

University of Toronto Department of Computer Science

Lecture 15: Modelling "State"

- What is State?
 - statespace for an object
 - concrete vs. abstract states
- Finite State Machines
 - states and transitions
 - events and actions
- Modularized State machine models: Statecharts
 - superstates and substates
 - Guidelines for drawing statecharts

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Getting objects to behave

- All objects have "state"
 - The object either exists or it doesn't
 - If it exists, then it has a value for each of its attributes
 - Each possible assignment of values to attributes is a "state"
 - (and non-existence is a state, although we normally ignore it)
- E.g. For a stack object

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What does the model mean?

- Finite State Machines
 - There are a finite number of states (all attributes have finite ranges)
 - E.g. imagine a stack with max length = 3

- The model specifies a set of traces
 - E.g. `new(); Push(); Push(); Top(); Pop(); Push(); ...`
 - E.g. `new(); Push(); Pop(); Push(); Pop(); ...`
 - There may be an infinite number of traces (and traces may be of infinite length)
- The model excludes some behaviours
 - E.g. no trace can start with a `Pop()`
 - E.g. no trace may have more Pops than Pushes
 - E.g. no trace may have more than 3 Pushes without a Pop in between

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Abstraction

- The state space of most objects is enormous
 - State space size is the product of the range of each attribute
 - E.g. object with five boolean attributes: 2^5+1 states
 - E.g. object with five integer attributes: $(\text{maxint})^5+1$ states
 - E.g. object with five real-valued attributes: ...?
 - If we ignore computer representation limits, the state space is infinite
- Only part of that state space is "interesting"
 - Some states are not reachable
 - Integer and real values usually only vary within some relevant range
 - We're usually not interested in the actual values, just certain ranges:
 - E.g. for Age, we may be interested in `age<18`; `18=age<65`; and `age>65`
 - E.g. for Cost, we may only be interested in `cost=budget`, `cost=0`, `cost>budget`, and `cost>(budget+10%)`

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Collapsing the state space

The abstraction usually permits more traces

- > E.g. this model does not prevent traces with more pops than pushes
- > But it still says something useful

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What are we modelling?

Application Domain

- D - domain properties
- R - requirements

Machine Domain

- C - computers
- P - programs

s - specification

Observed states of an application domain entity?

- > E.g. a phone can be idle, ringing, connected, ...
- Model shows the states an entity can be in, and how events can change its state
- This is an **indicative** model

Required behaviour of an application domain entity?

- > E.g. a telephone switch shall connect the phones only when the callee accepts the call
- Model distinguishes between traces that are desired and those that are not
- This is an **optative** model

Specified behaviour of a machine domain entity?

- > E.g. when the user presses the 'connect' button the incoming call shall be connected
- Model specifies how the machine should respond to input events
- This is an **optative** model, in which all events are shared phenomena

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Is this model indicative or optative?

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the world vs. the machine

World (Indicative Model)

```

classDiagram
    class person {
        age
        havebirthday()
    }
    class child {
        <age < 18
    }
    class adult {
        <age < 65
    }
    class senior {
        <age = 65
    }
    person --|> child
    person --|> adult
    person --|> senior
        
```

Machine (Optative Model)

```

classDiagram
    class person {
        dateOfBirth
        dateOfDeath
        recordBirth()
        setDOB()
        recordDeath()
        setDateOfDeath()
    }
    class blank
    class child
    class adult
    class senior
    class deceased
    blank --> child : recordBirth() / setDOB()
    child --> adult : when [thisyear-birthyear > 18]
    adult --> senior : when [thisyear-birthyear > 65]
    senior --> deceased : recordDeath() / setDateOfDeath()
        
```

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StateCharts

⇒ **Notation:**

- ↳ **States**
 - > "Interesting" configurations of the values of an object's attributes
 - > may include a specification of action to be taken on entry or exit
 - > States may be nested
 - > States may be "on" or "off" at any given moment
- ↳ **Transitions**
 - > Are enabled when the state is "on"; disabled otherwise
 - > Every transition has an **event** that acts as a trigger
 - > A transition may also have a **condition (or guard)**
 - > A transitions may also cause some action to be taken
 - > When a transition is enabled, it can **fire** if the trigger event occurs and it guard is true
 - > Syntax: **event [guard] / action**
- ↳ **Events**
 - > occurrence of stimuli that can trigger an object to change its state
 - > determine when transitions can fire

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Superstates

⇒ States can be nested, to make diagrams simpler

- ↳ A superstate consists of one or more states.
- ↳ Superstates make it possible to view a state diagram at different levels of abstraction.

OR superstates

- ↳ when the superstate is "on", only one of its substates is "on"

AND superstates (concurrent substates)

- ↳ When the superstate is "on", all of its states are also "on"
- ↳ Usually, the AND substates will be nested further as OR superstates

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A more detailed example

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States in UML

⇒ A state represents a time period during which

- ↳ A predicate is true
 - > e.g. $(\text{budget} - \text{expenses}) > 0$,
- ↳ An action is being performed, or an event is awaited:
 - > e.g. checking inventory for order items
 - > e.g. waiting for arrival of a missing order item

⇒ States can have associated activities:

- ↳ **do/activity**
 - > carries out some activity for as long as the state is "on"
- ↳ **entry/action** and **exit/action**
 - > carry out the action whenever the state is entered (exited)
- ↳ **include/stateDiagramName**
 - > "calls" another state diagram, allowing state diagrams to be nested

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Events in UML

⇒ Events are happenings the system needs to know about

- ↳ Must be relevant to the system (or object) being modelled
- ↳ Must be modellable as an instantaneous occurrence (from the system's point of view)
 - > E.g. completing an assignment, failing an exam, a system crash
- ↳ Are implemented by message passing in an OO Design

⇒ In UML, there are four types of events:

- ↳ **Change events** occur when a condition becomes true
 - > denoted by the keyword 'when'
 - > e.g. `when[balance < 0]`
- ↳ **Call events** occur when an object receives a call for one of its operations to be performed
- ↳ **Signal events** occur when an object receives an explicit (real-time) signal
- ↳ **Elapsed-time events** mark the passage of a designated period of time
 - > e.g. `after[10 seconds]`



Checking your Statecharts

⇒ Consistency Checks

- ↳ All events in a statechart should appear as:
 - > operations of an appropriate class in the class diagram
- ↳ All actions in a statechart should appear as:
 - > operations of an appropriate class in the class diagram and

⇒ Style Guidelines

- ↳ Give each state a unique, meaningful name
- ↳ Only use superstates when the state behaviour is genuinely complex
- ↳ Do not show too much detail on a single statechart
- ↳ Use guard conditions carefully to ensure statechart is unambiguous
 - > Statecharts should be deterministic (unless there is a good reason)

⇒ You probably shouldn't be using statecharts if:

- ↳ you find that most transitions are fired "when the state completes"
- ↳ many of the trigger events are sent from the object to itself
- ↳ your states do not correspond to the attribute assignments of the class