

Features and Constraints

May 20, 2014 2:32 PM

Search Strategies

A*
Backtracking
Local Search

Features

Domain

e.g.
 $\text{dom}(x_1) = \{a, b, c\}$
 $x_1 \leftarrow a$

Boolean Satisfiability (Example)

Variables

A, B, \dots, G

Domains

$\text{dom}(A) = \{\text{true}, \text{false}\}$

Constraints

$(\neg A \vee \neg B) \wedge (\neg B \vee \neg C \vee D)$

Constraint Terminology and Notation

Intentional Constraint Description

Formula to be satisfied

Extensional Constraint Description

A list of valid tuples

Tuples

$t = (1,4)$ with variables x_1, x_2
 $t[x_1] = 1$
 $t[x_2] = 4$

Vars

C is a constraint
 $\text{vars}(C)$ is variables in constraint C

Example: n-Queens

4-Queens as a constraint satisfaction problem (CSP)

Variables

Each grid location, x_{ij} , $i = 1, \dots, 4$, $j = 1, \dots, 4$

Domains

$\text{dom}(x_{ij}) = \{0,1\}$

$x_{ij} \leftarrow 1$: There is a queen on (i, j)

Constraints

$$\forall i \sum_{j=1}^4 x_{ij} = 1$$

$$\forall j \sum_{i=1}^4 x_{ij} = 1$$

And each diagonal $\sum x_{ij} \leq 1$

Alternate Formulation

Variables

x_i , $i = 1, \dots, 4$ (one for each column)

Domains

$\text{dom}(x_i) = \{1, 2, 3, 4\}$ (row positions)

$x_i \leftarrow j$ There is a queen in column i , row j

Constraints

$\forall i \forall j \ x_i \neq x_j \wedge |x_i - x_j| \neq |i - j|$

Example: Crossword Puzzle

Variables

x_1, \dots, x_{23}

Domains

$\text{dom}(x_i) = \{ 'a', 'b', 'c', \dots, 'd' \}$

Constraints

Consecutive grid locations form words in dictionary. All words used exactly once.

Non Binary

Alternate Formulation

Variables

1Across, 1Down, 2Down, ...

Domains

$\text{dom}(1\text{Across}) = \{\text{All 5 letter words}\}$

Constraints (Binary)

1Across and 1Down agree on assignment of the first letter.

... Same for all pairs of intersecting rows/columns.

Alldifferent constraint - 4 Queens Example

Variables

x_1, x_2, x_3, x_4 (each column)

Constraints

$\text{alldifferent}(x_1, x_2, x_3, x_4)$

...

Constraint Propagation

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Example

Variables

x, y, z

Domains

$\{1,2,3\}$

Constraints

$c_1: x < y$

$c_2: y < z$

Check Arc Consistency and Remove Inconsistent Values

x and c_1

$\text{dom}(x) = \{1,2,3\} \Rightarrow \{1,2\}$

y and c_1

$\text{dom}(y) = \{1,2,3\} \Rightarrow \{2,3\}$

y and c_2

$\text{dom}(y) = \{2,3\} \Rightarrow \{2\}$

z and c_2

$\text{dom}(z) = \{1,2,3\} \Rightarrow \{3\}$

x and c_1

$\text{dom}(x) = \{1,2\} \Rightarrow \{1\}$



n variables

m values for each

k constraints per variable

$\frac{nk}{2}$ constraints total

Constraints always satisfied.

Number of constraint checks:

Naïve backtracking

nk checks

MAC

$\frac{nk}{2}m + nkm$

Comparison of naïve backtracking vs MAC

n variables.

Each variable has domain size m

There is a single binary constraint for each pair of variables.

$\frac{n(n-1)}{2}$ constraints total.

Each constraint is satisfied with probability p

What is the branching factor of naïve backtracking?

Consider a node with l free variables.

This node is satisfiable if there is any assignment of the l variables that satisfy all $C = \frac{l(l-1)}{2} + l(k-l)$ constraints.

An assignment is satisfactory with probability p^C

None of the m^l assignments are satisfactory with probability

$(1 - p^C)^{m^l}$

So a node at height l is satisfiable with probability

$q(l) = 1 - (1 - p^C)^{m^l}$

Given that a node is satisfiable with probability $q(l)$, what is the expected branching factor?

Probability that a node at height l has branching factor b is

$P(B_l = b) = (1 - q(l))^{b-1} \times q(l)$

This is a geometric distribution with expected value

$$E(B_l) = \frac{1}{q(l)}$$

What is the expected number of nodes in the search tree starting at height l ?

N_l is the expected number of nodes. B_l is the random variable giving the branching factor of nodes at height l .

Recurrence:

$$N_l = \sum_{b=0}^m P(B_l = b) N_{l-1}$$

Local Search

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Example: 4-Queens

Alternative 1

All constraints into cost function

+1 for each constraint that isn't satisfied

Set of all states: CSP with no constraints.

Set of all solutions: set of all 4-tuples over the set $\{1, 2, 3, 4\}$

Neighbourhood function:

Swap pairs of values? Solution isn't necessarily reachable. e.g. from $(1, 1, 1, 1)$

Alternative 2

Cost function: +1 for each of $|x_i - x_j| \neq |i - j|$ that is not satisfied

Set of all states must satisfy $x_i \neq x_j \forall i, j$

More specifically, all different (x_1, x_2, x_3, x_4)

Set of all states: : all permutations of 1, 2, 3, 4.

Neighbourhood function: Swap pairs of values.

Local Search for TSP

Nodes: Permutations of Cities

Cost function: cost of tour

Neighbourhood function:

2-opt: delete two edges from tour to break tour into two pieces and then reconnect

Starting Tour

- Greedy Algorithm
 - Pick lowest cost one next
- Alternative: randomly pick a starting node, run greedy algorithm
- Alternative: pick randomly from lowest few in greedy.

Satisfiability

Set of states: all possible assignments of true or false to Boolean variables.

Cost function: +1 for each unsatisfied constraint

Neighbourhood function: Change/flip k variables

Example: Partition

Set of all states:

x_i : $i = 1, \dots, \#$ of objects

$\text{dom}(x_i) = \{0, 1\}$

All possible assignments where

$x_i = 0$ means x_i is in U

$x_i = 1$ means x_i is in V

Cost function : difference in weights of U and V

e.g. $u = \{a, b, c, d\}$, $v = \{e, f, g, h\}$, $|32 - 58| = 26$

Neighbourhood function

Poor:

Swap two: pick an object from U and one from V and swap them

Better:

Pick an object and move it to the other set.

Set Covering

Cost function:

- size/cost of cover setting
- penalize for uncovered rows

Genetic Algorithms

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Example Representations: 4-queens

What are the x_j ?

1. Permutation representation

e.g. $\langle 2, 1, 4, 3 \rangle$

2. Extended pair representation

For each pair of queens, which one comes before the other

$$\begin{array}{cccccc} x_{12} & x_{13} & x_{14} & x_{23} & x_{24} & x_{34} \\ 0 & 0 & 1 & 1 & 0 & 1 \end{array}$$

$x_{ij} = 1$ if $x_i < x_j$ and 0 otherwise

Solution: 1 0 1 0 0 1

3. Possible row positions encoded in binary

$$\begin{array}{cccc} x_1 & x_2 & x_3 & x_4 \\ 00 & 00 & 00 & 00 \\ 01 & 01 & 01 & 01 \\ 10 & 10 & 10 & 10 \\ 11 & 11 & 11 & 11 \end{array}$$

Fitness Function

of constraints satisfied

Genetic Operations

Mutation (Unary)

Flip a bit(s) with some small probability

Crossover (Binary)

Given $a = (a_1, \dots, a_m)$ and $b = (b_1, \dots, b_m)$

child = (c_1, \dots, c_m)

$c_i =$ choose between a_i or b_i (not a good description)

Logic & Inference

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Holmes Scenario

Variables

w – watson calls

g – gibbon calls

a – alarm

b – buglaring

Knowledge Base

$w \Rightarrow a, \quad g \Rightarrow a, \quad a \Rightarrow b$

But these are not categorically true. Logic insufficeint

Query

b ? Is there are burglary in progress)

Probability

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Axioms of Probability

1. All probabilities are between 0 and 1
 $0 \leq P(a) \leq 1$
2. Necessarily true propositions have probability 1
Necessarily false propositions have probability 0
 $P(\text{true}) = 1, \quad P(\text{false}) = 0$
3. The probability of a conjunction is given by,
 $P(A \wedge B) = P(A) + P(B) - P(A \vee B)$

Example - Slides: Holmes Example

$$P(B) = p_1 + p_3 + p_5 + p_7$$

$$P(W \wedge B) = p_5 + p_7$$

$$P(W \vee B) = p_1 + p_3 + p_4 + p_5 + p_6 + p_7$$

$$P(W \vee \neg W) = 1$$

$$P(B|W) = \frac{P(B \wedge W)}{P(W)} = \frac{p_5 + p_7}{p_4 + p_5 + p_6 + p_7}$$

$$P(\neg B|W \wedge A) = \frac{P(\neg B \wedge W \wedge A)}{P(W \wedge A)} = \frac{p_6}{p_6 + p_7}$$

Examples of Probabilistic Reasoning

Example: (B)urglary and (A)larm

Suppose the alarm in 95% of cases is accurate. i.e. if there is a burglary, the alarm goes.

In 97% of cases when not burglary, the alarm does not go

We get

$$\begin{array}{l} \text{False positive} \\ P(A|B) = 0.95, \quad P(A|\neg B) = 0.03 \\ P(\neg A|B) = 0.05, \quad P(\neg A|\neg B) = 0.97 \end{array}$$

$$\text{Probability of burglary } P(B) = 0.0001, \quad P(\neg B) = 0.9999$$

Suppose alarm goes. What is the probability of a burglary.

$$\begin{aligned} P(B|A) &= \frac{P(B \wedge A)}{P(A)} = \frac{P(A|B)P(B)}{P(A|B)P(B) + P(A|\neg B)P(\neg B)} = \frac{0.95 \times 0.0001}{0.95 \times 0.0001 + 0.03 \times 0.9999} \\ &= \frac{0.000095}{0.030092} = 0.00316 \end{aligned}$$

Belief Network

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Edges represent dependencies between variables.

What do the numbers mean?

Frequentist approach / statistics

- objective

Bayesian / subjectivist approach

- degrees of belief

Exact algorithms for finding a particular joint probability given a belief network:

Variable elimination

Cache intermediate results

Factor as much as possible

Exact query answering: #P-Complete (worse than NP-Complete)

Approximate Algorithms

Example

$P(B = \text{false}, G = \text{true}, W = \text{true})$

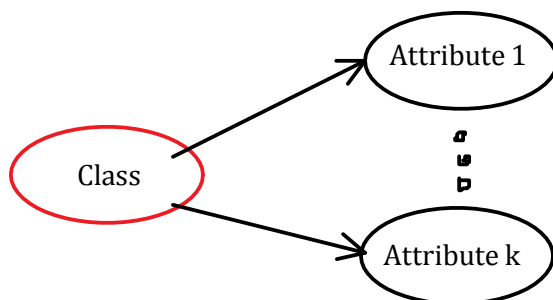
$$\begin{aligned} &= \sum_{e \in \text{dom}(E)} \sum_{a \in \text{dom}(A)} \sum_{r \in \text{dom}(R)} P(B = \text{false})P(G = \text{true}|A = a)P(W = \text{true}|A = a)P(A = a|B = \text{false}, E = e)P(E = e)P(R = r|E = e) \\ &= P(B = \text{false}) \left[\sum_a \sum_e \sum_r P(G = \text{true}|A = a)P(W = \text{true}|A = a)P(A = a|B = \text{false}, E = e)P(E = e)P(R = r|E = e) \right] \\ &= P(B = \text{false}) \left[\sum_a \sum_e P(G = \text{true}|A = a)P(W = \text{true}|A = a)P(A = a|B = \text{false}, E = e)P(E = e) \underbrace{\left(\sum_r P(R = r|E = e) \right)}_1 \right] \\ &= P(B = \text{false}) \left[\sum_a P(G = \text{true}|A = a)P(W = \text{true}|A = a) \left[\sum_e P(A = a|B = \text{false}, E = e)P(E = e) \right] \right] \end{aligned}$$

Supervised Learning

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Naïve Bayes

Querying a Naïve Bayes Network



Let domain of class variable be $\{c_1, \dots, c_k\}$

Given values for the attributes

Attribute 1 = a_1

⋮

Attribute k = a_k

To predict class

$$\operatorname{argmax}_{c_i} P(\text{class} = c_1 | \text{evidence}) = \operatorname{argmax}_{c_i} P(\text{class} = c_i | \text{Attribute 1} = a_1, \dots, \text{Attribute k} = a_k)$$

$$= \operatorname{argmax}_{c_i} P(\text{class} = c_i | a_1, \dots, a_k) = \operatorname{argmax}_{c_i} \frac{P(\text{class} = c_i \wedge a_1, \dots, a_k)}{P(a_1, \dots, a_k)}$$

$$= \operatorname{argmax}_{c_i} \frac{P(\text{class} = c_i) \prod_{j=1}^k P(a_j | \text{class} = a_j)}{P(a_1, \dots, a_k)}$$

$$= \operatorname{argmax}_{c_i} P(\text{class} = c_i) \prod_{j=1}^k P(a_j | \text{class} = a_j)$$

Learning arcs and probabilities

Each attribute/features becomes a node in the network.

Steps

1. For each attribute and each possible set of parents, calculate a score

$$a_i, \quad a_1 \rightarrow a_i, \dots, a_k \rightarrow a_i, \dots, \quad (a_1, a_2) \rightarrow a_i, \dots, (a_{k-1}, a_k) \rightarrow a_i, \dots$$

Many possible scores. Scores capture goodness of fit and penalty term for complexity.

Two popular scores: BIC & BDeu

BIC = Bayesian Information Criterion

Bdeu = Bayesian Dirichlet (likelihood equivalence) (uniform joint distribution)

2. For each attribute/class variable pair pick a parent set such that

- a. there are no cycles, and
- b. the sum of scores is minimized

Pruning rule: Two parent sets p, p' for some attribute

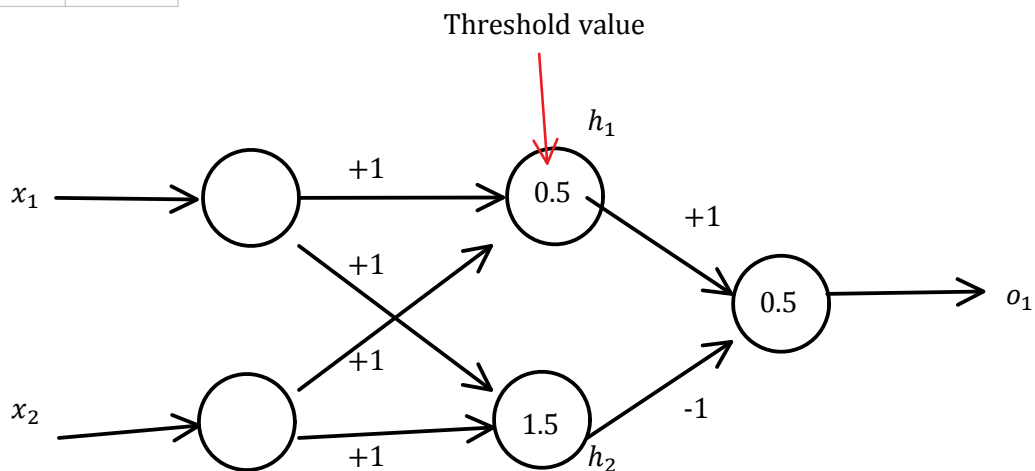
$p \subset p'$ and $\text{cost}(p) \leq \text{cost}(p')$ then prune (remove) p'

Neural Networks

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Example: XOR Function

Input	Output
$x_1 \ x_2$	y_1
0 0	0
0 1	1
1 0	1
1 1	0



$$\text{Step function } f(x) = \begin{cases} 0 & \text{if } x \leq 0 \\ 1 & \text{if } x > 0 \end{cases}$$

$$h_1 = f(x_1 + x_2 - 0.5)$$

$$h_2 = f(x_1 + x_2 - 1.5)$$

$$o_1 = f(h_1 - h_2 - 0.5)$$

x_1	x_2	h_1	h_2	o_1
0	0	0	0	0
0	1	1	0	1
1	0	1	0	1
1	1	1	1	0

Backpropagation Learning Algorithm

$$x_1 - h_1 - o_1$$

$$x_2 - h_2 - o_2$$

$$\vdots$$

$$x_A - h_B - o_C$$

Each hidden and output unit uses signal function $f(x) = \frac{1}{1+e^{-kx}}$

Output is a value between 0 and 1

Handling Thresholds

$$h_j = f\left(\left(\sum_{i=1}^A w_{1ij} \cdot x_i\right) - \beta_j\right), \quad j = 1, \dots, B$$

Rewrite as,

$$h_j = f\left(\sum_{i=0}^A w_{1ij} \cdot x_i\right), \quad j = 1, \dots, B$$

where $x_0 = -1$ and w_{10j} is the threshold for h_j

Same for output layer:

$$o_k = f\left(\sum_{j=0}^B w_{2jk} \cdot h_j\right), \quad k = 1, \dots, C$$

where $h_0 = -1$

Error Term

$$\text{error} = \frac{1}{2} \sum_{k=1}^C (y_k - o_k)^2$$

Algorithm

- Initialize weights & thresholds to small random values
 - $w_{1ij} = \text{random}(-0.5, 0.5), \quad i = 1, \dots, A, \quad j = 1, \dots, B$
 - $w_{2jk} = \text{random}(-0.5, 0.5), \quad j = 1, \dots, B, \quad k = 1, \dots, C$
 - $x_0 = -1, \quad h_0 = -1$ These never change
- Choose an input-output pair from the training set. Call it \bar{x}, \bar{y}
 - where $\bar{x} = (x_1, \dots, x_A), \quad \bar{y} = (y_1, \dots, y_C)$
 - Assign activation levels of x_1, \dots, x_A (input units)
- Determine activation levels of hidden units.

$$h_j = f\left(\sum_{i=0}^A w_{1ij} \cdot x_i\right), \quad j = 1, \dots, B$$
- Determine activation levels of output units

$$o_k = f\left(\sum_{j=0}^B w_{2jk} \cdot h_j\right), \quad k = 1, \dots, C$$
- Determine how to adjust weights between hidden and output layer for this example.

$$E2_j = \underbrace{k}_{\text{from sigmoid}} \cdot o_j(1 - o_j)(y_j - o_j), \quad j = 1, \dots, C$$

Sigmoid: $f(x) = \frac{1}{1 + e^{-kx}}$
- Determine how to adjust weights between input and hidden layer for this example.

$$E1_j = k \cdot h_j \cdot (1 - h_j) \sum_{i=1}^C E2_i \cdot w_{2ji}, \quad j = 1, \dots, B$$
- Adjust weights between hidden and output layer.

$$w_{2ij} = w_{2ij} + \text{LearningRate} \cdot E2_j \cdot h_i, \quad i = 0, \dots, B, j = 1, \dots, C$$
- Adjust weights between input and hidden layer

$$w_{1ij} = w_{1ij} + \text{LearningRate} \cdot E1_j \cdot x_i, \quad i = 0, \dots, A, j = 1, \dots, B$$
- Repeat steps 2-8 until done.

Parameters

Learning rate:

range: 0.05 to 0.35

Sigmoid constant k

$$f(x) = \frac{1}{1 + e^{-kx}}, \quad k \geq 0$$

Number of hidden units

Stopping Criteria

Maximum number of epochs. epoch = once through training set.

Error is acceptably small

- discrete/classification error
- total number of bit-errors
- continuous error $\sum (y_j - o_j)^2$