

On the design of widening operators

*“If you widen without principles
you may converge without precision”*

Nicolas Halbwachs

Verimag/CNRS
Grenoble

Automatic verification mainly consists in computing **fixpoints** of monotone functions on lattices.

Example: computation of reachable states

$$\text{Reach} = \text{Init} \cup \text{post}(\text{Reach}) \quad L = 2^S$$

Model-checking = exact fixpoint computation, generally in **finite** or **finite-depth** lattices.

(Finite) abstraction [Cousot-Cousot, POPL'77]

$$L_c \overset{\alpha}{\underset{\gamma}{\rightleftharpoons}} L_a \quad (\text{finite})$$

Let $F_a = \alpha \circ F_c \circ \gamma$, then $\text{lfp}(F_c) \sqsubseteq \gamma(\text{lfp}(F_a))$

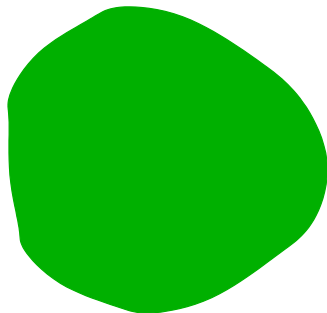
→ fixpoint **approximation**, **conservative** verification

now routinely used in model-checking

[Clarke-Grumberg-Long, TOPLAS'94] [Graf-Loiseaux, CAV'93]

Example: Predicate abstraction

S , a set of states

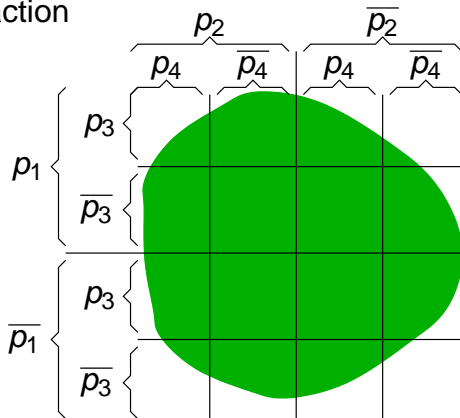


Example: Predicate abstraction

S , a set of states

P a finite set of predicates

$$p_i : S \mapsto \{0, 1\}$$

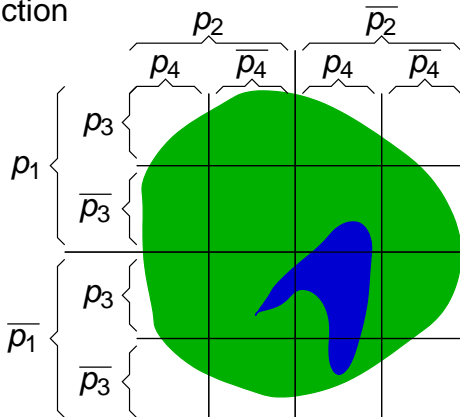


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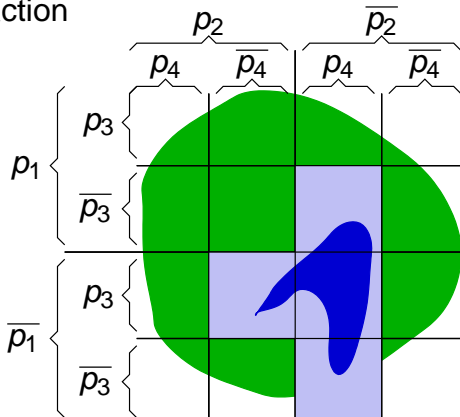


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$$L_c = 2^S, \quad L_a = 2^{Mon(P)}$$

$$\alpha(X) = \{\phi \in Mon(P) \mid \exists x \in X, x \models \phi\}$$

$$\gamma(Y) = \{x \mid \exists \phi \in Y, x \models \phi\}$$

So the main remaining difference between Model-Checking and Abstract Interpretation is the use of **widening**.

Widening often considered as a dirty heuristic!

So the main remaining difference between Model-Checking and Abstract Interpretation is the use of **widening**.

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Outline of the talk

- Introduction
- Reminders about Widening
- Widening on convex polyhedra
 - Reminders about linear relation analysis
 - Classical widenings
 - Correct and incorrect attempts for improvement
 - Taking the program into account
- Avoiding widening
 - Acceleration
 - Exact abstract solution
 - Can we combine the two?

Widening: basic idea

[Cousot-Cousot, POPL'77]:

- stay in an infinite lattice
- iterative computations of $lfp(F) = \bigsqcup_{n \in \mathbb{N}} F^n(\perp)$ may be infinite
- try to guess the limit from its first terms
($X_0 = \perp, X_1 = F(X_0), X_2 = F(X_1) \dots$)
- this guess is made through the computation of

$$Y_0 = X_0, \quad Y_{n+1} = Y_n \nabla F(Y_n)$$

where ∇ is a widening operator.

Widening: definition

$(L, \sqsubseteq, \sqcap, \sqcup, \perp, \top)$ a complete lattice.

$\nabla : L \times L \mapsto L$ is a **widening** iff

- $\forall x, y \in L, x \sqcup y \sqsubseteq x \nabla y$

- [chain condition]**

for all increasing chain $x_0 \sqsubseteq x_1 \sqsubseteq \dots \sqsubseteq x_n \dots$ in L ,

the increasing chain $y_0 = x_0, \dots, y_{n+1} = y_n \nabla x_{n+1}, \dots$

is not strictly increasing (i.e., stabilizes after a finite number of terms)

Widening: use

Instead of computing the (infinite) sequence

$$X_0 = \perp, X_{n+1} = F(X_n)$$

compute the **finite** sequence

$$Y_0 = X_0, Y_{n+1} = Y_n \nabla F(Y_n)$$

which limit is greater than $lfp(F)$

Basic example: intervals (1)

[Cousot-Cousot, ISP'76]

```

-----  $X_0$ 
x := 0
-----  $X_1$ 
while
  -----  $X_2$ 
    x < 100 do
      -----  $X_3$ 
        x := x + 1
      -----  $X_4$ 
    end
  -----  $X_5$ 

```

Basic example: intervals (1)

[Cousot-Cousot, ISP'76]

```

-----  $X_0 = [-\infty, +\infty]$ 
x := 0
-----  $X_1 = X_0[x := 0]$ 
while
  -----  $X_2 = X_1 \sqcup X_4$ 
  x < 100 do
    -----  $X_3 = X_2 \sqcap [-\infty, 99]$ 
    x := x + 1
    -----  $X_4 = X_3[x := x + 1]$ 
  end
  -----  $X_5 = X_2 \sqcap [100, +\infty]$ 

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$$X_2 = [0, 0] \sqcup ((X_2 \sqcap [-\infty, 99])[x := x + 1])$$

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Exact computation

$$X_2^{(0)} = \perp$$

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With widening

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convergence!

Basic example: intervals (3)

Widening on intervals:

$$\perp \nabla I = I$$

$$[a, b] \nabla [c, d] = \left[\text{if } c < a \text{ then } -\infty \text{ else } a, \text{ if } d > b \text{ then } \infty \text{ else } b \right]$$

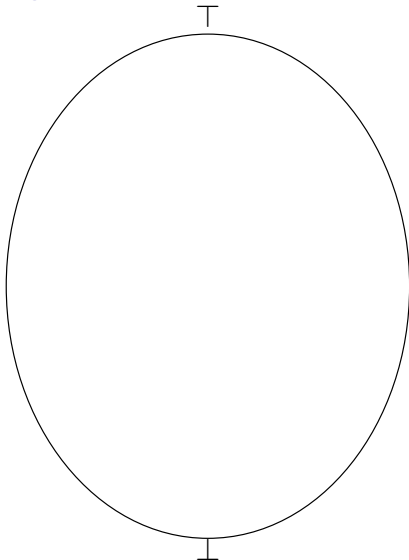
So,

$$\perp \nabla [0, 0] = [0, 0]$$

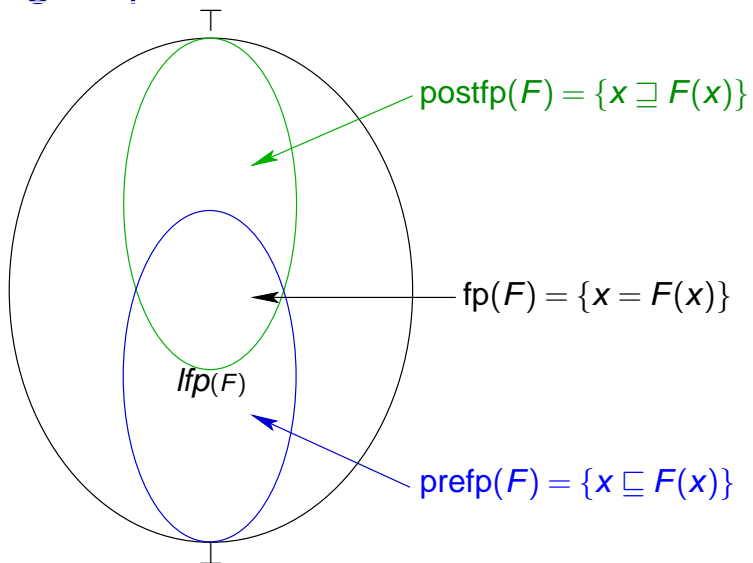
and

$$[0, 0] \nabla [0, 1] = [0, \infty]$$

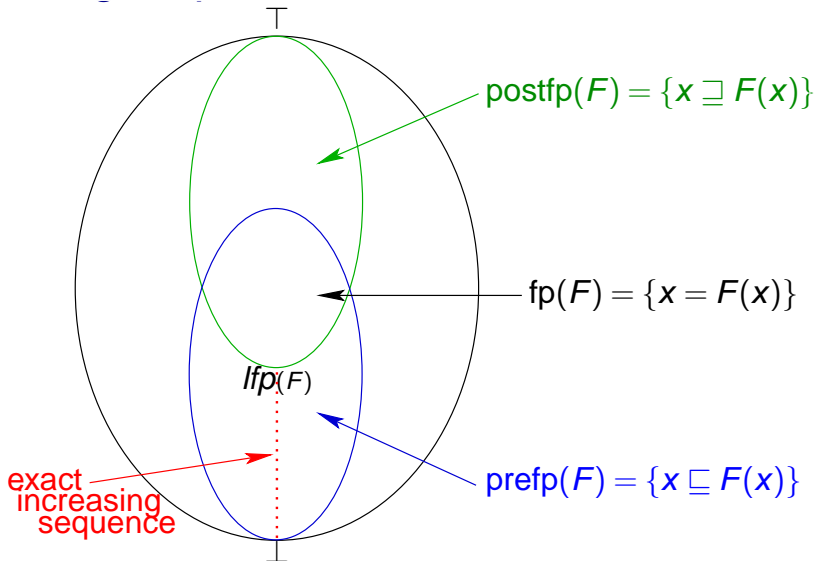
Descending sequence



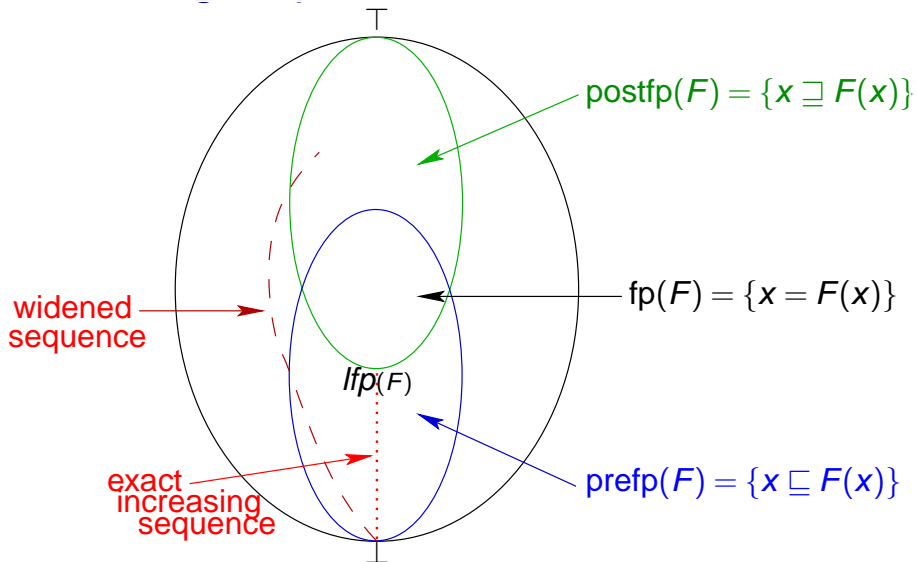
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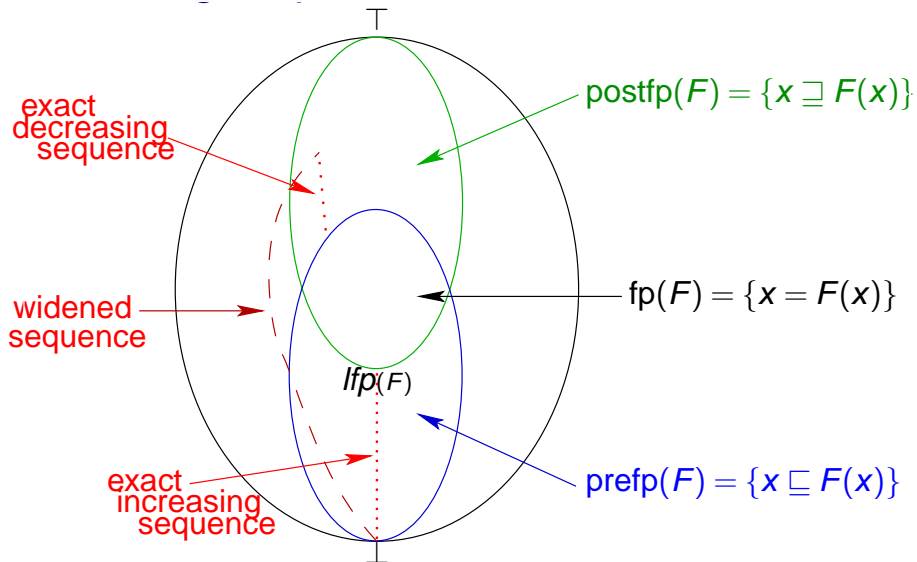
Descending sequence



Descending sequence



Descending sequence



Descending sequence: intervals

The widened sequence converged at $x_2^{(2)} = [0, \infty]$

Descending sequence:

$$\begin{aligned}
 x_2^{(3)} &= [0, 0] \sqcup \left(\left(x_2^{(2)} \cap [-\infty, 99] \right) [x := x + 1] \right) \\
 &= [0, 0] \sqcup ([0, 99][x := x + 1]) \\
 &= [0, 0] \sqcup [1, 100] \\
 &= [0, 100] \\
 x_2^{(4)} &= [0, 0] \sqcup \left(\left(x_2^{(3)} \cap [-\infty, 99] \right) [x := x + 1] \right) \\
 &= x_2^{(3)} \quad \text{Fixpoint!}
 \end{aligned}$$

Another old example: Karp & Miller

[Karp-Miller, J. Comput. Syst. Sci. 69] Boundedness of Petri nets

A Petri net with p places. Markings = \mathbb{N}^p

Order on markings: $M \preceq M' \Leftrightarrow \forall i = 1..p, M_i \leq M'_i$

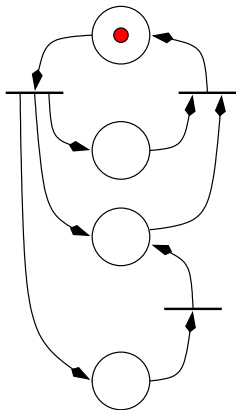
Obvious property: a set of mutually incomparable markings cannot be infinite

Enumerate the reachable markings, and whenever some marking M leads to a strictly greater marking M' , replace M' by $M \nabla M'$:

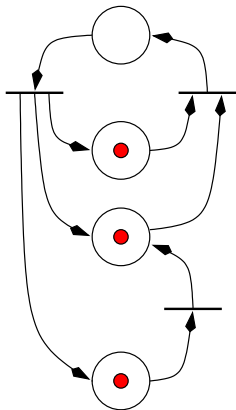
$$(M \nabla M')_i = \begin{cases} M_i & \text{if } M_i = M'_i \\ \infty & \text{if } M_i < M'_i \end{cases}$$

Karp & Miller: example

$(1, 0, 0, 0)$



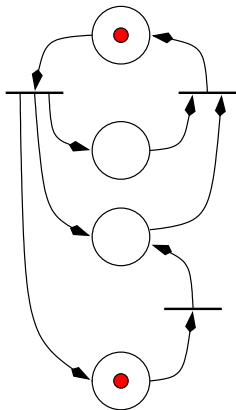
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$$(1, 0, 0, 0)$$

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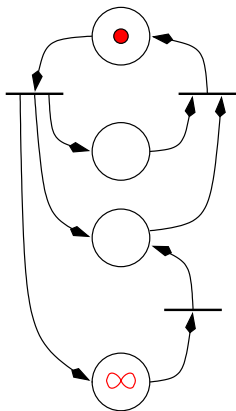


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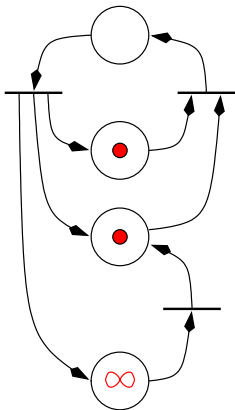
Karp & Miller: example


 $(1, 0, 0, 0)$

 $(0, 1, 1, 1)$


$$\begin{pmatrix} \underline{1, 0, 0, 1} \\ 1, 0, 0, \infty \end{pmatrix}$$

Karp & Miller: example

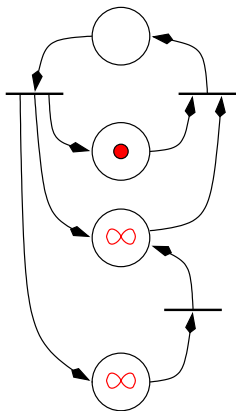

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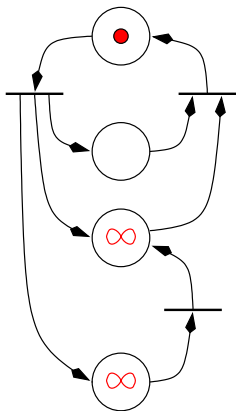
 $(\underline{1}, 0, 0, 1)$
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A more general definition

[Ball-Podelski-Rajamani, TACAS'02]

- Infinite states, infinite set of atomic predicates φ
- Abstract values = predicates in DNF: $\bigvee_{i \in I} \bigwedge_{j \in J_i} \varphi_{ij}$
- Widening (hint): keep in $X \nabla Y$ only the conjuncts of X which are still in Y :

$$\left(\bigvee_{i \in I} \bigwedge_{j \in J_i} \varphi_{ij} \right) \nabla \left(\bigvee_{i \in I} \bigwedge_{j \in J'_i} \varphi_{ij} \right) = \left(\bigvee_{i \in I} \bigwedge_{j \in J_i \cap J'_i} \varphi_{ij} \right)$$

Obvious need of **canonical form**.

Is widening useful?

- [Hankin-Hunt, ESOP'92]: All results that you get with widening can also be obtained by computing in a suitable finite lattice.

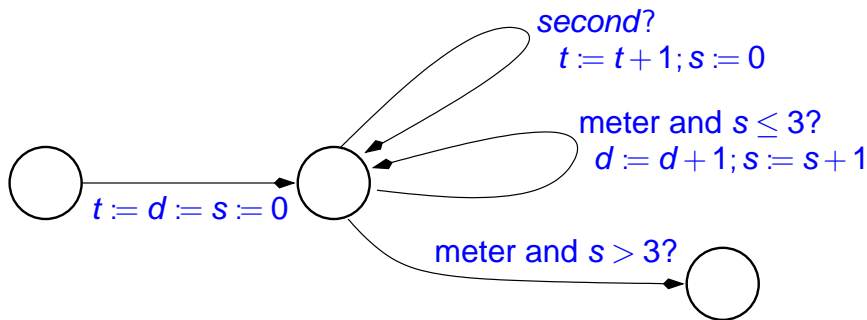
Is widening useful?

- [Hankin-Hunt, ESOP'92]: All results that you get with widening can also be obtained by computing in a suitable finite lattice.
- [Cousot-Cousot, PLILP'92]:
 - For each program, there exists a finite lattice which can be used for this program to obtain results equivalent to those obtained using widening;
 - No such finite lattice will do for all programs;
 - For a particular program, it is not possible to infer the set of needed abstract values by a simple inspection of the text of the program.

The case of convex polyhedra

Linear relation analysis: compute, in each point of a program, a set of linear inequalities invariantly satisfied by the numerical variables.

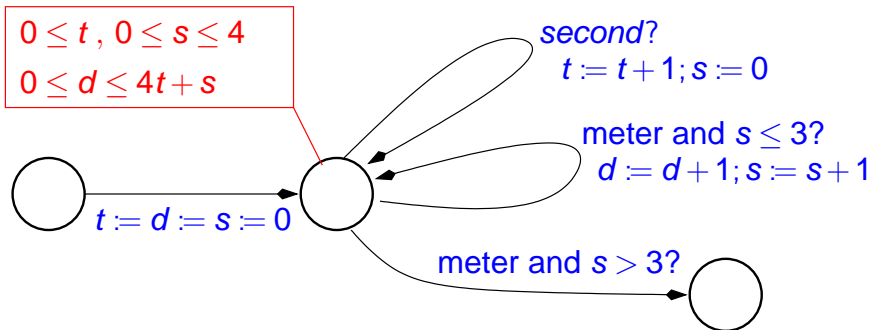
Example: a speedometer (speed limit: 4m/s)



The case of convex polyhedra

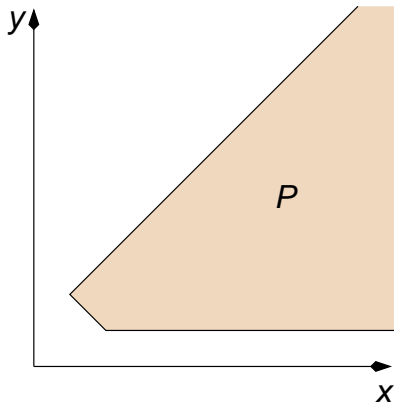
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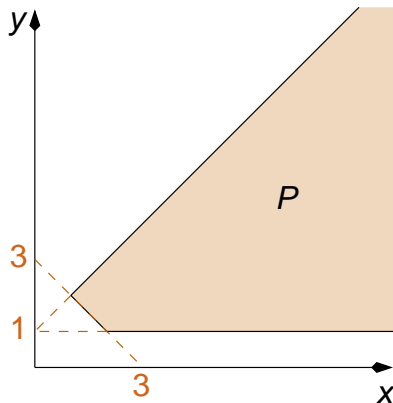
Computing over convex polyhedra (1/2)

The double representation



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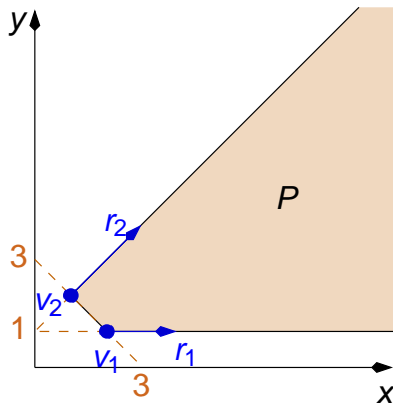
The double representation



$$\begin{aligned}
 P &= \{(x, y) \mid \\
 &\quad 1 \leq y \leq x+1 \wedge x+y \geq 3\} \\
 &= \mathcal{C}(AX \leq b)
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$$\begin{aligned}
 P &= \{\lambda v_1 + (1 - \lambda)v_2 + \mu_1 r_1 + \mu_2 r_2 \mid \\
 &\quad \lambda \in [0, 1], \mu_1, \mu_2 \geq 0\} \\
 &= \mathcal{S}(V, R)
 \end{aligned}$$

Computing over convex polyhedra (2/2)

Common operations:

- intersection:

$$\mathcal{C}(AX \leq B) \cap \mathcal{C}(A'X \leq B') = \mathcal{C}(AX \leq B \wedge A'X \leq B')$$

- convex hull (approximation of union):

$$\mathcal{S}(V, R) \sqcup \mathcal{S}(V', R') = \mathcal{S}(V \cup V', R \cup R')$$

- affine transformation: $CP + D = \{CX + D \mid X \in P\}$

$$\mathcal{S}(C\mathcal{S}(V, R) + D) = \{Cv + D \mid v \in V\}, \{Cr \mid r \in R\}$$

- test for inclusion:

$$\mathcal{S}(V, R) \subseteq \mathcal{C}(AX \leq B) \text{ iff } Av \leq B, \forall v \in V \text{ and } Ar \leq 0, \forall r \in R$$

- test for emptiness: $\mathcal{S}(V, R) = \emptyset$ iff $V = \emptyset$

Standard widening (1/3)

[Cousot-Halbwachs, POPL'78]

Basic idea: keep for $P \nabla Q$ the constraints of P which are still satisfied by Q

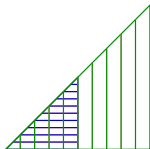
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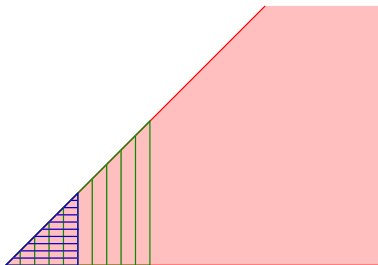
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$$P \nabla Q = \mathcal{C}(0 \leq y \leq x)$$

Standard widening (2/3)

Problem: None of the representations is canonical

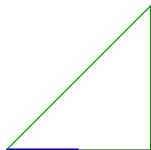
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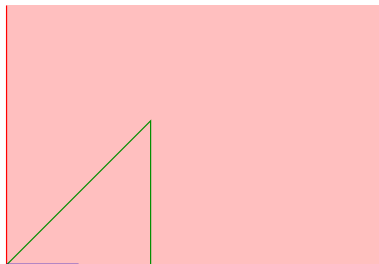
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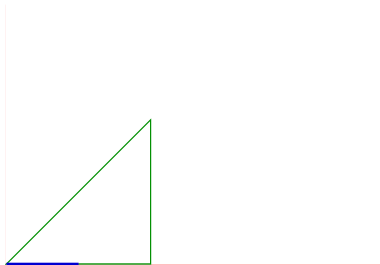
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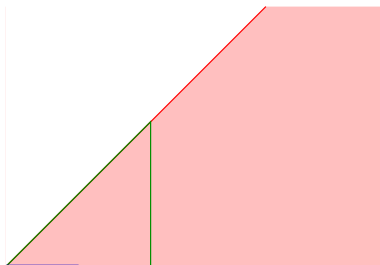
$$\mathcal{C}(0 \leq y \leq x \leq 1, y \leq 0)$$

$$Q = \mathcal{C}(0 \leq y \leq x \leq 2)$$

$$P \nabla Q = \mathcal{C}(0 \leq y, 0 \leq x)$$

Standard widening (2/3)

Problem: None of the representations is canonical



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$$P \nabla Q = \mathcal{C}(0 \leq y, 0 \leq x)$$

$$\mathcal{C}(0 \leq y \leq x)$$

Standard widening (3/3)

Solution [Halbwachs, Thesis 1979]: keep for $P \nabla Q$ the constraints of Q which are **mutually redundant** with constraints of P

(i.e., can replace some constraints of P without changing it)

2 constraints are mutually redundant for P if they are saturated by the same generators of P .

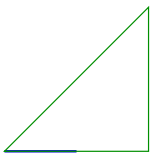
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$$P = \mathcal{C}(y = 0, 0 \leq x \leq 1)$$

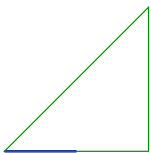
$$Q = \mathcal{C}(0 \leq y \leq x \leq 2)$$

Standard widening (3/3)

Solution [Halbwachs, Thesis 1979]: keep for $P \nabla Q$ the constraints of Q which are **mutually redundant** with constraints of P

(i.e., can replace some constraints of P without changing it)

2 constraints are mutually redundant for P if they are saturated by the same generators of P .



$$P = \mathcal{C}(y = 0, 0 \leq x \leq 1)$$

$$Q = \mathcal{C}(0 \leq y \leq x \leq 2)$$

$0 \leq y$ already in P

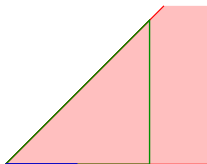
$y \leq x$ mut. red. with $0 \leq x$ in P

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$$P = \mathcal{C}(y = 0, 0 \leq x \leq 1)$$

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$$0 \leq y \text{ already in } P$$

$$y \leq x \text{ mut. red. with } 0 \leq x \text{ in } P$$

$$P \nabla Q = \mathcal{C}(0 \leq y \leq x)$$

Chain condition: either the number of constraints decreases, or the dimension increases

Improving the precision

- delaying the widening
- improve the operator
- take the program into account

Delaying the widening (1/2)

[Folk!], [Halbwachs, CAV'93], [Goubault, SAS'01],
[Blanchet et al., PLDI'03]

Instead of computing

$$X_0 = \perp, X_1 = X_0 \nabla F(X_0), X_2 = X_1 \nabla F(X_1) \dots X_{n+1} = X_n \nabla F(X_n)$$

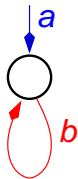
fix $k > 0$ and compute

$$X_n = \begin{cases} \perp & \text{if } n = 0 \\ F(X_{n-1}) & \text{if } n \leq k \\ X_{n-1} \nabla F(X_{n-1}) & \text{if } n > k \end{cases}$$

or, more generally, apply the widening sporadically but infinitely often.

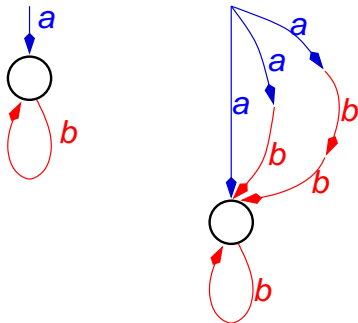
Delaying the widening (2/2)

Delay, loop unrolling



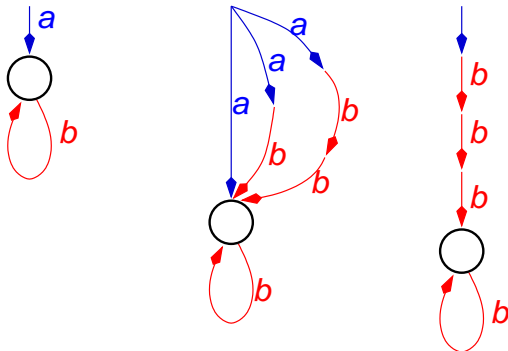
Delaying the widening (2/2)

Delay, loop unrolling



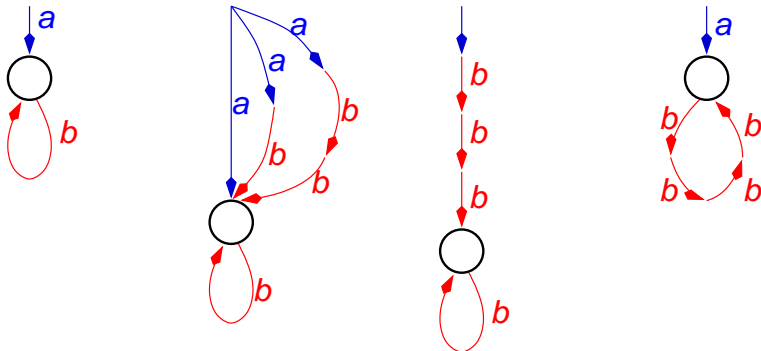
Delaying the widening (2/2)

Delay, loop unrolling



Delaying the widening (2/2)

Delay, loop unrolling



Easy, but often expensive.

The suitable number of delays or unrolling may depend on the program.

Improving the widening operator (1/4)

Correct and incorrect improvements of the standard widening on polyhedra

[Bagnara-Hill-Ricci-Zaffanella, SAS'03 and SCP'05] Hint:

$$P \nabla Q = \begin{cases} P \sqcup Q & \begin{cases} \text{if } \dim(Q) > \dim(P) \\ \text{or } \text{codim}(Q) > \text{codim}(P) \\ \text{or } \# \mathcal{C}_P > \# \mathcal{C}_{P \sqcup Q} \\ \text{or } \# V_P > \# V_{P \sqcup Q} \\ \text{or } \dots \end{cases} \\ P \nabla_S Q & \text{otherwise} \end{cases}$$

- Correct widening
- $\forall P, Q, P \nabla Q \subseteq P \nabla_S Q$
- Generally* better than the standard widening.

Improving the widening operator (2/4)

- The widening is generally not monotonic.
- So, the fact that $P\nabla_1 Q \subseteq P\nabla_2 Q$ does not imply that the limit computed with ∇_1 will be better than the one provided by ∇_2 .
- May slow down the convergence.
- **Ideal goal:** Converge **fast** towards a **precise** limit.

Improving the widening operator (3/4)

An attractive idea:

We look for the limit of the sequence $(X_n)_{n>0}$.

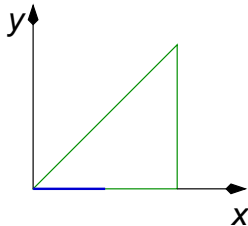
- Add a new variable k (loop counter)
- Set $X'_n = X_n \wedge (k = n)$
- express X'_n as a function of k , and let k tend to ∞ .

More precisely,

- Compute $X'_1 = (X_0 \wedge k = 0) \sqcup (X_1 \wedge k = 1)$.
- Forget the constraint $k \leq 1$ in X'_1
- Eliminate k by existential quantification.

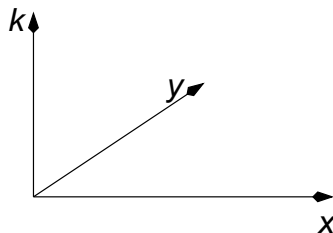
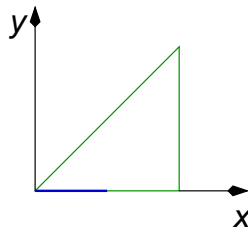
Improving the widening operator (4/4)

Example:



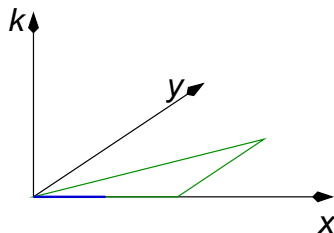
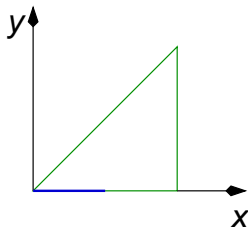
Improving the widening operator (4/4)

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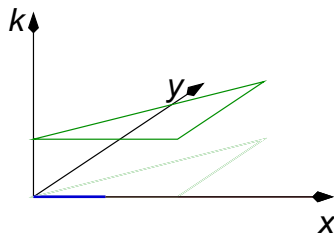
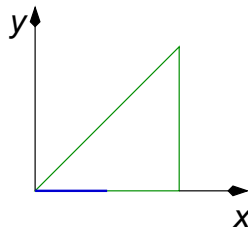
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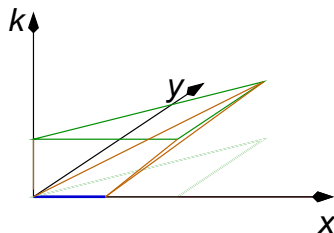
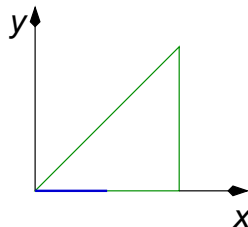
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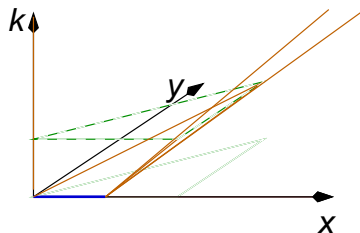
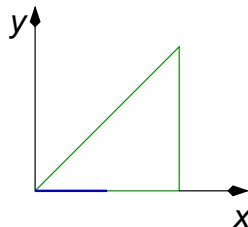
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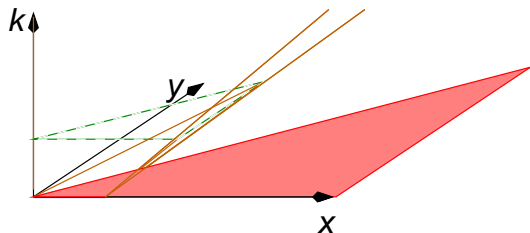
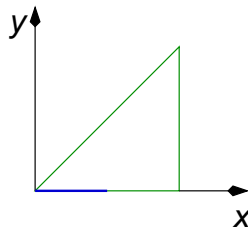
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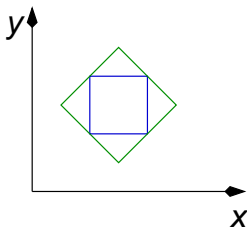
Improving the widening operator (4/4)

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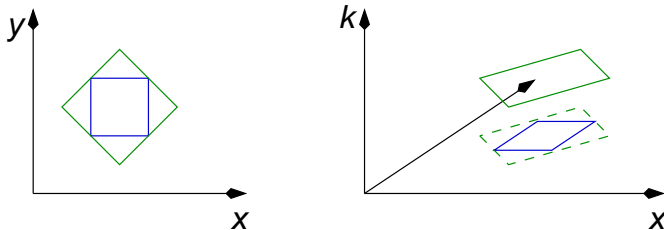
Improving the widening operator (4/5)

Unfortunately incorrect (does not fulfill the chain condition)



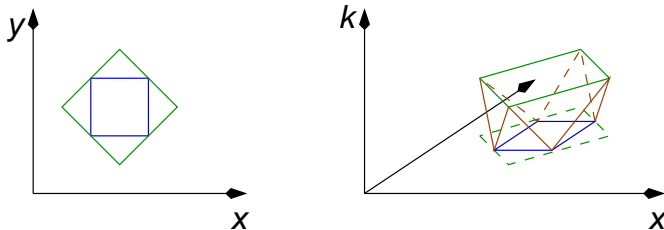
Improving the widening operator (4/5)

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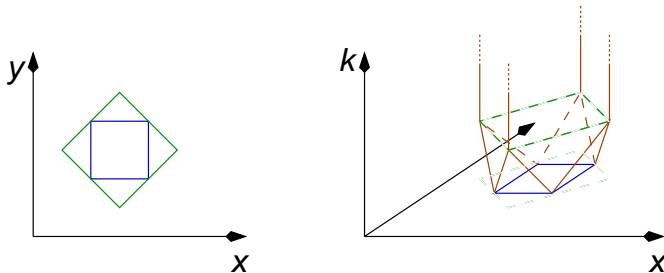
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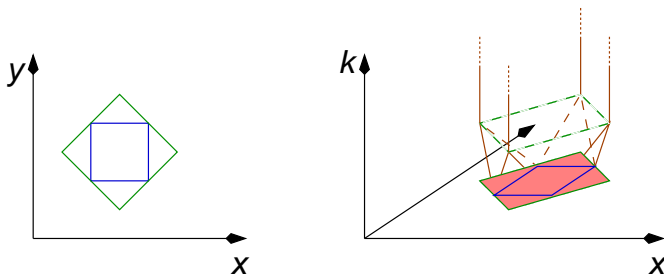
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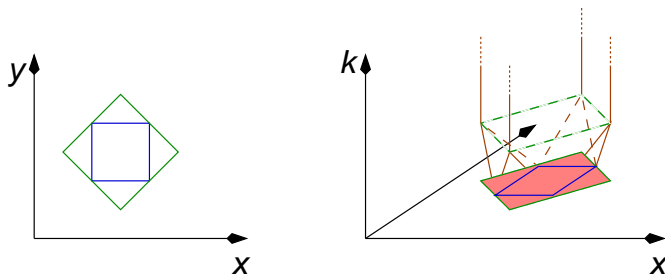
Improving the widening operator (4/5)

Unfortunately incorrect (does not fulfill the chain condition)



Improving the widening operator (4/5)

Unfortunately incorrect (does not fulfill the chain condition)



But adding loop counters often improves the precision of normal widening.

Taking the program into account

The widening $X \nabla F(X)$ uses the result $F(X)$ of F , but doesn't look into F .

Looking at F , i.e., at the program, can help in improving the precision:

- limited widening
- new control path
- (abstract) acceleration

Limited widening (1/2)

[Halbwachs, CAV'93], [Blanchet et al., PLDI'03]

Let C be a fixed finite set of linear constraints, then ∇_C^L defined by:

$$P \nabla_C^L Q = (P \nabla Q) \cap \mathcal{C}(\{c \in C \mid P \models c \wedge Q \models c\})$$

is a widening

Limited widening (1/2)

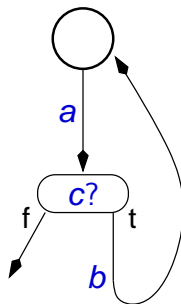
[Halbwachs, CAV'93], [Blanchet et al., PLDI'03]

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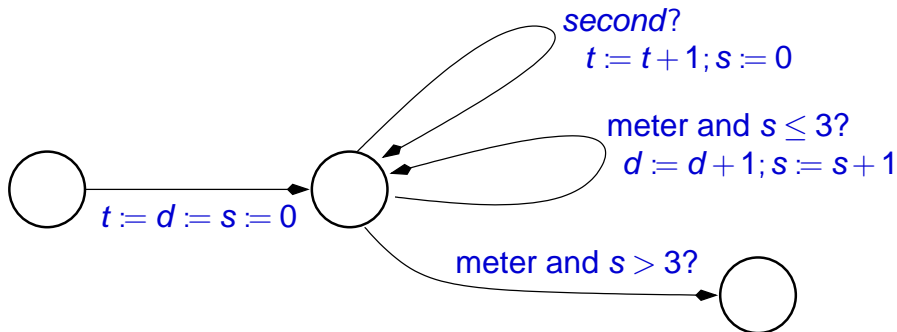
Choice of limiting constraints:



$$b(c) \in C$$

Limited widening (1/2)

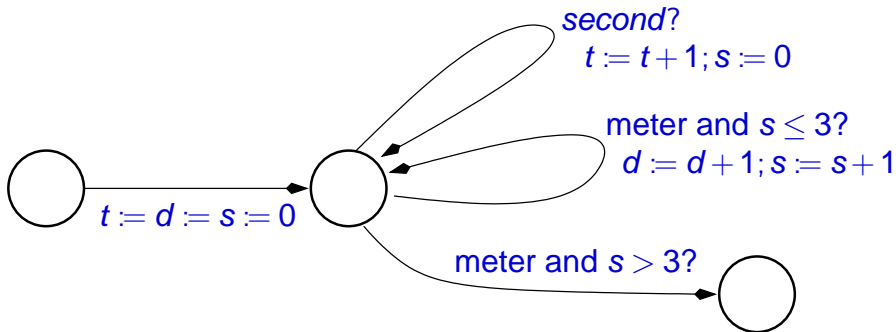
Example: speedometer



Limit the widening with $[s := s + 1](s \leq 3) = (s \leq 4)$.

Limited widening (1/2)

Example: speedometer



Limit the widening with $[s := s + 1](s \leq 3) = (s \leq 4)$.

Very efficient, often makes the descending sequence useless, sometimes gives better results than the descending sequence.

New control path (1/3)

The basic assumption behind the widening is that “the program behaves regularly” (inside a loop of the program)

Not true when some path in the loop is not feasible at first iterations.

```

i := j := 0 := k := 0;
while i' <= 100 do
  i := i+2; j := j+1;
  if ? then k := k+1;
  if j = 10 then
    j := 0; k := k+1;
end

```



New control path (1/3)

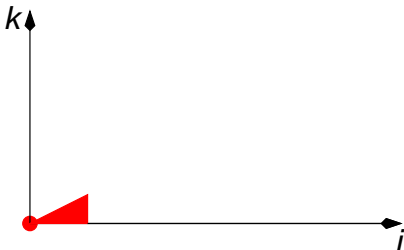
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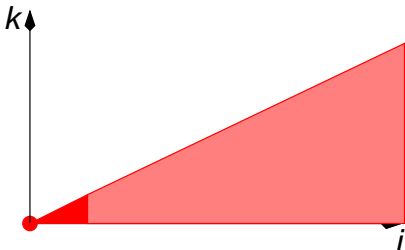
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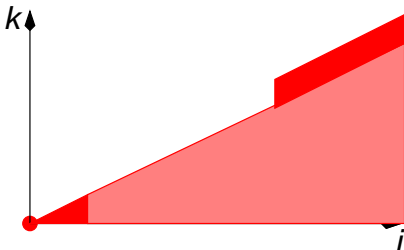
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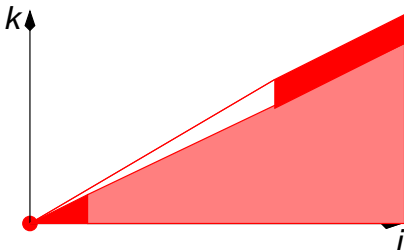
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New control path (1/3)

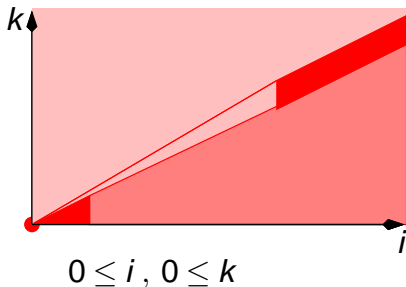
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end

```



New control path (2/3)

Solutions: If, at step n , a previously unfeasible path in the loop becomes feasible,

- either don't widen at this step [Astrée]
- or take $X_0 \nabla X_n$, instead of $X_{n-1} \nabla X_n$ [Halbwachs, CAV'93]

Can occur only finitely many times!

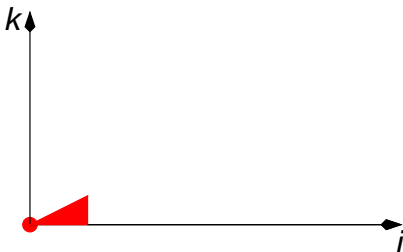
New control path (3/3)

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```



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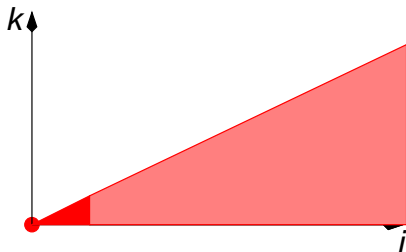


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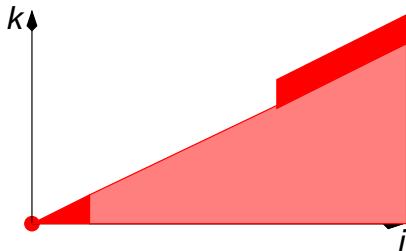


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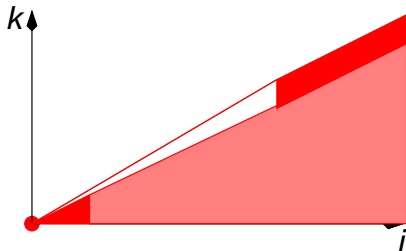


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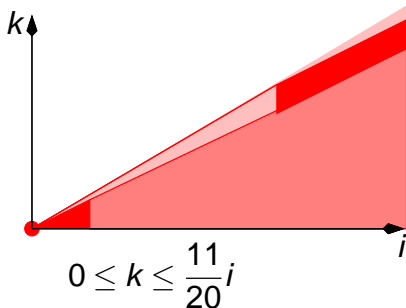


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```



Exact computations

Are there cases where the effect of a loop can be computed exactly?

- loop acceleration
- exact abstract computation

Loop acceleration (1/3)

Exact computations in Presburger arithmetic (for a widening in Presburger arithmetic, see [Bultan-Gerber-Pugh, CAV'97])

Convergence using **loop acceleration**

[Boigelot-Wolper, CAV'94 and CAV'98], [Common-Jurski, CAV'98], [Finkel-Sutre, MFCS'00], [Bardin et al., CAV'03]

τ being a relation in $\mathbb{N}^n \times \mathbb{N}^n$, in which cases can we compute exactly $\tau^* = \bigcup_{k \in \mathbb{N}} \tau^k$ or $\tau^*(X_0)$?



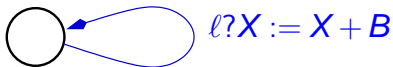
Loop acceleration (2/3)

- Restrictions on τ (e.g., $\ell(X) \wedge X' = X + B$, or $\ell(X) \wedge X' \# X + B$, $\# \in \{\leq, =, \geq\}$), **flat** automata (without nested loops), ...
 → exact computation in Presburger arithmetic
- Semi-algorithms for more general cases **[FAST]**

But,

- Exact computation does not scale up
- What to do with programs which don't meet the restrictions?

Loop acceleration (3/3)

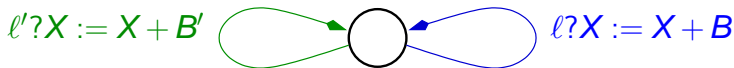


Loop acceleration (3/3)



$\tau^*(X_0) = \ell(X_0) \wedge \exists i \geq 0, X = X_0 + iB \wedge \ell(X_0 + (i-1)B)$
 is a Presburger formula

Loop acceleration (3/3)



$\tau^*(X_0) = \ell(X_0) \wedge \exists i \geq 0, X = X_0 + iB \wedge \ell(X_0 + (i-1)B)$
 is a Presburger formula

Not true for interleaving of transitions

Exact abstract computations (1/3)

In which cases can we solve exactly the **abstract** fixpoint equation?

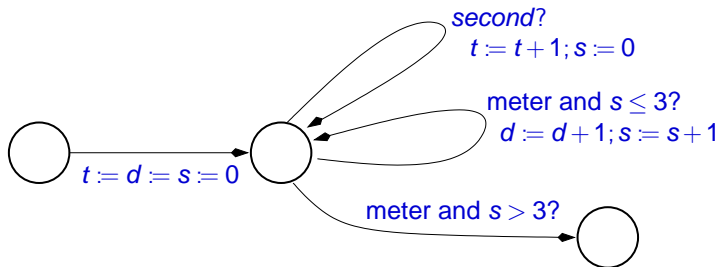
[Su-Wagner, TACAS'04]: Exact computation of the least fixpoint in interval analysis (in polynomial time)

using, basically, a suitable limited widening

Exact abstract computations (2/3)

Abstract acceleration on polyhedra [Gonnord-Halbwachs06]

Example: the speedometer in one abstract acceleration:



Exact abstract computations (3/3)

The speedometer in one abstract acceleration:

```
t:=d:=s:=0;  
while true do  
   $s \leq 3$  : s++; d++  
  □  
  true: t++; s:=0  
end
```



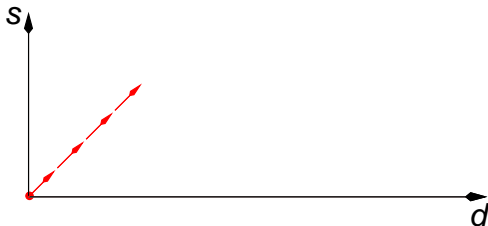
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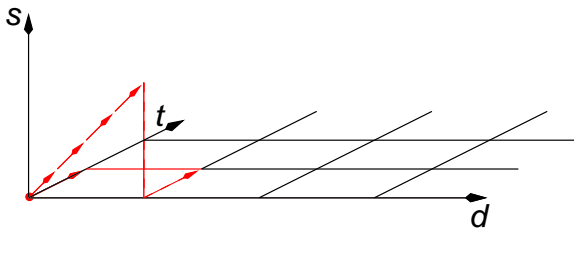
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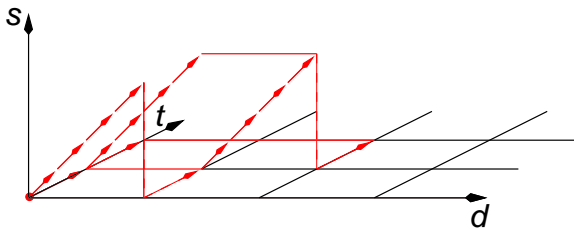
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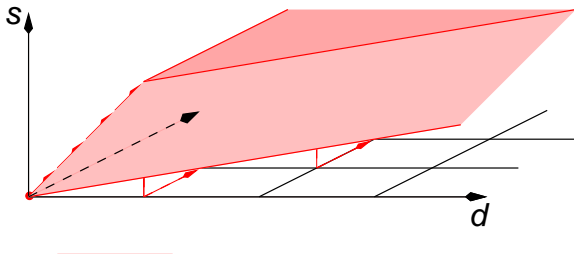
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Exact abstract computations (3/3)

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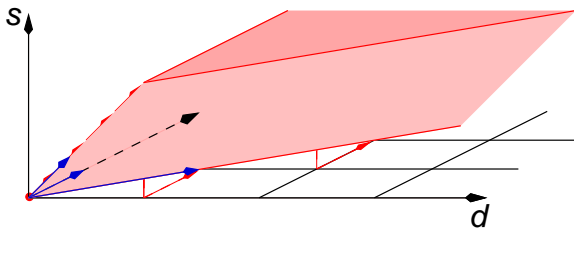
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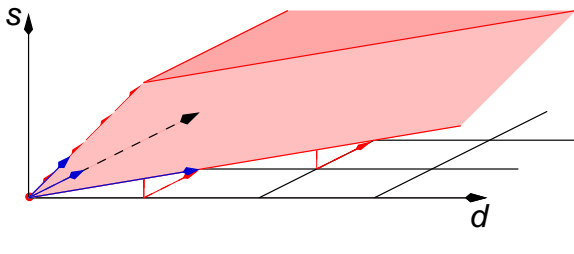
Exact abstract computations (3/3)

The speedometer in one abstract acceleration:

```

t:=d:=s:=0;
while true do
  s≤3 : s++; d++
□
  true: t++; s:=0
end

```



$$\begin{aligned}
 P &= (\{(0,0,0)\} \nearrow \{(1,0,0), (0,1,1), (1,4,0)\}) \cap (s \leq 4) \\
 &= (t \geq 0, 0 \leq s \leq 4, 0 \leq d \leq 4t + s)
 \end{aligned}$$

Exact abstract computations (4/3)

Obvious advantages:

- when it applies, it is both more precise and more efficient
- easy to combine with widening

Conclusions

- Widening is more than a dirty heuristic
 - it is based on a reasonable hypothesis:
Regular, foreseeable programs should be easy to analyse
 - It allows to work in quite expressive lattices.
 - It allows general programs to be analysed.
- It may be more effective to use well-chosen application strategies, (e.g., limited widening, specific cases when new pathes are discovered), than to endlessly look for “better” widening.
- Looking at the program can lead to significant improvements.