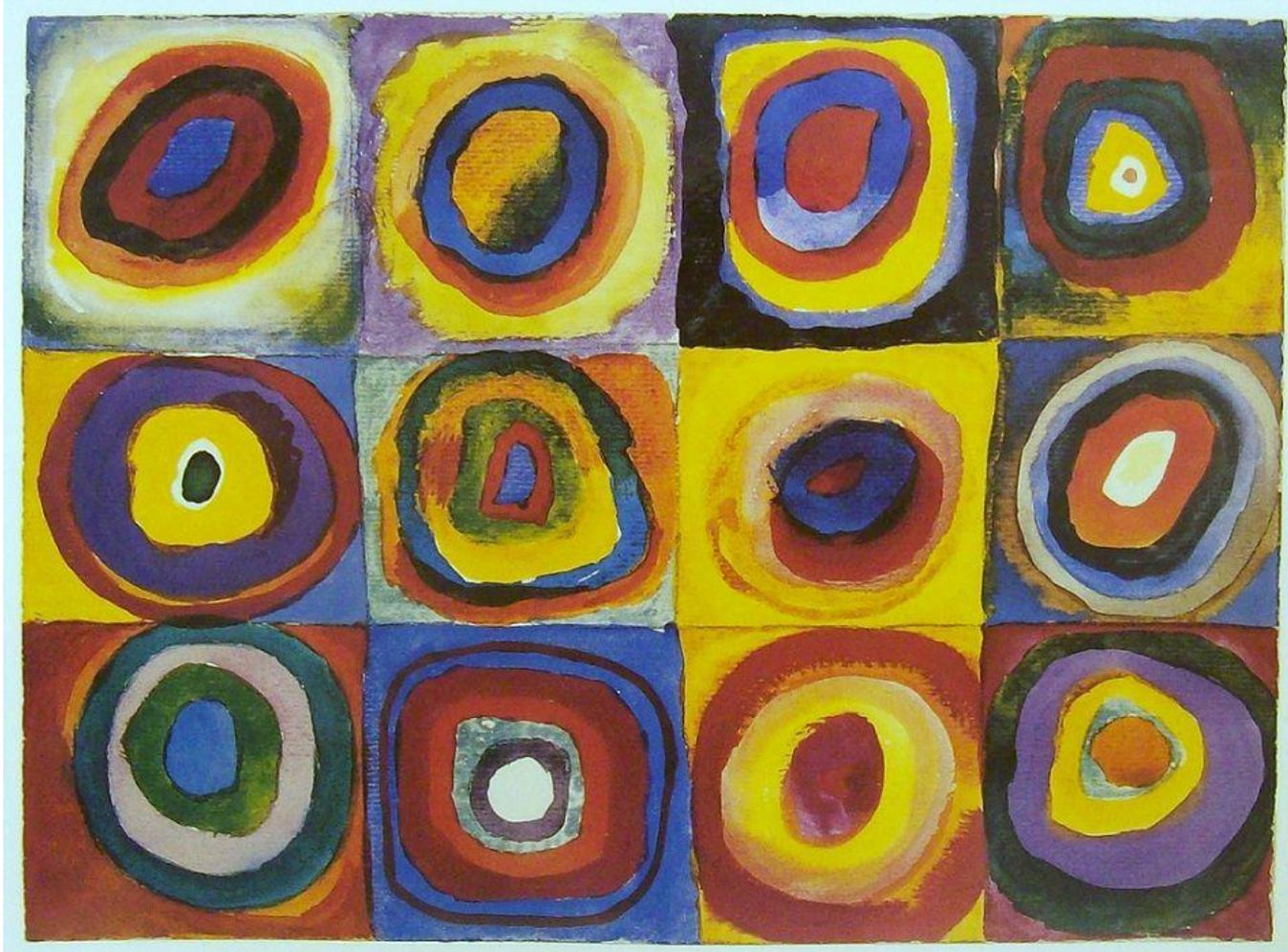


# Training, test, and validation sets



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# The General Scenario in Supervised Machine Learning

- We have a lot of labelled data
  - For example, we have 10,000 images, and we know which of the images are faces, and which aren't
- We would like to be able to predict the label for *new data*
  - For example, for a new image, we would like to decide whether it is a face or not
- General approach: we would like to come up with a function  $F(x, \alpha)$  which takes in an input  $x$  (e.g. an image) and some  $\alpha$  (e.g., a database of faces), and outputs the predicted label

# An example of (a bad) $F(x, \alpha)$

- Set  $\alpha$  to be all the faces in our database
- Now,  $F(x, \alpha)$  will be “face” if  $x$  is identical to one of the faces stores in  $\alpha$ , and “not a face” if  $x$  is different from all the faces in  $\alpha$ 
  - Will work well for some faces (the ones in  $\alpha$ ), but not for faces in general
- (Note: the performance of  $F$  on test  $S$  is the proportion faces in  $S$  that  $F$  labels correctly)

# Test Set

- To know how our  $F$  performs, will split our the face database into a **training set** and a **test set**
- We set alpha to the **training set**
- Now, we can test how  $F(x, \alpha)$  performs on the **test set**, and see that it doesn't do well
  - Because presumably, faces in the test set won't be identical to any of the faces in alpha
  - Note: on the **training set**,  $F(x, \alpha)$  will get things 100% right

# Reminder: Face Detection with Eigenfaces

- For each (centered) window  $x$  and for a set of principal components  $V$ , compute the Euclidean distance  $|VV^T x - x|$
- That is the distance between the reconstruction of  $x$  and  $x$ . The reconstruction of  $x$  is similar to  $x$  if  $x$  lies in the face subspace
- But how do we know how many eigenvectors in  $V$  to use, and how small  $|VV^T x - x|$  should be?
  - Could try different settings and see how good the performance is on the test set?

# Don't fit parameters using the Test Set

- Could try different settings and see how good the performance is on the test set
  - Bad idea! You would be picking the best settings for *one particular test set*, and then measuring the performance on the same set.
  - Biases the estimate for the performance on new data upwards

# Solution: Use a Validation Set

- Set aside a **validation set**, on which the different settings (reminder: number of eigenvectors, how small is a small distances....) can be tried
- Find the best settings on the **validation set**, and then use these settings to obtain the performance on the **test set**
- This way, we obtain the best estimate for how our algorithm will perform on new data

# Summary

- Training set
  - The set used to construct the classifier
    - The set used to construct the eigenfaces
    - The set of faces with known names to which we compare new faces for face recognition
    - ...
  - Generally, larger than the test and validation sets
- Validation set
  - The set used to tune the settings of the classifier
  - Try different settings, and keep the ones for which the performance on the validation set is the best
- Test set
  - The set the performance on which is hopefully similar to performance on new data