## Affect of FP Arith

Assume $f l\left(f\left(x_{j-1}, y_{j-1}\right)\right)=f\left(x_{j-1}, y_{j-1}\right)+\epsilon_{j}$ and

$$
\begin{aligned}
y_{j} & =y_{j-1} \oplus h \otimes f l\left(f\left(x_{j-1}, y_{j-1}\right)\right), \\
& =y_{j-1}+h f\left(x_{j-1}, y_{j-1}\right)+h \epsilon_{j}+\rho_{j},
\end{aligned}
$$

where $\left|\epsilon_{j}\right|,\left|\rho_{j}\right|<\mu$.
Then, proceeding as before we obtain,

$$
\left|e_{j}\right|<\left|e_{j-1}\right|(1+h L)+\frac{h^{2}}{2} \bar{M},
$$

where $\bar{M}=Y+\mu / h+\mu /\left(h^{2}\right)$.

## Affect of FP Arith (cont)

Therefore the revised error bound becomes:

$$
\begin{aligned}
\left|e_{j}\right| & \leq e^{(b-a) L}\left|e_{0}\right|+\frac{h \bar{M}}{2 L}\left(e^{(b-a) L}-1\right) \\
& =e^{(b-a) L}\left|e_{0}\right|+\left(e^{(b-a) L}-1\right)\left(\frac{h Y}{2 L}+\frac{\mu}{2 L}+\frac{\mu}{2 h L}\right)
\end{aligned}
$$

So, as $h \rightarrow 0$, the term $\frac{\mu}{2 h L}$ will become unbounded (unless the precision changes) and we will not observe convergence.

## Difficulties with fixed-h Euler

- The low order results in requiring a small stepsize, which leads to a large number of derivative evaluations and excessive amount of computer time.
- The use of a constant stepsize can be inappropriate if the solution behaves differently on parts of the interval of interest. For example in integrating satellite orbits 'close approaches' typically requires a smaller stepsize to ensure accuracy.


## Runge-Kutta Methods

We will consider a general class of one-step formulas of the form:

$$
\begin{equation*}
y_{j}=y_{j-1}+h \Phi\left(x_{j-1}, y_{j-1}\right) \tag{1}
\end{equation*}
$$

where $\Phi$ satisfies a Lipschitz condition with respect to $y$. That is,

$$
|\Phi(x, u)-\Phi(x, v)| \leq \mathcal{L}|u-v|
$$

We will consider a variety of choices for $\Phi$ and will observe that, in each case considered, $\Phi$ will be Lipschitz if $f$ is.
Two examples of such formulas are:
Euler: $\Phi \equiv f$.
Taylor Series: $\Phi \equiv T_{k}(x, y)$.

## Some Notation/Definitions

Definition: A formula (1) is of order $p$ if for all sufficiently differentiable functions $y(x)$ we have,

$$
\begin{equation*}
y\left(x_{j}\right)-y\left(x_{j-1}\right)-h \Phi\left(x_{j-1}, y\left(x_{j-1}\right)\right)=O\left(h^{p+1}\right) . \tag{2}
\end{equation*}
$$

Note that:

1. The LHS of (2) is defined to be the Local Truncatiom Error (LTE) of the formula.
2. Order $p$ implies that both the LE and the LTE are $O\left(h^{p+1}\right)$. (This follows by substituting $z_{j}(x)$ for $y(x)$ in the definition.)

## Main Result:

Theorem: A $p^{\text {th }}$ order formula applied to an IVP with constant stepsize $h$ satisfies,

$$
\left|y\left(x_{j}\right)-y_{j}\right| \leq\left|e_{0}\right| e^{\mathcal{L}(b-a)}+\frac{C h^{p}}{\mathcal{L}}\left(e^{\mathcal{L}(b-a)}-1\right) .
$$

## Runge-Kutta Methods (cont)

We wish to consider formulas $\Phi$ that are less 'expensive' than higher order Taylor Series and yet are higher order than Euler's formula. Consider a formula $\Phi$ based on $\underline{2}$ derivative evaluations. That is,

$$
\Phi\left(x_{j-1}, y_{j-1}\right)=\omega_{1} k_{1}+\omega_{2} k_{2}
$$

where,

$$
\begin{aligned}
k_{1} & =f\left(x_{j-1}, y_{j-1}\right) \\
k_{2} & =f\left(x_{j-1}+\alpha h, y_{j-1}+h \beta k_{1}\right)
\end{aligned}
$$

We determine the parameters $\omega_{1}, \omega_{2}, \alpha, \beta$ to obtain as high an order formula as possible.

## RK Methods (cont)

From the definition of order we have order $p$ if

$$
\begin{equation*}
y\left(x_{j}\right)=y\left(x_{j-1}\right)+h\left(\omega_{1} k_{1}+\omega_{2} k_{2}\right)+O\left(h^{p+1}\right) \tag{3}
\end{equation*}
$$

for all suff diff functions $y(x)$. To derive such a formula we expand $y\left(x_{j}\right), k_{1}, k_{2}$ in Taylor Series about the point $\left(x_{j-1}, y_{j-1}\right)$, equate like powers of $h$ on both sides of (3), and set $\alpha, \beta, \omega_{1}, \omega_{2}$ accordingly. In what follows we omit arguments when they are evaluated at the point $\left(x_{j-1}, y_{j-1}\right)$. The TS expansion of the LHS of (3) is:

$$
\begin{aligned}
y\left(x_{j}\right)= & y\left(x_{j-1}\right)+h y^{\prime}\left(x_{j-1}\right)+\frac{h^{2}}{2} y^{\prime \prime}\left(x_{j-1}\right)+\frac{h^{3}}{6} y^{\prime \prime \prime}\left(x_{j-1}\right)+O\left(h^{4}\right), \\
= & y\left(x_{j-1}\right)+h f+\frac{h^{2}}{2}\left(f_{x}+f_{y} f\right) \\
& +\frac{h^{3}}{6}\left(f_{x x}+2 f_{x y} f+f_{y y} f^{2}+f_{y} f_{x}+f_{y}^{2} f\right)+O\left(h^{4}\right) .
\end{aligned}
$$

## Expansion of the RHS

The TS expansion of the RHS of (3) is more complicated and first requires the expansions of $k_{1}$ and $k_{2}$,

$$
\begin{aligned}
k_{1}= & f \\
k_{2}= & f\left(x_{j-1}+\alpha h, y\left(x_{j-1}\right)+\beta h k_{1}\right) \\
= & f\left(x_{j-1}, y\left(x_{j-1}\right)+\beta h f\right)+(\alpha h) f_{x}\left(x_{j-1}, y\left(x_{j-1}\right)+\beta h f\right) \\
& +\frac{\alpha^{2} h^{2}}{2} f_{x x}\left(x_{j-1}, y\left(x_{j-1}\right)+\beta h f\right)+O\left(h^{3}\right), \\
= & {\left[f+\beta h f f_{y}+\frac{(\beta h f)^{2}}{2} f_{y y}+O\left(h^{3}\right)\right] } \\
& +\left[\alpha h f_{x}+\alpha \beta h^{2} f f_{x y}+O\left(h^{3}\right)\right]+\left[\frac{\alpha^{2} h^{2}}{2} f_{x x}+O\left(h^{3}\right)\right] \\
= & f+\left(\beta f f_{y}+\alpha f_{x}\right) h+\left(\frac{\beta^{2}}{2} f^{2} f_{y y}+\alpha \beta f f_{x y}+\frac{\alpha^{2}}{2} f_{x x}\right) h^{2}+O\left(h^{3}\right) .
\end{aligned}
$$

## TS Expansion of the RHS

The TS expansion of the RHS of (3) then is (with these substitutions for $k_{1}$ and $k_{2}$ )

$$
\begin{aligned}
R H S= & y\left(x_{j-1}\right)+h\left(\omega_{1} k_{1}+\omega_{2} k_{2}\right) \\
= & y\left(x_{j-1}\right)+h \omega_{1} f+h \omega_{2}[\cdots]+O\left(h^{4}\right) \\
= & y\left(x_{j-1}\right)+\left[\left(\omega_{1}+\omega_{2}\right) f\right] h+\left[\omega_{2}\left(\beta f f_{y}+\alpha f_{x}\right)\right] h^{2} \\
& +\left[\omega_{2}\left(\frac{\beta^{2}}{2} f^{2} f_{y y}+\alpha \beta f f_{x y}+\frac{\alpha^{2}}{2} f_{x x}\right)\right] h^{3}+O\left(h^{4}\right)
\end{aligned}
$$

and recall

$$
\begin{aligned}
\text { LHS }= & y\left(x_{j-1}\right)+h f+\frac{h^{2}}{2}\left(f_{x}+f_{y} f\right) \\
& +\frac{h^{3}}{6}\left(f_{x x}+2 f_{x y} f+f_{y y} f^{2}+f_{y} f_{x}+f_{y}^{2} f\right)+O\left(h^{4}\right) .
\end{aligned}
$$

## Equating like powers of $h$

Equating powers of $h$ for LHS and RHS we observe:
For order 0 : The coefficients of $h^{0}$ always agree and we have order at least zero for any choice of the parameters.
For order 1: If $\omega_{1}+\omega_{2}=1$ the coefficients of $h^{1}$ agree and we have at least order 1.

For order 2: In addition to satisfying the order 1 constraints we must have the coefficient of $h^{2}$ the same. That is $\alpha \omega_{2}=1 / 2$ and $\beta \omega_{2}=1 / 2$.

For order 3: In addition to satisfying the order 2 constraints we must have the coefficients of $h^{3}$ the same. That is we must satisfy the equations, $\omega_{2} \alpha^{2}=\frac{1}{3}, \omega_{2} \alpha \beta=\frac{1}{3}, \omega_{2} \beta^{2}=\frac{1}{3}, \frac{1}{6} f_{x y}=$ ?, $\frac{1}{6} f_{y}^{2}=$ ?.

## Family of $2^{\text {nd }}$-order RK Formula

Note that there are not enough terms in the coefficient of $h^{3}$ in the expansion of the RHS to match the expansion of the LHS. We cannot therefore equate the coefficients of $h^{3}$ and the maximum order we can obtain is order 2 . Our formula will be order 2 for any choice of $\omega_{2} \neq 0$, with $\omega_{1}=1-\omega_{2}$ and $\alpha=\beta=\frac{1}{2 \omega_{2}}$. This is a one-parameter family of $2^{n d}$-order Runge-Kutta formulas.
Three popular choices from this family are:
Modified Euler: $\omega_{2}=1 / 2$

$$
\begin{aligned}
k_{1} & =f\left(x_{j-1}, y_{j-1}\right) \\
k_{2} & =f\left(x_{j-1}+h, y_{j-1}+h k_{1}\right) \\
y_{j} & =y_{j-1}+\frac{h}{2}\left(k_{1}+k_{2}\right)
\end{aligned}
$$

## Family of $2^{\text {nd }}$-order RK Formula

Midpoint: $\omega_{2}=1$

$$
\begin{aligned}
k_{1} & =f\left(x_{j-1}, y_{j-1}\right) \\
k_{2} & =f\left(x_{j-1}+\frac{h}{2}, y_{j-1}+\frac{h}{2} k_{1}\right), \\
y_{j} & =y_{j-1}+h k_{2}
\end{aligned}
$$

Heun's Formula: $\omega_{2}=3 / 4$

$$
\begin{aligned}
k_{1} & =f\left(x_{j-1}, y_{j-1}\right) \\
k_{2} & =f\left(x_{j-1}+\frac{2}{3} h, y_{j-1}+\frac{2}{3} h k_{1}\right), \\
y_{j} & =y_{j-1}+\frac{h}{4}\left(k_{1}+3 k_{2}\right) .
\end{aligned}
$$

