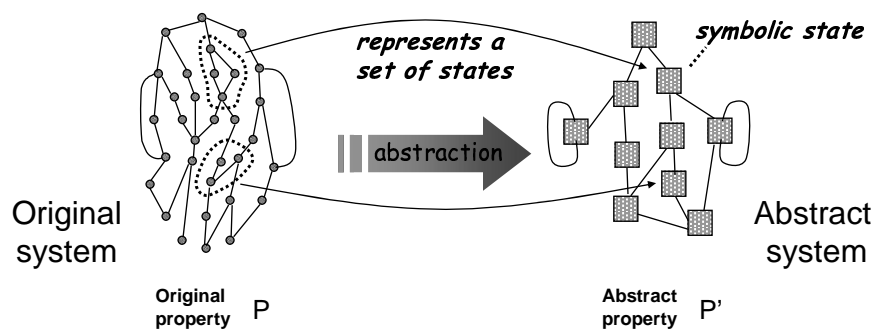


Abstraction of Source Code

(from Bandera lectures and talks)

Abstraction: the key to scaling up

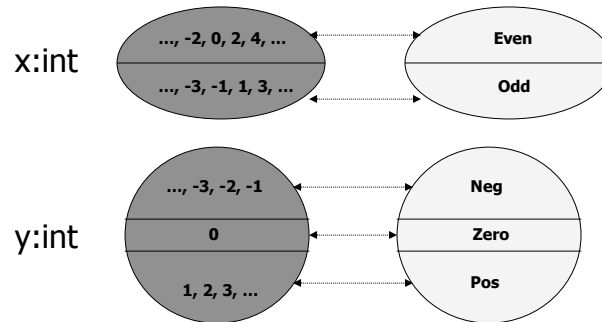


Safety: The set of behaviors of the abstract system over-approximates the set of behaviors of the original system

Data Abstraction

- Data Abstraction

- Abstraction proceeds component-wise, where variables are components



Data Type Abstraction

Collapses data domains via abstract interpretation:

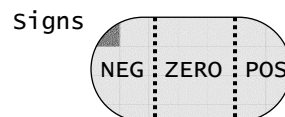
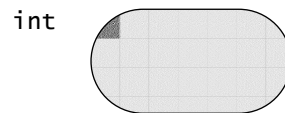
Code

```
int x = 0;
if (x == 0)
  x = x + 1;
```



```
Signs x = ZERO;
if (Signs(x) == ZERO)
  x = Signs(x) + POS;
```

Data domains



(n<0) : NEG
(n==0) : ZERO
(n>0) : POS

Hypothesis

Abstraction of data domains is necessary

Automated support for

- Defining abstract domains (and operators)
- Selecting abstractions for program components
- Generating abstract program models
- Interpreting abstract counter-examples

will make it possible to

- Scale property verification to realistic systems
- Ensure the safety of the verification process

Definition of Abstractions in BASL

```

st0000ti0n Signs 00st000ts int
00gin
00ENS = 0 NEG0 ZERO0 POS 0;

00st000t(n)
00gin
  n < 0 0> 0NEG0;
  n == 0 0> 0ZERO0;
  n > 0 0> 0POS0;
0n0
  
```

Automatic
Generation

```

00000t00 + 000
00gin
  (NEG 0 NEG) 0> 0NEG0 ←
  (NEG 0 ZERO) 0> 0NEG0 ;
  (ZERO 0 NEG) 0> 0NEG0 ;
  (ZERO 0 ZERO) 0> 0ZERO0 ;
  (ZERO 0 POS) 0> 0POS0 ;
  (POS 0 ZERO) 0> 0POS0 ;
  (POS 0 POS) 0> 0POS0 ;
  (000) 0> 0NEG0ZERO0POS0;
  00 00S0 (POS0NEG0)(NEG0POS0) 00
0n0
  
```

Example: Start safe, then refine: $+(NEG \sqsubseteq NEG) = \sqsubseteq NEG \sqsubseteq ZERO \sqsubseteq POS$

Proof obligations submitted to PVS...

- 000000 n10n0: n0g0(n1) 0n0 n0g0(n0) i000i0s n0t 00s0(n1+n0) ✓
- 000000 n10n0: n0g0(n1) 0n0 n0g0(n0) i000i0s n0t 00000(n1+n0) ✓
- 000000 n10n0: n0g0(n1) 0n0 n0g0(n0) i000i0s n0t n0g0(n1+n0) ✗

Compiling BASL Definitions

```

00000000 int Signs 00000000 int
00000000
00000000 NEG 00000000 POS 0;

00000000(n)
00000000
    n < 0    00000000 NEG;
    n == 0    00000000 ZERO;
    n > 0    00000000 POS;

00000000

00000000 + 00000000
00000000
    (NEG 00000000 NEG) 00000000 NEG;
    (NEG 00000000 ZERO) 00000000 NEG;
    (ZERO 00000000 NEG) 00000000 NEG;
    (ZERO 00000000 ZERO) 00000000 ZERO;
    (ZERO 00000000 POS) 00000000 POS;
    (POS 00000000 ZERO) 00000000 POS;
    (POS 00000000 POS) 00000000 POS;
    (00000000) 00000000 NEG ZERO POS;
    00000000 00000000 (POS NEG) (NEG POS) 00000000
    00000000

```

Compiled

```

00000000 Signs 0
00000000 statio finoo int NEG = 0; 00 00so 1
00000000 statio finoo int ZERO = 1; 00 00so 1
00000000 statio finoo int POS = 0; 00 00so 1
00000000 statio int oos(int n) 0
    if (n < 0) 00000000 NEG;
    if (n == 0) 00000000 ZERO;
    if (n > 0) 00000000 POS;
0
00000000 statio int 000(int oogl1 int oogl0 int oogl0) 0
    if (oogl1==NEG 00 00ogl0==NEG) 00000000 NEG;
    if (oogl1==NEG 00 00ogl0==ZERO) 00000000 NEG;
    if (oogl1==ZERO 00 00ogl0==NEG) 00000000 NEG;
    if (oogl1==ZERO 00 00ogl0==ZERO) 00000000 ZERO;
    if (oogl1==ZERO 00 00ogl0==POS) 00000000 POS;
    if (oogl1==POS 00 00ogl0==ZERO) 00000000 POS;
    if (oogl1==POS 00 00ogl0==POS) 00000000 POS;
    00000000 00000000000000000000(0);
    00 00so (POS NEG) (NEG POS) 00
0

```

Interpreting Results

- For an abstracted program, a counter-example may be infeasible because:
 - Over-approximation introduced by abstraction
- Example:

```
x = -2;  if(x + 2 == 0) then ...  
x = NEG; if(Signs.eq(Signs.add(x,POS),ZERO)) then ...  
                {NEG,ZERO,POS}
```

Choose-free state space search

- **Theorem [Saidi:SAS'00]**

Every path in the abstracted program where all assignments are deterministic is a path in the concrete program.

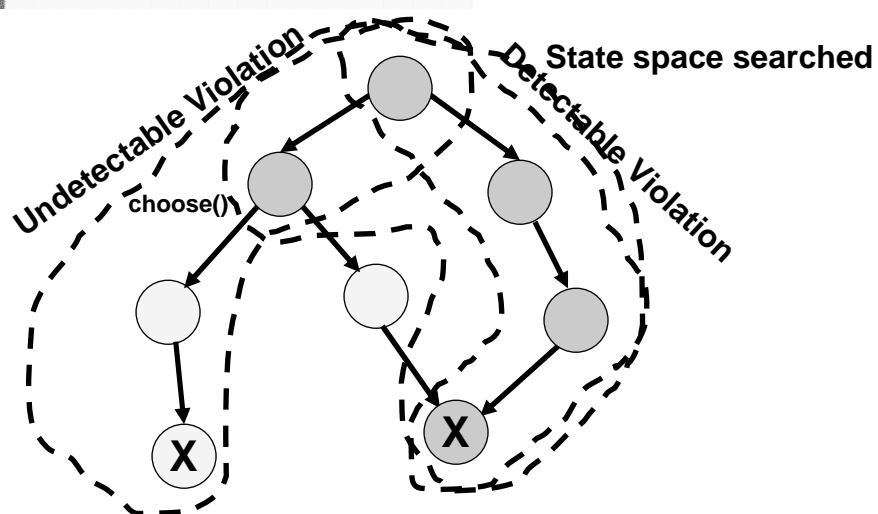
- **Bias the model checker**

- to look only at paths that do not include instructions that introduce non-determinism

- **JPF model checker modified**

- to detect non-deterministic choice (i.e. calls to `Bandera.choose()`); backtrack from those points

Choice-bounded Search



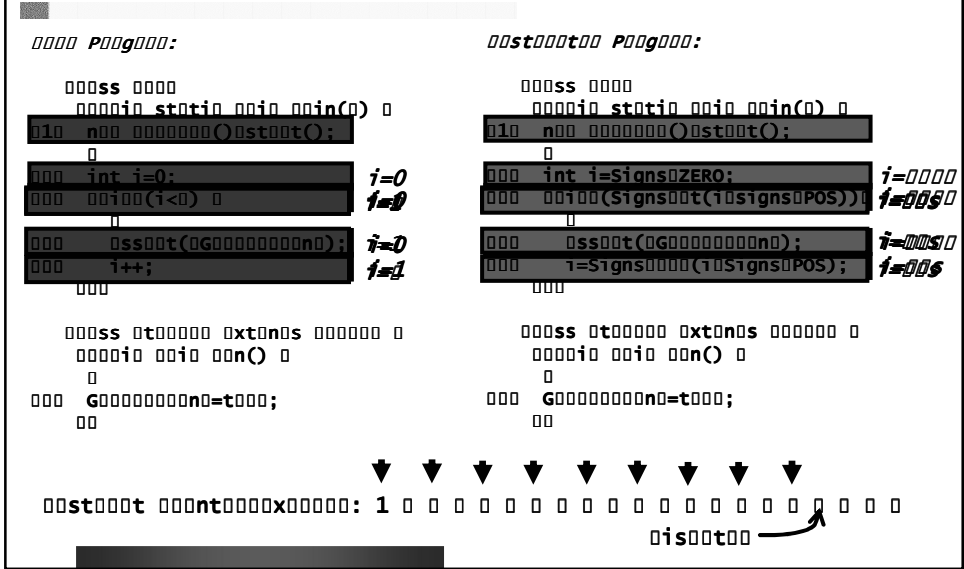
Counter-example guided simulation

- Use abstract counter-example to guide simulation of concrete program
- Why it works:
 - Correspondence between concrete and abstracted program
 - Unique initial concrete state

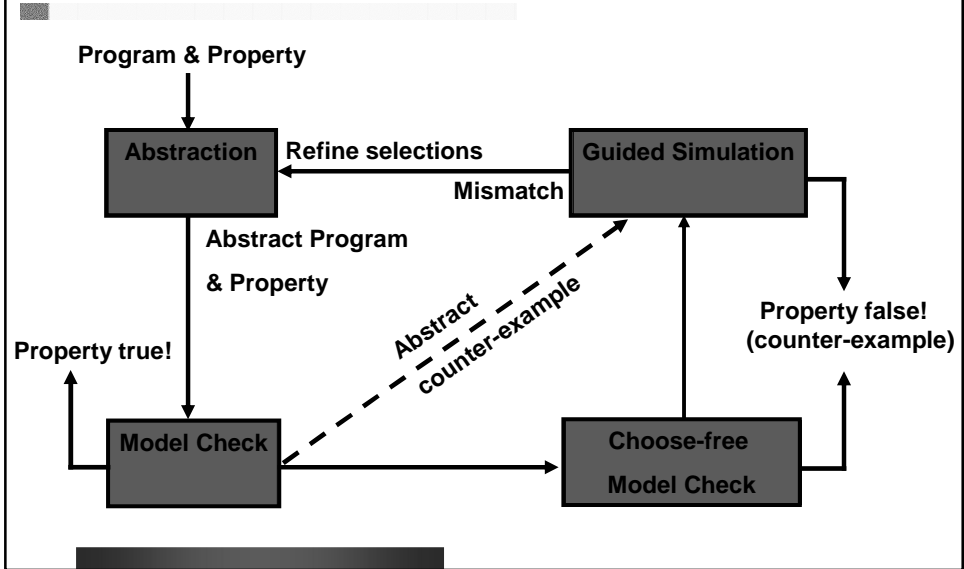
Example of Abstracted Code

```
0000 P00g000:  
000ss 0000  
0000io st0tio 00io 00in(0) 0  
010 n00 00000000()0st00t();  
0  
000 int i=0;  
000 00i00(i<0) 0  
0  
000 0ss00t(0G000000000n0);  
000 i++;  
000  
000ss 0t00000 0xt0n0s 000000 0  
0000io 00io 00n() 0  
0  
000 G000000000n0=t000;  
00  
0000s00f000 000nt0000x00000: 1 0 0 0 0 0 0 0  
  
00st000t00 P00g000:  
000ss 0000  
0000io st0tio 00io 00in(0) 0  
010 n00 00000000()0st00t();  
0  
000 int i=Signs0ZERO; 0inis00  
000 00i00(Signs00t(i0signs0POS))0 i=0000  
0  
000 0ss00t(0G000000000n0);  
000 i=Signs0000(i0Signs0POS);  
000  
000ss 0t00000 0xt0n0s 000000 0  
0000io 00io 00n() 0  
0  
000 G000000000n0=t000;  
00
```

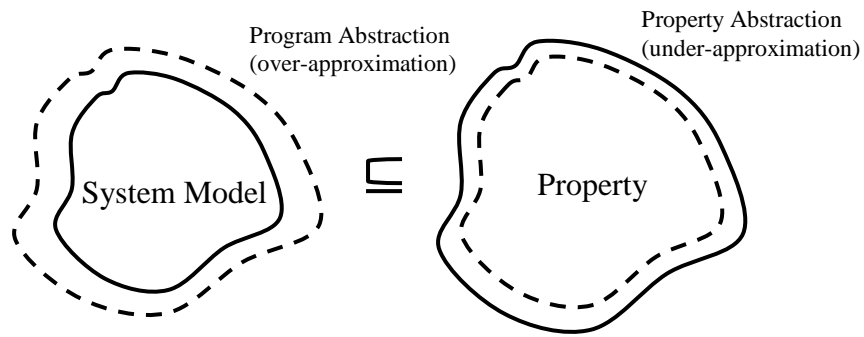
Example of Abstracted Code



Hybrid Approach



Property Abstraction



If the *abstract property* holds on the *abstract system*, then the *original property* holds on the *original system*

Property Abstraction

Properties are temporal logic formulas, written in negational normal form.

Abstract propositions under-approximate the truth of concrete propositions.

Examples:

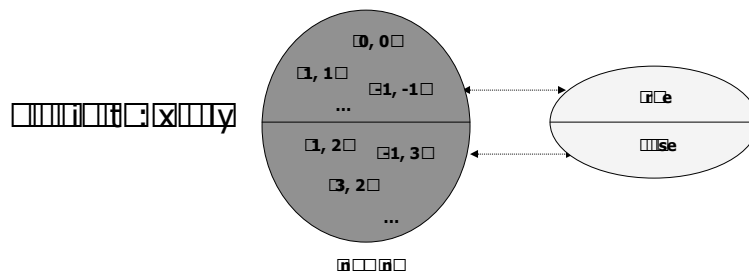
- **Invariance property:** $\Box (x > -1)$
- **Abstracted to:** $\Box ((x = \text{zero}) \rightarrow (x = \text{pos}))$

- **Invariance property:** $\Box (x > -2)$
- **Abstracted to:** $\Box ((x = \text{zero}) \rightarrow (x = \text{pos}))$

Predicate Abstraction

- Predicate Abstraction

- Use a boolean variable to hold the value of an associated predicate that expresses a relationship between variables



An Example

```
Unit:
  x := 0; y := 0; z := 1;
  goto loop;

loop:
  assert (y = 1);
  x := (x + 1);
  y := (y + 1);
  if (x = y) then z1 := z; z0 := z;

z1: y := 1;
  goto loop;

z0: y := 0;
  goto loop;
```

- x and y are unbounded
- Data abstraction does not work in this case --- abstracting component-wise (per variable) cannot maintain the *relationship* between x and y
- We will use predicate abstraction in this example

Predicate Abstraction Process

- Add boolean variables to your program to represent current state of particular predicates
 - E.g., add a boolean variable $\Box x = \Box$ to represent whether the condition $x = \Box$ holds or not
- These boolean variables are updated whenever program statements update variables mentioned in predicates
 - E.g., add updates to $\Box x = \Box$ whenever x or \Box or assigned

An Example

```

init:
  x := 0;  y := 0;  z := 1;
  goto loop;

loop:
  assert (y = 1);
  x := (x + 1);
  y := (y + 1);
  if (x = y) then z1 := z; z0;

z1:  y := 1;
  goto loop;

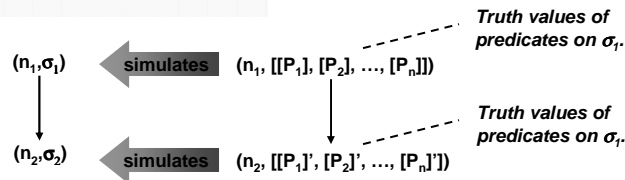
z0:  y := 0;
  goto loop;
  
```

- We will use the predicates listed below, and remove variables x and y since they are unbounded.
- Don't worry too much yet about how we arrive at this particular set of predicates; we will talk a little bit about that later

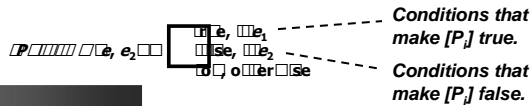
Predicates	Boolean Variables
$\Box 1: (x = 0)$	$\Box 1: \Box(x = 0)\Box$
$\Box 2: (y = 0)$	$\Box 2: \Box(y = 0)\Box$
$\Box 3: (x = (y + 1))$	$\Box 3: \Box(x = (y + 1))\Box$
$\Box 4: (x = y)$	$\Box 4: \Box(x = y)\Box$

This is our new syntax for representing boolean variables that helps make the correspondence to the predicates clear

Computing Abstracted Programs

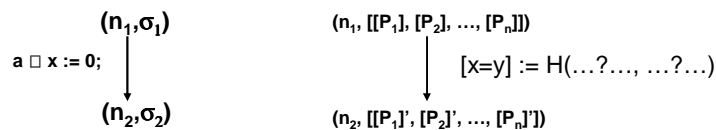


- For each statement s in the original program, we need to compute a new statement that describes how the given predicates change in value due to the effects of s .
- To do this for a given predicate P_i , we need to know if we should set $[P_i]$ to true or false in the abstract target state.
- Thus, we need to know the conditions at (n_1, σ_1) that guarantee that $[P_i]$ will be true in the target state and the conditions that guarantee that $[P_i]$ will be false in the target state. These conditions will be used in the helper function H .



Computing Abstracted Programs

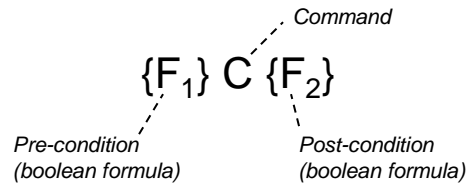
Example



- What conditions have to hold before a is executed to guarantee that $x=y$ is true (false) after a is executed?
 - Note: we want the least restrictive conditions
- The technical term for what we want is the “weakest pre-condition of a with respect to $x=y$ ”

Let's take a little detour to learn about weakest preconditions.

Floyd-Hoare Triples



A triple is a logical judgement that holds when the following condition is met:

For all states s that satisfies F_1 (I.e., $s \models F_1$), if executing C on s terminates with a state s' , then $s' \models F_2$.

Weaker/Stronger Formulas

- If $F' \models F$ (F' implies F), we say that F is weaker than F' .
- Intuitively, F' contains at least as much information as F because whatever F says about the world can be derived from F' .
- Intuitively, stronger formulas impose more restrictions on states.

Thinking in terms of sets of states...

Let $S_{F'} = \{s \mid s \models F'\}$ Note that $S_{F'} \subseteq S_F$ since F' imposes more restrictions than F
 $S_F = \{s \mid s \models F\}$

Question: what formula is the weakest of all? (In other words, what formula describes the largest set of states? What formula imposes the least restrictions?)

Weakest Preconditions

The *weakest precondition* of C with respect to F_2 (denoted $WP(C, F_2)$) is a formula F_1 such that

$$\{F_1\} C \{F_2\}$$

and for all other F'_1 such that $\{F'_1\} C \{F_2\}$,
 $F'_1 \sqsubseteq F_1$ (F_1 is weaker than F'_1).

- This notion is useful because it answers the question: “what formula F_1 captures the fewest restrictions that I can impose on a state s so that when $s' = [[C]]s$ then $s' \models F_2$?”
- WP is interesting for us when calculating predicate abstractions because for a given command C and boolean variable $[P_i]$, we want to know the least restrictive conditions that have to hold before C so that we can conclude that P_i is definitely true (false) after executing C .

Calculating Weakest Preconditions

Calculating WP for assignments is easy:

$$WP(x := e, F) = F[x \sqsubseteq e]$$

- Intuition: x is going to get a new value from e , so if F has to hold after $x := e$, then $F[x \sqsubseteq e]$ is required to hold before $x := e$ is executed.

Examples

$$WP(x := 0, x = y) = (x = y)[x \sqsubseteq 0] = (0 = y)$$

$$WP(x := 0, x = y + 1) = (x = y + 1)[x \sqsubseteq 0] = (0 = y + 1)$$

$$WP(x := x + 1, x = y + 1) = (x = y + 1)[x \sqsubseteq x + 1] = (x + 1 = y + 1)$$

Calculating Weakest Preconditions

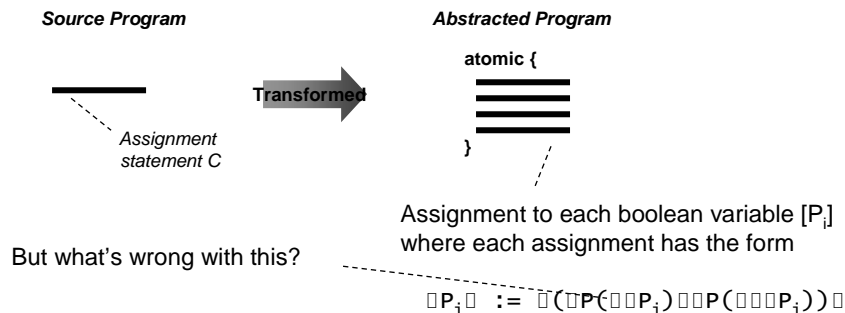
Calculating WP for other commands (state transformers):

$$\begin{aligned} \text{WP}(\text{skip}, F) &= F \\ \text{WP}(\text{assert } e, F) &= e \sqcap F \quad (\sqcap e \sqcap F) \\ \text{WP}(\text{assume } e, F) &= e \sqcap F \quad (\sqcap e \sqcap F) \end{aligned}$$

- Skip: since the store is not modified, then F will hold afterward iff it holds before.
- Assert and Assume: even though we have a different operational interpretation of assert and assume in the verifier, the definition of WP of these rely on the fact that we assume that if an assertion or assume condition is violated, it's the same as the command "not completing". Note that if e is false, then the triple $\{(\sqcap e \sqcap F)\} \text{ assert } e \{F\}$ always holds since the command never completes for any state.

Assessment

Intuition:



Answer: the predicates P_i refer to concrete variables, and the entire purpose of the abstraction process is to remove those from the program. The point is that the conditions in the 'H' function should be stated in terms of the boolean variables $[P_i]$ instead of the predicates P_i .

Assessment

- In the case of $x := 0$ and the predicate $x = y$, we have

$$WP(x := 0, x=y) = (0=y)$$

$$WP(x := 0, !x=y) = !(0=y)$$

- In this case, the information in the predicate variables is enough to decide whether $0=y$ holds or not. That is, we can simply generate the assignment statement

$\square(x=\square) \square := \square(\square\square(\square = 0)\square\square\square\square(\square=0)\square);$

Assessment

- In the case of $x := 0$ and the predicate $x = (y+1)$, we have

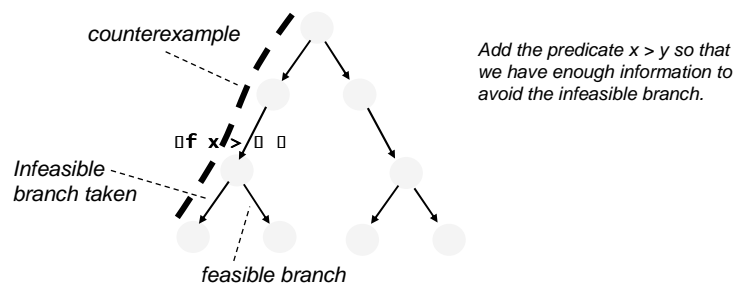
$$WP(x := 0, (x=y+1)) = (0=y+1)$$

$$WP(x := 0, !(x=y+1)) = !(0=y+1)$$

- In this case, we don't have a predicate variable $[0=y+1]$.
- We must consider combinations of our existing predicate variables that imply the conditions above. That is, we consider *stronger (more restrictive, less desirable but still useful)* conditions formed using the predicate variables that we have.

What Are Appropriate Predicates?

- In general, a difficult question, and subject of much research
- Research focuses on automatic discovery of predicates by processing (infeasible) counterexamples
- If a counterexample is infeasible, add predicates that allow infeasible branches to be avoided



What Are Appropriate Predicates?

Some general heuristics that we will follow

- Use the predicates A mentioned in property P , if variables mentioned in predicates are being removed by abstraction
 - At least, we want to tell if our property predicates are true or not
- Use predicates that appear in conditionals along “important paths”
 - E.g., $(x = 0)$
- Predicates that allow predicates above to be decided
 - E.g., $(x = 0) \vee (y = 0) \vee (x = (y + 1))$

Interpreting Results

Example of Infeasible Counter-example

```

    000
    010 if (00 + 0 > 0)
        t00n
    000 0ss00t(t000);
    00s0
    000 0ss00t(f00s0);
    000
  
```



NEG ZERO POS

```

    000
    010 if(Signs0gt(Signs0000 (NEG0POS)0ZERO))
        t00n
    000 0ss00t(t000);
    00s0
    000 0ss00t(f00s0);
    000
  
```

