

CSC2420: Algorithm Design, Analysis and Theory

Fall 2022

**An introductory (i.e. foundational) level
graduate course.**

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Week 8

Announcements

- Assignment 2 is complete and due Wednesday, November 23 at 1PM. There are three questions. I did not add an additional question.

Today's ambitious agenda

- I will repeat comments from Week 7 introducing randomized algorithms.
- The Schwartz-Zippel lemma and polynomial identity testing.
- The naive randomize algorithm for Max-k-Sat and de-randomization
- Johnson's algorithm and improvements.
- Input models for online and greedy algorithms for Max-Sat
- Randomized rounding of an LP.
- Max-cut and Max-di-cut: naive randomized algorithm
- Non-monotone submodular maximization: the double sided greedy algorithm.
- De-randomizing by parallelization
- Max-cut and Max-2-Sat: randomized rounding of a vector program

An old but new topic: randomized algorithms

Our next theme will be randomized algorithms. Of course we have already seen randomization in a few online algorithms. However, for the main part, our previous themes have been on algorithmic paradigms, so far online algorithms, variants of greedy and local-search and primal dual algorithms. Randomization is not per se an algorithmic paradigm (in the same sense as greedy algorithms, DP, local search, LP rounding, primal dual algorithms).

An old but new topic: randomized algorithms

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Rather, randomization can be thought of as an additional algorithmic idea that can be used in conjunction with any algorithmic paradigm. However, its use is so prominent and varied in algorithm design and analysis, that it takes on the sense of an algorithmic way of thinking.

The why of randomized algorithms

- There are applications (e.g. simulation, cryptography, interactive proofs, sublinear time algorithms, small space streaming algorithms, contention resolution in a distributed system) where randomization is *necessary*.
- We can use randomization to improve approximation ratios.
- Often a naive randomization provides “good” results.
- Even when a given algorithm can be efficiently derandomized, there is often conceptual insights to be gained from the initial randomized algorithm.
- In complexity theory a fundamental question is how much can randomization lower the time complexity of a problem. For decision problems, there are three polynomial time randomized classes ZPP (zero-sided), RP (1-sided) and BPP (2-sided) error. The big question (and conjecture?) is $BPP = P$?
- One important aspect of randomized algorithms (in an offline setting) is that the probability of success can be amplified by repeated independent trials of the algorithm.

Some applications of randomized algorithms to the online setting

In addition to the important role of randomization in the more standard offline algorithm setting, as we have already seen, randomization plays a very central role in online algorithms as the online setting is particularly vulnerable to worst case adversarial examples. Here are some results we will consider in the online setting:

- 1 Naive exact max- k -sat algorithm
- 2 De-randomization by the method of conditional expectation
- 3 The Buchbinder et al two sided online greedy algorithm for the unconstrained maximization of a non-monotone submodular function. and application to max-sat.
- 4 Online with advice and relation to randomized online algorithms
- 5 De-randomization using two and multi pass algorithms

But first a few more comments on randomization and complexity theory.

Some problems in randomized polynomial time not known to be in polynomial time

- 1 The symbolic determinant problem.
- 2 Given n , find a prime in $[2^n, 2^{n+1}]$
- 3 Estimating volume of a convex body given by a set of linear inequalities.
- 4 Solving a quadratic equation in $Z_p[x]$ for a large prime p .

We will see that often a naive randomization provides the best current results. One can think of *naive randomization* as a paradigm. That is, instead of looking for a particular solution, try a random solution.

Polynomial identity testing

- The general problem concerning polynomial identities is that we are **implicitly given** two multivariate polynomials and wish to determine if they are identical. One way we could be implicitly given these polynomials is by an arithmetic circuit. A specific case of interest is the following **symbolic determinant problem**.
- Consider an $n \times n$ matrix $A = (a_{i,j})$ whose entries are polynomials of total degree (at most) d in m variables, say with integer coefficients. The determinant $\det(A) = \sum_{\pi \in S_n} (-1)^{\text{sgn}(\pi)} \prod_{i=1}^n a_{i,\pi(i)}$, is a polynomial of degree nd . The symbolic determinant problem is to determine whether $\det(A) \equiv \mathbf{0}$, the zero polynomial.

Schwartz-Zippel Lemma

Schwartz Zippel Lemma

Let $P \in \mathbf{F}[x_1, \dots, x_m]$ be a non zero polynomial over a field \mathbf{F} of total degree at most d . Let S be a finite subset of \mathbf{F} . Then

$$\text{Prob}_{r_i \in_u S}[P(r_1, \dots, r_m) = 0] \leq \frac{d}{|S|}$$

Schwartz Zippel is clearly a multivariate generalization of the fact that a univariate polynomial of degree d can have at most d zeros.

Polynomial identity testing and symbolic determinant continued

- Returning to the symbolic determinant problem, suppose then we choose a sufficiently large set of integers S (for definiteness say $|S| \geq 2nd$). Randomly choosing $r_i \in S$, we evaluate each of the polynomial entries at the values $x_i = r_i$. We then have a matrix A' with (not so large) integer entries.
- We know how to compute the determinant of any such integer matrix $A'_{n \times n}$ in $O(n^3)$ arithmetic operations. (Using the currently fastest, but not necessarily practical, matrix multiplication algorithm, the determinant can be computed in $O(n^{2.373})$ arithmetic operations.)
- That is, we are computing the $\det(A)$ at random $r_i \in S$ which is a degree nd polynomial. Since $|S| \geq 2nd$, then $\text{Prob}[\det(A') = 0] \leq \frac{1}{2}$ assuming $\det(A) \neq \mathbf{0}$. The probability of correctness can be amplified by choosing a bigger S or by repeated trials.
- In complexity theory terms, the problem (is $\det(A) \equiv \mathbf{0}$) is in co-RP.

The naive randomized algorithm for exact Max- k -Sat

We continue our discussion of randomized algorithms by considering the use of randomization for improving approximation algorithms. In this context, randomization can be (and is) combined with any type of algorithm.

Note: For the following maximization problems, we will follow the prevailing convention by stating competitive ratios as fractions $c < 1$.

- Consider the exact Max- k -Sat problem where we are given a CNF propositional formula in which every clause has exactly k literals. We consider the weighted case in which clauses have weights. The goal is to find a satisfying assignment that maximizes the size (or weight) of clauses that are satisfied.
- As already noted, since exact Max- k -Sat generalizes the exact k -SAT decision problem, it is clearly an NP hard problem for $k \geq 3$. It is interesting to note that while 2-SAT is polynomial time computable, Max-2-Sat is still NP hard.
- The naive randomized (online) algorithm for Max- k -Sat is to randomly set each variable to *true* or *false* with equal probability.

Analysis of naive Max- k -Sat algorithm continued

- Since the expectation of a sum is the sum of the expectations, we just have to consider the probability that a clause is satisfied to determine the expected weight of a clause.
- Since each clause C_i has k variables, the probability that a random assignment of the literals in C_i will set the clause to be satisfied is exactly $\frac{2^k-1}{2^k}$. Hence \mathbf{E} [weight of satisfied clauses] = $\frac{2^k-1}{2^k} \sum_i w_i$
- Of course, this probability only improves if some clauses have more than k literals. It is the small clauses that are the limiting factor in this analysis.
- This is not only an approximation ratio but moreover a “totality ratio” in that the algorithm’s expected value is a factor $\frac{2^k-1}{2^k}$ of the sum of all clause weights whether satisfied or not.
- We can hope that when measuring against an optimal solution (and not the sum of all clause weights), small clauses might not be as problematic as they are in the above analysis of the naive algorithm.

Derandomizing the naive algorithm

We can derandomize the naive algorithm by what is called the method of conditional expectations. Let $F[x_1, \dots, x_n]$ be an exact k CNF formula over n propositional variables $\{x_i\}$. For notational simplicity let *true* = 1 and *false* = 0 and let $w(F)|\tau$ denote the weighted sum of satisfied clauses given truth assignment τ .

- Let x_j be any variable. We express $\mathbf{E}[w(F)|_{x_i \in_U \{0,1\}}]$ as $\mathbf{E}[w(F)|_{x_i \in_U \{0,1\}} | x_j = 1] \cdot (1/2) + \mathbf{E}[w(F)|_{x_i \in_U \{0,1\}} | x_j = 0] \cdot (1/2)$
- This implies that one of the choices for x_j will yield an expectation at least as large as the overall expectation.
- It is easy to determine how to set x_j since we can calculate the expectation clause by clause.
- We can continue to do this for each variable and thus obtain a deterministic solution whose weight is at least the overall expected value of the naive randomized algorithm.
- NOTE: The derandomization can be done so as to achieve an online algorithm. Here the (online) input items are the propositional variables. What input representation is needed/sufficient?

(Exact) Max- k -Sat

- For exact Max-2-Sat (resp. exact Max-3-Sat), the approximation (and totality) ratio is $\frac{3}{4}$ (resp. $\frac{7}{8}$).
- For $k \geq 3$, using PCPs (probabilistically checkable proofs), Hastad proves that it is NP-hard to improve upon the $\frac{2^k-1}{2^k}$ approximation ratio for Max- k -Sat.
- For Max-2-Sat, the $\frac{3}{4}$ ratio can be improved by the use of semi-definite programming (SDP) and randomized rounding.
- The analysis for exact Max- k -Sat clearly needed the fact that all clauses have at least k clauses. What bound does the naive online randomized algorithm or its derandomization obtain for (not exact) Max-2-Sat or arbitrary Max-Sat (when there can be unit clauses)?

Johnson's Max-Sat Algorithm

Johnson's [1974] algorithm

For all clauses C_i , $w'_i := w_i / (2^{|C_i|})$

Let L be the set of clauses in formula F and X the set of variables

For $x \in X$ (or until L empty)

Let $P = \{C_i \in L \text{ such that } x \text{ occurs positively}\}$

Let $N = \{C_j \in L \text{ such that } x \text{ occurs negatively}\}$

If $\sum_{C_i \in P} w'_i \geq \sum_{C_j \in N} w'_j$

$x := \text{true}; L := L \setminus P$

For all $C_r \in N$, $w'_r := 2w'_r$ **End For**

Else

$x := \text{false}; L := L \setminus N$

For all $C_r \in P$, $w'_r := 2w'_r$ **End For**

End If

Delete x from X

End For

Aside: This reminds me of boosting (Freund and Shapire [1997])

Johnson's algorithm is the derandomized algorithm

- Twenty years after Johnson's algorithm, Yannakakis [1994] presented the naive algorithm and showed that Johnson's algorithm is the derandomized naive algorithm.
- Yannakakis also observed that for arbitrary Max-Sat, the approximation of Johnson's algorithm is at best $\frac{2}{3}$. For example, consider the 2-CNF $F = (x \vee \bar{y}) \wedge (\bar{x} \vee y) \wedge \bar{y}$ when variable x is first set to true. Otherwise use $F = (x \vee \bar{y}) \wedge (\bar{x} \vee y) \wedge y$.
- Chen, Friesen, Zheng [1999] showed that Johnson's algorithm achieves approximation ratio $\frac{2}{3}$ for arbitrary weighted Max-Sat.
- For arbitrary Max-Sat (resp. Max-2-Sat), the current best approximation ratio is .7968 (resp. .9401) using semi-definite programming and randomized rounding.
Note: While existing combinatorial algorithms do not come close to these best known ratios, it is still interesting to understand simple and even online algorithms for Max-Sat.

Modifying Johnson's algorithm for Max-Sat

- In proving the $(2/3)$ approximation ratio for Johnson's Max-Sat algorithm, Chen et al asked whether or not the ratio could be improved by using a random ordering of the propositional variables (i.e. the input items). This is another example of the random order model (ROM), a randomized variant of online algorithms.
- To precisely model the Max-Sat problem within an online or priority framework, we need to specify the input model.
- In increasing order of providing more information (and possibly better approximation ratios), we can consider (on the next slide) four input models.

The MaxSat online and priority input models

- M0** Each propositional variable x is represented by the names of the positive and negative clauses in which it appears.
- M1** Each propositional variable x is represented by the length of each clause C_i in which x appears positively, and for each clause C_j in which it appears negatively.
- M2** In addition, for each C_i and C_j , a list of the other variables in that clause is specified.
- M3** The variable x is represented by a complete specification of each clause it which it appears.

The naive randomized algorithm can be implemented in a “model 0” where we don’t even specify the lengths of the clauses and Johnson’s algorithm can be implemented using input model 1.

Improving on Johnson's algorithm

- The question asked by Chen et al was answered by Costello, Shapira and Tetali [2011] who showed that in the ROM model, Johnson's algorithm achieves approximation $(2/3 + \epsilon)$ for $\epsilon \approx .003653$
- Poloczek and Schnitger [same SODA 2011 conference] show that the approximation ratio for Johnson's algorithm in the ROM model is at most $2\sqrt{15}-7 \approx .746 < 3/4$, noting that $\frac{3}{4}$ is the ratio first obtained by Yannakakis' IP/LP approximation that we will soon present.
- Poloczek and Schnitger first consider a “**canonical randomization**” of Johnson's algorithm; namely, the canonical randomization sets a variable $x_i = true$ with probability $\frac{w'_i(P)}{w'_i(P)+w'_i(N)}$ where $w'_i(P)$ (resp. $w'_i(N)$) is the current combined weight of clauses in which x_i occurs positively (resp. negatively). Their substantial additional idea is to adjust the random setting so as to better account for the weight of unit clauses in which a variable occurs.

A few comments on the Poloczek and Schnitger algorithm

- The Poloczek and Schnitger algorithm is called **Slack** and has approximation ratio $= 3/4$.
- The Slack algorithm is a randomized online algorithm (i.e. adversary chooses the ordering) where the variables are represented within input **Model 1**.
- This approximation ratio is in contrast to Azar et al [2011] who prove that no randomized online algorithm can achieve approximation better than $2/3$ when the input model is input **model 0**.
- Finally (in this regard), Poloczek [2011] shows that no deterministic priority algorithm can achieve a $3/4$ approximation within input **model 2**. This provides a sense in which to claim that Poloczek and Schnitger Slack algorithm **“cannot be derandomized”**.
- The best deterministic priority algorithm in the third (most powerful) model remains an open problem as does the best randomized priority algorithm and the best ROM algorithm.

Revisiting the “cannot be derandomized comment”

Spoiler alert: we will be discussing how algorithms that cannot be derandomized in one sense can be derandomized in another sense.

- The Buchbinder et al [2012] online randomized $1/2$ approximation algorithm for Unconstrained Submodular Maximization (USM) cannot be derandomized into a “similar” deterministic algorithm by a result of Huang and Borodin [2014].
- However, Buchbinder and Feldman [2016] show how to derandomize the Buchbinder et al algorithm into an algorithm that generates $2n$ parallel streams where each stream is an online algorithm.
- The Buchbinder et al USM algorithm is the basis for a randomized $3/4$ approximation online MaxSat (even Submodular Max Sat) algorithm.
- Pena and Borodin show how to derandomize this $3/4$ approximation algorithm following the approach of Buchbinder and Feldman.
- Poloczek et al [2017] de-randomize an equivalent Max-Sat algorithm using a 2-pass online algorithm.

Yannakakis' IP/LP randomized rounding algorithm for Max-Sat

- We will formulate the weighted Max-Sat problem as a $\{0, 1\}$ IP.
- Relaxing the variables to be in $[0, 1]$, we will treat some of these variables as probabilities and then round these variables to 1 with that probability.

- Let F be a CNF formula with n variables $\{x_i\}$ and m clauses $\{C_j\}$.

The Max-Sat formulation is :

$$\text{maximize } \sum_j w_j z_j$$

$$\text{subject to } \sum_{\{x_i \text{ is in } C_j\}} y_i + \sum_{\{\bar{x}_i \text{ is in } C_j\}} (1 - y_i) \geq z_j$$
$$y_i \in \{0, 1\}; z_j \in \{0, 1\}$$

- The y_i variables correspond to the propositional variables and the z_j correspond to clauses.
- The relaxation to an LP is $y_i \geq 0; z_j \in [0, 1]$. Note that here we cannot simply say $z_j \geq 0$.

Randomized rounding of the y_i variables

- Let $\{y_i^*\}, \{z_j^*\}$ be the optimal LP solution,
- Set $\tilde{y}_i = 1$ with probability y_i^* .

Theorem

Let C_j be a clause with k literals and let $b_k = 1 - (1 - \frac{1}{k})^k$. Then $\text{Prob}[C_j \text{ is satisfied}]$ is at least $b_k z_j^*$.

- The theorem shows that the contribution of the j^{th} clause C_j to the expected value of the rounded solution is at least $b_k w_j$.
- Note that b_k converges to (and is always greater than) $1 - \frac{1}{e}$ as k increases. It follows that the expected value of the rounded solution is at least $(1 - \frac{1}{e}) \text{LP-OPT} \approx .632 \text{LP-OPT}$.
- Taking the max of this IP/LP and the naive randomized algorithm results in a $\frac{3}{4}$ approximation algorithm that can be derandomized. (The derandomized algorithm will still be solving LPs.)

The weighted max-cut and max-di-cut problems

Given a graph $G = (V, E)$, the max-cut objective is to partition the vertices into subsets S and T so as to maximize $|\{(u, v) \in E \mid u \in S, v \in T\}|$.

In the weighted max-cut problem, there is a weight function $w : E \rightarrow \mathbb{R}^+$ and the objective is to maximize $\sum_{(u,v) \in E \mid u \in S, v \in T} w(u, v)$.

In the max-di-cut problem, we are given a directed graph $G = (V, E)$ and the objective is to partition the vertices into subsets S, T so as to maximize $|\{\langle u, v \rangle \in E \mid u \in S, v \in T\}|$. Here I am using the notation $\langle u, v \rangle$ to indicate that the edge is a directed edge from u to v .

In the weighted max-di-cut problem, there is again a weight function $w : E \rightarrow \mathbb{R}^+$ and the objective is to maximize $\sum_{\langle u,v \rangle \in E \mid u \in S, v \in T} w(\langle u, v \rangle)$.

The most naive randomized algorithms for weighted max-cut

Consider max-cut and random and independently set each u to be in S with probability $\frac{1}{2}$.

What is the (expected) approximation bound for this naive algorithm?

For any edge (u, v) , it is easy to see that the probability that the random assignment assigns different values to u and v is exactly $\frac{1}{2}$. Hence, the expected approximation ratio is $\frac{1}{2}$ and similar to the discussion of the naive randomized algorithm for exact-max-2-sat, this is a totality ratio.

And like the de-randomization of the exact-max-2-sat algorithm, the de-randomization for the max-cut algorithm can be implemented as a deterministic online algorithm. How would you represent the graph and what information (if any) about the graph is needed initially and what information do you need to maintain so as to implement the de-randomization as a deterministic algorithm? Can you state the de-randomized algorithm without reference to the randomized algorithm?

The same naive algorithm for weighted max-di-cut

Suppose we use the same naive algorithm for weighted max-di-cut. What is the resulting expected approximation ratio?

Now the expected ratio is only $\frac{1}{4}$ since now there is only $\frac{1}{4}$ probability of choosing $u \in S$ and $v \in T$.

This algorithm can also be de-randomized and there is an implementation as a deterministic online algorithm IF the algorithm is given some initial information about the graph. **What information is needed?**

Somewhat strange fact: The de-randomization can be implemented achieving competitive ratio $\frac{1}{3}$ improving upon the expectation. The de-randomization of the max-cut algorithm does not result in an improved approximation ratio.

Max-cut and max-di-cut are the prime examples of non-monotone submodular functions. In the development to follow we will see relatively simple randomized algorithm (but not at all naive) that achieves the ratio $\frac{1}{2}$ for *any* submodular function.

Unconstrained (non monotone) submodular maximization

- Feige, Mirrokni and Vondrak [2007] began the study of approximation algorithms for the unconstrained non monotone submodular maximization (USM) problem establishing several results:
 - 1 Choosing S uniformly at random provides a $1/4$ approximation.
 - 2 An oblivious local search algorithm results in a $1/3$ approximation.
 - 3 A non-oblivious local search algorithm results in a $2/5$ approximation.
 - 4 Any algorithm using only value oracle calls, must use an exponential number of calls to achieve an approximation $(1/2 + \epsilon)$ for any $\epsilon > 0$.
- The Feige et al paper was followed up by improved local search algorithms by Gharan and Vondrak [2011] and Feldman et al [2012] yielding (respectively) approximation ratios of .41 and .42.
- The $(1/2 + \epsilon)$ inapproximation (assuming an exponential number of value oracle calls), was augmented by Dobzinski and Vondrak showing the same bound for an explicitly given instance under the assumption that $RP \neq NP$.

The Buchbinder et al (1/3) and (1/2) approximations for USM

In the FOCS [2012] conference, Buchbinder et al gave an elegant linear time deterministic 1/3 approximation and then extend that to a randomized 1/2 approximation. The conceptually simple form of the algorithm is (to me) as interesting as the optimality (subject to the proven inapproximation results) of the result. Let $U = u_1, \dots, u_n$ be the elements of U in any order.

The deterministic 1/3 approximation for USM

$X_0 := \emptyset; Y_0 := U$

For $i := 1 \dots n$

$a_i := f(X_{i-1} \cup \{u_i\}) - f(X_{i-1}); b_i := f(Y_{i-1} \setminus \{u_i\}) - f(Y_{i-1})$

If $a_i \geq b_i$

then $X_i := X_{i-1} \cup \{u_i\}; Y_i := Y_{i-1}$

else $X_i := X_{i-1}; Y_i := Y_{i-1} \setminus \{u_i\}$

End If

End For

The randomized 1/2 approximation for USM

- Buchbinder et al show that the “natural randomization” of the previous deterministic algorithm achieves approximation ratio 1/2.
- That is, the algorithm chooses to either add $\{u_i\}$ to X_{i-1} with probability $\frac{a'_i}{a'_i+b'_i}$ or to delete $\{u_i\}$ from Y_{i-1} with probability $\frac{b'_i}{a'_i+b'_i}$ where $a'_i = \max\{a_i, 0\}$ and $b'_i = \max\{b_i, 0\}$.
- If $a_i = b_i = 0$ then add $\{u_i\}$ to X_{i-1} .
- **Note:** Part of the proof for both the deterministic and randomized algorithms is the fact that $a_i + b_i \geq 0$.
- This fact leads to the main lemma for the deterministic case:

$$f(OPT_{i-1}) - f(OPT_i) \leq [f(X_i) - f(X_{i-1})] + [f(Y_i) - f(Y_{i-1})]$$

Here $OPT_i = (OPT \cup \{X_i\}) \cap Y_i$ so that OPT_i coincides with X_i and Y_i for elements $1, \dots, i$ and coincides with OPT on elements $i + 1, \dots, n$. Note that $OPT_0 = OPT$ and $OPT_n = X_n = Y_n$. That is, the loss in OPT 's value is bounded by the total value increase in the algorithm's solutions.

Applying the algorithmic idea to Max-Sat

Buchbinder et al are able to adapt their randomized algorithm to the Max-Sat problem (and even to the Submodular Max-Sat problem). So assume we have a monotone normalized submodular function f (or just a linear function as in the usual Max-Sat). The adaption to Submodular Max-Sat is as follows:

- Let $\phi : X \rightarrow \{0\} \cup \{1\} \cup \emptyset$ be a standard partial truth assignment. That is, each variable is assigned exactly one of two truth values or not assigned.
- Let \mathcal{C} be the set of clauses in formula Ψ . Then the goal is to maximize $f(\mathcal{C}(\phi))$ where $\mathcal{C}(\phi)$ is the set of formulas satisfied by ϕ .
- An extended assignment is a function $\phi' : X \rightarrow 2^{\{0,1\}}$. That is, each variable can be given one, two or no values. (Equivalently $\phi' \subseteq X \times \{0,1\}$ is a relation.) A clause can then be satisfied if it contains a positive literal (resp. negative literal) and the corresponding variable has value $\{1\}$ or $\{0,1\}$ (resp. has value $\{0\}$ or $\{0,1\}$).
- $g(\phi') = f(\mathcal{C}(\phi'))$ is a monotone normalized submodular function. ‘

Buchbinder et al Submodular Max-Sat

Now starting with $X_0 = X \times \emptyset$ and $Y_0 = Y \times \{0, 1\}$, each variable is considered and set to either 0 or to 1 (i.e. a standard assignment of precisely one truth value) depending on the marginals as in USM problem.

Algorithm 3: RandomizedSSAT(f, Ψ)

```
1  $X_0 \leftarrow \emptyset, Y_0 \leftarrow \mathcal{N} \times \{0, 1\}$ .
2 for  $i = 1$  to  $n$  do
3    $a_{i,0} \leftarrow g(X_{i-1} \cup \{u_i, 0\}) - g(X_{i-1})$ .
4    $a_{i,1} \leftarrow g(X_{i-1} \cup \{u_i, 1\}) - g(X_{i-1})$ .
5    $b_{i,0} \leftarrow g(Y_{i-1} \setminus \{u_i, 0\}) - g(Y_{i-1})$ .
6    $b_{i,1} \leftarrow g(Y_{i-1} \setminus \{u_i, 1\}) - g(Y_{i-1})$ .
7    $s_{i,0} \leftarrow \max\{a_{i,0} + b_{i,1}, 0\}$ .
8    $s_{i,1} \leftarrow \max\{a_{i,1} + b_{i,0}, 0\}$ .
9   with probability  $s_{i,0}/(s_{i,0} + s_{i,1})^*$  do:
    $X_i \leftarrow X_{i-1} \cup \{u_i, 0\}, Y_i \leftarrow Y_{i-1} \setminus \{u_i, 1\}$ .
10  else (with the compliment probability
    $s_{i,1}/(s_{i,0} + s_{i,1})$ ) do:
11   $X_i \leftarrow X_{i-1} \cup \{u_i, 1\}, Y_i \leftarrow Y_{i-1} \setminus \{u_i, 0\}$ .
12 return  $X_n$  (or equivalently  $Y_n$ ).
```

* If $s_{i,0} = s_{i,1} = 0$, we assume $s_{i,0}/(s_{i,0} + s_{i,1}) = 1$.

Further discussion of the Unconstrained Submodular Maximization and Submodular Max-Sat algorithms

- The Buchbinder et al [2012] online randomized $1/2$ approximation algorithm for Unconstrained Submodular Maximization (USM) cannot be derandomized into a “similar” deterministic online or priority style algorithm by a result of Huang and Borodin [2014]. Like the Poloczek result, we claimed that this was “in some sense” evidence that this algorithm cannot be derandomized.
- Their algorithm is shown to have a $\frac{3}{4}$ approximation ratio for Monotone Submodular Max-Sat.
- Poloczek et al [2017] show that the Buchbinder et al algorithm turns out to be equivalent to a previous Max-Sat algorithm by van Zuylen.

The randomized (weighted) max-sat $\frac{3}{4}$ approximation algorithm

The idea of the algorithm is that in setting the variables, we want to balance the weight of clauses satisfied with that of the weight of clauses that are no longer satisfiable.

Let S_i be the assignment to the first i variables and let SAT_i (resp. $UNSAT_i$) be the weight of satisfied clauses (resp., clauses no longer satisfiable) with respect to S_i . Let $B_i = \frac{1}{2}(SAT_i + W - UNSAT_i)$ where W is the total weight of all clauses.

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The algorithm's plan is to randomly set variable x_i so as to increase $\mathbb{E}[B_i - B_{i-1}]$.

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Let S_i be the assignment to the first i variables and let SAT_i (resp. $UNSAT_i$) be the weight of satisfied clauses (resp., clauses no longer satisfiable) with respect to S_i . Let $B_i = \frac{1}{2}(SAT_i + W - UNSAT_i)$ where W is the total weight of all clauses.

The algorithm's plan is to randomly set variable x_i so as to increase $\mathbb{E}[B_i - B_{i-1}]$.

To that end, let t_i (resp. f_i) be the value of $w(B_i) - w(B_{i-1})$ when x_i is set to true (resp. false).

The randomized max-sat approximation algorithm continued

```
For  $i = 1 \dots n$   
  If  $f_i \leq 0$ , then set  $x_i = \text{true}$   
  Else if  $t_i \leq 0$ ,  
    then set  $x_i = \text{false}$   
  Else set  $x_i$  true with probability  $\frac{t_i}{t_i + f_i}$ .  
End For
```

The randomized max-sat approximation algorithm continued

```
For  $i = 1 \dots n$ 
  If  $f_i \leq 0$ , then set  $x_i = \text{true}$ 
  Else if  $t_i \leq 0$ ,
    then set  $x_i = \text{false}$ 
  Else set  $x_i$  true with probability  $\frac{t_i}{t_i + f_i}$ .
End For
```

Consider an optimal solution (even an LP optimal) \mathbf{x}^* and let OPT_i be the assignment in which the first i variables are as in S_i and the remaining $n - i$ variables are set as in \mathbf{x}^* . (Note: \mathbf{x}^* is not calculated.)

The analysis follows as in Poloczek and Schnitger, Poloczek, and explicitly in Buchbinder et al. One shows the following:

- $t_i + f_i \geq 0$
- $\mathbb{E}[w(OPT_{i-1}) - w(OPT_i)] \leq \mathbb{E}[w(B_i) - w(B_{i-1})]$

The Buchbinder and Feldman derandomization of the USM algorithm

- Contrary to the Poloczek, (resp. Huang and B.) priority inapproximations for Max-Sat (resp. USM), there is another sense in which these algorithms can be derandomized.
- In fact the derandomization becomes an “online algorithm” in the sense that an adversary is choosing the order of the input variables. However rather than creating a single solution, the algorithm is creating a tree of solutions and then taking the best of these.
- The idea is as follows. The analysis of the randomized USM approximation bound shows that a certain linear inequality holds at each iteration of the algorithm. Namely,

$$E[f(OPT_{i-1}) - f(OPT_i)] \leq \frac{1}{2}E[f(X_i) - f(X_{i-1}) + f(Y_i) - f(Y_{i-1})]$$

That is, the expected change in restricting OPT in an iteration (by setting the i^{th} variable) is bounded by the average change in the two values being maintained by the algorithm.

Continuing the Buchbinder and Feldman derandomization idea

- These inequalities induce two additional inequalities per iteration on the distributions of solutions that can exist at each iteration.
- This then gets used to describe an LP corresponding to these $2i$ constraints we have for the distributions that hold at each iteration of the algorithm.
- But then using LP theory again (i.e. the number of non-zero variables in a basic solution). It follows that we only need distributions with support $2i$ at each iteration rather than the naive 2^i that would follow from just considering the randomized tree.
- Finally, since there must be at least one distribution (amongst the final $2n$ distributions) for which the corresponding solution is at least as good as the expected value. Thus it suffices to take the max over a “small” number of solutions.