

CSC2503: Foundations of Computer Vision

Object Recognition

*Most slides are modified from the excellent course notes
and tutorials by Antonio Torralba, Fei-Fei Li and Rob Fergus.*

<http://people.csail.mit.edu/torralba/cvpr2007/>

What's involved in object recognition?



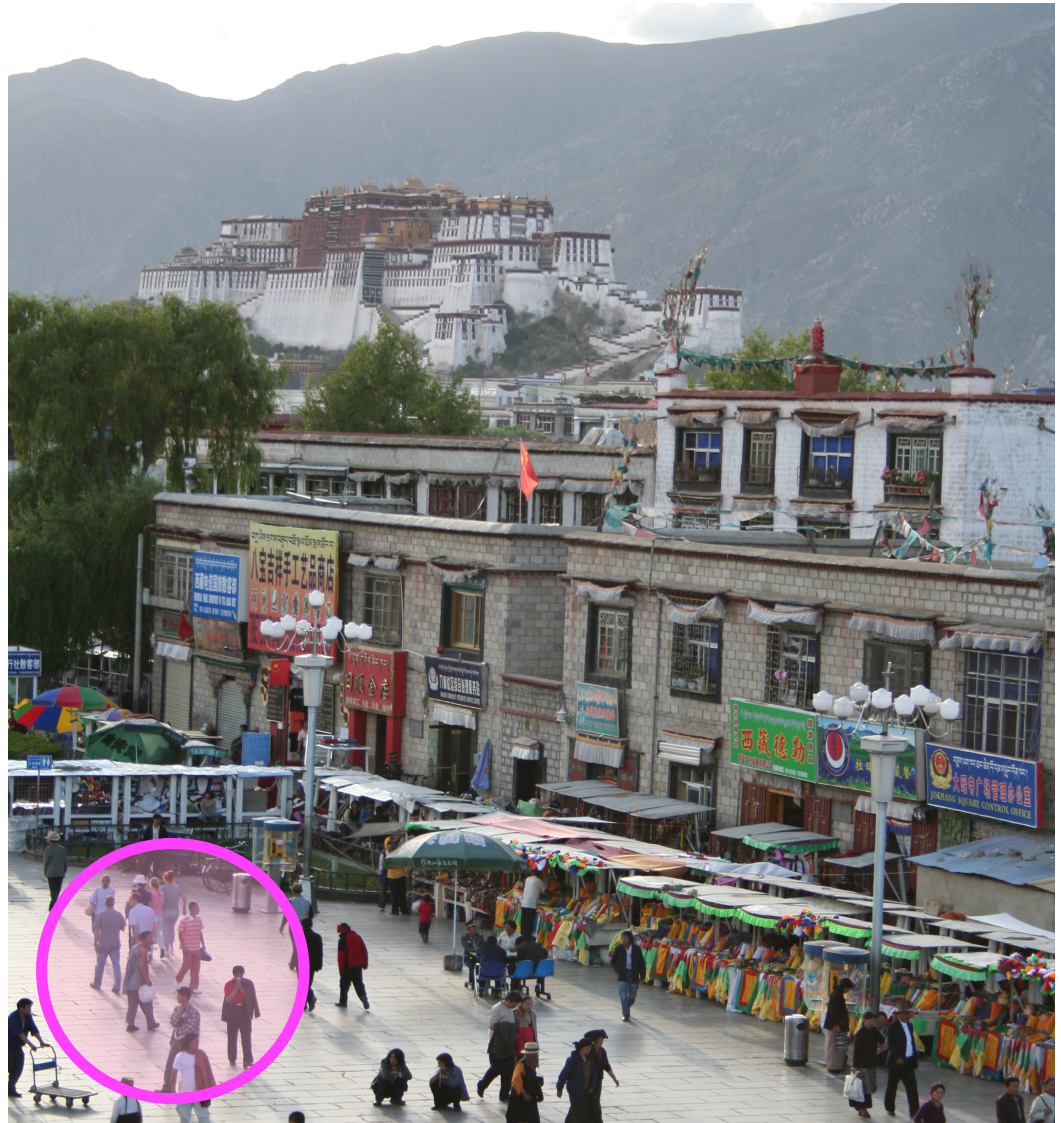
Verification

Is this a lamp?



Detection

Are there people
in the image?



Identification

Is this Potala Palace?



Category recognition



Scene and context categorization

- outdoor
- city
- daytime
- ...



Viewpoint and space

Are the distances large or small?

How far are the distant buildings?



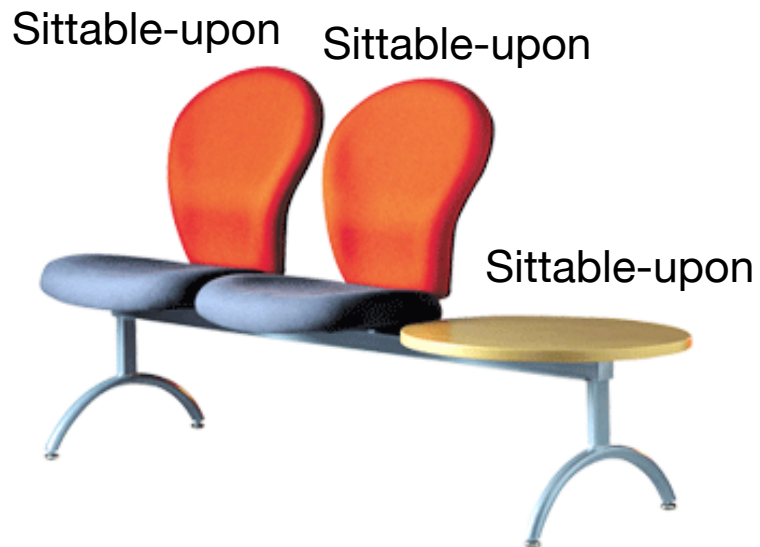
Activity recognition



Perception, categories and function?

- ▶ Gestalt perception (1920s/1930s)
- ▶ Direct perception (affordances): Gibson (1950s/60s)
- ▶ Mediated perception (categorization)

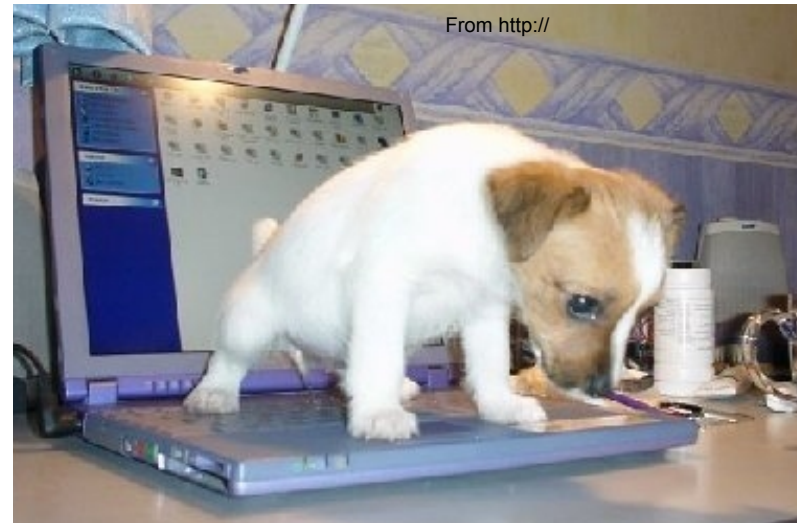
Some aspects of object function can be perceived directly (container, supporting surface, ...)



It does not seem easy to sit-upon this...



Perception, categories and function?



Some aspects of function are observer dependent

Perception, categories and function?

Objects with similar structure might have very different functions

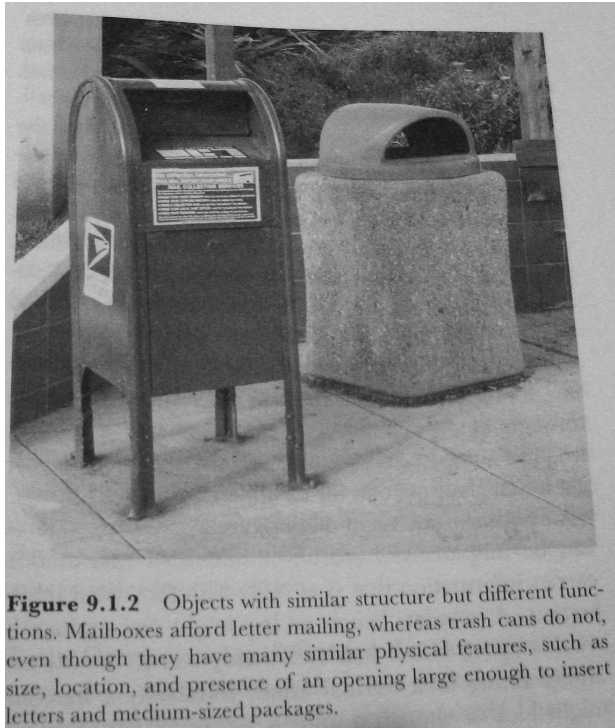


Figure 9.1.2 Objects with similar structure but different functions. Mailboxes afford letter mailing, whereas trash cans do not, even though they have many similar physical features, such as size, location, and presence of an opening large enough to insert letters and medium-sized packages.

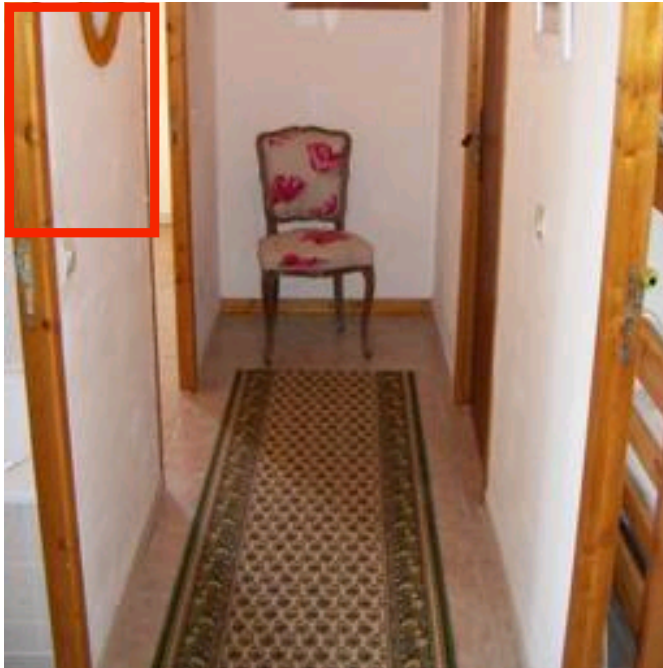


Not all functions seem to be available from direct visual information only. Here the functions are the same at some level: we can put things inside in both and somebody will come later to empty them. However, we are not expected to put inside the same kinds of things...

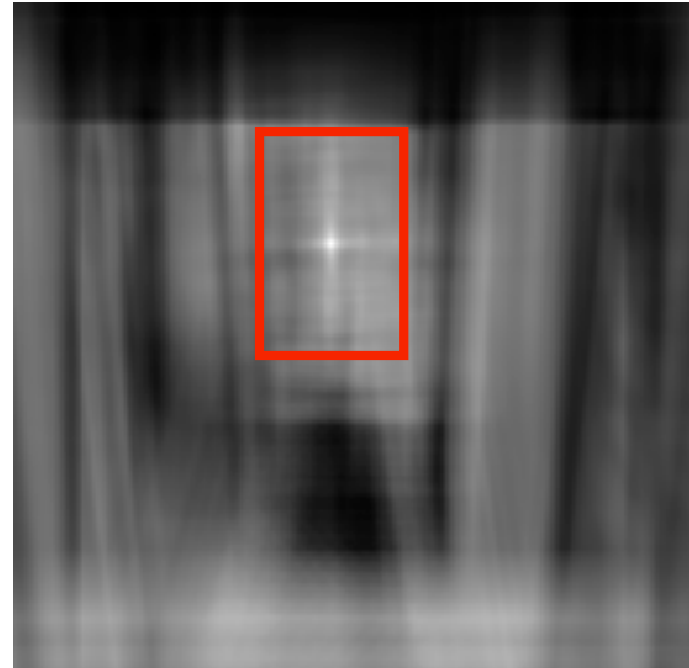
Is recognition really that hard?

Find the chair in this image

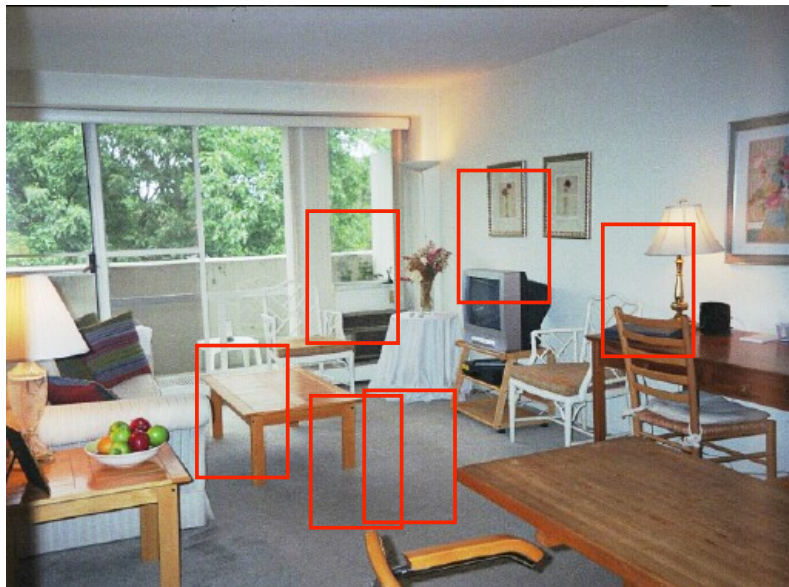
This is
a chair



Normalized correlation



Is recognition really that hard?



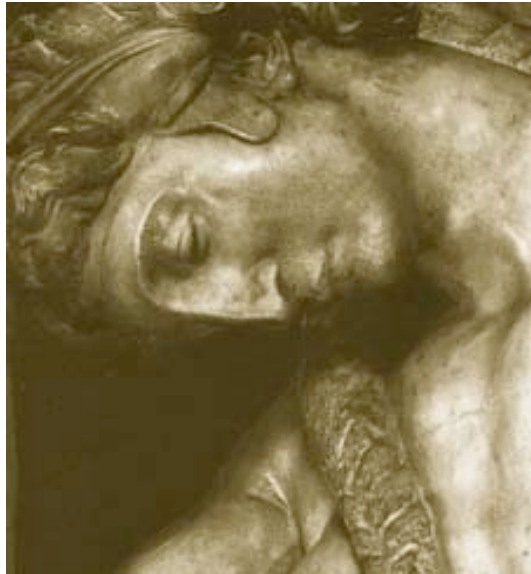
Find the chair in this image



Will template matching work?

What makes object recognition hard?

Challenges: Viewpoint



Michelangelo 1475-1564

Challenges: Illumination



slide credit: S. Ullman

Challenges: Occlusion

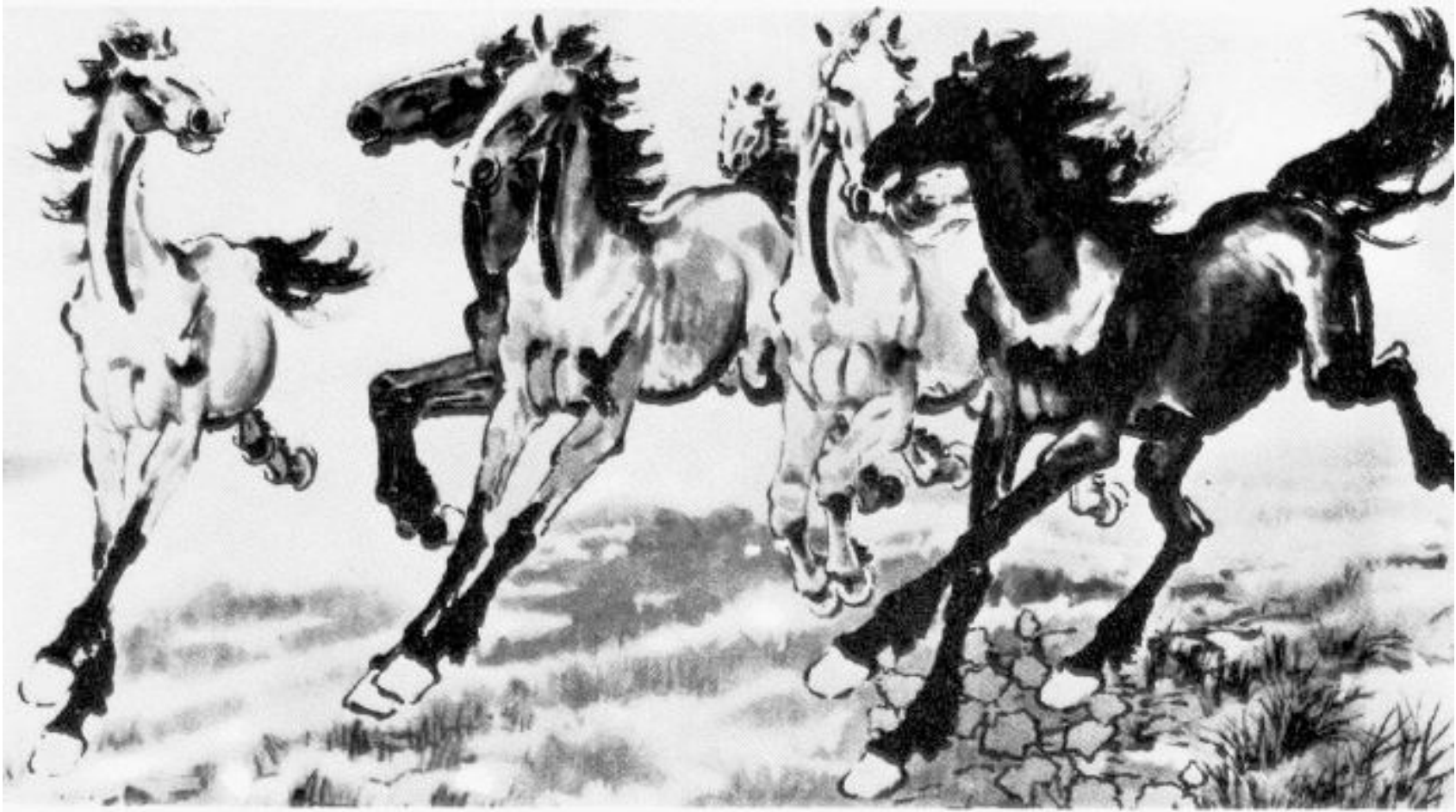


Magritte, 1957

Challenges: Scale



Challenges: Deformation



Xu, Beihong 1943

Challenges: Background clutter



Klimt, 1913

Challenges: Intra-class variation



Historical perspective

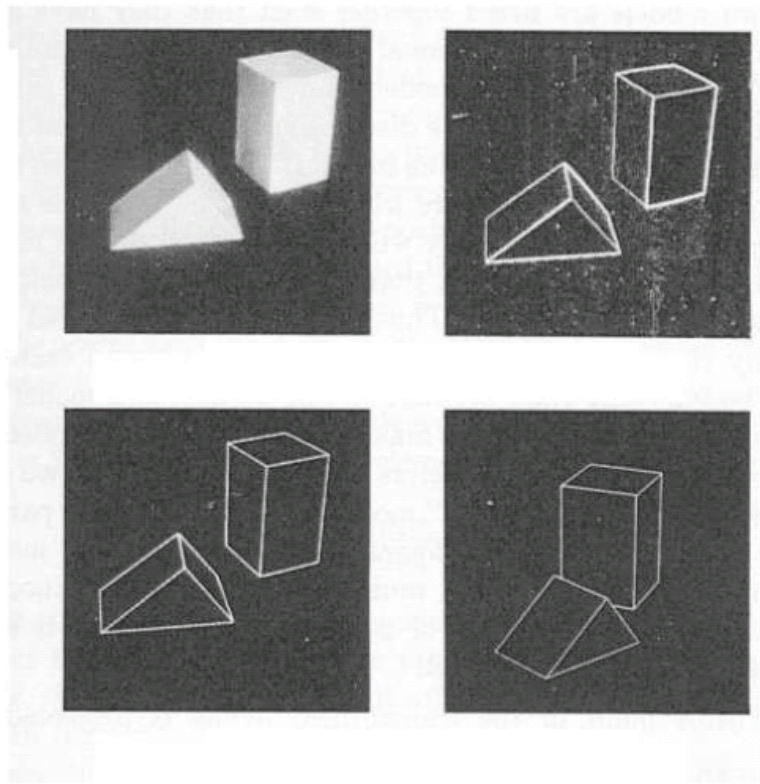
Dickinson, S. (2009) The Evolution of object categorization and the challenge of image abstraction.

Mundy, J. (2006) Object recognition in the geometric era: A retrospective.

Blocks World

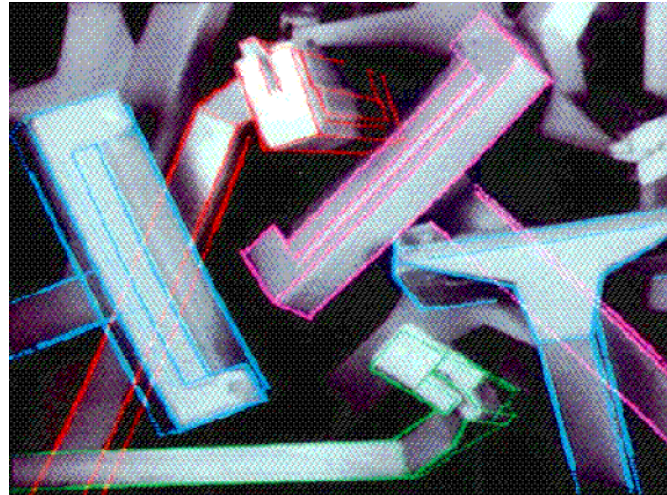
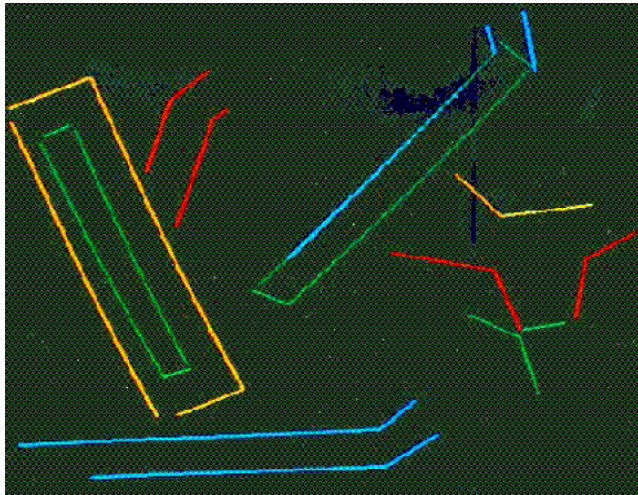
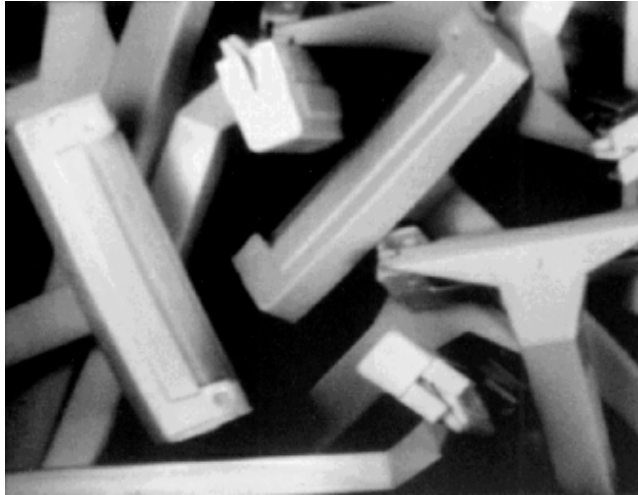


L. Roberts



1960s-70s: Constrained 3D scene models to allow object recognition from very simple image features (lambertian, trihedral objects), edge labeling (junction analysis), and object recognition.

Geometric Matching

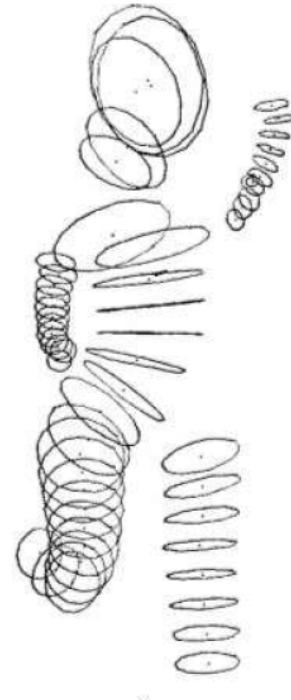


D Lowe circa 1985

Generalized Cylinders



T. Binford



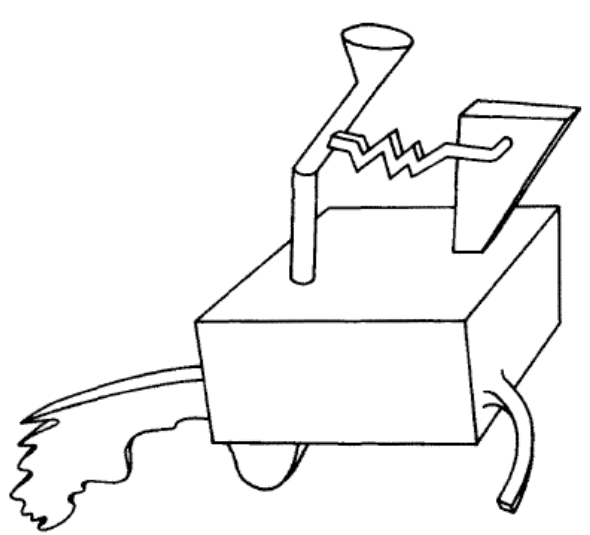
1970s-80s: Representing 3D shapes and parts in terms of “Generalized Cylinders” (cylinders modulated with a sweeping rule)

Recognition by parts



I. Biederman

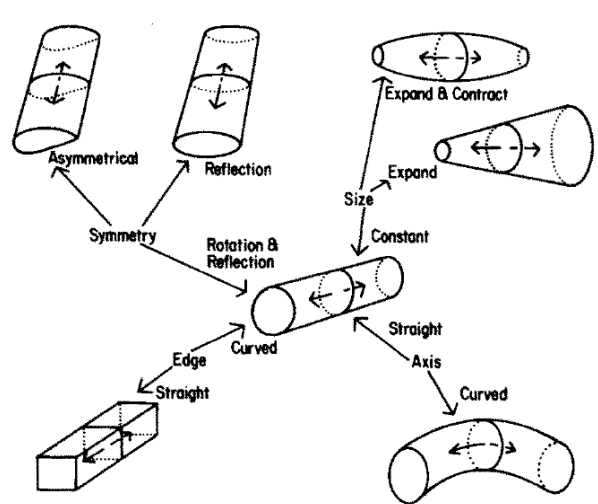
Late 1980s: Vocabulary for shape parts, estimated from images via rules of “perceptual organization” (e.g., collinearity, symmetry, parallelism, ...)



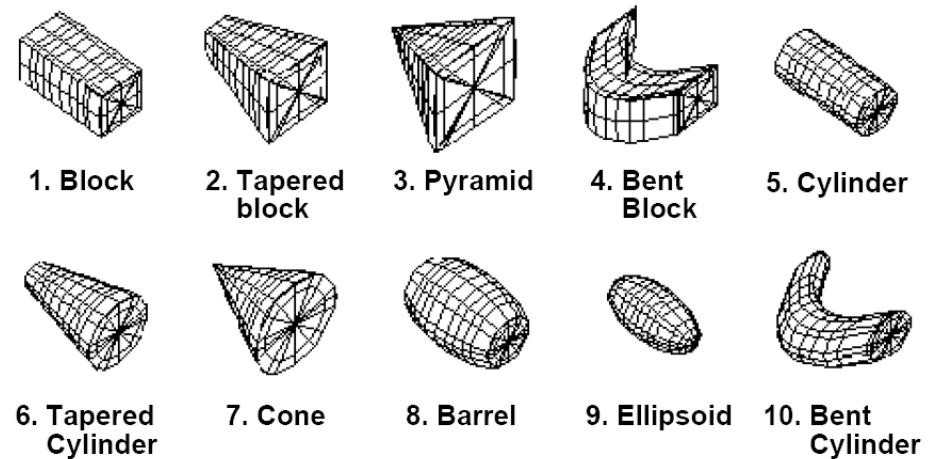
Unfamiliar fictional objects are consistently perceived in terms of parts, with similarity to familiar objects (“a hot dog cart”).

Recognition by parts

Geons: Shape primitives + deformations, with predictable edge properties under perspective.



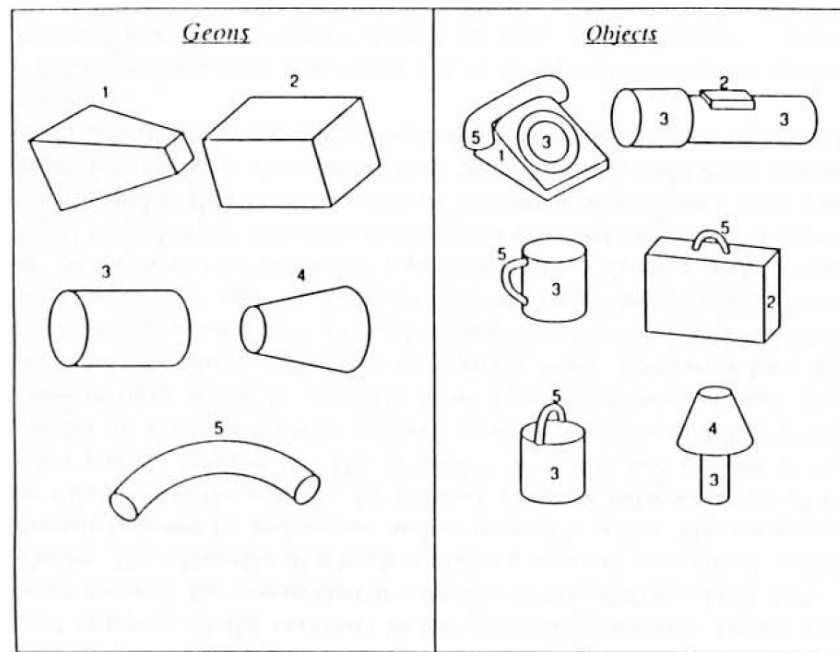
I. Biederman, 1987








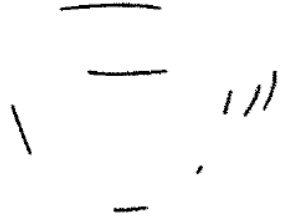
Introduced in vision by
A. Pentland, 1986.

Recognition by parts

Geons: Shape primitives + deformations, with predictable edge properties under perspective.



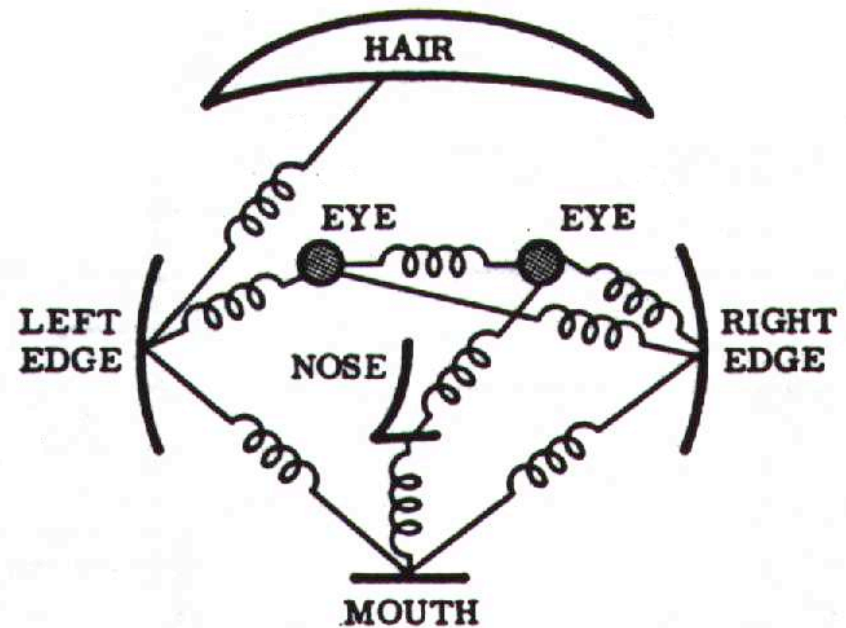
Recognition by parts

Proportion Contour Deleted	Locus of Deletion	
	At Midsegment	At Vertex
25%		
45%		
65%		
	Recoverable	Unrecoverable

Parsing based on contours, non-accidental properties & concavities

Parts + Spatial Configurations

There is more to shape than just the right part primitives, i.e., their spatial relationships.



[Fischler & Elschlager 73]

View-based recognition

Lose the 3D and just find things in 2D.

View-based models



The “Margaret Thatcher Illusion”, by Peter Thompson

View-based models

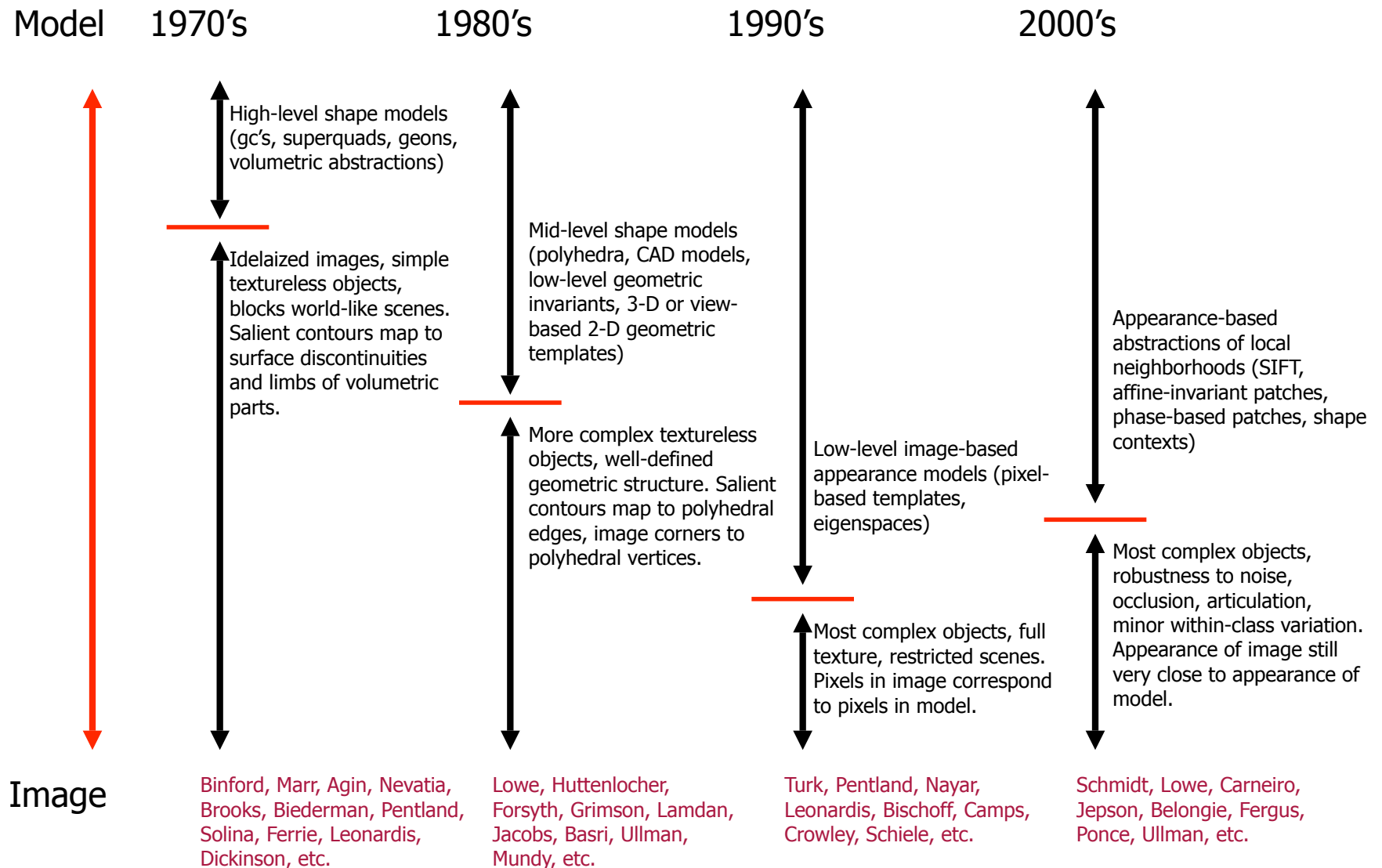


The “Margaret Thatcher Illusion”, by Peter Thompson

View-based models

Turk and Pentland: Face detection using PCA

What really happened?



Courtesy of Sven Dickinson