CSC2302H

Assignment 3

March 4, 2014 University of Toronto D

Due: April 1, 2014

From 'Solving Ordinary Differential Equations II', E. Hairer and G. Wanner, Springer 1991, p. 163.

You are to investigate, by numerical experiments using a method suitable for stiff systems, the "circular nerve model" defined by the system of ODEs developed below. You are to use a stiff solver such as ode15s (from matlab) or the Fortran code RADAU (available from a link on the course webpage). In particular you are to show that this system loses its limit cycle when the diffusion coefficient D becomes either too large or too small. This system of ODEs models a combination of a threshold-nerve-impulse mechanism, a cusp catastrophe

$$\epsilon y' = -(y^3 + ay + b),$$

(with a "smooth return" – see Zeeman, 1972 reference of HW), and a Van der Pol oscillator to keep the solution away from the origin. The unknown functions y, a and b are each functions of time and space, where y(t, x) is the value of the nerve impulse at time $t \ge 0$ at location x associated with a one-dimensional nerve $(0 \le x \le 1)$.

$$\begin{array}{lll} \frac{\partial y}{\partial t} &=& -\frac{1}{\epsilon}(y^3 + ay + b) + \sigma \frac{\partial^2 y}{\partial x^2} \\ \frac{\partial a}{\partial t} &=& b + 0.07v + \sigma \frac{\partial^2 a}{\partial x^2} \\ \frac{\partial b}{\partial t} &=& (1 - a^2)b - a - 0.4y + .035v + \sigma \frac{\partial^2 b}{\partial x^2} \end{array}$$

where

$$v = \frac{u}{u+0.1}$$
, $u = (y-0.7)(y-1.3)$.

We consider discretizing the space dimension using a uniform mesh, $(0 = x_0 < x_1 \cdots x_N = 1)$, with $x_i = i * \Delta x$. When the partial derivatives with respect to x are replaced by finite differences (for example, $\frac{\partial^2 y}{\partial x^2}|_{x_i}$ is replaced by $\frac{y_{i+1}-2y_i+y_{i-1}}{(\Delta x)^2}$) this model becomes a system of ODEs in time (with $y_i(t)$ being an approximation to the one dimensional function $y(t, x_i)$). We let the "nerve" be closed like a torus so that the nerve impulse goes around without stopping. (That is, for any $t \geq 0$ we assume y(t, 1) = y(t, 0), a(t, 1) = a(t, 0)

and b(t, 1) = b(t, 0).) The Jacobian of the resulting system is then sparse, although not banded. Stiffness in this problem has two sources: firstly the parameter ϵ becoming small, secondly the diffusion term *D* becoming large for small discretization intervals Δx .

For example with $\epsilon=10^{-4}$, $\sigma=1/144$, $0\leq x\leq 1$, $\Delta x=1/32$ and $N=32\,$, we obtain

$$\begin{aligned} y'_i &= -10^4 (y_i^3 + a_i y_i + b_i) + D(y_{i-1} - 2y_i + y_{i+1}) \\ a'_i &= b_i + 0.07 v_i + D(a_{i-1} - 2a_i + a_{i+1}) \\ b'_i &= (1 - a_i^2) b_i - a_i - 0.4 y_i + 0.035 v_i + D(b_{i-1} - 2b_i + b_{i+1}) \end{aligned}$$

for $i = 1, \dots, N$, where

$$v_i = \frac{u_i}{u_i + 0.1}, \ u_i = (y_i - 0.7)(y_i - 1.3), \ D = N^2 \sigma = \frac{N^2}{144},$$

and the required "boundary conditions" (to define the finite differences near the endpoint values of x) are

$$y_0 = y_N, \ a_0 = a_N, \ b_0 = b_N,$$

 $y_{N+1} = y_1, \ a_{N+1} = a_1, \ b_{N+1} = b_1.$

This defines a system of ODEs of dimension 3N = 96. The initial values are

$$y_i(0) = 0, \ a_i(0) = -2\cos(\frac{2i\pi}{N}), \ b_i(0) = 2\sin(\frac{2i\pi}{N}), \ \text{ for } i = 1 \cdots N.$$

- 1. For this particular discretization and choice of parameters you are to solve this problem using a Stiff solver with and without supplying analytic derivatives for the Jacobian matrix. In your write-up discuss whether, on this problem, the extra effort required to supply the analytic Jacobian is reflected in reduced costs, improved accuracy, or improved robustness.
- 2. By experimenting with different values of σ (and possibly N) show that this system loses its limit cycle when D becomes too large or too small). (Note that the system of ODEs given above for N = 32, will change if N is increased.)