

**CSC304: Algorithmic Game Theory and
Mechanism Design
Fall 2016**

Allan Borodin (instructor)
Tyrone Strangway and Young Wu (TAs)

October 24, 2016

Lecture 12

- Announcements

- ▶ Office hours: Tuesdays 3:30-4:30 SF 2303B or schedule meeting; or drop by.
- ▶ I have posted the three questions for Assignment 2 which is due this Friday, October 28. This is now the entire assignment.
- ▶ Assignment 1 has been graded. Some statistics: average 73.9%, median 78.9%, 6 below 50%
One person did not submit via Markus.

- Today's agenda

- ▶ Concluding comments on Chapter 14
- ▶ Chapter 15
 - ★ Chapter 15: The single parameter win-lose setting with respect to social welfare/surplus
 - ★ VCG in the single parameter individually rational setting.
 - ★ Some examples
 - ★ sponsored search; VCG vs GSP

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In other valuations, it is better not to bundle and in some valuations it may be best to offer the buyer a choice of individual prices or a bundle.

Selling multiple items to an additive buyer: a little good news

There are now a few results within the spirit of “simple (and approximate) vs optimal auctions”. This is very much a topic within the field of algorithmic game theory (AGT) given our interest in computational efficiency and conceptual simplicity

For those interested I suggest looking at the following:

- 1 Hart and Nisan (2014) show that if two items are distributed independently, then selling them separately obtains at least a fraction $\frac{1}{2}$ of the optimal revenue. Moreover, if the items are i.i.d., then pricing individually obtains at least a fraction $\frac{e}{e-1}$ of the optimal revenue.
- 2 Hart and Nisan also show that for an arbitrary number of items, neither pricing separately or as a grand bundle can guarantee a constant fraction of the optimal revenue.
- 3 However, in contrast, Babaioff et al (2014) show that the maximum of separate prices and grand bundle pricing guarantees a constant fraction independent of the number of items.

Begin chapter 15: Social welfare for auctions in the single parameter setting

In Lecture 9, for definiteness, we described a general auction type setting where we postulated a set of items, and buyers and sellers for those items. As I remarked then, the text (and other texts such as the AGT book edited by Nisan, Roughgarden, Tardos and Vazirani) do not mention “items” but rather frame the outcomes in terms of feasible allocations. We’ll adopt that viewpoint and terminology now.

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What we are assuming throughout our discussions is *quasi linear utility*, namely that an agent's utility $u_i(a)$ for an outcome a having value $v_i(a)$ is $u_i(a) = v_i(a) + m$ where m is some quantity of (say) money. In our auctions thus far, m is negative as it represents a payment from the buyers. In a *procurement auction* (example 15.1.2 and section 15.4.2), m is positive representing a payment to the agents who are providers of a service which has some private intrinsic cost (i.e. the “value” is negative).

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The single parameter setting for Chapter 15 (Definition 15.2.1)

- There is a set U of agents, and a set $\mathcal{L} \subset 2^U$ of *feasible allocations*.
- We say that agent i is a “winner” in a feasible allocation $L \in \mathcal{L}$ if $i \in L$. Each agent i has a single private value v_i which is the value for agent i if i is a winner.

Chapter 16 considers the more general setting where an agent can have different values for different allocations.

Social welfare: deterministic and randomized mechanisms

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We are considering sealed bid (direct) auctions where each agent i offers a bid b_i and the mechanism uses an allocation rule to determine the winners and the payment rule for each (winning) agent. We will assume that the payment of losing agents is 0. We will also assume a finite set U of n agents.

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For a deterministic mechanism, an *allocation rule* is a mapping $\alpha : \mathbf{b} \rightarrow \mathcal{L}$. Equivalently, $\alpha : \mathbf{b} \rightarrow \{0, 1\}^n : \alpha_i = \alpha(\mathbf{b})_i = 1$ iff agent i is a winner.

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The payment rule $p : \mathbf{b} \rightarrow \mathbb{R}^n$ determines the payment for each winning agent where we assume the payment $p_i = p_i(\mathbf{b})_i = 0$ if agent i is not a winner.

The utility of agent i with value v_i when bidding b_i is

$$u_i(\mathbf{b} | v_i) = v_i \alpha_i(\mathbf{b}) - p_i(\mathbf{b})$$

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For randomized mechanisms, we will also have to distinguish between worst case truthfulness vs truthfulness in the sense of the expectation.

Some examples

- A combinatorial auction CA consists of a set of items M where each agent i has a value $v_i(S)$ for different desired sets $S \subseteq M$. In a single parameter CA, the value $v_i = v_i(S)$ is the same for each desired set and we assume that the mechanism knows what particular sets agent i desires. (S_1, \dots, S_n) with $S_i \subseteq M$ is a feasible allocation if $S_i \cap S_j = \emptyset$ for all $i \neq j$. Here the winners are those agents i such that $S_i \neq \emptyset$.

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- The feasible allocations in a single item auction (as in chapter 14) are those with just one winner.

More examples

- In the shared communication channel example in Example 15.1.3, the agents have known bandwidth requirements w_i and a feasible allocation is one in which $\sum_{i:i} w_i \leq C$ for some known capacity C .

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These examples are all different in terms of the underlying combinatorial allocation problem.

- As we mentioned before, the allocation problem for a general CA is the set packing problem, which is NP-hard to approximate to within a factor $\min(n, m^{\frac{1}{2}-\epsilon})$ where $m = |M|$.
- For the special case of the spectrum auction, this is the interval selection problem which can be optimally solved (for the single-minded case) by an efficient (greedy) algorithm.
- The single item case is a rather trivial allocation problem.
- The allocation problem for the shared communication channel is the knapsack problem which is NP-hard but can be approximately solved to within any factor $(1 - \epsilon)$ by a computationally efficient (dynamic programming) algorithm.

The procurement auction in section 15.4.2

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In the spanning tree auction problem, a service provider (such as Netflix) needs to build a spanning tree by purchasing edges in a network from different agents. Assume each edge e_i is owned by a different agent i who has some private cost if that edge is used by the provider.

The feasible solutions are spanning trees and the mechanism is trying to minimize the cost of the spanning tree it computes. Each agent i is trying to maximize the price p_i it receives minus its (private) cost. This becomes a social welfare maximization problem when setting $v_i = -c_i$.

The truthful VCG mechanism

The Vickery Clarke Groves (VCG) mechanism is a deterministic mechanism that is truthful (ex-post incentive compatible) and individually rational. In Chapter 16, it is stated and proven to be truthful for the general case (i.e. not restricted to single parameter auctions) whenever we have a quasi-linear utility function $u_i = v_i - p_i$.

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As the name might suggest, the Vickery auction is VCG applied to the special case of a single item auction. It is also the special case of the Vickery auction for the multi item case when there are k copies of the same item and the winners are the agents with the top k values and the price is the $k + 1$ -st value. (Do not just quote result for question 2 of assignment.)

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Since we are considering social welfare (and not revenue), we do not have to consider reserve prices but as we have mentioned, reserve prices do not cause a problem for truthfulness.

The VCG mechanism in a figure

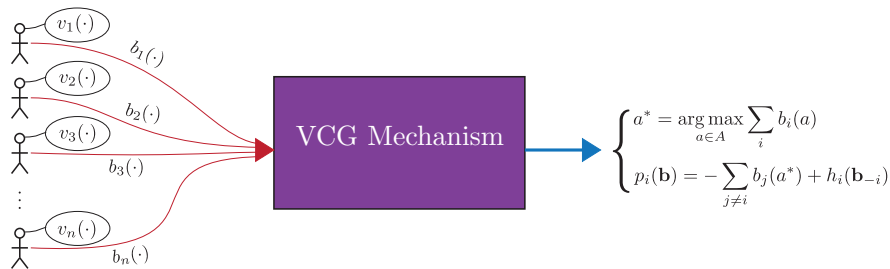


Figure : The depiction of VCG for arbitrary function $h_i(\mathbf{b}_{-i})$.

Here A is the set of feasible allocations. VCG is truthful for any h_i that does not depend on b_i . To make VCG IR and all payments non-negative, we use the “Clarke pivot”:

$$h_i(\mathbf{b}_{-i}) = \max_{a \in A} \sum_{j \neq i} b_j(a)$$

VCG in words

VCG is a deterministic sealed bid auction. Each agent i submits their bids $b_i(a_i)$ for each desired outcome a_i .

Note: In the single-minded case, the agent has just one desired outcome but (say) in the general CA, an agent could desire many different sets each having its own valuation.

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Given this optimal allocation a^* , the payment $p_i(\mathbf{b})$ for agent i is :

$$p_i(\mathbf{b}) = \max_{a \in A} \sum_{j \neq i} b_j(a) - \sum_{j \neq i} b_j(a^*)$$

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That is, agent i is being charged his impact on the social welfare of the other agents. Be sure you understand this statement!