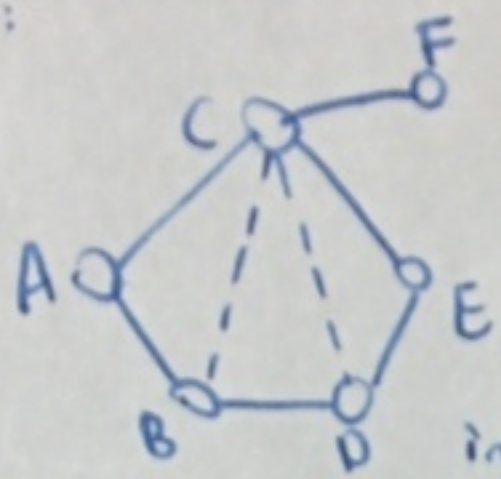


Junction tree algorithm.

We start from Variable Elimination.

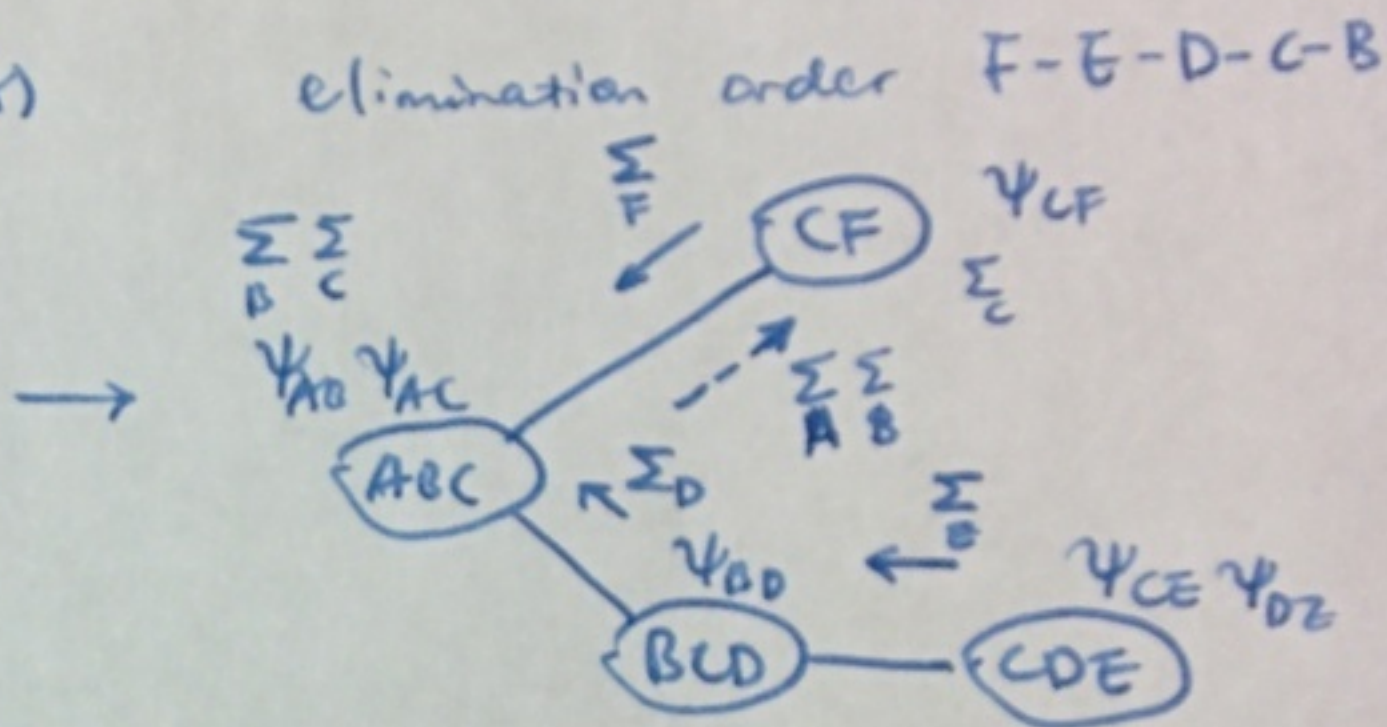
Example:



$$P(x) = \frac{1}{Z} \psi_{AB} \psi_{AC} \psi_{BD} \psi_{DE} \psi_{CE} \psi_{CF}$$

If we want marginal distribution $P(A)$

$$P(A) \propto \sum_B \psi_{AB} \sum_C \psi_{AC} \underbrace{\sum_F \psi_{CF} \psi_C}_{\psi'_{CD}} \underbrace{\sum_D \psi_{BD} \sum_E \psi_{DE} \psi_{CE}}_{\psi'_{BC}}$$



$P(F)$: E-D-B-A-C

$$\sum_C \psi_{CF} \sum_A \psi_{AC} \sum_B \psi_{AB} \underbrace{\sum_D \psi_{BD} \sum_E \psi_{DE} \psi_{CE}}_{\psi'_{CD}} \underbrace{\psi_{BC}}_{\psi'_{BC}}$$

reuse partial sums.

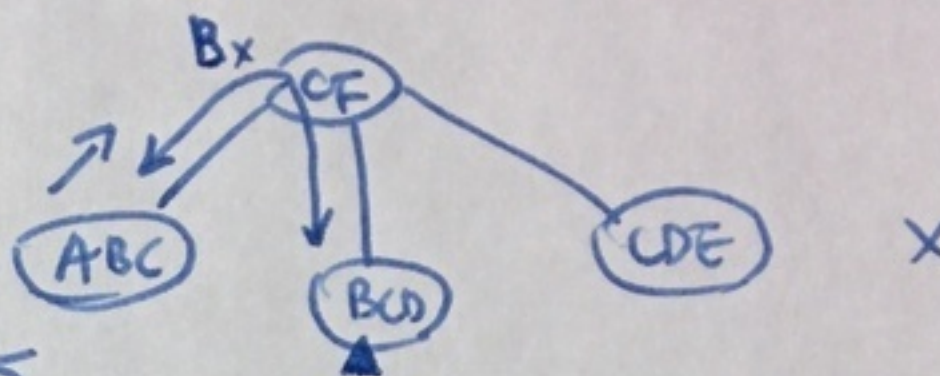
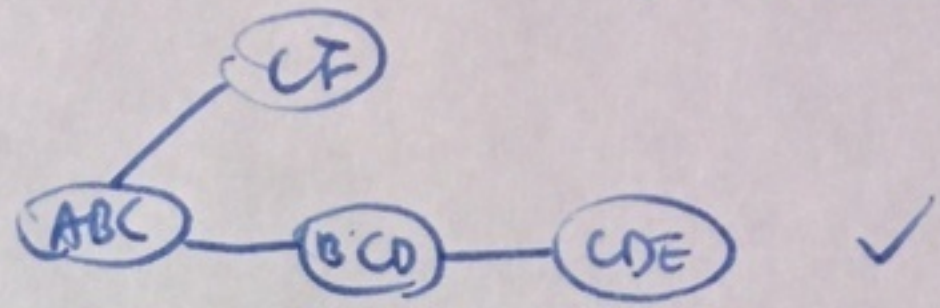
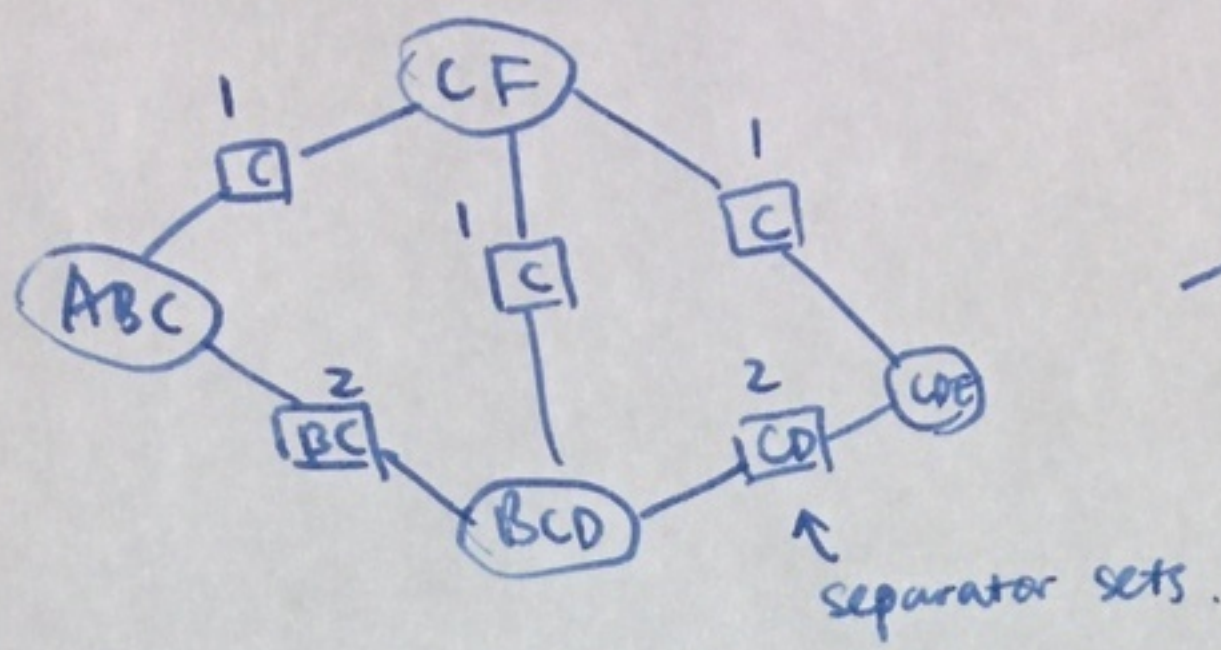
Junction tree: data structure that can store partial computations, which can be reused to make computation of multiple queries efficient.
 → no need to redo elimination each time.

Once we get a clique tree, simply run sum-product on it.

$$[s = c \cap c', s'' = c \cap c''] \quad m_{c \rightarrow c'}(s) = \sum_{c \setminus s} \psi_c \prod_{c'' \in N(c) \setminus c'} m_{c'' \rightarrow c}(s'')$$

marginals: $p(c) \propto \psi_c \prod_{c' \in N(c)} m_{c' \rightarrow c}(s)$

There could be multiple clique trees, not all of them junction trees.



$\sum_A \sum_{B_n}$

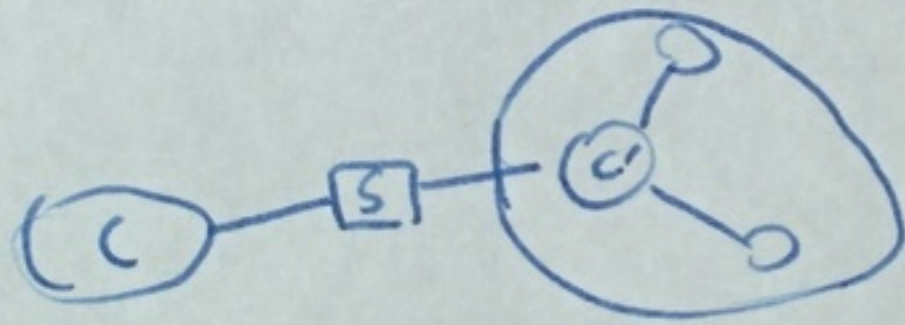
when passing messages cannot safely sum out variables.

★ Junction tree property / Running intersection property.

For any clique nodes c, c' in a clique tree, $S = c \cap c'$ must be contained in every node on the path connecting c and c' .

Def Junction tree: clique trees that have this property.

Why useful?



$R = C \setminus S$ only appears in C .

So guarantees safe sum over R .

How to get a junction tree?

- Maximum weight spanning tree.

Specifying an initial elimination order is also unnecessary.

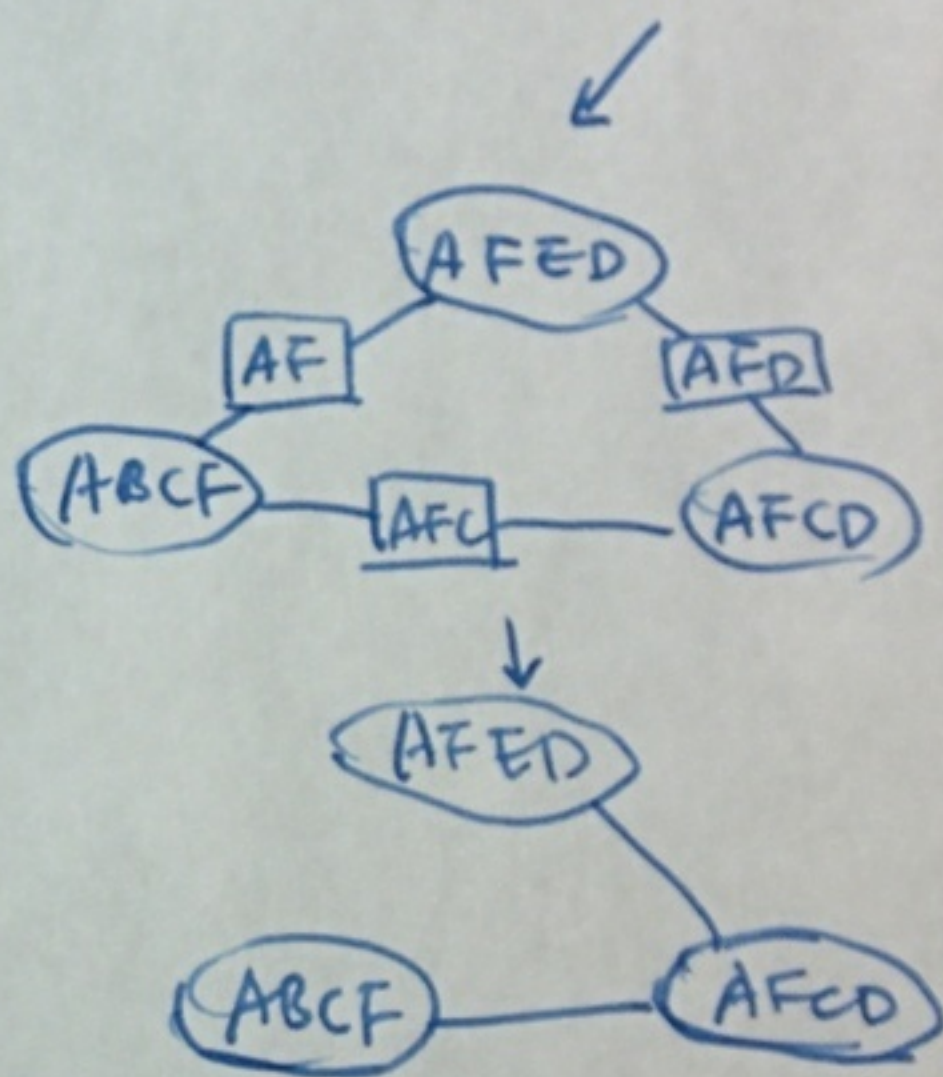
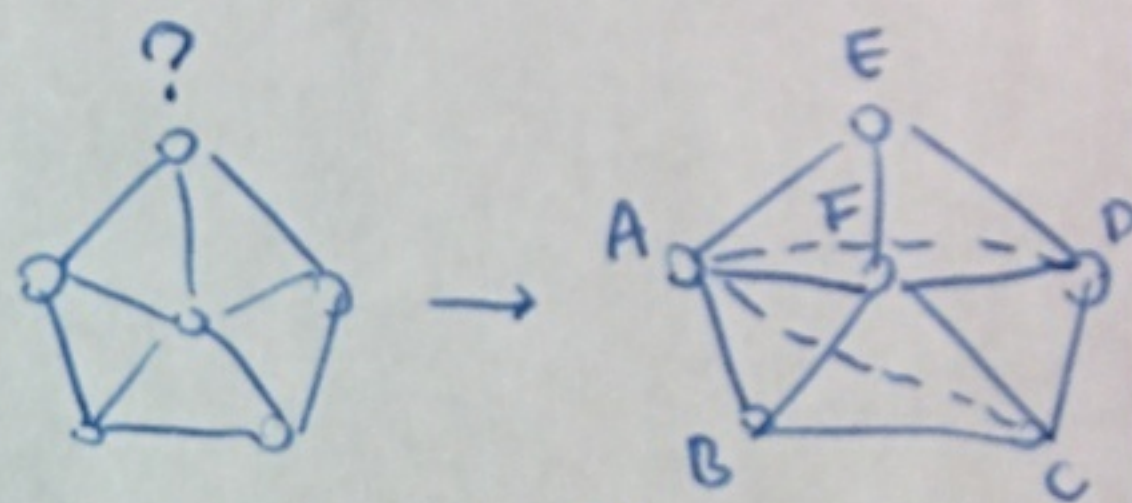
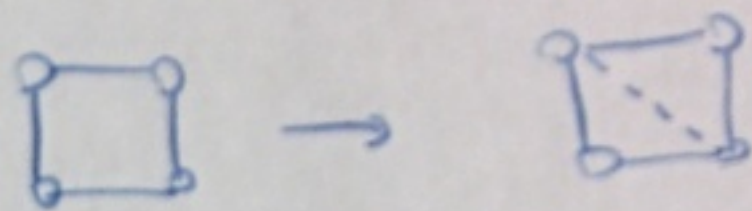
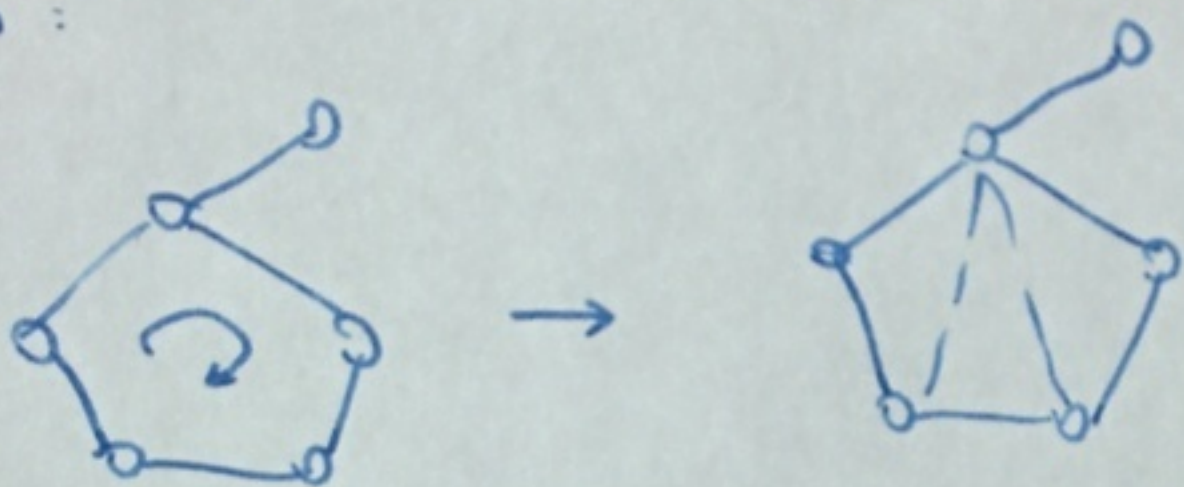
More generally, the operation of adding fill edges to get the induced graph is called "triangulation"

→ adding edges so that any cycle of length ≥ 4 will have at least a chord.

→ after this, the only possible chordless cycles are triangles

→ elimination guarantees a triangulated graph.

Examples:



Summary:

1. triangulation, find maximal cliques.
2. build junction tree.
3. initialize clique potentials.
4. run sum-product on junction tree.

Complexity:

1. 2. 3. only need to do once for a given graph, can be reused for any distribution that factorizes according to this graph.

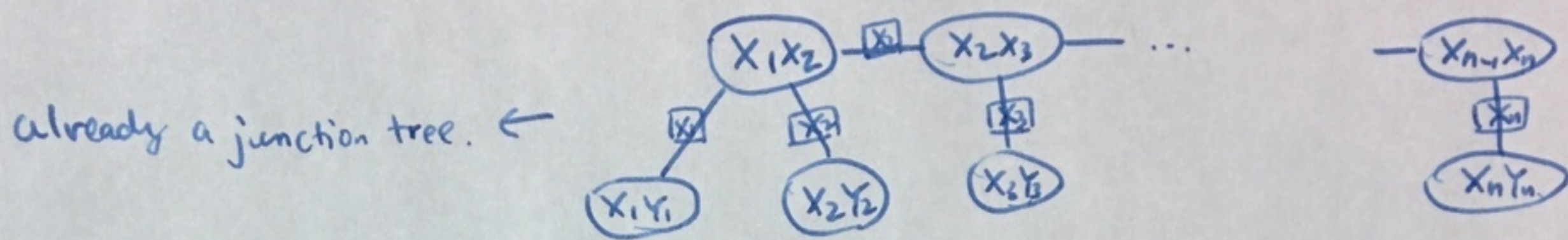
4. complexity at most $O(NK^{w+1})$.

N : # cliques.
 K : # states for each variable
 w : tree-width.

Example: HMM:

$$P(X, Y) = P(x_1) \prod_{i=2}^n P(x_i | x_{i-1}) \prod_{i=1}^n P(y_i | x_i)$$

$$\prod_{i=2}^n \psi_{i,i-1}(x_i, x_{i-1}) \prod_{i=1}^n \psi_i(x_i, y_i)$$



$$\psi_{12}(x_1, x_2) = P(x_1) P(x_2 | x_1)$$

$$\psi_{i,i-1}(x_i, x_{i-1}) = P(x_i | x_{i-1}), \quad i > 2.$$

$$\psi_i(x_i, y_i) = P(y_i | x_i).$$

Assume condition on Y , we want marginals of $P(X|Y)$. → simply clamp Y to the specified value and everything else the same.

"Forward pass"

$$m_{x_1 y_1 \rightarrow x_1 x_2}(x_1) = \psi_1(x_1, y_1) = P(y_1 | x_1)$$

$$m_{x_i y_i \rightarrow x_{i-1} x_i}(x_i) = \psi_i(x_i, y_i) = P(y_i | x_i)$$

$$\begin{aligned} m_{x_1 x_2 \rightarrow x_2 x_3}(x_2) &= \sum_{x_1} \psi_{x_1 x_2}(x_1, x_2) m_{x_1 y_1 \rightarrow x_1 x_2}(x_1) m_{x_2 y_2 \rightarrow x_1 x_2}(x_2) \\ &= \sum_{x_1} P(x_1) P(x_2 | x_1) \cdot P(y_1 | x_1) P(y_2 | x_2) \\ &= \sum_{x_1} P(x_1, x_2, y_1, y_2) \\ &= P(x_2, y_1, y_2) \propto P(x_2 | y_1, y_2) = P(x_2 | y_{1:2}) \end{aligned}$$

~~$$m_{x_{i-1} x_i \rightarrow x_i x_{i+1}}(x_i) = \sum_{x_{i-1}} \psi_{x_{i-1} x_i}(x_{i-1}, x_i) m_{x_{i-2} x_{i-1} \rightarrow x_{i-1} x_i}(x_{i-1}) m_{x_i y_i \rightarrow x_{i-1} x_i}(x_i)$$~~

$$\begin{aligned} m_{x_{i-1} x_i \rightarrow x_i x_{i+1}}(x_i) &= \sum_{x_{i-1}} \psi_{x_{i-1} x_i}(x_{i-1}, x_i) \cdot m_{x_{i-2} x_{i-1} \rightarrow x_{i-1} x_i}(x_{i-1}) m_{x_i y_i \rightarrow x_{i-1} x_i}(x_i) \\ &= \sum_{x_{i-1}} P(x_i | x_{i-1}) P(x_{i-1} | y_{1:i-1}) P(y_i | x_i) \\ &= \sum_{x_{i-1}} P(x_i, x_{i-1} | y_{1:i-1}) \\ &= P(x_i, y_i | y_{1:i-1}) \propto P(x_i | y_{1:i}) \end{aligned}$$

Other variants and more discussions on junction trees

can be found in

D. Koller & N. Friedman

Probabilistic Graphical Models: principles & techniques.

M. Jordan & C. Bishop

A Introduction to Graphical Models (draft)