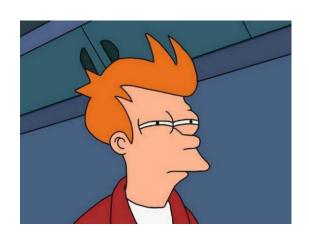
## Where are they looking?





## But why?







#### Goal

- Perform gaze-following in natural settings.
- Only a single view available.
- Without restrictive assumptions.

#### Related work

#### Saliency:

Mainly fixations of an observer free-viewing pictures.

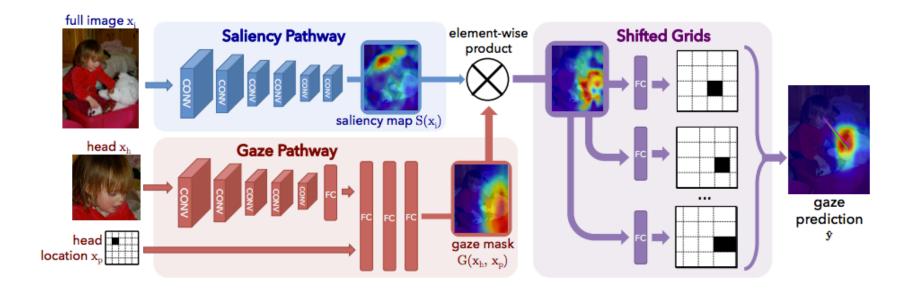
#### • Gaze:

- Only estimate gaze direction.
- Rely on face detection (so only work for people facing the camera).

### GazeFollow: the dataset







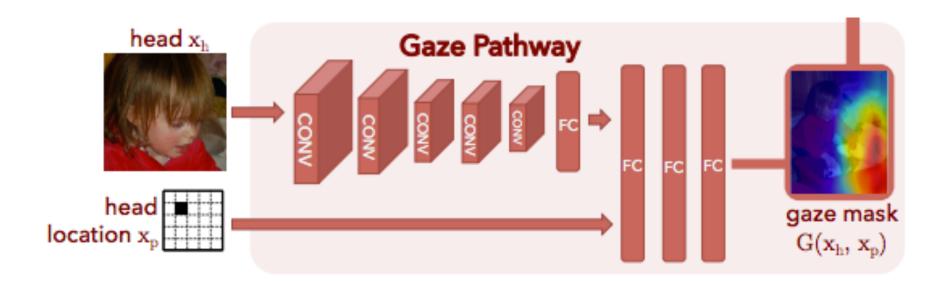
$$\hat{y} = F\left(G(x_h, x_p) \otimes S(x_i)\right)$$

### Saliency map



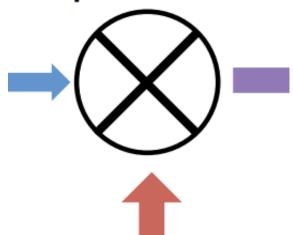
$$S(x_i)$$

#### Gaze mask



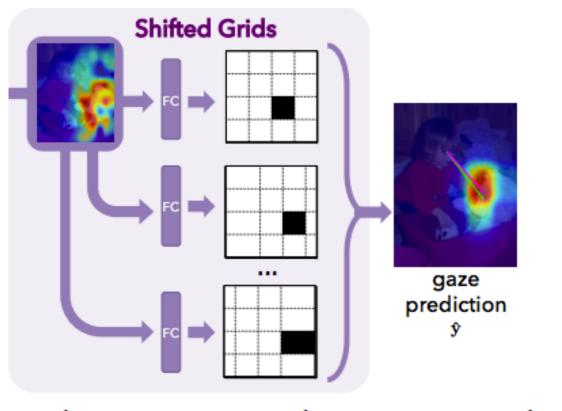
$$G(x_h, x_p)$$

## element-wise product



$$G(x_h, x_p) \otimes S(x_i)$$

### Shifted grids



$$F\left(G(x_h,x_p)\otimes S(x_i)\right)$$

## Quantitative results (pears to apples)

		Min			
Model	AUC	Dist.	Dist.	Ang.	
Our	0.878	0.190	0.113	<b>24</b> °	
SVM+shift grid	0.788	0.268	0.186	$40^{\circ}$	
SVM+one grid	0.758	0.276	0.193	$43^{\circ}$	
Judd [11]	0.711	0.337	0.250	$54^{\circ}$	
Fixed bias	0.674	0.306	0.219	$48^{\circ}$	
Center	0.633	0.313	0.230	$49^{\circ}$	
Random	0.504	0.484	0.391	$69^{\circ}$	
One human	0.924	0.096	0.040	11°	

## Ablation study (removing stuff)

			Min	
Model	AUC	Dist.	Dist.	Ang.
No image	0.821	0.221	0.142	27°
No position	0.837	0.238	0.158	$32^{\circ}$
No head	0.822	0.264	0.179	$41^{\circ}$
No eltwise	0.876	0.193	0.117	$25^{\circ}$
$5 \times 5$ grid	0.839	0.245	0.164	$36^{\circ}$
$10 \times 10$ grid	0.873	0.218	0.138	$30^{\circ}$
L2 loss	0.768	0.245	0.169	$34^{\circ}$
Our full	0.878	0.190	0.113	24°

# Qualitative Results (pew pew pew)

















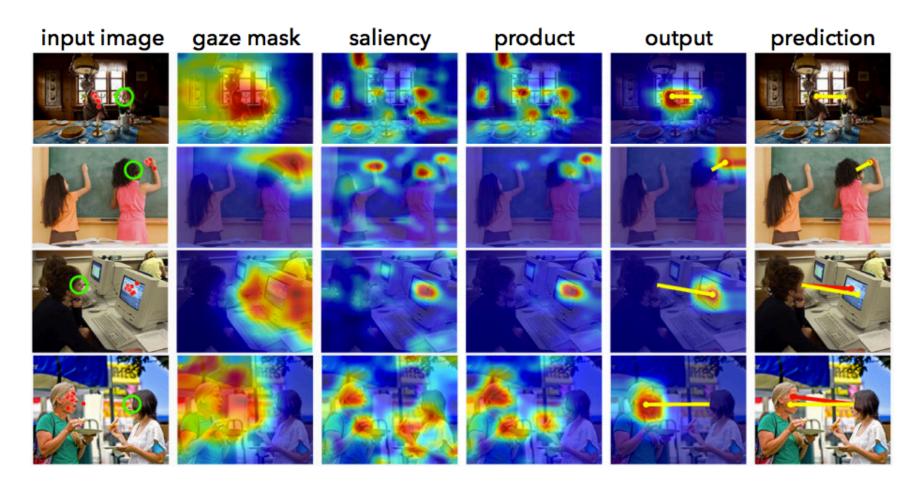








## Visualization of internal representations



### Critique

#### Negatives:

- Not using "just one image as input" (but they do in the demo).
- In the quantitative analysis, they compare with methods that solve different problems.

## Critique

#### Positives:

- Awesome new dataset.
- Nice first attempt (and baseline for future work).
- Lots of room to improve.
- Great as a future project.

Thanks!