#### **Num. Integration - Quadrature**

#### **Basic Problem – Approximation of integrals**

We will investigate methods for computing an approximation to the definite integral:

$$I(f) \equiv \int_{a}^{b} f(x) dx.$$

The obvious generic approach is to approximate the integrand f(x) on the interval [a, b] by a function that can be integrated exactly (such as a polynomial) and then take the integral of the approximating function to be an approximation to I(f).



#### **Interpolatory Rules**

When an interpolating polynomial,  $P_n(x)$ , is used the corresponding approximation  $I(P_n(x))$  is called an <u>interpolatory rule</u>, Consider writing  $P_n(x)$  in Lagrange form,

$$P_n(x) = \sum_{i=0}^n f(x_i)l_i(x),$$

where  $l_i(x)$  is defined by

$$l_i(x) = \prod_{j=0, j\neq i}^n \left(\frac{x-x_j}{x_i-x_j}\right).$$

We then have

$$\int_{a}^{b} P_{n}(x)dx = \int_{a}^{b} \sum_{i=0}^{n} f(x_{i})l_{i}(x)dx$$
$$= \sum_{i=0}^{n} f(x_{i}) \int_{a}^{b} l_{i}(x)dx \equiv \sum_{i=0}^{n} \omega_{i}f(x_{i}).$$



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#### **Observations**

- The 'weights' (the  $\omega_i$ 's) depend only on the interval (the value of a and b) and on the  $x_i$ 's. In particular these weights are independent of the integrand.
- The interpolatory rules then approximate I(f) by a linear combination of sampled integrand evaluations.
- If  $a = x_0 < x_1 < \cdots x_n = b$  are equally spaced the corresponding interpolatory rule is called a <u>Newton-Coates</u> quadrature rule.



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### **Errors in Interpolatory Rules**

The error associated with an interpolatory rule is  $E(f) = I(f) - I(P_n)$  and satisfies,

$$\begin{split} E(f) &= \int_{a}^{b} f(x) dx - \int_{a}^{b} P_{n}(x) dx = \int_{a}^{b} [f(x) - P_{n}(x)] dx, \\ &= \int_{a}^{b} E_{n}(x) dx, \end{split}$$

where  $E_n(x)$  is the error in polynomial interpolation and satisfies,

$$E_n(x) = (x - x_0)(x - x_1) \cdots (x - x_n) f[x_0 x_1 \cdots x_n x],$$
  
=  $\Pi_n(x) f[x_0 x_1 \cdots x_n x].$ 

In some special cases we can simplify this expression to obtain estimates and/or more insight into the behaviour of the error.



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#### **Error Analysis - Special Cases**

First special case – If  $\Pi_n(x)$  is of one sign (on [a, b]) then the Mean Value Theorem for Integrals implies,

$$E(f) = \int_{a}^{b} f[x_{0}x_{1}\cdots x_{n}x]\Pi_{n}(x)dx,$$
$$= f[x_{0}x_{1}\cdots x_{n}\xi]\int_{a}^{b}\Pi_{n}(x)dx,$$

for some  $\xi \in [a, b]$ . Also since  $f[x_0x_1 \cdots x_n\xi] = \frac{f^{n+1}(\eta)}{(n+1)!}$  for some  $\eta \in (a, b)$ , we have shown that if  $\Pi_n(x)$  is of one sign then,

$$E(f) = \frac{1}{(n+1)!} f^{n+1}(\eta) \int_{a}^{b} \prod_{n} (x) dx$$



#### **Error Analysis - Special Cases**

Second special case – If  $\int_a^b \Pi_n(x) dx = 0$  we have, for arbitrary  $x_{n+1}$ ,  $f[x_0x_1\cdots x_nx] = f[x_0x_1\cdots x_nx_{n+1}] + f[x_0x_1\cdots x_{n+1}x](x-x_{n+1}),$ and therefore,

$$E(F) = \int_{a}^{b} f[x_{0}x_{1}\cdots x_{n}x]\Pi_{n}(x)dx,$$
  
=  $\int_{a}^{b} f[x_{0}x_{1}\cdots x_{n+1}]\Pi_{n}(x)dx + \int_{a}^{b} f[x_{0}x_{1}\cdots x_{n+1}x]\Pi_{n+1}(x)dx,$   
=  $\int_{a}^{b} f[x_{0}x_{1}\cdots x_{n+1}x]\Pi_{n+1}(x)dx.$ 

As a result, if  $\int_a^b \Pi_n(x) dx = 0$  and we can choose  $x_{n+1}$  so that  $\Pi_{n+1}(x)$  is of one sign, then using a similar argument as for the first special case, it follows that, if  $\int_a^b \Pi_n(x) dx = 0$  and  $\Pi_{n+1}(x)$  is of one sign,

$$E(f) = \frac{1}{(n+2)!} f^{n+2}(\eta) \int_a^b \Pi_{n+1}(x) dx$$



#### **Examples of Interp. Rules**

Trapezoidal Rule (an example of the first special case):

$$T(f) \equiv \int_{a}^{b} P_{1}(x) dx,$$

where  $x_0 = a$  and  $x_1 = b$ . We then have,

$$P_1(x) = l_0(x)f_0 + l_1(x)f_1 = \frac{x - x_1}{x_0 - x_1}f_0 + \frac{x - x_0}{x_1 - x_0}f_1.$$

Therefore we have

$$T(f) = \int_{a}^{b} \frac{x-b}{a-b} dx f(a) + \int_{a}^{b} \frac{x-a}{b-a} dx f(b),$$
  
=  $\left(\frac{b-a}{2}\right) f(a) + \left(\frac{b-a}{2}\right) f(b) = \left(\frac{b-a}{2}\right) [f(a) + f(b)].$ 



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## **Examples of Interp. Rules**

We also have that  $\Pi_1(x) = (x - a)(x - b)$  is negative for  $x \in [a, b]$  and  $\int_a^b \Pi_1(x) dx = -\frac{(b-a)^3}{6}$ . We therefore have satisfied the conditions of the first special case and this implies,

$$T(f) = (\frac{b-a}{2})[f(a) + f(b)], \quad E^T(f) = \frac{-f''(\eta)}{12}(b-a)^3.$$

Simpsons Rule (an example of the second special case):

$$S(f) \equiv \int_{a}^{b} P_{2}(x) dx,$$

with  $x_0 = a, x_1 = \frac{a+b}{2}, x_2 = b$ .



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#### **Simpsons Rule**

Exercise: Using

$$P_2(x) = l_0(x)f(a) + l_1(x)f\left(\frac{a+b}{2}\right) + l_2(x)f(b),$$

where

$$l_0(x) = \frac{(x - \frac{a+b}{2})(x-b)}{(a - \frac{a+b}{2})(a-b)}, \quad l_1(x) = \frac{(x-a)(x-b)}{(\frac{a+b}{2}-a)(\frac{a+b}{2}-b)},$$
$$l_2(x) = \frac{(x-a)(x - \frac{a+b}{2})}{(b-a)(b - \frac{a+b}{2})}.$$

Simplify and verify (after some tedious algebra) that,

$$S(f) = \left[\int_{a}^{b} l_{0}(x)dx\right]f(a) + \left[\int_{a}^{b} l_{1}(x)dx\right]f(\frac{a+b}{2}) + \left[\int_{a}^{b} l_{2}(x)dx\right]f(b),$$
  

$$\vdots \qquad \vdots$$
  

$$= \left(\frac{b-a}{6}\right)\left[f(a) + 4f(\frac{a+b}{2}) + f(b)\right].$$



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#### **Simpsons Rule (cont)**

Note that for  $x \in [a, b]$ ,  $\Pi_2(x)$  is antisymetric about  $\frac{a+b}{2}$  and this implies  $\int_a^b \Pi_2(x) dx = 0$ . Furthermore by choosing  $x_3 = \frac{a+b}{2}$  we have

$$\Pi_3(x) = (x-a)(x - \frac{a+b}{2})^2(x-b),$$

is of one sign and this implies,

$$E^{S}(f) = I(f) - S(f) = \frac{1}{4!}f^{4}(\eta)\int_{a}^{b}\Pi_{3}(x)dx.$$

But  $\int_{a}^{b} \Pi_{3}(x) dx = -\frac{4}{15} (\frac{b-a}{2})^{5}$  so we have,

$$S(f) = \left(\frac{b-a}{6}\right) \left[f(a) + 4f(\frac{a+b}{2}) + f(b)\right] \quad E^S(f) = \frac{-f^4(\eta)}{90} \left(\frac{b-a}{2}\right)^5$$



#### **Gaussian Quadrature**

Recall that the error for interp. rules satisfies,  $E(f) = \int_a^b f[x_0x_1\cdots x_nx]\Pi_n(x)dx$ , and if  $\int_a^b \Pi_n(x)dx = 0$  we have,  $E(f) = \int_a^b f[x_0x_1\cdots x_{n+1}x]\Pi_{n+1}(x)dx$ ,

for any  $x_{n+1}$ . Now if  $\int_a^b \Pi_{n+1}(x) = 0$  as well we can show similarly,

$$E(f) = \int_{a}^{b} f[x_0, x_1, \cdots x_{n+2}, x] \Pi_{n+2}(x) dx.$$

In general if we let  $q_0(x) \equiv 1$  and  $q_i(x) \equiv (x - x_{n+1}) \cdots (x - x_{n+i})$  for  $i = 1, 2, \cdots (m-1)$ . We can then show that if  $\int_a^b \Pi_n(x)q_i(x)dx = 0$ , for  $i = 0, 1, \cdots (m-1)$  then,

$$E(f) = \int_a^b f[x_0 x_1 \cdots x_{n+m} x] \Pi_{n+m}(x) dx.$$



#### **Gaussian Quadrature (cont)**

The key idea of GQ is to choose the interpolation points,  $(x_0, x_1, \dots x_n)$ such that  $\int_a^b \prod_n (x)q(x)dx = 0$  for all polynomials, q(x), of degree at most n. In particular for the choice  $q(x) = q_i(x)$  for  $i = 0, 1, \dots n$  we have  $\int_a^b \prod_n (x)q_i(x)dx = 0$  and,

$$E(f) = \int_{a}^{b} f[x_0 x_1 \cdots x_{2n+1} x] \Pi_{2n+1}(x) dx.$$

To ensure that  $\Pi_{2n+1}(x)$  is of one sign for  $x \in [a \ b]$  we can choose  $x_{n+i+1} = x_i$  for  $i = 0, 1, \dots n$  and we then have  $\Pi_{2n+1}(x) = \Pi_n^2(x)$ ,

$$E(f) = f[x_0 x_1 \cdots x_{2n+1} \xi] \int_a^b \Pi_n^2(x) dx = \frac{1}{(2n+2)!} f^{2n+2}(\eta) \int_a^b \Pi_n^2(x) dx.$$

Note that these rules will be exact for all polynomials of degree at most 2n + 1 since  $f^{2n+2}(\eta) \equiv 0$ .

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# **GQ – Orthoganal Polynomials**

How do we choose the  $x_i$ 's to ensure that  $\int_a^b \Pi_n(x)q(x)dx = 0$  for all polynomials, q(x) of degree at most n? This question leads to the study of orthogonal polynomials.

- Definition: The set of polynomials  $\{r_0(x), r_1(x), \dots r_k(x)\}$  is orthogonal on [-1, 1] iff the following two conditions are satisfied:
  - $\int_{-1}^{1} r_i(x) r_j(x) dx = 0$ , for  $i \neq j$ ,
  - The degree of  $r_i(x)$  is *i* for  $i = 0, 1, \dots k$ .



## **Properties**

- Properties of orthogonal polynomials:
  - Any polynomial  $q_s(x)$  of degree  $s \le k$  can be expressed as.

$$q_s(x) = \sum_{j=0}^s c_j r_j(x).$$

- $r_k(x)$  is orthogonal to <u>all</u> polynomials of degree less than k. That is,  $\int_{-1}^{1} r_k(x)q_s(x)dx = 0$  for s < k. (This follows from the previous property.)
- $r_k(x)$  has k simple zeros all in the interval [-1, 1].



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## **Proof (last property)**

For  $r_k(x)$ , let  $\{\mu_1, \mu_2, \dots, \mu_m\}$  be the set of points in [-1, 1] where  $r_k(x)$  changes sign. It is clear that each  $\mu_j$  is a zero of  $r_k(x)$  and all simple zeros of  $r_k(x)$  in [-1, 1] must be in this set. We then have  $m \leq k$  as the maximum number of zeros of a polynomial of degree k is k. Assume m < k. We then have, m

$$\hat{q}_m(x) \equiv \prod_{i=1}^m (x - \mu_i),$$

is a polynomial of degree m < k that changes sign at each  $\mu_i$  and,

$$\int_{-1}^{1} \hat{q}_m(x) r_k(x) dx = 0.$$

But  $\hat{q}_m(x)$  and  $r_k(x)$  have the same sign for all x in [-1,1] (they change sign at the same locations). This implies a contradiction (the integrand is of one sign but the integral is zero)– our assumption must be false. We must therefore have m = k.



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#### **3-Term Recurrence**

The  $r_k(x)$  also satisfy,

$$r_{s+1}(x) = a_s(x - b_s)r_s(x) - c_s r_{s-1}(x),$$

for  $s = 1, 2, \dots k$ , where the  $a_s$  are normalization constants,  $r_{-1}(x) = 0$ , and if  $t_s = \int_{-1}^{1} r_s^2(x) dx$  then,

$$b_s = \frac{1}{t_s} \int_{-1}^{1} x r_s^2(x) dx, \quad c_s = \frac{a_s t_s}{a_{s-1} t_{s-1}}$$

For example, we obtain the classical Legendre polynomials if we normalise so  $r_s(-1) = 1$ . This leads to,

$$a_s = \frac{2s+1}{s+1}, \ b_s = 0, \ c_s = \frac{s}{s+1}.$$

