

Computation Tree Logic

Readings: Huth, Ryan, 3.2-3.4

Computational tree logic - propositional branching time logic, permitting explicit quantification over all possible futures.

Fixed set of atomic formulas (p, q, r), standing for atomic descriptions of a system:

The printer is busy

There are currently no requested jobs for the printer

Conveyor belt is stopped

Choice of atomic propositions depends on our intension (but usually does not involve time)

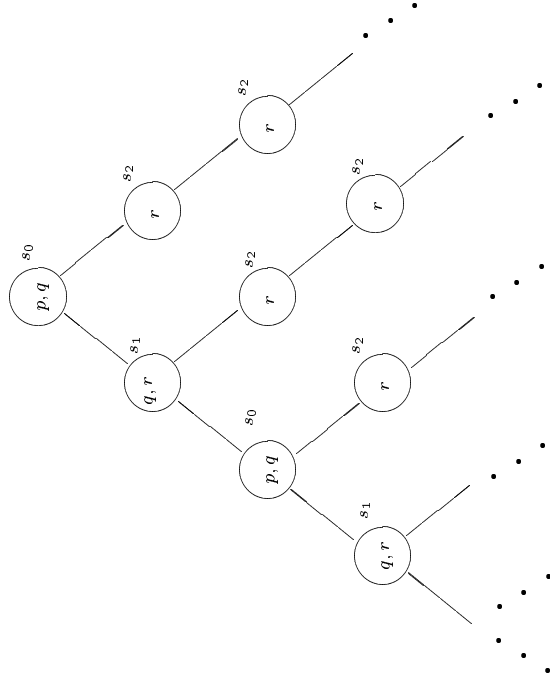
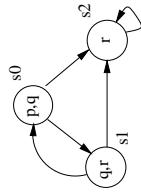
Computation Tree Logic (Cont'd)

Syntax:

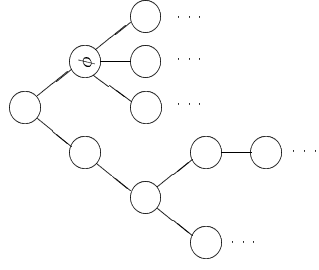
1. \perp , T , and every atomic proposition is a CTL formula
2. If f and g are CTL formulae, then so are $\neg f$, $f \wedge g$, $f \vee g$, AXf , EXf , $A[fUg]$, $E[fUg]$, AFf , EFf , AGf , EGf .

Temporal operators - quantifier (A or E) followed by F (future), G (global), U (until), or X (next).

Where did the "tree" come from?

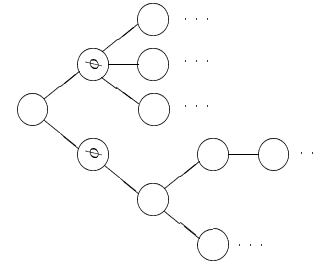


Examples (Part 1)



EX (exists next)
"on some path in the next state"

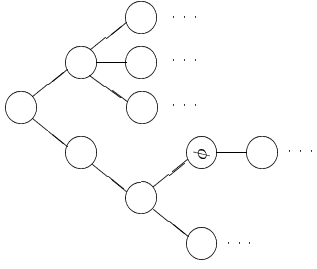
EG (exists global)
"on some path in all states"



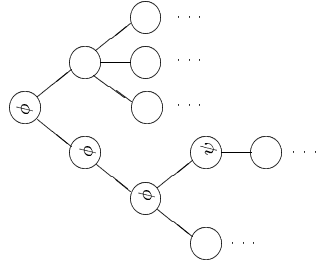
AX (all next)
"on all paths in the next state"

AG (all global)
"on all paths in all states"

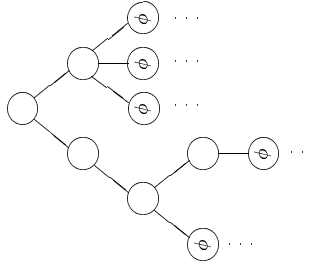
Examples (Part 2)



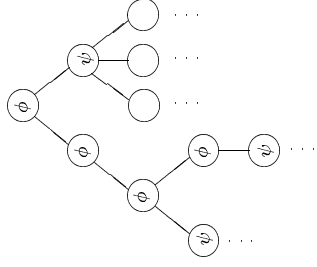
EF (exists future)
"on some path in some state"



EU (exists until)
"on some path until some state"



AF (all future)
"on all paths in some state"



AU (all until)
"on all paths until some state"

CTL Syntax - Cont'd

Which of these are well-formed and which are not:

EG r

FG r

AG AF r

E [A [p₁ U p₂] U p₃]

AF [(r U q) ∧ (p U r)]

EF E[r U q] AF[(r U q) ∧ (p U r)]

Formulas, Subformulas and Parse Trees

Draw parse tree for $E[A[p \text{ U } q] \text{ U } r]$

Draw parse tree for $AG(p \rightarrow A[p \text{ U } (\neg p \wedge A[\neg p \text{ U } q])])$

Definition: A subformula of a CTL formula ϕ is any formula ψ whose parse tree is a subtree of ϕ 's parse tree.

Semantics of CTL

$M, s \models f$ means that formula f is true in state s . M is often omitted since we always talk about the same model.

E.g. $s \models x = 1 \wedge \exists n : nat \cdot y = 2 \times n$ means that in state s , variable x has value 1 and variable y has an even natural value.

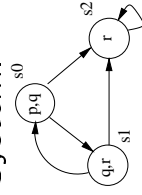
$p = p_0 \ p_1 \ p_2 \ \dots$ is a path
 p_0 is the current state (root)
 p_{i+1} is one of p_i 's successor states. Then,

- AX $f = \forall p \cdot p_1 \models f$
- EX $f = \exists p \cdot p_1 \models f$
- AG $f = \forall p \cdot \forall i \cdot p_i \models f$
- EG $f = \exists p \cdot \forall i \cdot p_i \models f$
- AF $f = \forall p \cdot \exists i \cdot p_i \models f$
- EF $f = \exists p \cdot \exists i \cdot p_i \models f$
- $A[f \text{ U } g] = \forall p \cdot \exists i \cdot p_i \models g \wedge \forall j \cdot 0 \leq j < i \rightarrow p_j \models f$
- $E[f \text{ U } g] = \exists p \cdot \exists i \cdot p_i \models g \wedge \forall i \cdot 0 \leq j < i \rightarrow p_j \models f$

Note: the i in $\exists i$ could be 0.

Why Do These Properties Hold?

System:



- $M, s_0 \models p \wedge q$
- $M, s_0 \models \neg r$
- $M, s_0 \models \top$
- $M, s_0 \models EX(q \wedge r)$
- $M, s_0 \models \neg AX(q \wedge r)$
- $M, s_0 \models \neg EF(p \wedge r)$
- $M, s_2 \models EG r$
- $M, s_2 \models AG r$
- $M, s_0 \models E[(p \wedge q) \cup r]$
- $M, s_0 \models A[p \cup r]$

Examples

It is possible to get to a state where *started* holds, but *ready* does not hold. $EF(\text{started} \wedge \neg \text{ready})$

When a request (of some resource) occurs, it will eventually be acknowledged.

$AG(\text{request} \rightarrow AF \text{acknowledge})$

A process is enabled infinitely often on every computation path. $AG AF \text{enabled}$

A process will eventually be permanently deadlocked.

$AF AG \text{deadlock}$

It is always possible to get to a *restart* state. $AG EF \text{restart}$

An elevator does not change direction when it has passengers wishing to go in the same direction.

$\forall f, b. AG(\text{floor} = f \wedge \text{direction} = \text{up} \wedge \text{pressed}(b) \wedge b > f) \rightarrow A[\text{direction} = \text{up} \cup \text{floor} = b]$

An elevator can remain idle on the third floor with its doors closed:

$AG((\text{floor} = 3 \wedge \text{idle} \wedge \text{door} = \text{closed}) \rightarrow EG(\text{floor} = 3 \wedge \text{idle} \wedge \text{door} = \text{closed}))$

More Examples

Which situation does this signify:

$$AG(p \rightarrow AF(s \wedge AX(AF(t))))$$

Specify in CTL:

Temperature is always above normal, below normal or normal.

We can always reach a resolution.

Whenever p is followed by q (after some finite amount of steps), then the system enters an "interval" in which no r occurs until t .

Laws

$$\begin{aligned} \neg AF f &= EG \neg f \\ \neg EF f &= AG \neg f \\ \neg AX f &= EX \neg f \\ AF f &= A[\top U f] \\ EF f &= E[\top U f] \\ A[\perp U f] &= E[\perp U f] = f \\ AG f &= f \wedge AX AG f \\ EG f &= f \wedge EX EG f \\ AF f &= f \vee AX AF f \\ EF f &= f \vee EX EF f \\ A[f U g] &= g \vee (f \wedge AX A[f U g]) \\ E[f U g] &= g \vee (f \wedge EX E[f U g]) \end{aligned}$$

What Do We Do with CTL?

Mutual Exclusion Problem. Aimed to ensure that two processes do not have access to some shared resource (database, file on disk, etc.) at the same time. Identify *critical* sections and ensure that at most one process is in that section.

Interested in the following properties:

(Safety): The protocol allows only one process to be in its critical section at any time.

Formalization:

Why is this not enough?

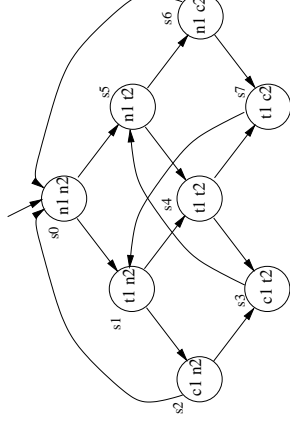
(Liveness): Whenever any process wants to enter its critical section, it will eventually be permitted to do so.

Formalization:

(Non-blocking): A process can always request to enter its critical section.

Formalization:

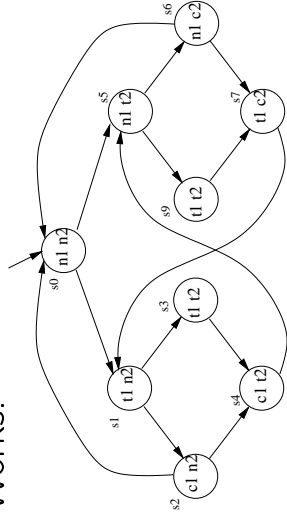
The first modeling attempt



Does it work?

Second modeling attempt

Works!



The problem is a bit simplified (cannot stay in *critical* forever!)

Adequate Sets

Definition: A set of connectives is *adequate* if for every formula there is an equivalent formula with only connectives from that set.

E.G. $\{\neg, \vee\}$ is adequate for propositional logic

Theorem: The set of operators \perp , \neg and \wedge together with AF EU and EX are adequate for CTL.

Other adequate sets: $\{AU, EU, EX\}$, $\{AG, AU, AX\}$.

Kripke Structures (Our Model)

Formula is defined with respect to a model

$M = \langle V, S, s_0, R, I \rangle$, where

V is a set of atomic propositions

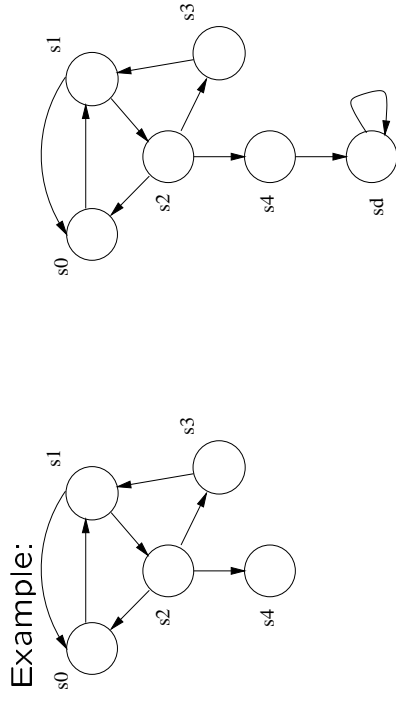
S is a set of states

$s_0 \in S$ is the start state

R is a transition relation (every state has a successor)

I is a set of interpretations specifying which propositions are true in each state.

food for the slide eater



How to deal with deadlock states?