies $1 \leq t_n \leq 50$. Show that the approximation ratio of FirstArrival for this mix of jobs is no worse than $7/6$.

Solution for Q1: In the lecture notes, we showed that the optimal makespan, L^* , satisfies

$$L^* \geq \frac{1}{m} \sum_{n=1}^N t_n = \frac{1}{m} T. \quad (1)$$

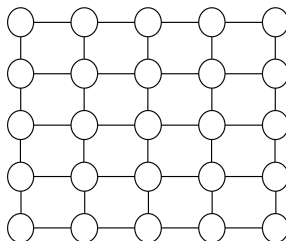
Moreover, we showed the makespan $L(s)$ provided by the FirstArrival algorithm is the runtime for the last machine to finish, say L_i , which satisfies (slide 9):

$$(L_i - t_j) \leq \frac{1}{m} \sum_{n=1}^N t_n = \frac{1}{m} T. \quad (2)$$

Therefore

$$\begin{aligned} \frac{L(s)}{L^*} &= \frac{(L_i - t_j) + t_j}{L^*}, \\ &\leq \frac{(L_i - t_j) + t_j}{(T/m)}, \quad \text{by (1),} \\ &\leq \frac{(T/m) + t_j}{(T/m)}, \quad \text{by (2),} \\ &\leq \frac{(T/m) + \max(t_i)}{(T/m)}, \\ &\leq \frac{300 + 50}{300} = 7/6. \quad \text{since } \frac{1}{m} T = 300 \text{ and } t_i \leq 50. \end{aligned}$$

2. **Q10, Chp 11, Kleinberg and Tardos.** Suppose you are given a weighted graph $G = (V, E, w)$ where G has the form of an $n \times n$ grid graph (see figure below). Assume the weights $w(v)$ are non-negative integers.



Prof. Jot proposes the following greedy algorithm for obtaining an approximate solution to the maximally weighted independent set problem for this type of graph:

```

[S] = wIndSet(V, E, w)
Initialize  $F \leftarrow (V, E)$  and  $S \leftarrow \{ \}$ .
While the graph  $F$  is not empty:
    Find a vertex  $u$  in  $F$  with the largest weight  $w(u)$ .
     $S \leftarrow S \cup \{u\}$ 
    Update  $F$  by deleting the vertex  $u$  and all its neighbouring vertices  $v$  (i.e., all vertices  $v$  with
    an edge  $(u, v)$  still in  $F$ ), and delete all the edges ending at any of these deleted vertices.
End while
return S

```

- (a) Write a loop invariant for the above code that is useful for proving that the set S returned by `wIndSet` is an independent set for the graph G .
- (b) Prove the loop invariant in part (a), and that the returned set S is an independent set for the graph G .
- (c) Show that $w(S) = \sum_{v \in S} w(v)$ is at least $(1/4)w(S^*)$, where S^* is an independent set of G with the maximum possible weight $w(S^*)$.

Solution for Q2:

Soln Q2a Add the following loop invariant to the end of the loop in the above algorithm:

LI: S is an independent set of G , and the updated graph F does not contain any vertex $u \in S$ nor any neighbour vertex (with respect to G) of u .

Soln Q2b This loop invariant can be proved by induction. The key is that whenever a vertex u is added to S , all remaining neighbours of u are deleted from F .

The algorithm removes at least one vertex from F each step, so it must terminate.

Upon termination, the algorithm returns S , and the LI guarantees that this is an independent set of G . We skip the details.

Soln Q2c Remember that to be a ρ -approximation we need to show the algorithm is poly-time. If, say, a heap is used to store the weights $w(v)$ (paired with v), then this algorithm runs in $O(|E| + |V| \log |V|)$ time.

To show the algorithm achieves an approximation ratio of 4, let S^* be a minimum weight independent set, and suppose S is the set produced by this algorithm. We build a “association” mapping, say $A(v)$, which maps each element $v \in S^*$ to one of its neighbours $u \in S$ as follows.

Let $v \in S^*$. If $v \in S$, define $A(v) = v$. Otherwise, $v \notin S$ and this means that, at some point, the algorithm above must have eliminated v from F when it selected one of v 's neighbours, say u , to add to S . Given this $u \in S$, we define $A(v) = u$. Moreover, for the algorithm to choose u over v , it must be the case that $w(u) \geq w(v)$. Note that, in both of the above cases we have $A(v) \in S$ and the $w(A(v)) \geq w(v)$.

For each $u \in S$ let $c(u) = |\{v \mid v \in S^* \text{ and } A(v) = u\}|$. That is, $c(u)$ is the number of different vertices $v \in S^*$ that are associated with u . Since S^* is an independent set, it follows that $0 \leq c(u) \leq \text{degree}(u) \leq 4$ (see the above figure).

We now have

$$W^* \equiv \sum_{v \in S^*} w(v) \leq \sum_{v \in S^*} w(A(v)), \quad (3)$$

$$= \sum_{u \in S} c(u)w(u), \quad \text{by the definition of } c(u), \quad (4)$$

$$\leq \sum_{u \in S} 4w(u) = 4w(S) = 4W. \quad (5)$$

Therefore, $W^*/W \leq 4$ and the above maximization algorithm is a ρ -approximation with $\rho = 4$.

3. Modified Q3 Chp 11 Kleiberg and Tardos. Suppose you are given a list of N integers $L = [a_1, a_2, \dots, a_N]$, and a positive integer C . The problem is to find a subset $S \subseteq \{1, 2, \dots, N\}$ such that

$$T(S) = \sum_{i \in S} a_i \leq C, \quad (6)$$

and $T(S)$ is as large as possible.

(a) Prof. Jot proposes the following greedy algorithm for obtaining an approximate solution to this maximization problem:

```
[S] = maxBoundedSetSum([a1, ..., aN], C)
Initialize S ← { }, T = 0
For i = 1, 2, ..., N:
    If T + ai ≤ C:
        S ← S ∪ {i}
        T ← T + ai
End for
return S
```

Show that Prof. Jot's algorithm is not a ρ -approximation algorithm for any fixed value ρ . (Use the convention that $\rho > 1$.)

(b) Describe a 2-approximation algorithm for this maximization problem that runs in $O(N \log(N))$ time.

Solution for Q3:

Soln Q3a Let $\rho > 1$ be a given positive integer. Consider the input set $L = [1, \rho + 1]$, with the upper bound $C = \rho + 1$. Then the Prof. Jot's algorithm returns $S = \{1\}$, for which $T(S) = 1$, while the optimum solution is $S^* = \{2\}$, for which $T(S^*) = \rho + 1$. Therefore

$$\frac{T(S^*)}{T(S)} = \frac{\rho + 1}{1} > \rho, \quad (7)$$

so the algorithm is not a ρ -approximation for this value of ρ . Finally, since ρ was an arbitrary choice bigger than one, this is true for any $\rho > 1$. Therefore this algorithm is not a ρ -approximation.

Soln Q3b Consider the slightly modified algorithm (next page):

```

[S] = maxBoundedSetSum( $[a_1, \dots, a_N]$ ,  $C$ )
Initialize  $S \leftarrow \{ \}$ ,  $T = 0$ 
For  $i = 1, 2, \dots, N$ :
  If  $a_i \leq C$ :
    If  $T + a_i \leq C$ :
       $S \leftarrow S \cup \{i\}$ 
       $T \leftarrow T + a_i$ 
    Else:
      If  $T < C/2$ :
         $S \leftarrow \{i\}$ 
      break
End for
return  $S$ 

```

The algorithm runs in $O(N)$ time.

For the analysis, it is useful to first consider any item for which $a_i > C$. Such items cannot appear in any solution, and are simply discarded by the algorithm above. In the remainder of this proof we can therefore assume, without loss of generality, that $a_i \leq C$ for all i .

Given that $a_i \leq C$ for all i , there are now two general cases: 1) $\sum_{i=1}^N a_i = A \leq C$; and 2) $\sum_{i=1}^N a_i = A > C$. In the first case the algorithm above produces the optimum solution. In the second case, the algorithm above produces a set S such that $T(S) \geq C/2$. But note that, for any optimal solution S^* , it follows that $T(S^*) \leq C$. Therefore $T(S) \geq \frac{1}{2}T(S^*)$, and so the algorithm is a 2-approximation.