# **TS Method – Summary**

Let  $T_k(x, y_{j-1})$  denote the first k + 1 terms of the Taylor series expanded about the discrete approximation,  $(x_{j-1}, y_{j-1})$ , and  $\hat{z}_{k,j}(x)$  be the polynomial approximation (to y(x)) associated with this truncated Taylor series,

$$\begin{aligned} \hat{z}_{k,j}(x) &= y_{j-1} + \Delta T_k(x, y_{j-1}), \\ T_k(x, y_{j-1}) &\equiv f(x_{j-1}, y_{j-1}) + \frac{\Delta}{2} f'(x_{j-1}, y_{j-1}) \cdots + \frac{\Delta^{k-1}}{k!} f^{(k-1)}(x_{j-1}, y_{j-1}), \\ \end{aligned}$$
where  $\Delta = (x - x_{j-1}).$ 

A simple, constant stepsize (fixed h) TS method is then given by:

-Set 
$$h = (b - a)/N$$
;  
-for  $j = 1, 2, \dots N$   
 $x_j = x_{j-1} + h$ ;  
 $y_j = y_{j-1} + h T_k(x_j, y_{j-1})$ ;  
-end



### **Local/Global Errors**

Note that, strictly speaking,  $z_{k,j}(x)$  is not a <u>direct</u> approximation to y(x) but to the solution of the 'local' IVP:

$$z'_j = f(x, z_j), \ z_j(x_{j-1}) = y_{j-1}.$$

Since  $y_{j-1}$  will not be equal to  $y(x_{j-1})$  in general, the solution to this local problem,  $z_j(x)$ , will not then be the same as y(x).

To understand and appreciate the implications of this observation we distinguish between the 'local' and 'global' errors. Definitions:

■ The local error associated with step j is  $z_j(x_j) - y_j$ .

• The global error at 
$$x_j$$
 is  $y(x_j) - y_j$ .



# **A Classical Approach**

A Classical (pre 1965) numerical method approximates y(x) by dividing [a, b] into equally spaced subintervals,  $x_j = a + j h$  (where h = (b - a)/N) and, proceeding in a step-by-step fashion, generates  $y_j$  after  $y_1, y_2, \dots y_{j-1}$  have been determined.

If the Taylor series method is used in this way, then the TS theorem with remainder shows that the local error on step j (for the TS method of order k) is:

$$E_j = \frac{h^{k+1} f^{(k)}(\eta_j, z_j(\eta_j))}{(k+1)!} = \frac{h^{k+1} z_j^{(k+1)}(\eta_j)}{(k+1)!}.$$

If *k* = 1 we have <u>Eulers Method</u> where  $y_j = y_{j-1} + h f(x_{j-1}, y_{j-1})$ ,
 and the associated local error satisfies,

$$LE_j = \frac{h^2}{2}y''(\eta_j).$$



#### **Error Bounds for IVP Methods**

Definition: A method is said to converge iff,

$$\lim_{h \to 0, (N \to \infty)} \left\{ \max_{j=1,2,\dots,N} |y(x_j) - y_j| \right\} \to 0.$$

**●** Theorem: (typical of classical convergence results) Let  $[x_j, y_j]_{j=0}^N$  be the approximate solution of the IVP,  $y' = f(x, y), \ y(a) = y_0$  over [a, b] generated by Euler's method with constant stepsize h = (b - a)/N. If the exact solution,  $y(x), \in C^2[a, b]$ and  $|f_y| < L, \ |y''(x)| < Y$  then the associated GE,  $e_j = y(x_j) - y_j$ ,  $x_j = a + j h$  satisfies (for all j > 0),

$$\begin{aligned} |e_j| &\leq \frac{hY}{2L} (e^{(x_j - x_0)L} - 1) + e^{(x_j - x_0)L} |e_0|, \\ &\leq \frac{hY}{2L} (e^{(b-a)L} - 1) + e^{(b-a)L} |e_0|. \end{aligned}$$



## **Observations re Convergence**

- 1.  $e_0$  will usually be equal to zero.
- 2. This bound is generally pessimistic as it is exponential in (b a) where linear error growth is often observed on practical or realistic problems.
- 3. In the general case one can show that when local error is  $O(h^{p+1})$  the global error is  $O(h^p)$ .



### **Proof of Conv Th (outline)**

Eulers Method satisfies,

$$y_j = y_{j-1} + hf(x_{j-1}, y_{j-1}).$$

A Taylor series expansion of y(x) about  $x = x_{j-1}$  implies

$$y(x_j) = y(x_{j-1}) + hf(x_{j-1}, y(x_{j-1})) + \frac{h^2}{2}y''(\eta_j).$$

Subtracting the first equation from the second we obtain,

$$y(x_{j}) - y_{j} = y(x_{j-1}) - y_{j-1} + h[f(x_{j-1}, y(x_{j-1})) - f(x_{j-1}, y_{j-1})] + \frac{h^{2}}{2}y''(\eta_{j}).$$

If  $Y = \max_{x \in [a,b]} |y''(x)|$  and  $|f_y| \le L$ , then, from the definition of  $e_j$  and the observation that f(x, y) satisfies a Lipschitz condition with respect to y, we have ...



# **Proof (cont)**

$$|e_{j}| \leq |e_{j-1}| + hL|y(x_{j-1}) - y_{j-1}| + |\frac{h^{2}}{2}y''(\eta_{j})|,$$
  
$$\leq |e_{j-1}| + hL|e_{j-1}| + \frac{h^{2}}{2}Y,$$
  
$$= |e_{j-1}|(1 + hL) + \frac{h^{2}}{2}Y.$$

This is a linear recurrence relation (or inequality) which after some work (straightforward) can be shown to imply our desired result,

$$|e_j| \le \frac{hY}{2L}(e^{(b-a)L} - 1) + e^{(b-a)L}|e_0|.$$

Note that this is only an upper bound on the global error and it may not be sharp.



### An Example

Consider the following equation,

$$y' = y, y(0) = 1, \text{ on } [0,1].$$

Now since  $\frac{\partial f}{\partial y} = 1$ , L = 1 and since  $y(x) = e^x$ , we have Y = e and  $e_0 = 0$ . Applying our error bound with h = 1/N and  $y_N \approx y(1) = e$  we obtain,

$$|GE_N| = |y_N - e| \le \frac{he}{2}(e - 1) < 2.4h.$$

But for h = .1 we observe that  $y_{10} = 2.5937$ .. with an associated true error of .1246.. ( $\equiv e - y_{10}$ ). This error bound is .24. This is an overestimate by a factor of 2.

Exercise: Compare the bound to the true error for h = .01, h = .001.



# **Limitations of Classical Approach**

- Analysis is valid only in the limit as  $h \rightarrow 0$ .
- Bounds are usually very pessimistic (can overestimate the error by several orders of magnitude).
- Analysis does not consider the affect of f.p. arithmetic.



### **Affect of FP Arith**

Assume  $fl(f(x_{j-1}, y_{j-1})) = f(x_{j-1}, y_{j-1}) + \epsilon_j$  and

$$y_{j} = y_{j-1} \oplus h \otimes fl(f(x_{j-1}, y_{j-1})),$$
  
=  $y_{j-1} + hf(x_{j-1}, y_{j-1}) + h\epsilon_{j} + \rho_{j},$ 

where  $|\epsilon_j|, |\rho_j| < \mu$ .

Then, proceeding as before we obtain,

$$|e_j| < |e_{j-1}|(1+hL) + \frac{h^2}{2}\bar{M},$$

where  $\overline{M} = Y + \mu/h + \mu/(h^2)$ .



### **Affect of FP Arith (cont)**

Therefore the revised error bound becomes:

$$\begin{aligned} |e_j| &\leq e^{(b-a)L} |e_0| + \frac{h\bar{M}}{2L} (e^{(b-a)L} - 1), \\ &= e^{(b-a)L} |e_0| + (e^{(b-a)L} - 1) (\frac{hY}{2L} + \frac{\mu}{2L} + \frac{\mu}{2hL}). \end{aligned}$$

So, as  $h \to 0$ , the term  $\frac{\mu}{2hL}$  will become unbounded (unless the precision changes) and we will not observe convergence.

